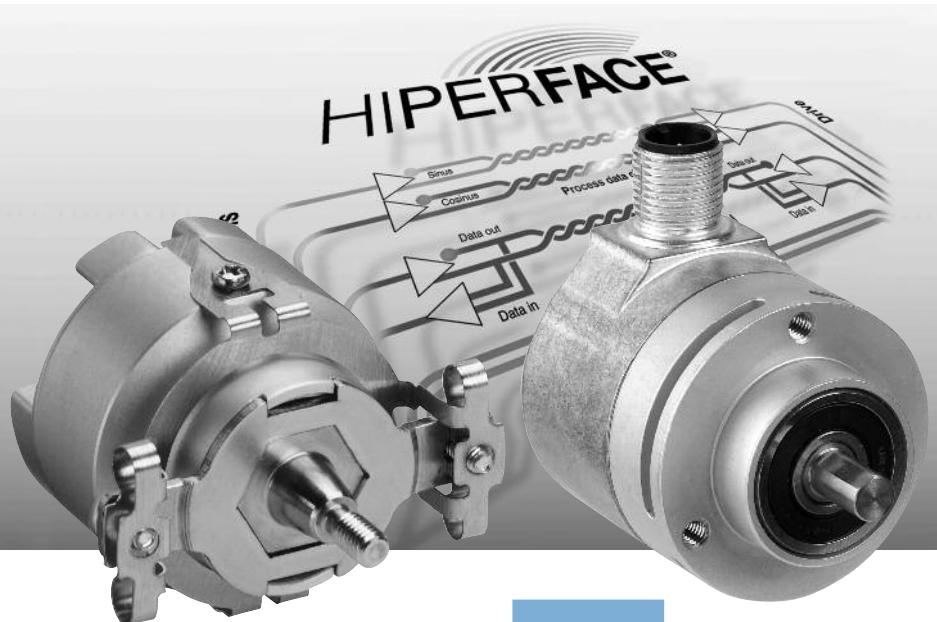


SinCos® SKS36S, SKM36S, SKS36S Standalone, SKM36S Standalone: Safety Motor Feedback Systems with HIPERFACE®- Interface for Servo Motors



 **128 sine/
cosine periods**

Motor Feedback Systems

HIPERFACE®
by SICK|STEGMANN

 Functional Safety
Type Approved
FS

TDue to their high electrical and mechanical reliability, as well as their high immunity to electromagnetic and electrostatic interference (EMC), SIL 2 certified

SKS36S/SKM36S series MFB systems are well suited for application in functional chains of safety-oriented machine functions.

The SKS36S/SKM36S encoder is the first member of a generation of optical encoders within the SinCos product range.

They all share the new Mini-Disc (MiDi) technology.

The special feature of this generation: a very small code disc of only 2 mm code track radius employs holistic (full) scanning.

In doing so, the system compensates for eccentricity errors of code disc, ball bearing and shaft which are inevitably found in conventional systems.

By arranging the code disc in the middle of the rotational axis, high angular velocities are no longer limited by the code disc. The encoder size is essentially determined by the mechanical and electrical interfaces. Technologies such as "Chip On Board" are used to achieve this. The number of components is reduced to a minimum.

The small size of the SinCos SKS36S/SKM36S enables manufacturers of miniature and subminiature motors to significantly shorten their motors.

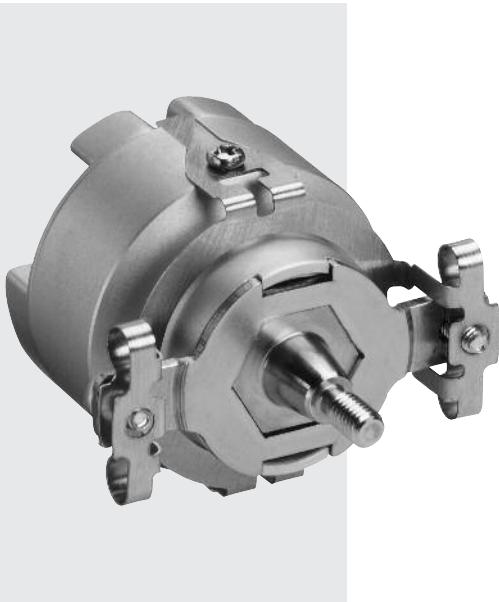
SICK|STEGMANN



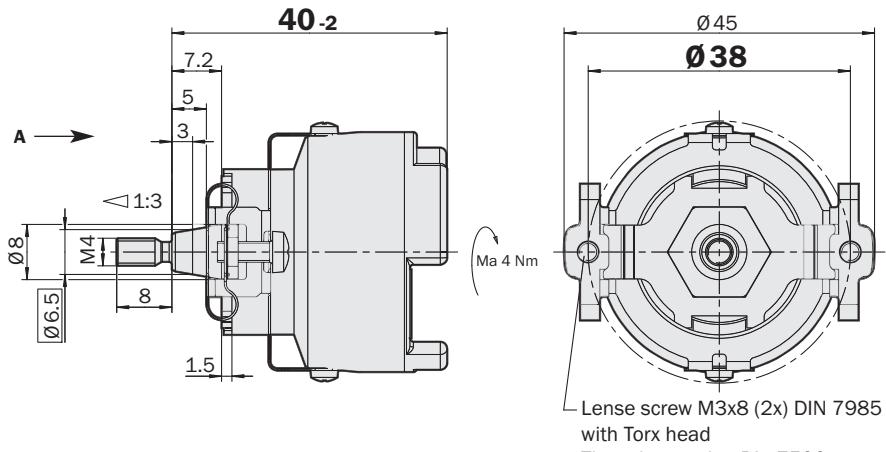
128 sine/ cosine periods

Motor Feedback Systems

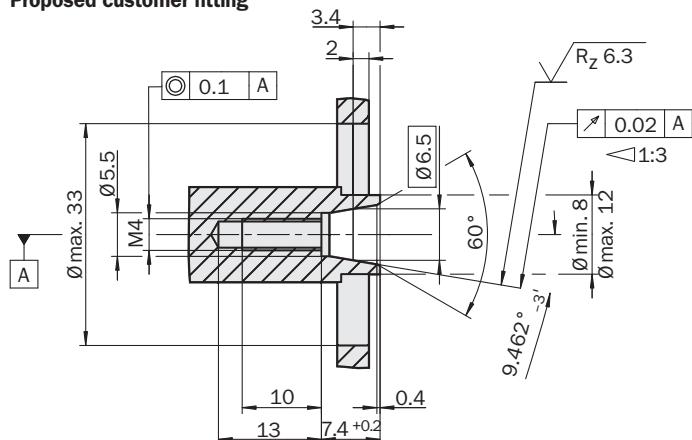
- Certified according SIL-CL2/
SIL2 (EN62061 and IEC61508)
- 128 sine/cosine periods
per revolution
- 4,096 revolutions can be
measured (multiturn)
- Programming of the
positional value
- Electronic type label



Dimensional drawing SKS36S/SKM36S



Proposed customer fitting



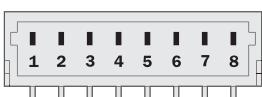
General tolerances to DIN ISO 2768-mk

PIN and wire allocation

PIN	Signal	Colour of Wires	Explanation
1	U _s	red	Supply voltage 7 ... 12 V
2	+ SIN	white	Process data channel
3	REFSIN	brown	Process data channel
4	+ COS	pink	Process data channel
5	REFCOS	black	Process data channel
6	GND	blue	Ground connection
7	Data +	grey or yellow	RS-485-parameter channel
8	Data -	green or purple	RS-485-parameter channel

The housing is electrically connected to the motor housing, via the stator coupling.

The GND (0 V) connection of the supply voltage has no connection to the housing.



View of the plug-in face

Accessories

Connection technology

Fixing technology

Programming tool

Technical Data to DIN 32878		Tapered shaft SKS36S/SKM36S	Single	Multi							
Number of sine/cosine periods per revolution	128										
Number of the absolute ascertainable revolutions	Single SKS 1 Multi SKM 4,096										
Dimensions	mm (see dimensional drawing)										
Mass	0.07 kg										
Inertial rotor moment	4.5 gcm ²										
Code type for the absolute value	Binary										
Code sequence for clockwise shaft rotation, looking in direction "A" (see dimensional drawing)	Increasing										
Measurement step at interpolation of the sine/cosine signals with e. g. 12 bits	2.5 angular seconds										
Error limits for the digital absolute value via RS 485	± 320 angular seconds										
Error limits for evaluating the "128" signals, integral non-linearity	± 80 angular seconds										
Non-linearity within a sine/cosine period differential non-linearity	± 40 angular seconds										
Output frequency for sine/cosine signals	0 ... 65 kHz										
Operating speed	SKS 12,000 min ⁻¹ SKM 9,000 min ⁻¹										
Max. angular acceleration	5 x 10 ⁵ rad/s ²										
Operating torque	0.2 Ncm										
Starting torque	0.3 Ncm										
Permissible shaft movement											
static	radial/axial	± 0.1 mm/± 0.2 mm									
dynamic	radial/axial	± 0.05 mm/± 0.1 mm									
Life of ball bearings	3.6 x 10 ⁹ revolutions										
Working temperature range	- 20 ... + 110 °C										
Storage temperature range (without packaging)	- 40 ... + 125 °C										
Permissible relative humidity	(Condensation not permissible)	90 %									
Resistance											
to shocks EN 60068-2-27	100 g/6 ms										
to vibration EN 60068-2-6	50 g/10...2000Hz										
Protection to IEC 60529¹⁾	IP 50										
EMC²⁾											
Operating voltage range	7 ... 12 V										
Recommended supply voltage	8 V										
Max. operating current, no load	60 mA										
Available memory area within EEPROM³⁾	1,792 bytes										
Interface signals											
Process data channel = SIN, REFSIN, COS, REFCOS	Analogue, differential										
Parameter channel = RS 485	Digital										
Safety data according ISO 13849											
Category (by operation at synchronous motor)	3										
Performance Level	PLd										
PFHd	1.3 * 10 ⁻⁸ [1/h]										
MTTFd	100 [a]										
Mission Time	20 [a]										
DCavg	90 %										

¹⁾ With mating connector inserted and closed cover²⁾ To DIN EN 61000-6-2 and DIN EN 61000-6-3

The EMC according to the standards quoted is achieved when the motor feedback system is mounted in an electrically conductive housing, which is connected to the central earthing point of the motor controller via a cable screen. This is also where the GND (0 V) connection of the supply voltage is linked to earth.

Users must perform their own tests when other screen designs are used.

³⁾ If applying the electronic type label, in connection with numeric controllers, attention should be paid to Patent EP 425 912 B 2; Application of the electronic type label in connection with speed regulation is exempt.

The Motor feedback system can be used in safety relevant drive systems. It fulfils the requirements for Category 3 (EN 954-1) and PL d (ISO 13849-1) or. SIL-CL 2/SIL 2 (EN 62061 and IEC 61508).

If applying safety certified HIPERFACE Motor Feedback Systems in safety relevant drive systems attention has to be paid to the implementation manual 8012332.

Ordering information

SKS36S/SKM36S Tapered shaft

Type	Part no.	Description
SKS36S-HFAO-K02	1036556	Single
SKM36S-HFAO-K02	1036558	Multi

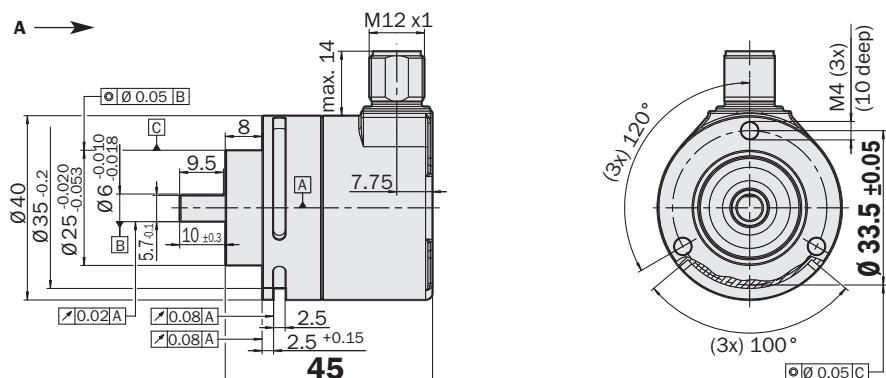


**128 sine/
cosine periods**

Motor Feedback Systems

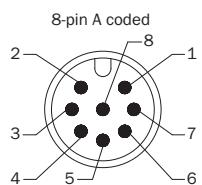
- Certified according SIL-CL2/
SIL2 (EN62061 and IEC61508)
- 128 sine/cosine periods
per revolution
- 4,096 revolutions can be
measured (multiturn)
- Programming of the
positional value
- Electronic type label

Dimensional drawing SKS36S/SKM36S Standalone, Face mount-/servo flange



General tolerances to DIN ISO 2768-mk

PIN and wire allocation



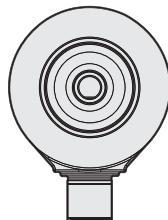
View of the plug-in face

PIN	Colour of wires	Signal	Explanation
1	brown	REFSIN	Process data channel
2	white	+ SIN	Process data channel
3	black	REFCOS	Process data channel
4	pink	+ COS	Process data channel
5	grey or yellow	Daten +	RS-485 Parameter channel
6	green or purple	Daten -	RS-485 Parameter channel
7	blue	GND	Ground connection
8	red	+ U _s	Encoder Supply voltage
		Screen	Housing potential



Connection type

Connector radial



Accessories

- Connection technology
- Fixing technology
- Programming tool

Technical Data to DIN 32878		Solid shaft 6 mm SKS36S/SKM36S	Single	Multi								
Number of sine/cosine periods per revolution		128										
Number of the absolute ascertainable revolutions		Single SKS 1 Multi SKM 4,096										
Dimensions		mm (see dimensional drawing)										
Mass		0.14 kg										
Inertial rotor moment		6 g/cm ²										
Code type for the absolute value		Binary										
Code sequence for clockwise shaft rotation, looking in direction "A" (see dimensional drawing)		Increasing										
Measurement step at interpolation of the sine/cosine signals with e. g. 12 bits		2.5 angular seconds										
Error limits for the digital absolute value via RS 485		± 320 angular seconds										
Error limits for evaluating the "128" signals, Non-linearity		± 120 angular seconds										
Output frequency for sine/cosine signals		0 ... 65 kHz										
Operating speed		6,000 min ⁻¹										
Max. angular acceleration		5 × 10 ⁵ rad/s ²										
Operating torque		0.6 Ncm										
Starting torque		0.9 Ncm										
Load capacity of shaft												
radial/axial		10 Nm/5 Nm										
Life of ball bearings		2 × 10 ⁹ revolutions										
Working temperature range		- 20 ... + 100 °C										
Storage temperature range (without packaging)		- 40 ... + 125 °C										
Permissible relative humidity		(Condensation not permissible)	90 %									
Resistance												
to shocks EN 60068-2-27		100 g/6 ms										
to vibration EN 60068-2-6		50 g/10...2000Hz										
Protection to IEC 60529¹⁾		IP 65										
EMC²⁾												
Operating voltage range		7 ... 12 V										
Recommended supply voltage		8 V										
Max. operating current, no load		60 mA										
Available memory area within EEPROM³⁾		1,792 bytes										
Interface signals												
Process data channel = SIN, REFSIN, COS, REFCOS		Analogue, differential										
Parameter channel = RS 485		Digital										
Safety data according ISO 13849												
Category (by operation at synchronous motor)		3										
Performance Level		PLd										
PFHd		1.3 * 10 ⁻⁸ [1/h]										
MTTFd		100 [a]										
Mission Time		20 [a]										
DCavg		90 %										



The Motor feedback system can be used in safety relevant drive systems. It fulfills the requirements for Category 3 (EN 954-1) and PL d (ISO 13849-1) or. SIL-CL 2/SIL 2 (EN 62061 and IEC 61508).

If applying safety certified HIPERFACE Motor Feedback Systems in safety relevant drive systems attention has to be paid to the implementation manual 8012332.

¹⁾ With mating connector inserted

²⁾ To DIN EN 61000-6-2 and DIN EN 61000-6-3

³⁾ If applying the electronic type label, in connection with numeric controllers, attention should be paid to Patent EP 425 912 B 2; Application of the electronic type label in connection with speed regulation is exempt.

Ordering information

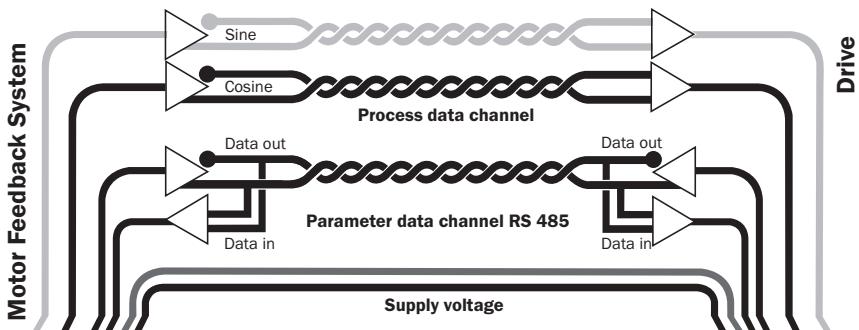
SKS36S/SKM36S, Standalone; Solid shaft 6 mm; Face mount-/servo flange

Type	Part no.	Description
SKS36S-HVAO-K02	1036557	Single; EEPROM 2048; Connector
SKM36S-HVAO-K02	1036559	Multi; EEPROM 2048; Connector



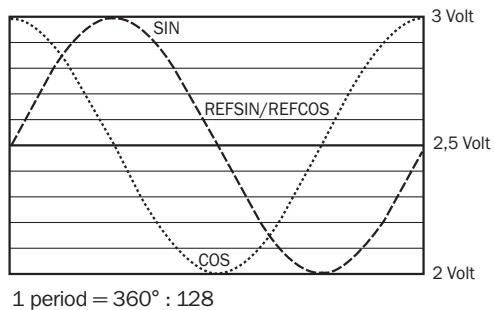
Electrical interface

- Safe data transmission
- High information content
- Electronic type label
- Only 8 leads
- Bus-enabled parameter channel
- Process data channel in real time



Signal specification of the process data channel

Signal diagram for clockwise rotation of the shaft, looking in direction "A"



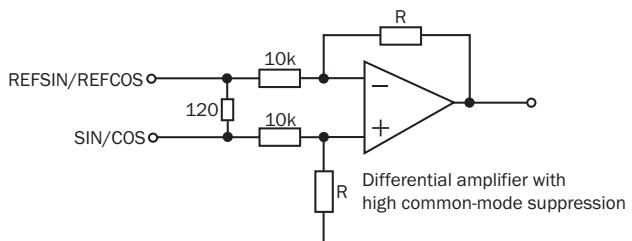
Access to the process data used for speed control, i.e. to the sine and cosine signals, is practically always "online". When the supply voltage is applied, the speed controller has access to this information at any time.

Sophisticated technology guarantees stable amplitudes of the analogue signals across all specified environmental conditions, with a maximum variation of only 30 %.

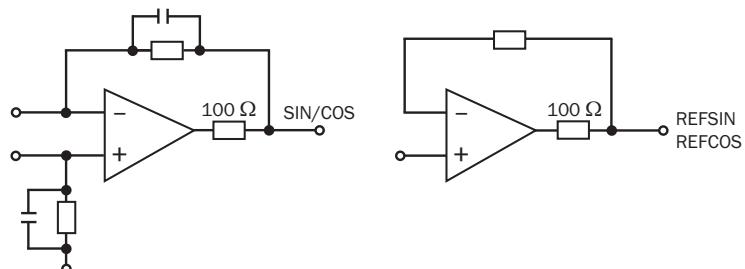
Characteristics applicable to all permissible environmental conditions

Signal	Value/Units
Signal peak, peak V_{ss} of SIN, COS	0.8 ... 1.1 V
Signal offset REFSIN, REFCOS	2.2 ... 2.8 V

Recommended receiver circuit for sine and cosine signals



The output circuit of the process data channel within the SinCos encoder





by SICK STEGMANN

Type-specific settings	SKS	SKM
Type ID (command 52h)	32h	37h
Free EEPROM [bytes]	1,792	1,792
Address	40h	40h
Mode_485	E4h	E4h
Codes 0 ... 3	55h	55h
Counter	0	0

Overview of commands supported		
Command byte	Function	Code 0 ¹⁾
42h	Read position	
43h	Set position	•
44h	Read analogue value	
		Channel number 48h
46h	Read counter	
47h	Increase counter	
49h	Reset counter	•
4Ah	Read data	
4Bh	Save data	
4Ch	Determine status of a data field	
4Dh	Create data field	
4Eh	Determine available memory area	
4Fh	Change access code	
50h	Read encoder status	
52h	Read out name plate	
53h	Encoder reset	
55h	Allocate encoder address	•
56h	Read serial number and program version	
57h	Configure serial interface	•

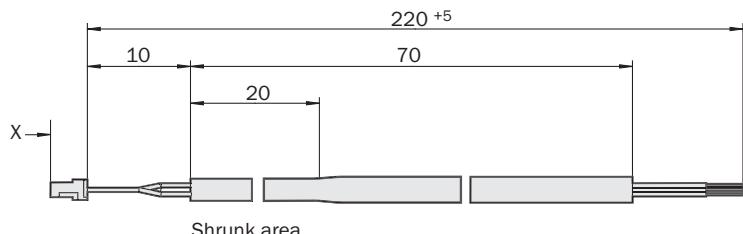
- ¹⁾ The commands thus labelled include the parameter "Code 0".
 Code 0 is a byte inserted into the protocol, for additional safeguarding of vital system parameters against accidental overwriting.
 When shipped, "Code 0" = 55h.

Overview of status messages				
Error type	Status code	Description	SKS	SKM
	00h	The encoder has recognised no error	•	•
Initialisation	01h	Faulty compensating data	•	•
	02h	Faulty internal angular offset	•	•
	03h	Data field partitioning table damaged	•	•
	04h	Analogue limit values not available	•	•
	05h	Internal I ² C bus not operational	•	•
	06h	Internal checksum error	•	•
Protocol	07h	Encoder reset occurred as a result of program monitoring	•	•
	09h	Parity error	•	•
	0Ah	Checksum of the data transmitted is incorrect	•	•
	0Bh	Unknown command code	•	•
	0Ch	Number of data transmitted is incorrect	•	•
	0Dh	Command argument transmitted is not allowed	•	•
Data	0Eh	The selected data field must not be written to	•	•
	0Fh	Incorrect access code	•	•
	10h	Size of data field stated cannot be changed	•	•
	11h	Word address stated, is outside data field	•	•
	12h	Access to non-existent data field	•	•
Position	01h	Analogue signals outside specification		
	1Fh	Speed too high, no position formation possible		
	20h	Singleturn position unreliable	•	•
	21h	Positional error Multiturn		
	22h	Positional error Multiturn		
	23h	Positional error Multiturn		
Other	1Ch	Monitoring the value of the analogue signals (process data)		
	1Dh	LED current critical (dirt, LED breakage)	•	•
	1Eh	Encoder temperature critical	•	•
	08h	Counter overflow	•	•

Dimensional drawings and ordering information

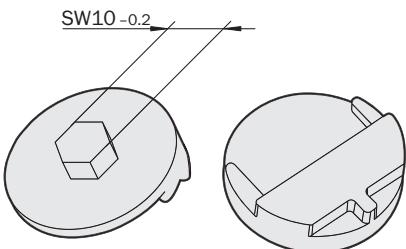
Stranded cable/connector, straight, 8 wires, 8 x 0.15 mm²

Type	Part no.	Contacts	Wire length
DOL-0J08-GOM2XB6	2031086	8	0.2 m



Assembly tool

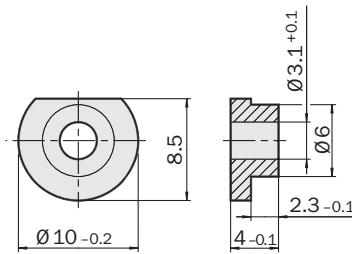
Type	Part no.	Description
BEF-MW-SKX36	2031079	Assembly tool SKX36



General tolerances according to DIN ISO 2768-mk

Servo clamps, Set (comprises 3 pieces)

Type	Part no.	Description
BEF-WK-RESOL	2039082	Servo clamp



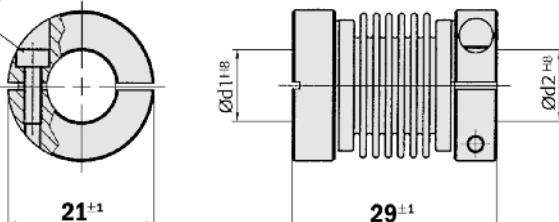
General tolerances according to DIN ISO 2768-mk

Couplings

**Bellows coupling, max. shaft offset radial ± 0.3 mm, axial 0.4 mm,
angle ± 4 degrees, torsion spring stiffness 120 Nm/rad,
bellows of stainless steel, hubs of aluminium**

Type	Part no.	Shaft diameter
KUP-0606-B	5312981	6 mm ... 6 mm
KUP-0610-B	5312982	6 mm ... 10 mm

Cheese-head screw
M2.5x8 DIN912 A2



Programming tool for HIPERFACE® devices

Type	Part no.	Motor Feedback System
PGT-03-S	1034252	SKS36S/SKM36S

Dimensional drawings and ordering information

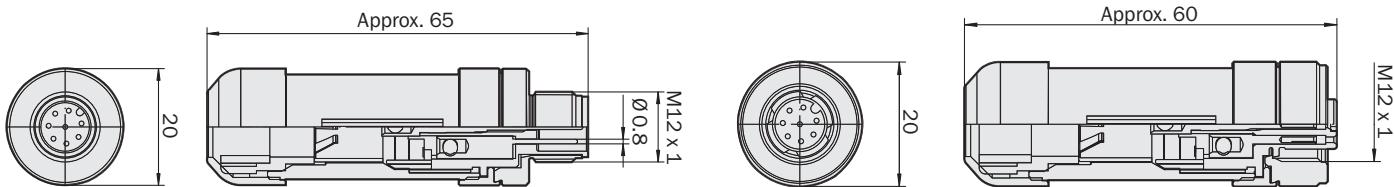
Round screw system M12

Loose male connector M12, 8-pin, straight, screened,
for field assembly (adapter side)

Type	Part no.	Contacts/cable diameter
STE-1208-GA	6028370	8 / 4 ... 8 mm

Loose female connector M12, 8-pin, straight, screened,
for field assembly (encoder side)

Type	Part no.	Contacts/cable diameter
DOS-1208-GA	6028369	8 / 4 ... 8 mm

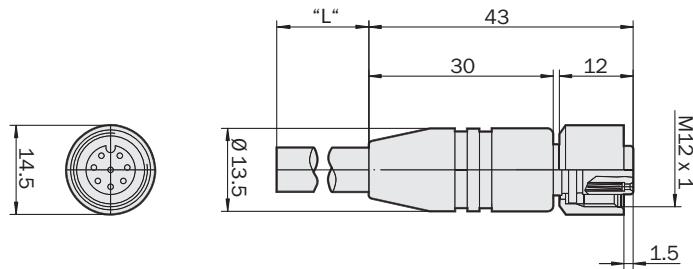
Cable HIPERFACE®, 8-wire, per metre 4 x 2 x 0.15 mm²

Type	Part no.	Wires
LTG-2708-MW	6028361	8

Female connector M12, 8-pin, straight, pre-wired with cable

8-wire, 4 x 2 x 0.25 mm², screened, flexible (adapter side)

Type	Part no.	Contacts	Cable length
DOL-1208-G02MAC1	6032866	8	2.0 m
DOL-1208-G05MAC1	6032867	8	5.0 m
DOL-1208-G10MAC1	6032868	8	10.0 m
DOL-1208-G20MAC1	6032869	8	20.0 m

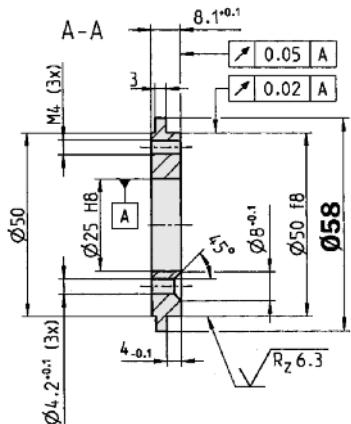
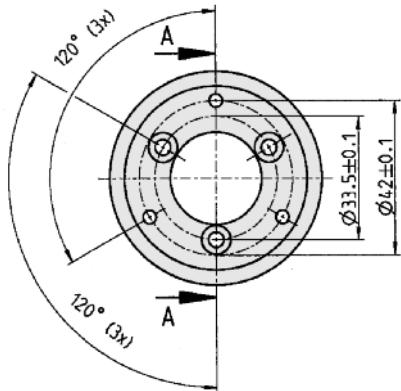


Dimensional drawings and ordering information

Mechanical Adaptors

Adaptor flange of aluminium for face mount flange, spigot 25 mm

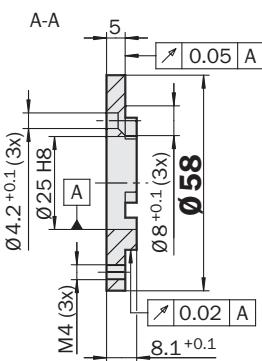
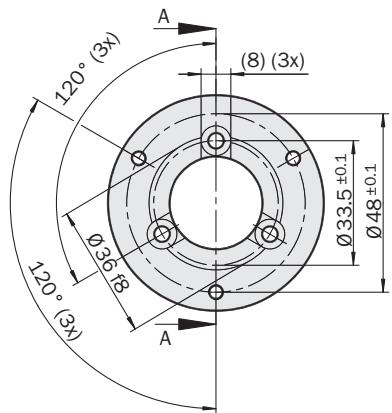
Type	Part no.	Adaption
BEF-FA-025-050	2032622	To 50 mm servo flange



General tolerances according to DIN ISO 2768-mk

Adaptor flange of aluminium for face mount flange, spigot 25 mm

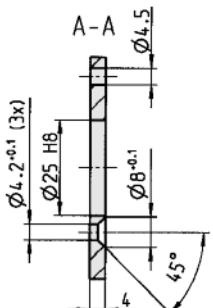
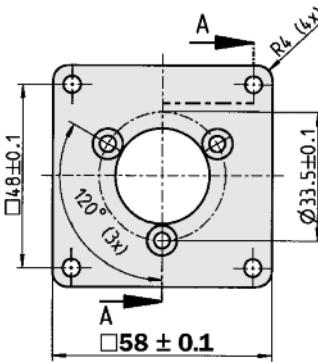
Type	Part no.	Adaption
BEF-FA-025-036	2034226	To 36 mm face mount flange



General tolerances according to DIN ISO 2768-mk

Adaptor flange of aluminium for face mount flange, spigot 25 mm

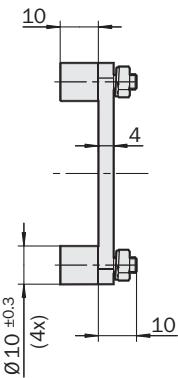
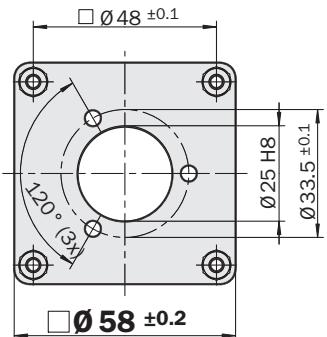
Type	Part no.	Adaption
BEF-FA-025-060RCA	2032623	To 60 mm square mounting plate



General tolerances according to DIN ISO 2768-mk

Adaptor flange of aluminium for face mount flange, spigot 25 mm

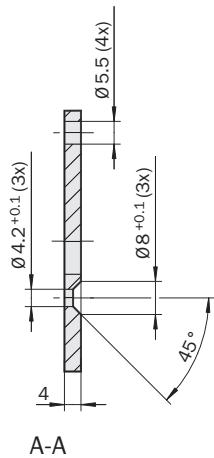
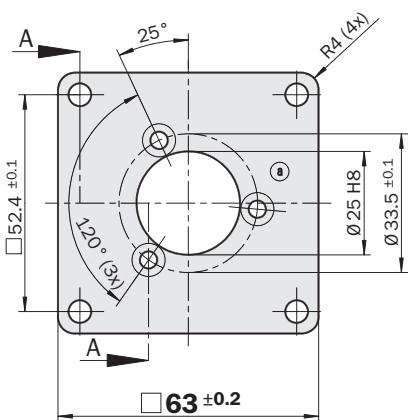
Type	Part no.	Adaption
BEF-FA-025-060RSA	2032624	To 60 mm square mounting plate with shock absorbers



General tolerances according to DIN ISO 2768-mk

Adaptor flange of aluminium for face mount flange, spigot 25 mm

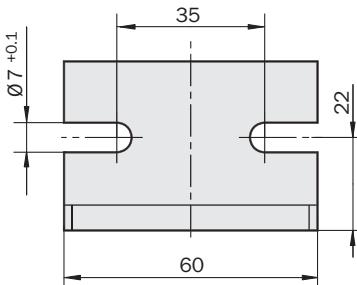
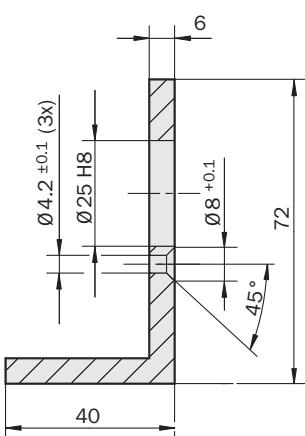
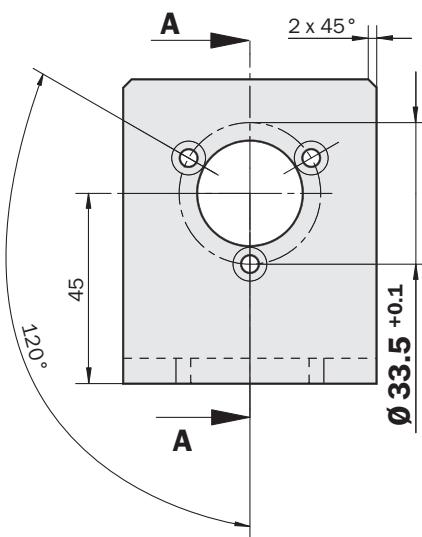
Type	Part no.	Adaption
BEF-FA-025-063REC	2033631	To 63 mm square mounting plate



General tolerances according to DIN ISO 2768-mk

Mounting angle incl. fixing set for encoder with face mount flange

Type	Part no.	Flange spigot
BEF-WF-25	2032621	Diameter 25 mm



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