Features

With holding torques to 5700 oz-in (356 lb-in), the N and K Series provide the highest torques per frame size in the industry—more than 3 and 5 phase designs.

- Improved torque linearity (above rated current) provides high peak torque capability (duty cycle dependent, contact factory)
- High torque at moderate speeds
- Low detent torque harmonic
- K Series uses Sigmax™ technology to develop 25% more torque than N Series
- Runs cooler than comparable steppers using identical drive parameters
- Special rotor design for high acceleration
- Rugged "housingless" square frame
- Sealed per IP65
- Outer bearing races won’t turn—front locked (in steel insert) and rear held by O-ring
- Extensive selection of shaft configurations, terminations, standard and special windings
- Two phase design
- Optional encoder mounting provisions

Benefits

- Optimized magnetics provide maximum performance in small envelope, reducing space required for the motor.
- Acceleration boost to move loads even faster. Provides more torque for intermittent duty applications.
- Cost effective alternative to servo motors
- Provides smoother microstepping performance
- Select from broad performance range to meet your requirement
- Longer, more reliable motor life—backed by a two year warranty
- Move/position loads fast
- Efficient use of volume for optimal magnetic circuit
- For splashproof requirements
- Long life bearings—also prevents axial shaft movement for encoder applications
- Match your requirements
- Compatible with most drivers, smoother microstepping, and lower input power required vs. three phase for same torque
- Optimizes control scheme

LEADWIRE HOOKUP MODELS

(SPLASHPROOF CONSTRUCTION-TERMINAL BOARD CONNECTIONS)

Motor | L MAX |
--- | --- |
41xx | (98.81) | 4.02 |
42xx | (121.11) | 4.91 |
43xx | (201.11) | 7.92 |

Motor | L MAX |
--- | --- |
41xx | (113.28) | 4.46 |
42xx | (164.59) | 6.48 |
43xx | (215.65) | 8.49 |

Motor | X | L MAX |
--- | --- | --- |
41xx | (113.28) | 4.46 |
42xx | (164.59) | 6.48 |
43xx | (215.65) | 8.49 |

Motor | X | L MAX |
--- | --- | --- |
41xx | (113.28) | 4.46 |
42xx | (164.59) | 6.48 |
43xx | (215.65) | 8.49 |

Motor | X | L MAX |
--- | --- | --- |
41xx | (113.28) | 4.46 |
42xx | (164.59) | 6.48 |
43xx | (215.65) | 8.49 |

Motor | X | L MAX |
--- | --- | --- |
41xx | (113.28) | 4.46 |
42xx | (164.59) | 6.48 |
43xx | (215.65) | 8.49 |

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42xx | (164.59) | 6.48 |
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42xx | (164.59) | 6.48 |
43xx | (215.65) | 8.49 |

Motor | X | L MAX |
--- | --- | --- |
41xx | (113.28) | 4.46 |
42xx | (164.59) | 6.48 |
43xx | (215.65) | 8.49 |
### PACIFIC SCIENTIFIC N&K-SERIES NEMA 42 HIGH TORQUE MOTORS

#### RATINGS AND CHARACTERISTICS

Motor parameters and winding data.

<table>
<thead>
<tr>
<th>Model Number ±10% (amps DC)</th>
<th>Leadwire Motor oz-in (N-m)</th>
<th>Typical oz-in (N-m)</th>
<th>Rated Inductance</th>
<th>Detent Torque</th>
<th>Thermal Resistance</th>
<th>Rotor Inertia oz-in² (kgm² x 10⁻³)</th>
<th>Net Weight kg (lbs)</th>
</tr>
</thead>
<tbody>
<tr>
<td>K41HRF</td>
<td>4320 (20.48)</td>
<td>9.9</td>
<td>0.28</td>
<td>7.5</td>
<td>0.0783</td>
<td>10.66</td>
<td>11.64</td>
</tr>
<tr>
<td>K42HRF</td>
<td>4365 (20.81)</td>
<td>9.9</td>
<td>0.28</td>
<td>7.5</td>
<td>0.0783</td>
<td>10.66</td>
<td>11.64</td>
</tr>
</tbody>
</table>

#### MOTOR PARAMETERS AND WINDING DATA

**RATINGS AND CHARACTERISTICS**

With rated current applied.

**Refer to Selection Guide for more information.**

**All ratings typical and at 25°C unless otherwise noted.**

**Windings at 130°C and motor in still air at 40°C (without heat sink). Operation of these motors above rated current may cause demagnetization. Contact factory.**

**Small signal inductance as measured with impedance bridge at 1 kHz, 1 amp.**

**Thermal resistance measured with motor hanging in still air (unmounted).**

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**MOTIONEERING® CD-ROM**

For more detailed product and selection information, see the MOTIONEERING® CD-ROM inside the back cover of this catalog or visit our website at www.DanaherMotion.com.
The performance information shown in the torque/speed curves that follow show the N & K series of NEMA 42 step motors with windings, connections and current levels selected for maximum performance with the drives shown on this page. For additional assistance in sizing or selecting the stepper system appropriate for your application, contact Danaher Motion Customer Support at 815-226-2222.

**6410/6415 Microstepping Drives** SEE PAGE 72
- 24-75 VDC input
- Step/direction input or oscillator models
- Current selectable from 0.625 to 7.1 amps peak
- Selectable step sizes, binary or decimal, full to 1/250 or 1/256

**Impulse Microstepping Drives** SEE PAGE 75
- 90-120 VAC input, 160 VDC bus
- Step/direction input
- Programmable inputs/outputs
- Current selectable from 0.75 to 4.0 amps
- Microstepping 200 to 100,000, selectable in increments of 200

**NextStep® Microstepping Drives** SEE PAGE 76
- 90-120 VAC input, 160 VDC bus, 240 V model available
- Step/direction input
- Current selectable from 0 to 7.9 amps, to 3.9 A for 240 V model
- 5,000 steps/rev to 50,000 steps/rev microstepping

**SMARTSTEP Microstepping Drives** SEE PAGE 77
- 90-120 VAC input, 160 VDC bus, 240 V model available
- Programmable indexing
- Current selectable from 0 to 7.9 amps, to 3.9 A for 240 V model
- 36,000 steps/rev microstepping