

# DIRECT DRIVE DC MOTORS



**KOLLMORGEN**

Inland Motor



# INTRODUCTION

The direct-drive DC torque motor is a servo actuator which can be directly attached to the load it drives. It has a permanent magnet (PM) field and a wound armature which act together to convert electrical power to torque. This torque can then be utilized in positioning or speed-control systems. In general, torque motors are designed for three different types of operation:

- 1) high stall torque ("stand-still" operation) for positioning systems;
- 2) high torque at low speeds for speed-control systems, and
- 3) optimum torque at high speed for positioning, rate, or tensioning systems.

## FEATURES of DIRECT-DRIVE DC TORQUE MOTORS

Direct-drive torque motors are particularly suited for servo-system applications where it is desirable to minimize size, weight, power and response time, and to maximize rate and position accuracies. Torque motors have the following important advantages over other servo-system actuators.

### High Torque-to-Inertia Ratio at the Load

A direct-drive motor provides the highest practical torque-to-inertia ratio where it counts — at the load. Because the torque motor is mounted directly on the driven shaft or is directly coupled to the load, there is no gear train. In a geared system, reflected output torque is proportional to the gear reduction while reflected output inertia is proportional to the square of the gear reduction. Thus, the torque-to-inertia ratio in a geared system is less than that of a gearless system by a factor equal to the gear-train ratio. The higher torque-to-inertia ratio of direct-drive motors makes them ideally suited for high acceleration applications with rapid starts and stops.

### High Torque-to-Power Ratio

Most torque motors are designed with a large number of poles and a high volume of

copper to achieve a high torque-to-power ratio. Thus, input power requirements are usually low.

### Low Electrical Time Constant

Typical torque motor design features — such as high-level magnetic saturation of the armature core and the use of a large number of poles — keep armature inductance at very low values. Consequently, the electrical time constant (the ratio of armature inductance to armature resistance) is very low, allowing the motor to respond rapidly at all operating speeds.

### High Linearity

In a DC torque motor, torque increases directly with input current at all speeds and angular positions. The theoretical speed-torque characteristic is a set of parallel straight lines (See Figure 1-1). This torque linearity is maintained even at low excitation, assuring no dead-band created by torque non-linearities.

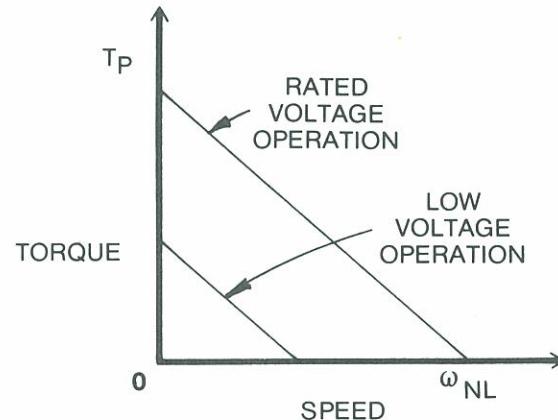


Figure 1-1

### Reliability and Long Life

Basic simplicity and an absolute minimum of moving parts make a torque motor inherently reliable. Extensive design and production experience have placed Inland's motors in most major defense programs in the last two decades. These include applications in all conditions and environments, ranging from thousands of feet underwater to years of unattended operation in outer space.

## **Compact, Adaptable Design**

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Frameless torque motors are built to be “designed-in” as an integral part of a system, thus saving the weight and space associated with conventional motor frames or housings. This frameless design allows the motors to be mounted anywhere along the driven shaft. The “pancake” configuration (thin, compared to diameter) minimizes the volume required for mounting and offers a convenient packaging arrangement for combinations of torque motors and tachometer generators.

Inland also supplies housed motors, complete with housing, shaft and bearings for use in similar applications.

## **SYSTEM PERFORMANCE CHARACTERISTICS**

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The same features which give torque motors an advantage over other types of servo actuators also allow the designer to obtain the following system performance characteristics:

### **High Servo Stiffness**

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The direct-drive torque motor is coupled directly to the load, thus eliminating gears and backlash errors. The resulting high coupling stiffness and associated high mechanical resonance frequency yield high servo stiffness.

### **Fast Response**

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The low electrical time constant of torque motors allows torque to develop very rapidly when voltage is applied. This fast response is an important aid to servo stiffness.

### **High Resolution**

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The direct-drive use of torque motors allows them to position a shaft more precisely than a geared system. With typical gearing, the backlash contributes to a “dead zone” which falls in the region of the system null point and reduces positional accuracy. In a direct-drive system, however, the positional accuracy is, in practice, limited only by the error-detecting transducer system.

### **Low Speeds with High Accuracy**

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Because of the high coupling stiffness and high resolution of direct-drive torque motors, it is possible to achieve high accuracy at low speeds. An example is a table for testing rate and integrating gyros. This table has a speed range of 0.017 rpm to 100 rpm with absolute

instantaneous accuracy over this speed range of 0.1 percent.

## **Smooth, Quiet Operation**

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Torque motors exhibit smooth, quiet operation when they are run at low speeds. They typically have a large number of slots per pole to reduce cogging and allow for smooth operation.

## **MOTOR SELECTION**

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### **Frameless or Housed?**

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Both the torque motor section and the servo motor section of this catalog are divided into subsections of frameless motors and housed motors.

Housed motors have a traditional configuration including frame, bearings and shaft. In use, the housed motor shaft is coupled to the system element being driven. Housed motors are ideal for use in harsh environments or other applications requiring totally closed units.

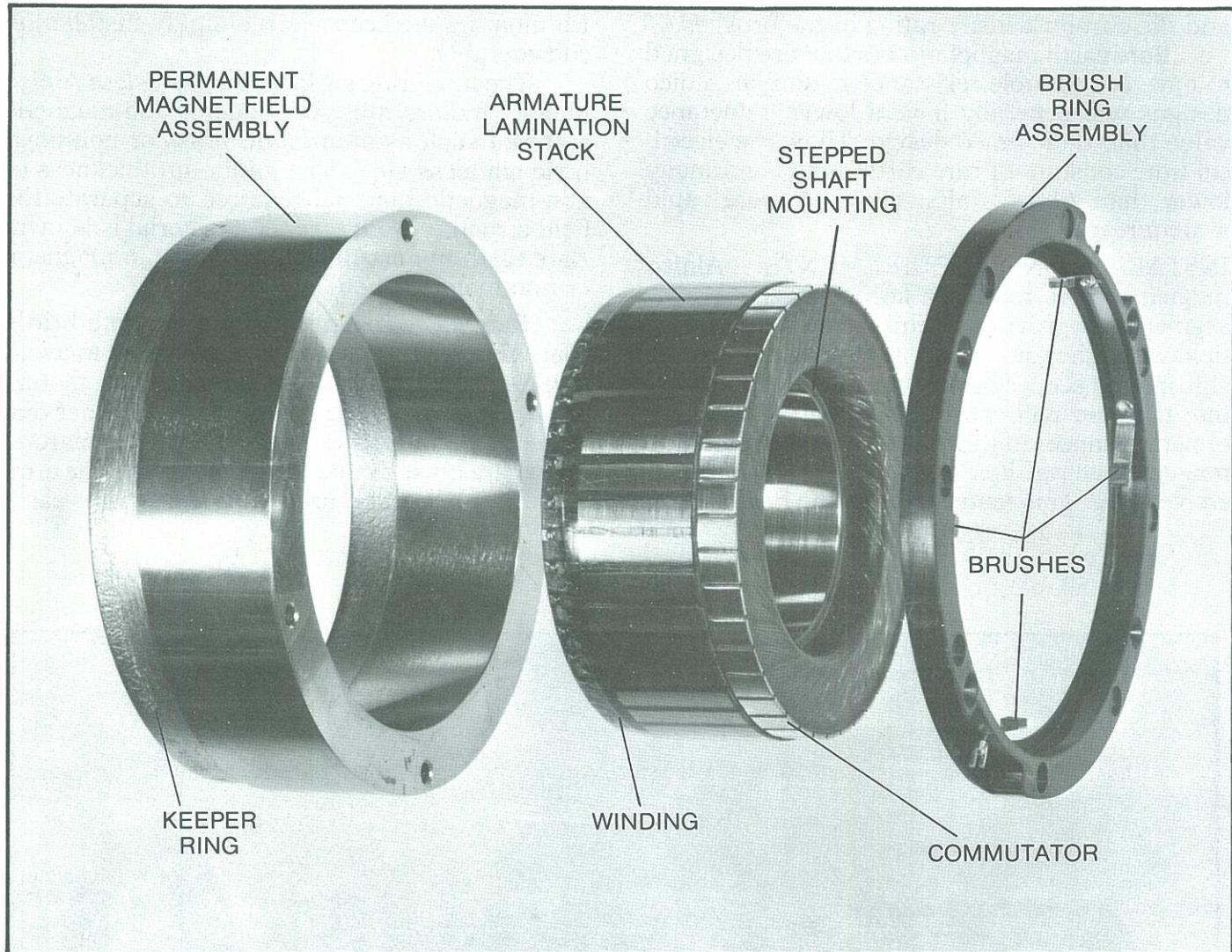
The frameless motor concept was developed to meet the need for motors with a large hole through the center. This need is still one of the main reasons that the large diameter, narrow width frameless configuration is often selected over the traditional housed configuration. The large rotor bore can be used as a route for lead wires, as a mounting area for other hardware such as tachometer generators or resolvers, or as an optical path.

Frameless motors are built to be “designed in” as an integral part of the system hardware. They are generally supplied as three separate components: stator (field) assembly, rotor (armature) assembly and brush ring or brush segment assembly (See Figures 1-2, 1-3). The frameless motor can be integrated into the customer hardware rather than coupling a motor shaft to the element being driven. This allows significant savings in space and weight over housed motors by eliminating the motor housings, bearings and shaft. Also, since the frameless motor can be mounted on the driven shaft, the coupling stiffness is improved. The backlash normally associated with couplings or gear trains is eliminated from the drive system.

### **Torque Motor or Servo Motor?**

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A torque motor is typically described as having a “pancake” configuration, i.e., a large diameter and a narrow width. This configuration generally has a large number of poles to increase the torque available in a given volume. This large number of poles, however, also causes more commutation arcing as speed increases than for a motor with few poles. Torque motors are most



**Figure 1-2**

Details of a frameless Alnico torque motor, showing hole for axial-shaft mounting.

commonly used in positioning and slow-speed rate applications where commutation is not a limitation.

A servo motor is characterized by a long, small diameter configuration. Lengthening a motor while maintaining a small diameter allows a significant increase in torque while minimizing the increase in rotor inertia. The end result is an improved mechanical time constant and, therefore, improved motor response. Servo motors are most commonly used in running applications where good high-speed commutation is demanded and operation at or near stall is not required.

### Magnet Material?

The motors in this catalog are manufactured with one of two magnet materials: Alnico or rare earth (Samarium Cobalt). Model numbers pre-

ceded by "T", "NT" or "OT" have Alnico magnets and models preceded by "QT" have rare earth magnets. These magnet materials have different characteristics which determine their suitability for various applications. This section will examine the differences in magnet material in the areas of performance, installation requirements, leakage flux, and weight and volume.

**PERFORMANCE:** A major advantage of rare earth magnet motors is maintenance of magnetic characteristics in overcurrent conditions. In Alnico magnet motors, exceeding the rated current  $I_P$  to develop more torque may demagnetize the permanent magnet field and cause a permanent reduction in torque per unit current. The degree of demagnetization is determined by the magnitude of the overload current. In rare earth magnet units, currents in excess of  $I_P$  can be applied for short duration to develop higher torque with-

out demagnetization of the PM field. The limits now become the thermal capacity of the motor and the current density rating of the brushes.

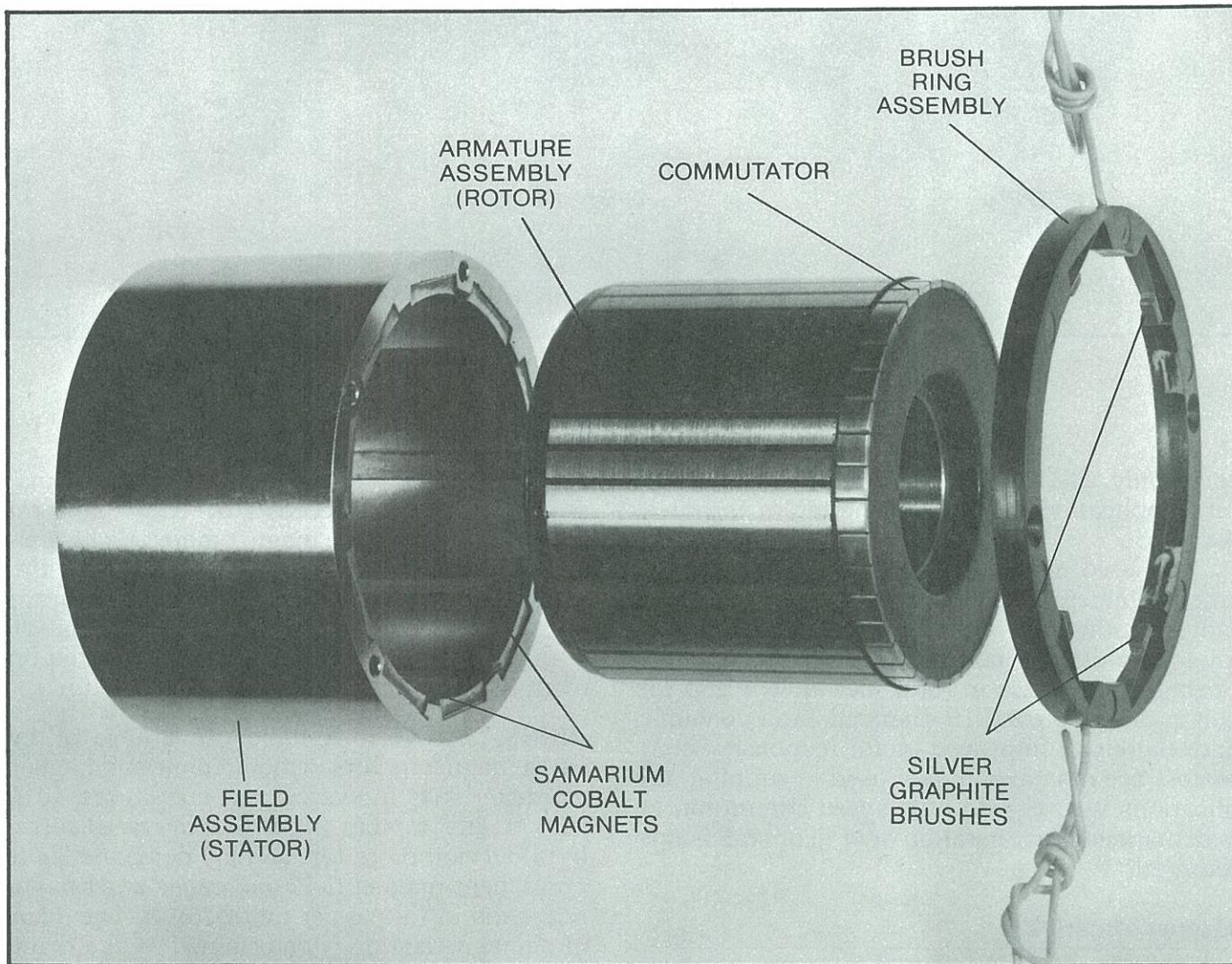
Rare earth magnet motors that are designed to have comparable resistance to similar Alnico designs will generally have a lower inductance value than that Alnico design. Thus, the electrical time constant of rare earth units is normally lower than Alnico units, allowing more rapid system response.

**INSTALLATION REQUIREMENTS:** Alnico magnet motors require a keeper ring or keeper segments to provide a return flux path for the field when the rotor is not in place. Removing or shifting the keeper before inserting the armature into the field will cause significant degradation of performance. In rare earth magnet motors the magnet material has much higher intrinsic coercive force. This feature makes the field assem-

bly immune to the effects of an open magnetic circuit and therefore a keeper is not required. Eliminating the keeper can simplify installation considerably.

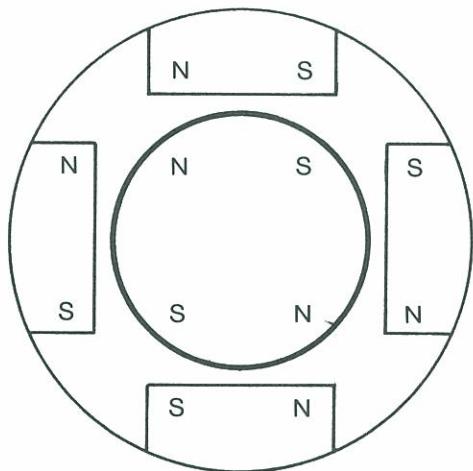
The mounting surfaces for frameless Alnico magnet motors must be made of non-magnetic material such as aluminum, brass or non-magnetic stainless steel. The minimum thickness of non-magnetic material required to separate the field structure from magnetic material is  $\frac{1}{4}$  inch. Rare earth motors may be mounted in magnetic or non-magnetic housings.

Rare earth magnet material is more brittle than Alnico, and care must be exercised to avoid chipping or cracking. Because rare earth motors are designed with the magnets on the inner diameter of the stator assembly facing the armature, extra care must be taken when inserting the armature into the field assembly. Most rare earth



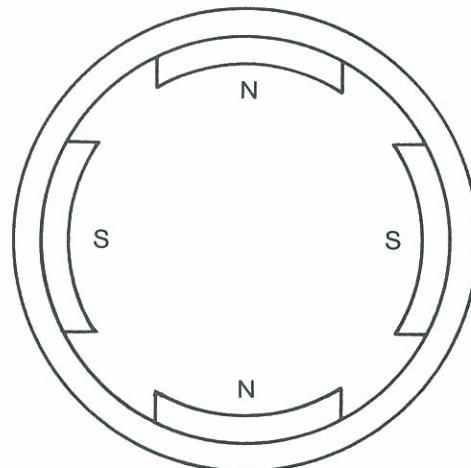
**Figure 1-3**  
Details of a frameless rare earth torque motor.

units have larger radial air gaps than similar size Alnico units. The larger air gap of rare earth units makes rotor-to-stator concentricity less critical (See Figure 1-4).



ALNICO DESIGN

Alnico and rare earth field designs.



RARE EARTH DESIGN

Figure 1-4

**LEAKAGE FLUX:** In the rare earth field assembly design, the magnets are magnetized in a radial direction. The Alnico field assembly is magnetized in a circumferential direction. The radial orientation of the rare earth design, along with the unique properties of the magnet material, combine to reduce the leakage flux in the motor. This not only improves the motor performance because motor flux is retained within the magnetic circuit of the motor, but there is also a much lower flux density around the outside of the motor. There is, therefore, less interference in surrounding wires, electronics and electromagnetic devices.

**WEIGHT AND VOLUME:** Alnico motors have a maximum torque available from a given volume because the magnets will demagnetize if the peak current ( $I_p$ ) is exceeded. To increase the torque available the motor volume must be increased. Typically, this is accomplished by increasing the diameter or the length of the motor. As the volume increases, so does the weight.

Rare earth motor designs can produce more torque per volume than Alnico designs of the same dimensions. This occurs because rare earth units can be designed with a thinner stator assembly. The rotor therefore has a larger diameter while the outer diameter of the stator remains the same. Such a motor with an increased rotor diameter will produce more torque than an Alnico design of the same dimensions for the same input power.

A comparison between Alnico and rare earth designs is possible using three motors from the catalog.

The T-7203, an Alnico design, is rated for 22 lb.ft. If more torque is required, a larger motor must be used. Assuming a particular application requires 40 lb.ft., the T-9902 can be used.

A comparison of the two follows:

	T-7203	T-9902
Peak Torque (lb.ft.)	22	40
Power (watts)	530	512
Motor Constant (lb. ft. / $\sqrt{\text{watt}}$ )	0.96	1.77
Outer Diameter (in.)	9.00	12.00
Inner Diameter (in.)	5.157	8.00
Length (in.)	2.562	2.500
Weight (lbs.)	18.3	32.3

By using a rare earth design to provide the 40 lb.ft. of torque, the QT-7801 can be used within the same dimensions as the T-7203. Our comparison is now expanded to include the rare earth design:

	T-7203	QT-7801	T-9902
Peak Torque (lb.ft.)	22	40	40
Power (watts)	530	800	512
Motor Constant (lb. ft. / $\sqrt{\text{watt}}$ )	0.96	1.41	1.77
Outer Diameter (in.)	9.00	9.00	12.00
Inner Diameter (in.)	5.157	5.157	8.00
Length (in.)	2.562	2.396	2.500
Weight (lbs.)	18.3	20	32.3

The rare earth design requires an increase in power and a slight increase in weight, but will provide significantly improved torque-to-weight and torque-to-volume ratios. This is due not only to the capability of momentary excess current without demagnetization, but also the

improved motor constant ( $K_M$ ) which results from a larger rotor diameter and a higher flux density.

### Size Constants

There are fourteen motor parameters, or size constants, listed on the individual data page for each motor. These parameters are dependent upon the size and shape of the model, but are independent of the winding used. Following is a brief description of each parameter.

**PEAK TORQUE ( $T_P$ )** is the nominal value of developed torque with the rated current  $I_P$  applied to the motor. In Alnico magnet motors, exceeding the rated current  $I_P$  to develop more torque may demagnetize the permanent magnet (PM) field and cause a permanent reduction in torque per unit current. The extent of demagnetization is determined by the magnitude of the overload current. In rare earth magnet units, however, currents in excess of  $I_P$  can be applied to develop higher torque without demagnetization of the PM field.

**POWER INPUT, STALLED AT  $T_P$  ( $P_P$ )** is the value of  $I^2R$  power when the armature resistance  $R_M$  is measured at 25°C and the current is  $I_P$ .

**MOTOR CONSTANT ( $K_M$ )** is the ratio of peak torque to the square root of power input at stall and 25°C;

$$K_M = \frac{T_P}{\sqrt{P_P}}.$$

This ratio is useful during the initial selection of a motor because it indicates the ability of a motor to convert electrical power into torque.  $K_M$  also defines the slope of the developed torque versus speed characteristic at constant voltage, which is

$$F_0 = \frac{T_P}{\omega_{NL}} \quad \text{where} \quad F_0 = 1.356 K_M^2$$

with torque in pound-feet.

**NO LOAD SPEED** at  $V_P$  ( $\omega_{NL}$ ) is the theoretical speed at which a motor will operate without any external load and with nominal voltage  $V_P$  applied. The actual value of no load speed is slightly less than  $\omega_{NL}$  because of the effects of brush friction and magnetic drag ( $T_f$ ) and the effects of viscous drag ( $F_I \omega$ ).

**ELECTRICAL TIME CONSTANT ( $\tau_E$ )** is the ratio of armature inductance  $L_M$  to armature resistance  $R_M$ . This value of time constant is a maximum because it applies only if the motor power source has negligible impedance. Usually,

the inductance in a power source is negligible but the power source resistance  $R_S$  is not negligible. Then the applicable time constant is

$$\frac{L_M}{R_M + R_S}$$

which is less than  $\tau_E$ .

**STATIC FRICTION ( $T_f$ )** is the sum of the retarding torques at stall within the motor. These retarding torques change the value of the developed torque to the value of the net output torque that is available to a system. Static friction subtracts from developed torque when rotor displacement is in the same direction as developed torque and adds to developed torque when displacement is opposite the developed torque. Static friction is the sum of brush-commutator friction and magnetic friction, which includes cogging torque and hysteresis drag. Factory acceptance tests for static friction are performed by measuring the current required to start a motor. The corresponding value of starting friction, or static friction, is determined by multiplying the measured starting current by the measured torque sensitivity of the motor. In general, static friction is about 2% of  $T_P$  in sizes up to the T-5730. This percentage decreases for larger units, being only about 0.5% for the largest models.

**VISCOUS DAMPING COEFFICIENTS ( $F_0$  and  $F_I$ )** are of considerable importance in control systems. The sum of  $F_0$  and  $F_I$  is approximately equal to the total viscous damping coefficient  $F$ , which represents the loss in motor torque per unit speed. The coefficient  $F_0$  gives an indication of the torque lost due to back EMF in the unit. The constant  $F_0$  can be understood by analysis of the current diagram in Figure 1-5 and the torque-speed relationship in Figure 1-6. Rotation of the motor armature generates a back EMF,  $V_B$ , which is directly proportional to speed and which opposes the applied voltage  $V_s$ . The net voltage which produces current flow in the circuit is  $V_s - V_B$ . Under steady-state conditions, current in the circuit is zero when the speed reaches the theoretical value

$$\omega_0 = \frac{V_s}{K_B}$$

making  $V_B = V_s$ . With zero current, the developed torque (which is proportional to current) is also zero. At any speed  $\omega$  other than  $\omega_0$ , the steady-state current is

$$I = \frac{(V_s - V_B)}{(R_s + R_M)}$$

and the developed torque is

$$T = \frac{K_T(V_s - V_B)}{R_s + R_M}$$

Substituting  $K_B \omega$  for  $V_B$  and rearranging the terms yields

$$T = \frac{K_T V_S}{R_S + R_M} - \frac{K_T K_B \omega}{R_S + R_M}.$$

The term

$$\frac{K_T V_S}{R_S + R_M}$$

represents the torque which is constant and independent of speed that would be developed if  $V_S$  were applied to a theoretical motor with no back EMF and no rotational losses. The term

$$\frac{K_T K_B \omega}{R_S + R_M}$$

is a component of viscous drag, or the torque which is lost due to back EMF. This term is represented as  $F_B \omega$ , where the coefficient  $F_B$  equals

$$\frac{K_T K_B}{R_S + R_M}.$$

As  $R_S$  approaches zero,  $F_B$  becomes the zero source impedance coefficient

$$F_0 = \frac{K_T K_B}{R_M}.$$

The coefficient  $F_I$  gives an indication of the torque lost due to rotational losses (mainly eddy current losses) which are proportional to speed. The losses are represented by  $F_I \omega$ , where the coefficient  $F_I$  is determined experimentally for

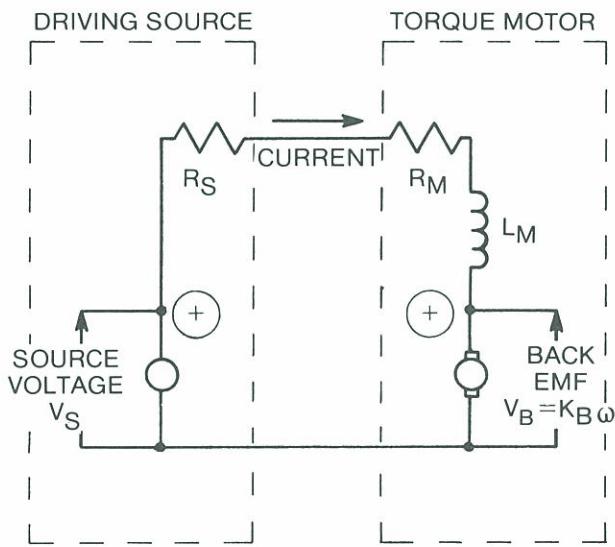


Figure 1-5

Equivalent circuits of driving source and torque motor, showing effect of source resistance (impedance) on motor back EMF relations.

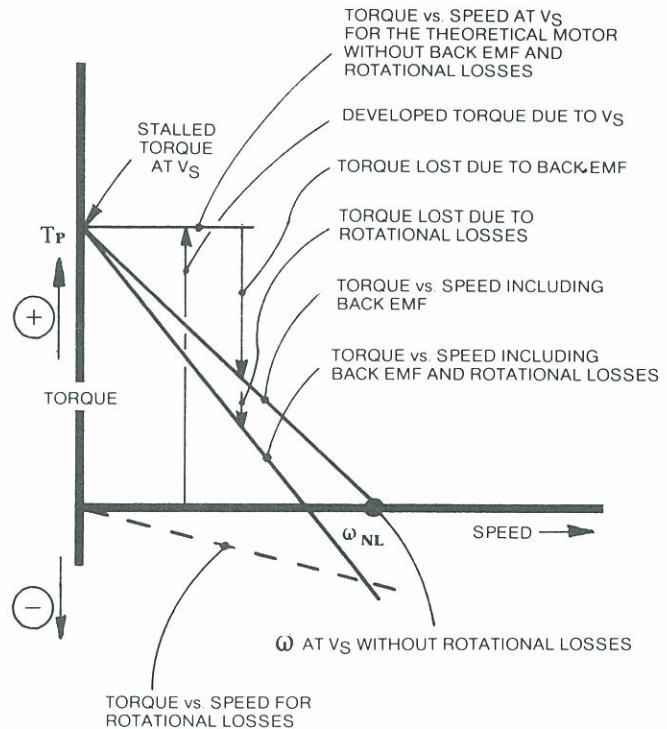


Figure 1-6

Effect of back EMF and friction on motor output torque and speed.

each motor model.  $F_I$  is usually 3% to 5% of  $F_0$ . The total viscous damping coefficient, or torque loss per unit speed, is

$$F = F_B + F_I = \frac{K_T K_B}{R_S + R_M} + F_I.$$

The minimum value of  $F$  is  $F_I$  when the source impedance is infinite. The maximum value of  $F$  is  $F_0 + F_I$  when the source impedance is zero. In usual torque motor applications, the damping effect of  $F$  is insufficient for system stability. Therefore, additional damping in the form of circuit compensation or tachometer generator damping is used.

**MAXIMUM WINDING TEMPERATURE** is the maximum temperature that the motor winding is allowed to reach. This temperature is the sum of the ambient temperature and the temperature rise in the motor windings due to motor operation. The minimum operating temperature for standard motors is  $-40^\circ\text{C}$ . Alnico magnet designs are available in either  $105^\circ\text{C}$  or  $155^\circ\text{C}$  winding temperature ratings. Rare earth magnet motors are usually designed with a maximum winding temperature of  $+155^\circ\text{C}$ . Special units of either type can be supplied with operating temperatures up to  $+200^\circ\text{C}$ .

TEMPERATURE RISE PER WATT (TPR) is essentially the "worst case" ratio of winding temperature rise to average power continuously dissipated from the armature. TPR is useful in selecting the smallest motor size for an application. Unless otherwise indicated, the TPR values listed for frameless motors with model numbers up to T-9908 are based experimentally on the average  $I^2R$  loss in an armature suspended in air without heat sink or forced air cooling. In a typical application, the actual value of temperature rise per watt may be much smaller than the listed TPR because the armature may be mounted on a shaft with good heat conductivity or may be air cooled. In many cases, the actual value is 25% to 50% of the listed TPR. For frameless units larger than the T-9908, the listed TPR value is determined with the unit mounted on a standard test fixture. The listed TPR value for housed motors is based on testing of the assembled unit.

RIPPLE TORQUE ( $T_R$ ) is a small variation in average torque during rotation of the armature. This variation is due to the fact that commutation is done in discrete steps. As the armature rotates, its field is rotated through a small angular displacement before commutation restores the field to its original position. The resulting ripple effect is diagrammed in Figure 1-7.  $T_R$  is expressed as a percentage of average torque. This ripple is also seen as an equally small percentage of variation in torque per current sensitivity, or gain, in a system.

RIPPLE FREQUENCY is the number of ripple cycles in one revolution of the armature. This fundamental frequency is equal to the number

of commutator bars used in the design. Higher frequency components may also be present due to the non-sinusoidal form of the ripple torque.

NUMBER OF POLES is the number of magnetic poles used in the design of the permanent magnet field.

ROTOR INERTIA ( $J_M$ ) is the moment of inertia of the armature about its axis of rotation.

MOTOR WEIGHT is the total weight of the motor parts. For frameless motors, the weight includes the armature, field assembly and brush assembly, but does not include any keepers. For housed motors the weight includes the armature, field assembly, brush assembly, housing, bearings, shaft, and any other housing components.

### Winding Constants

There are six parameters, or winding constants, listed on the individual data page for each motor which vary according to the winding that is used in the model. The variations are governed by the number of wire turns per coil and the wire size.

In most cases, values for more than one winding are listed. If none of the specified windings are suitable for a given application, additional windings are available by consulting the factory. The winding constants for different gage wire may be calculated by the method shown in Table 1-1. Following is a brief description of each winding parameter:

VOLTAGE, STALLED AT  $T_P$  ( $V_P$ ) is the nominal voltage required to develop peak torque when

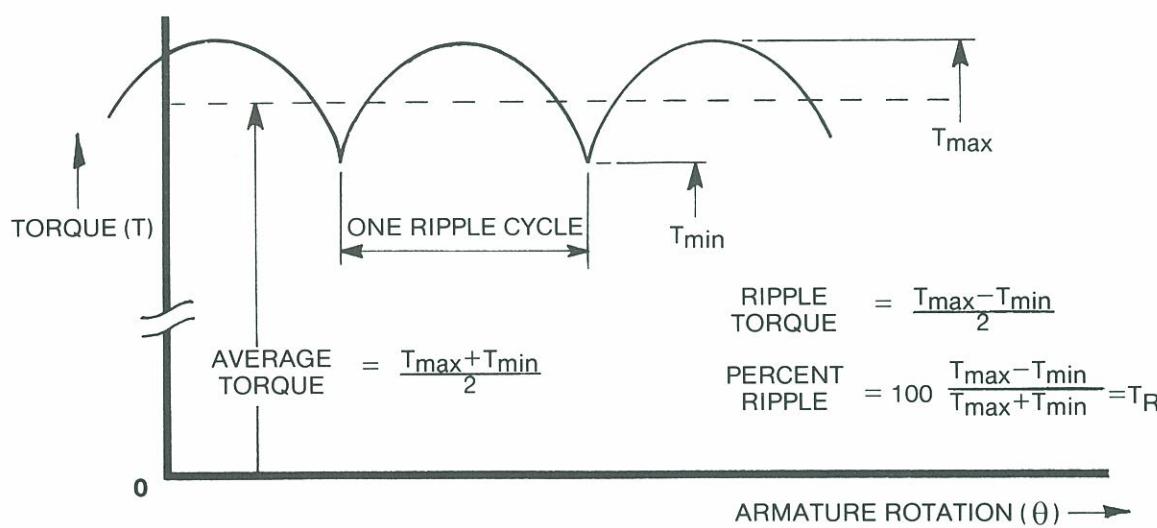


Figure 1-7

Definition of torque ripple percentage factor listed in data sheets.

the rotor speed is zero and the winding temperature is 25°C. As such,  $V_P$  is the product of  $I_P$  and  $R_M$ . At any temperature greater than 25°C, the required voltage is greater than  $V_P$  because resistance increases with temperature. To maintain peak torque, therefore, the voltage must be increased.

**PEAK CURRENT ( $I_P$ )** is the current required to obtain the rated torque  $T_P$  from the motor. For Alnico magnet motors,  $I_P$  is the maximum allowable value of current that can be used in the designated winding. In these units, exceeding the value of  $I_P$  may demagnetize the permanent magnet field to some extent and cause a permanent reduction in torque per unit current. If it is desired to operate Alnico units at current values in excess of  $I_P$ , the factory should be consulted for additional information. Rare earth magnet motors can be operated at current values greater than  $I_P$  without demagnetization of the PM field. The limits of thermal capacity of the motor and the current density rating of the brushes must not be exceeded.

**TORQUE SENSITIVITY ( $K_T$ )** is the ratio of developed torque to armature input current for the designated winding. This torque-current relationship prevails regardless of armature speed. Thus, any value of current in a winding will develop a corresponding value of torque whether the armature is at standstill or is running forward or backward at any speed. Normally the tolerances on  $K_T$  are  $\pm 10\%$ .

**BACK EMF CONSTANT ( $K_B$ )** is the ratio of voltage generated in the armature to the speed of the armature. Since both  $K_B$  and  $K_T$  are determined by the same factors,  $K_B$  is directly pro-

portional to  $K_T$ . Normally the tolerances on  $K_B$  are  $\pm 10\%$ .  $K_B$  is expressed in volts per rad/s.

**DC RESISTANCE ( $R_M$ )** is the resistance measured between the motor terminals at 25°C as shown in Figure 1-8. The normal tolerances on  $R_M$  are  $\pm 12.5\%$ . Approximately three-fourths of this tolerance is due to changes in brush resistance that occur with commutation. The remaining one-fourth of the tolerance is due to variations in the winding resistance. Since the actual temperature of a motor in a given application is usually different from the 25°C at which  $R_M$  is stated, it is useful to know that the change in resistance of copper wire per unit change in temperature is approximately 0.4% per °C.

**INDUCTANCE ( $L_M$ )** is the series equivalent of armature inductance as measured at the motor terminals. It is usually measured at 60 Hz and normally has tolerances of  $\pm 30\%$ .

## Winding Designation

In many applications, the motor is not the first element of a system to be specified. If a power supply or amplifier is specified before the motor, the motor must be selected to match the voltage and current characteristics of the system. Variations in the rated voltage and current for a given motor model are achieved by changing the number of turns and the size of the wire used for the winding. In this manner, a "family" of motors is developed which differ only in the values of the winding constants discussed in the previous section. The peak voltage, torque sensitivity and back EMF constant vary in direct proportion

WINDING CONSTANT	NEW VALUE FOR HEAVIER WIRE	NEW VALUE FOR FINER WIRE
DC Resistance (25°C)	$R_M / (1.59)^n$	$R_M \times (1.59)^n$
Voltage, stalled at $T_P$	$V_P / (1.26)^n$	$V_P \times (1.26)^n$
Peak current	$I_P \times (1.26)^n$	$I_P / (1.26)^n$
Torque Sensitivity	$K_T / (1.26)^n$	$K_T \times (1.26)^n$
Back EMF Constant	$K_B / (1.26)^n$	$K_B \times (1.26)^n$
Inductance	$L_M / (1.59)^n$	$L_M \times (1.59)^n$

Table 1-1 illustrates the method used to calculate new winding parameters from an existing set of winding parameters. "n" is an integer representing the difference in wire gage between the existing winding and the desired winding, that is, the number of wire sizes larger or smaller than the existing wire. The factors 1.26 and 1.59 are used to calculate the new winding parameters because each step in the wire gage system involves the same degree of change in wire cross-section and in resistance per unit length. If the new winding being calculated is outside the extremes of the windings listed on the data page, the factory should be consulted. There are limitations on wire size because it can be too fine to work with or too large to fit in the lamination slot.

Table 1-1

to the number of turns in the winding. The peak current varies inversely with the number of turns, and the resistance and inductance vary as the square of the number of turns. When a new winding is designed, the number of turns and the wire size are chosen so that approximately the same total volume of copper is used. This means that the motor size constants, such as peak torque, motor constant, etc., do not change as a result of a winding change.

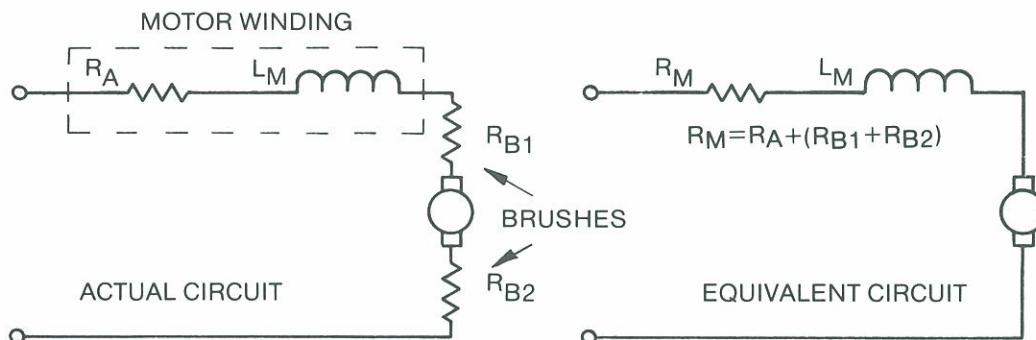
Different windings are specified by a letter which follows the model number of the unit. For example, a T-5730 can be specified with a 19.8 volt winding as a T-5730-A, or with a 37.8 volt winding as a T-5730-C. In order for a model number to be complete, it must include a winding designation letter.

The individual data page for each unit usually lists several windings. If none of the specified windings are suitable for the system requirements, an alternate winding can be derived by the procedure shown in Table 1-1. If an alternate winding is determined in this manner, the factory should be consulted to verify that a unit with the new winding parameters can be manufactured.

Electro-magnetic interference (EMI) can be transmitted from a source to a sensitive location in four ways: (1) direct conduction along wires; (2) capacitive coupling between source wires and nearby leads; (3) inductive coupling between wires, and (4) direct radiation due to an "antenna effect."

The first three of these transmission pathways are of particular interest in the application of torque motors. These pathways are illustrated in Figure 1-9, in which noise voltages are: (1) conducted along the motor supply leads from the amplifier; (2) transferred to nearby tachometer generator leads by capacitive coupling, and (3) transferred to nearby tachometer generator leads by inductive coupling. Because the tachometer generator leads terminate at the input of the preamplifier, voltages of a few microvolts may be sufficient to interfere with proper system operation.

The simplest way to correct such brush noise conditions is to keep the armature leads separated from the generator leads. If this does not sufficiently attenuate the noise, or if it is not feasible to separate the cables, the use of a



**Figure 1-8**

Motor terminal-resistance  $R_M$  is the sum of armature and brush resistance. The equivalent circuit is used for servo design calculations.

## BRUSH NOISE CONSIDERATIONS

In a DC motor, the direction of current flow in each armature coil is reversed for each change in the magnetic circuit polarity. This switching process is known as commutation. As the motor operates it generates a self-induced EMF which can produce electrical noise at the brushes. By careful design of the torque motor, brush noise can be minimized. However, arcing transients may occasionally find their way into sensitive control circuits and produce undesirable results.

shielded, twisted pair, carefully grounded at the preamplifier end only, is recommended for the tachometer generator leads. In some cases, it may be desirable to also use a shielded, grounded pair for the armature leads, as in Figure 1-10.

The most important factor in the elimination of brush noise is a *continuous system ground*. The preamplifier, amplifier and cable points should all be connected to a common ground. In some cases it may be necessary to provide a separate ground bus.

Another method of reducing brush noise is by connecting a capacitor across the input terminals *as close to the brush ring as possible*. The value of this capacitor should not exceed

$$C = \frac{500L_M}{R_M^2}$$

where  $L_M$  is in millihenries,  $R_M$  is in ohms, and  $C$  is in microfarads.

opposite the brush ring assembly. The structures designed to support the field assembly must be sufficiently strong to avoid any distortion of the field assembly when it is bolted in place. The field assemblies of Alnico magnet motors must be mounted in non-magnetic structures in order to preserve the specified performance characteristics. Satisfactory materials are aluminum, brass and non-magnetic stainless steel. The minimum thickness of non-magnetic

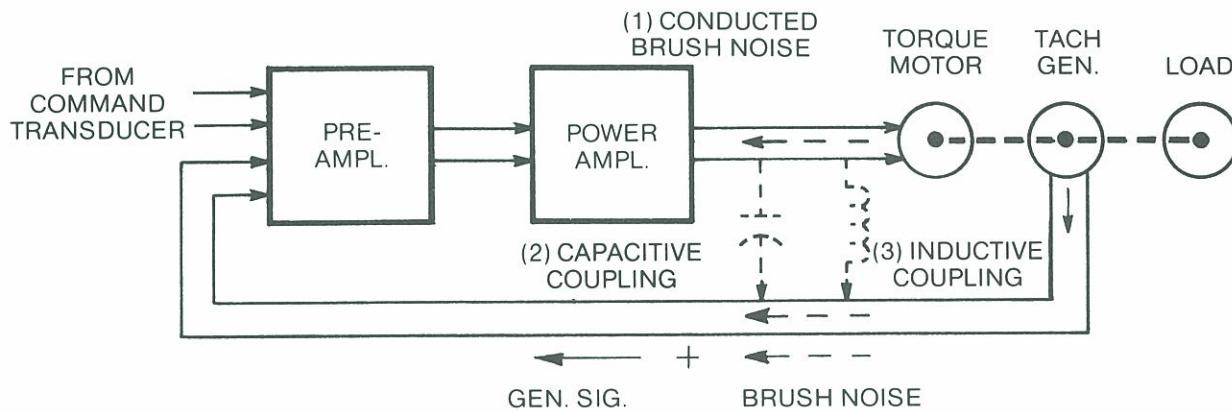


Figure 1-9

Methods by which electromechanical interference is transmitted to control circuitry.

## HOUSING DESIGN for FRAMELESS MOTORS

The frameless motors in this catalog fall into three basic configuration categories: frameless, frameless with armature adapter machined to existing mounting dimensions (See Figure 1-11) and units with a partial housing and mounting flange or tabs (See Figure 1-12).

For the purely frameless units and units with armature adapters, a housing for the field structure must be incorporated into the system design. In general, the field structure is piloted on the outer diameter and is mated on the face

material required to separate the field structure from magnetic material is  $\frac{1}{4}$  inch. Samarium Cobalt motors may be mounted in magnetic or non-magnetic housings.

Units with a partial housing do not require a special field housing. They can be bolted onto a flat plate, and thus are ideal for mounting on the exposed end of a shaft. Mounting features for this arrangement include round or square flanges or tabs.

To maintain the integrity of the mechanical and magnetic structure of the motor, the armature should be mounted on a shaft in such a way as to minimize eccentricity around any point in

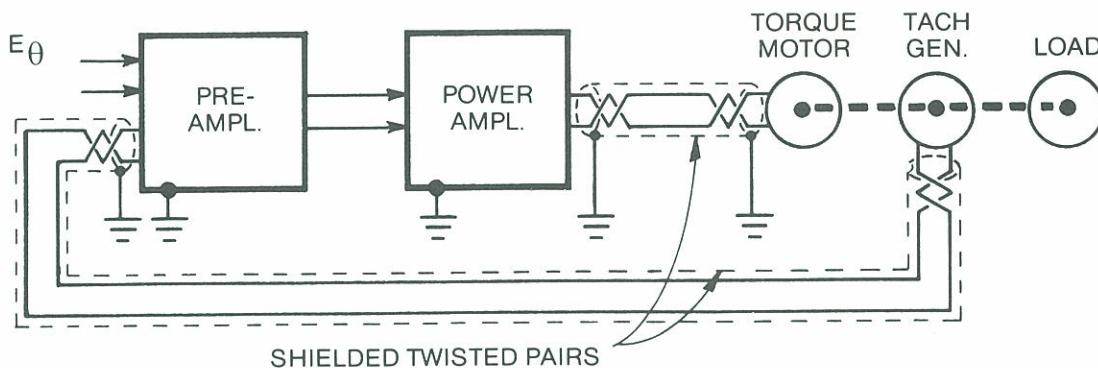
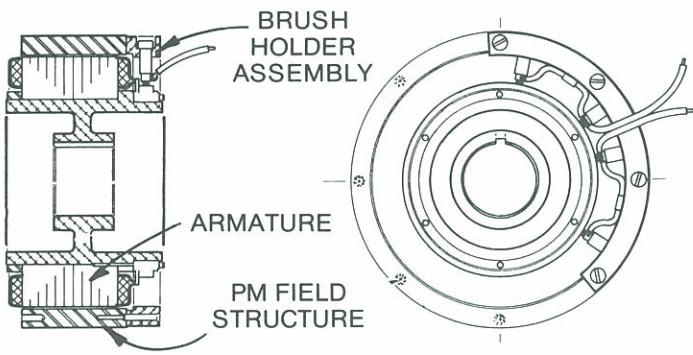


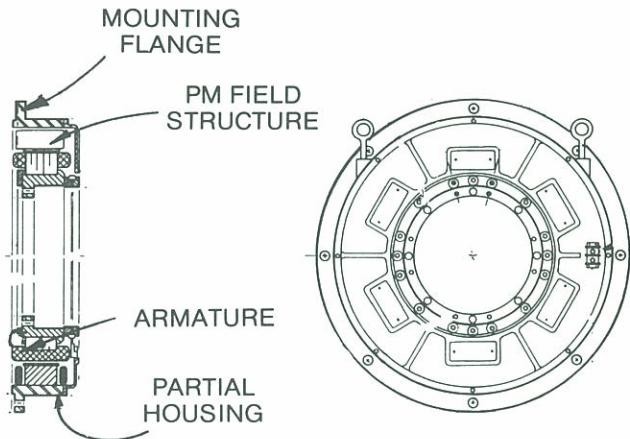
FIGURE 1-10

Recommended methods of protection against EMI.



**Figure 1-11**

Frameless torque motor with armature adapter machined to existing mounting dimensions.



**Figure 1-12**

Frameless unit with partial housing.

the armature plane. Each individual data page specifies a required concentricity between the stator and rotor. This mounting requirement stems from a maximum run-out of one-third of the air gap dimension.

The rotor bore, as indicated on the individual data pages, may be used as a pilot for shaft mounting. Standard rotor-to-shaft mounting methods include shrink fits, interference fits, adhesives (such as Loctite®)\* and axial clamping of both sides of the laminations. Units can be supplied with keyways or with adapter hubs suitable for mounting directly onto the customer's shaft.

\*Trademark of Loctite Corp., Newington, CT

## MOTOR HANDLING and STORAGE

### Frameless Motors

Because frameless DC motors are designed to be an integral part of system equipment, they require some special handling procedures. Improper handling in shipping or installation can substantially degrade motor performance.

When received, a frameless motor should be unpacked carefully to avoid damaging the brush ring assembly or the commutator surface. Precautions must be taken to avoid bending any of the brush springs or scoring the mounting diameters. The commutator surface must remain free of scratches, fingerprints and oils. For Alnico magnet motors, DO NOT LOOSEN OR REMOVE THE FLUX KEEPERS until

installation (See page xvii for details). If motors must be transported, they should be packed in the original shipping packages for protection against shock and vibration. Electrical performance tests and mechanical inspection of parts for critical dimensions are performed at the factory before shipment. If performance tests are required by the customer at receiving inspection, they should be limited to those tests described on the Inland test data form which accompanies each unit.

Inland motor parts are tested, assigned serial numbers and guaranteed only as matched sets. Tested performance is not valid if parts are interchanged between motors.

In storage, containers and racks should be of non-magnetic materials. Field assemblies should be spaced a minimum of  $\frac{1}{2}$  inch apart. Motor parts should be protected against exposure to, or contact with, small magnetic particles such as iron filings, chips or dust. If such particles are attracted to the magnetic areas of the motor, they are very difficult to remove. In addition, should any material lodge in or across the motor airgap, performance may be seriously degraded.

Storing motor parts in normal factory ambient temperatures is acceptable. For extended storage, corrosion should be guarded against by storing the parts in a sealed plastic bag together with a desiccant suitable for protecting the motor against excessive humidity. The original packaging by the factory is adequate if it is kept intact.

## Housed Motors

Inland housed motors require handling similar to that of conventional frame-type motors. Care should be taken to protect the unit against exposure to small magnetic particles such as iron filings, chips or dust.

As with frameless units, storage at factory ambient temperatures is acceptable. For extended storage, motors should be packaged with a desiccant to protect against excessive humidity. The original packaging by the factory is adequate if it is kept intact.

## INSTALLATION

The exact manner in which frameless torque motors are installed varies with the motor. However, there are five basic methods, each of which depends upon the particular motor configuration: rare earth frameless, Alnico frameless and partially housed frameless with shipping clamp plate, clamp bolt or pole piece clamp.

The procedure to be followed when installing frameless rare earth magnet motors is as follows:

- 1) Insert the permanent magnet field assembly into the housing cavity allocated for it. If the housing material is magnetic, exert care to avoid sudden impact of stator against the housing.
- 2) Secure the field assembly to the housing with mounting screws. The screw size is specified on the motor drawing, but the screws are not provided.
- 3) Guide the rotor into its final position within the field assembly, being careful to avoid scratching the commutator surface or chipping the magnets. If possible, it is recommended that the rotor be wrapped with a piece of polyester film (such as Mylar®)\* thinner than the air gap before it is inserted. Once the rotor is in place the polyester film should be removed.
- 4) Install the brush ring. Take care in slipping the brushes over the commutator. Avoid bending the brush springs or scratching the commutator surface. For proper position, line up the numbers marked on the stator and brush ring assembly. Then secure the brush ring assembly in place with the mounting screws provided.

Frameless Alnico units should be installed as follows:

- 1) Insert the permanent magnet field assembly into the housing cavity allocated for it. DO NOT LOOSEN OR REMOVE THE KEEPER.
- 2) Guide the rotor into its final position within the field assembly, being careful to avoid damage to the commutator surface.
- 3) Remove the keeper ring using the jack screw as shown in Figure 1-13.

4) Secure the field assembly to the housing with mounting screws. The screw size is specified on the motor drawing, but the screws are not provided.

5) Install the brush ring. Take care in slipping the brushes over the commutator. Avoid bending the brush springs or scratching the commutator surface. For proper position, line up the numbers marked on the stator and brush ring assembly. Then secure the brush ring assembly in place with the mounting screws provided.

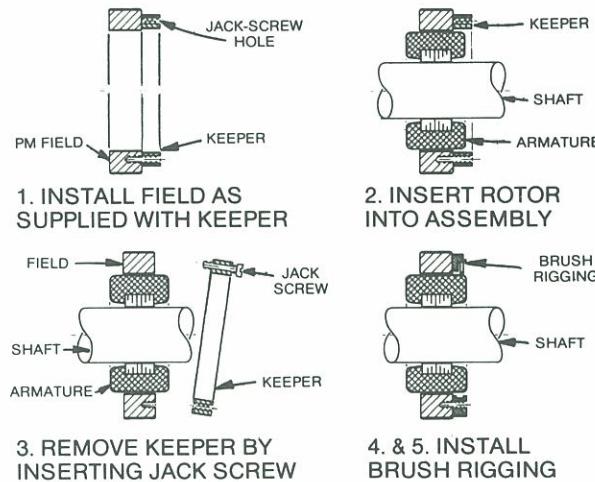


Figure 1-13

Keeper removal.

For partially housed Alnico units with shipping clamp-plates, typified by type T-10036 (See Figure 1-14) the rotor must not be removed from the stator or partial demagnetization and change of motor torque characteristics will occur. The field and armature assemblies are installed into the shaft and the field support as a single unit. The clamp plate is then removed to permit rotation of the armature. After removing the clamp plate, be sure to tighten the mounting bolts.

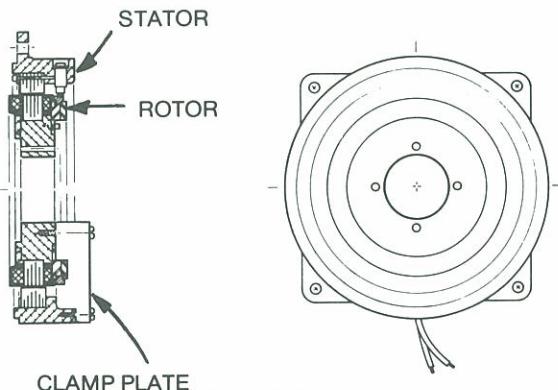


Figure 1-14

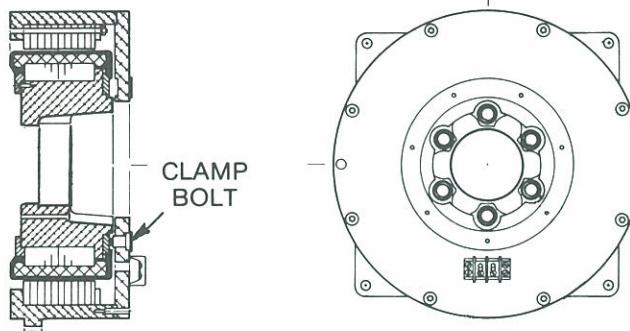
Clamp-plate motor, type T-10036.

\*Trademark of DuPont, Wilmington, DE.

Partially housed Alnico units with clamp-bolt or pole-piece clamp are similar to each other in that the accessory clamp elements are simple screws. In the case of the clamp-bolt types, which are typified by the T-10035 motor (See Figure 1-15), securing the clamping bolts moves the rotor axially a sufficient amount to lock the rotor and field together at an existing interface.

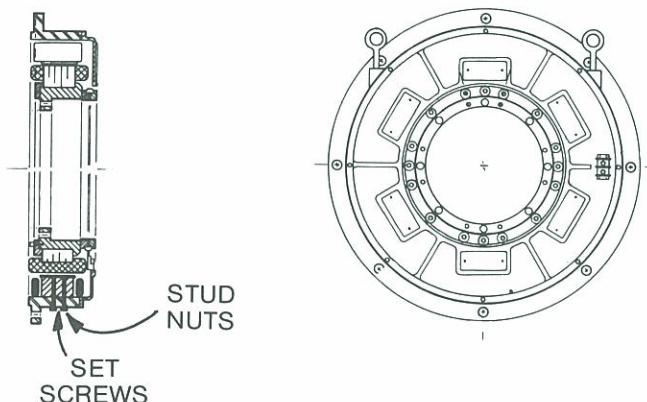
The pole-piece clamp type, typified by the

T-18002 motor (See Figure 1-16), locks the rotor to the field at the air gap by forcing a number of movable field pole-pieces radially inward until clamping action takes place. After installation of this type motor, the clamping set screws are loosened, and the main pole-piece stud nuts are retightened to secure the pole pieces in their proper position.



**Figure 1-15**

Clamp-bolt motor, type T-10035.



**Figure 1-16**

Pole-piece clamp motor, type T-18002.

## **TORQUE MOTORS**

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Torque motors are typically used in positioning or slow-speed rate applications where the accuracy is critical. The large diameter, narrow width configuration delivers high torque in small volume.

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*This section contains both frameless and housed versions of the basic torque motor.*

## Frameless Torquer Selection Guide (oz. in.)

MODEL NUMBER	Peak Torque @ Stall		Motor Constant	No Load Speed	Electrical Time Constant	Friction	Rotor Inertia	Physical Dimensions			Weight oz.
	T <sub>P</sub> oz. in.	P <sub>P</sub> watts						J <sub>M</sub> oz. in. sec. <sup>2</sup>	OD in.	ID in.	
NT-0786	2.8	46	0.41	2300	0.13	0.20	4.5 × 10 <sup>-5</sup>	1.13	0.19	0.38	1.4
QT-0717	3.84	53	0.529	1940	0.12	0.25	4.5 × 10 <sup>-5</sup>	1.13	0.19	0.38	1.4
T-0709	6.6	60	0.85	1300	0.26	0.25	1.1 × 10 <sup>-4</sup>	1.13	0.19	0.56	1.6
QT-0707	7.7	50	1.09	925	0.25	0.30	1.1 × 10 <sup>-4</sup>	1.13	0.19	0.56	1.6
T-2003	9.5	41	1.48	610	0.10	0.40	1.6 × 10 <sup>-3</sup>	2.46	1.50	0.31	2.5
NT-0796	10.6	73	1.24	990	0.35	0.40	1.64 × 10 <sup>-4</sup>	1.13	0.19	0.75	2.3
QT-1106	11	49	1.57	636	0.14	0.60	3.2 × 10 <sup>-4</sup>	1.38	0.50	0.39	1.5
QT-1204	11	57	1.46	732	0.11	0.6	4.2 × 10 <sup>-4</sup>	1.50	0.63	0.39	1.7
QT-0706	12.3	63	1.55	725	0.32	0.40	1.6 × 10 <sup>-4</sup>	1.13	0.19	0.75	2.5
T-1218	15	63	1.9	580	0.31	0.5	6.0 × 10 <sup>-4</sup>	1.50	0.63	0.51	2.3
T-1259	15	40	2.4	374	0.50	0.50	5.7 × 10 <sup>-4</sup>	1.50	0.46	0.51	2.4
QT-1207	20	81.8	2.21	580	0.20	0.70	6.0 × 10 <sup>-4</sup>	1.50	0.63	0.51	2.3
T-1292	20	64	2.51	450	0.37	0.55	9.0 × 10 <sup>-4</sup>	1.75	0.62	0.53	2.8
T-1352	20	60	2.58	400	0.34	0.7	8.8 × 10 <sup>-4</sup>	1.94	0.62	0.51	4.3
T-1410	21	49	3.0	360	0.31	0.7	1.5 × 10 <sup>-3</sup>	1.94	0.62	0.51	5
NT-1319	24	64	3.0	375	0.29	0.8	8.8 × 10 <sup>-4</sup>	1.94	0.62	0.51	4.3
T-1915	24	36	4.0	209	0.22	1.9	4.0 × 10 <sup>-3</sup>	2.47	1.25	0.47	5
T-1242	25	55	3.4	307	0.68	1.1	1.5 × 10 <sup>-3</sup>	1.50	0.63	0.96	5.5
T-3001	26.5	9.6	8.55	51	0.23	2.8	1.5 × 10 <sup>-2</sup>	3.62	2.18	0.42	8
NT-1372	30	52	4.15	245	0.3	1.8	9.0 × 10 <sup>-4</sup>	1.94	0.62	0.54	4.4
QT-2406	30	53.5	4.1	250	0.13	1.8	5.4 × 10 <sup>-3</sup>	2.78	1.80	0.44	3.9
T-2413	30	50.5	4.22	238	0.20	1.7	6.0 × 10 <sup>-3</sup>	2.78	1.80	0.44	4
T-2509	30	48	4.33	220	0.25	1.0	6.0 × 10 <sup>-3</sup>	3.00	1.75	0.37	4.5
T-2804	30	67	3.66	320	0.30	1.5	8.6 × 10 <sup>-3</sup>	3.38	2.25	0.41	5.1
NT-1383	32	83	3.5	368	0.5	1.0	1.1 × 10 <sup>-3</sup>	1.94	0.62	0.67	6
T-2157	35	41	5.45	160	0.60	1.1	6.2 × 10 <sup>-3</sup>	2.81	1.00	0.62	8.8
T-1342	40	98	4.05	340	0.30	1.0	1.6 × 10 <sup>-3</sup>	1.94	0.62	0.84	7.6
QT-2104	48	39	7.7	114	0.50	1.8	6.0 × 10 <sup>-3</sup>	2.81	1.00	0.62	9.2
QT-2502	48	27	9.25	79	0.184	2.5	1.05 × 10 <sup>-2</sup>	3.00	1.75	0.61	9
QT-1217	50	165	3.9	467	0.38	1.1	1.5 × 10 <sup>-3</sup>	1.50	0.63	0.96	5.5
QT-1906	50	115	4.66	326	0.174	1.0	3.4 × 10 <sup>-3</sup>	2.38	1.25	0.50	5
QT-2202	52	40	8.28	107	0.844	2.5	8.5 × 10 <sup>-3</sup>	2.81	1.00	0.62	11
T-2314	54	57.5	7.1	150	0.66	1.7	9.0 × 10 <sup>-3</sup>	2.88	1.00	0.58	11
QT-1401	55	217	3.74	557	0.21	1.8	1.3 × 10 <sup>-3</sup>	1.94	0.63	0.54	4.4
T-1911	60	60	7.75	143	0.40	2.5	8.8 × 10 <sup>-3</sup>	2.34	1.25	0.85	9.5
T-2170	60	33.8	10.5	79	0.91	1.5	1.1 × 10 <sup>-2</sup>	2.81	1.00	1.00	13.8
QT-2504	60	55	8.1	128	0.29	1.8	1.1 × 10 <sup>-2</sup>	3.00	1.75	0.53	8
T-2516	60	55	8.1	127	0.43	1.8	1.1 × 10 <sup>-2</sup>	3.00	1.75	0.53	8
QT-1404	65	98	6.55	214	0.238	3.0	2.55 × 10 <sup>-3</sup>	1.94	0.63	0.84	8.4
QT-2105	75	35	12.8	65	0.77	3.0	1.1 × 10 <sup>-2</sup>	2.81	1.00	1.00	13.5
T-1421	77.4	112	7.31	205	0.55	2.0	2.3 × 10 <sup>-3</sup>	1.94	0.62	1.20	15
T-2809	85	103	8.4	170	0.30	3.5	2.0 × 10 <sup>-2</sup>	3.38	2.25	0.71	11
NT-1308	90	255	5.65	407	0.40	3.0	3.5 × 10 <sup>-3</sup>	1.94	0.62	1.86	16.1
QT-1903	90	107	8.7	167	0.22	2.8	8.8 × 10 <sup>-3</sup>	2.38	1.25	0.85	9.5
T-2719	97	37.5	15.8	54	0.77	4.3	2.2 × 10 <sup>-2</sup>	3.38	1.69	0.69	15

Continued on next page.

**Frameless Torquers (oz. in.) cont.**

MODEL NUMBER	Peak Torque @ Stall		Motor Constant	No Load Speed	Electrical Time Constant	Friction	Rotor Inertia	Physical Dimensions			Weight
	T <sub>P</sub> oz. in.	P <sub>P</sub> watts	K <sub>M</sub> oz. in./watt	ω <sub>NL</sub> rad/sec	τ <sub>e</sub> msec.	T <sub>f</sub> oz. in.	J <sub>M</sub> oz. in. sec. <sup>2</sup>	OD in.	ID in.	Length in.	oz.
T-2967	100	67.5	12.2	95	1.2	2	3.5 × 10 <sup>-2</sup>	3.73	1.64	0.89	17.5
QT-4101	100	76	11.5	107	0.15	4.0	4.7 × 10 <sup>-2</sup>	4.59	3.33	0.43	9.5
T-2215	108	41	16.9	54	1.74	3.3	1.7 × 10 <sup>-2</sup>	2.81	1.00	1.13	20
T-2171	120	50	17.0	57	1.5	3.0	1.9 × 10 <sup>-2</sup>	2.81	1.00	1.50	25
QT-3104	149.5	97.2	15.2	92	0.38	3.0	3.4 × 10 <sup>-2</sup>	3.63	2.50	0.80	14
T-4601	153.6	200	10.94	184	0.467	4.8	9.2 × 10 <sup>-2</sup>	5.13	4.00	0.58	13.3
QT-1406	157	347	8.42	313	0.277	3.5	3.73 × 10 <sup>-3</sup>	1.94	0.63	1.11	12
T-2955	163	77	18.6	67	1.6	2.5	4.42 × 10 <sup>-2</sup>	3.73	1.64	1.09	24
QT-4602	163	211	11.33	183	0.265	5.0	8.26 × 10 <sup>-2</sup>	5.13	4.00	0.56	13.3
T-3203	192	87	20.54	63	2.3	3.8	6.72 × 10 <sup>-2</sup>	4.09	2.00	1.09	25.6
T-3910	192	50	26.88	36	0.84	8.06	6.5 × 10 <sup>-2</sup>	4.56	2.94	0.69	17.6
T-4436	192	70	23.04	51	0.70	5.76	1.06 × 10 <sup>-1</sup>	5.13	3.50	0.65	19.2
T-2987	211	113	19.97	75	2.13	5.76	6.1 × 10 <sup>-2</sup>	3.73	1.64	1.34	32

## Frameless Torquer Selection Guide (lb. ft.)

MODEL NUMBER	Peak Torque @ Stall		Motor Constant	No Load Speed	Electrical Time Constant	Friction	Rotor Inertia	Physical Dimensions			Weight
	T <sub>P</sub> lb. ft.	P <sub>P</sub> watts	K <sub>M</sub> lb. ft./watt	ω <sub>NL</sub> rad/sec	τ <sub>e</sub> msec.	T <sub>f</sub> lb. ft.	J <sub>M</sub> lb. ft. sec <sup>2</sup>	OD. in.	ID in.	Length in.	lbs.
T-2950	1.2	79	0.135	48	2.13	0.017	2.9 × 10 <sup>-4</sup>	3.73	1.64	1.34	2.2
T-3912	1.2	34.8	0.201	21.6	1.25	0.05	6.1 × 10 <sup>-4</sup>	4.56	2.94	0.88	1.9
NT-2146	1.25	75	0.15	42.1	1.5	0.04	1.4 × 10 <sup>-4</sup>	2.81	0.88	2.51	3.0
T-5403	1.3	120	0.119	68	0.67	0.04	8.6 × 10 <sup>-4</sup>	6.13	4.50	0.67	1.2
T-3208	1.5	113	0.14	56	3.0	0.027	4 × 10 <sup>-4</sup>	4.09	2.00	1.34	2.4
T-4412	1.5	120	0.139	58	0.84	0.04	6.2 × 10 <sup>-4</sup>	5.13	3.50	0.78	1.5
T-2959	1.7	110	0.16	47	2.5	0.026	3.3 × 10 <sup>-4</sup>	3.73	1.64	1.59	2.5
T-4036	1.8	87.8	0.19	36	1.79	0.035	8.7 × 10 <sup>-4</sup>	5.13	2.39	1.25	2.9
T-5406	2	52	0.28	19.2	1.5	0.12	1.5 × 10 <sup>-3</sup>	6.13	4.50	1.17	3.0
T-8902	2.08	61	0.27	21.6	0.40	0.05	5.4 × 10 <sup>-3</sup>	9.69	7.94	0.81	4.5
QT-7602	2.1	16.7	0.514	5.9	0.58	0.30	6.0 × 10 <sup>-3</sup>	8.50	6.88	1.30	7.3
QT-3801	2.4	187	0.175	57.5	0.58	0.05	3.6 × 10 <sup>-4</sup>	4.50	2.67	0.69	1.3
T-2406	2.5	285	0.15	84	1.75	0.05	1.6 × 10 <sup>-4</sup>	3.18	1.44	1.55	1.9
QT-3102	2.5	263	0.154	77	1.2	0.041	4.1 × 10 <sup>-4</sup>	3.73	1.64	1.24	2
QT-2404	3	260	0.19	64	1.04	0.062	2.0 × 10 <sup>-4</sup>	3.18	1.00	1.53	2.4
QT-3103	3.3	190	0.24	39	1.52	0.057	5.7 × 10 <sup>-4</sup>	3.73	1.64	1.70	3.1
T-4076	3.6	127	0.32	26	2.7	0.052	1.4 × 10 <sup>-3</sup>	5.13	2.39	1.75	5.6
QT-3403	4	126	0.357	23.2	2.1	0.10	9.8 × 10 <sup>-4</sup>	4.10	2.00	1.80	4
QT-7004	4	58.2	0.524	10.7	2.0	0.20	6.3 × 10 <sup>-3</sup>	7.73	5.25	0.94	4.2
QT-6302	4.2	67	0.51	12	1.44	0.16	6.3 × 10 <sup>-3</sup>	7.00	4.73	1.29	6.3
QT-4402	4.2	160	0.335	27.7	1.10	0.12	1.52 × 10 <sup>-3</sup>	5.13	3.25	1.23	3.0
QT-3802	4.8	256	0.30	39.3	0.84	0.10	7.2 × 10 <sup>-4</sup>	4.50	2.67	1.07	2.6
QT-2603	5	313	0.28	46	2.1	0.10	4.0 × 10 <sup>-4</sup>	3.18	1.14	2.35	3.5
QT-5404	5	227	0.33	33	0.60	0.15	1.9 × 10 <sup>-3</sup>	6.13	4.50	1.17	2.9
T-6204	6	103	0.59	12.8	2.49	0.15	6.5 × 10 <sup>-3</sup>	7.20	3.95	1.32	7.0
T-7501	6.5	177	0.49	20	1.60	0.25	1.1 × 10 <sup>-2</sup>	8.69	5.94	1.26	7.5
T-5730	7	261	0.433	28	3.13	0.09	5.0 × 10 <sup>-3</sup>	7.20	3.95	1.63	7.3
QT-7201	9	490	0.41	40	0.79	0.15	5.6 × 10 <sup>-3</sup>	8.20	5.94	1.08	4
T-6205	10	125	0.87	9.2	2.6	0.35	9.0 × 10 <sup>-3</sup>	7.20	3.95	1.97	10
QT-12901	10	135	0.86	10	0.37	0.4	2.4 × 10 <sup>-2</sup>	13.63	12.13	1.10	5
QT-6202	11	330	0.61	22	1.8	0.18	5.8 × 10 <sup>-3</sup>	7.20	3.95	1.24	6.2
T-7202	11	325	0.61	22	3.15	0.15	1.0 × 10 <sup>-2</sup>	9.00	5.37	1.63	10.3
T-15602	11	198	0.78	13.3	2.2	0.25	8.0 × 10 <sup>-2</sup>	16.50	13.88	1.34	13
T-11306	12.4	260	0.77	16	1.0	0.37	2.0 × 10 <sup>-2</sup>	11.97	10.25	1.00	7.2
T-8905	13.6	666	0.53	36.2	1.38	0.22	1.5 × 10 <sup>-2</sup>	9.69	7.63	1.47	9.9
T-5745	14	357	0.74	18.8	5.3	0.15	8.0 × 10 <sup>-3</sup>	7.20	3.95	2.37	15
T-13301	14.4	260	0.9	13	1.0	0.4	3.2 × 10 <sup>-2</sup>	14.00	12.25	1.05	8.5
QT-6301	20	576	0.83	21	2.1	0.25	1.0 × 10 <sup>-2</sup>	7.00	4.73	1.99	9
QT-9704	20	235	1.3	8.6	1.5	0.72	2.5 × 10 <sup>-2</sup>	11.00	8.00	1.56	10.5
T-9901	20	400	1.0	14.5	4.0	0.25	2.5 × 10 <sup>-2</sup>	12.00	8.00	1.75	15
T-11308	20	218	1.35	8	1.4	0.71	3.0 × 10 <sup>-2</sup>	11.97	10.05	1.27	9
T-7203	22	530	0.96	18	5.7	0.25	1.9 × 10 <sup>-2</sup>	9.00	5.16	2.55	18.3
QT-11302	22	232	1.44	7.8	0.93	1.0	3.0 × 10 <sup>-2</sup>	11.97	10.05	1.28	8.7
QT-7802	23	620	0.92	19.9	2.45	0.37	1.6 × 10 <sup>-2</sup>	9.00	5.37	1.65	10.2
QT-6205	25	627	1.0	18.5	2.41	0.35	1.0 × 10 <sup>-2</sup>	7.20	3.95	1.99	12

Continued on next page.

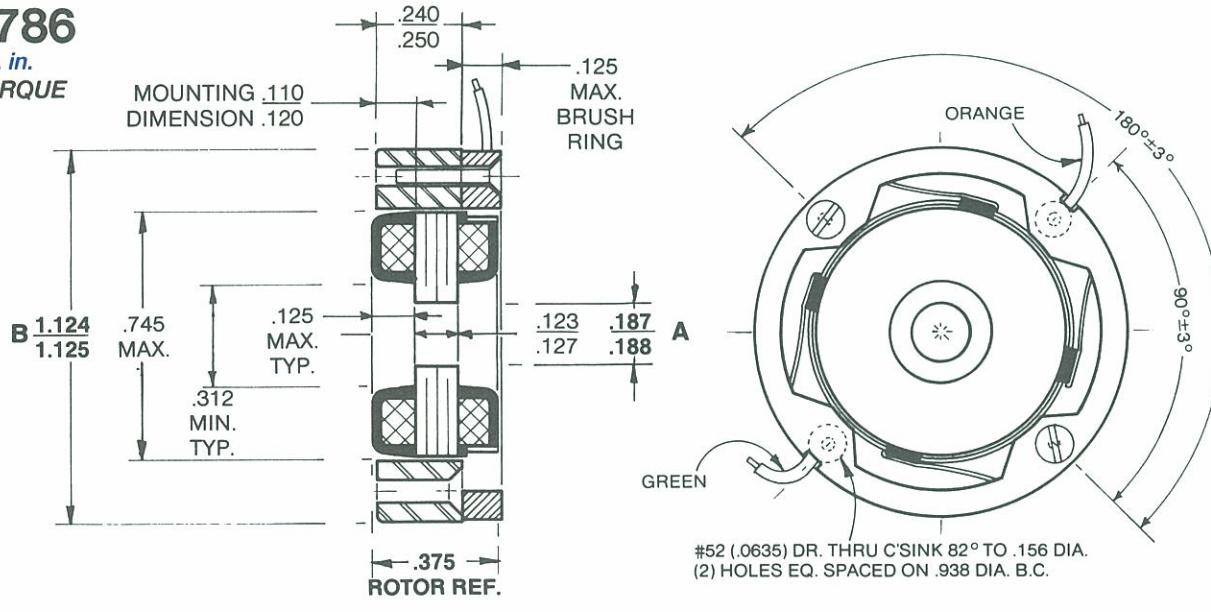
**Frameless Torquers (lb. ft.) cont.**

MODEL NUMBER	Peak Torque @ Stall		Motor Constant	No Load Speed	Electrical Time Constant	Friction	Rotor Inertia	Physical Dimensions			Weight
	T <sub>P</sub> lb. ft.	P <sub>P</sub> watts	K <sub>M</sub> lb. ft./watt	ω <sub>NL</sub> rad/sec	τ <sub>e</sub> msec.	T <sub>f</sub> lb. ft.	J <sub>M</sub> lb. ft. sec <sup>2</sup>	OD. in.	ID in.	Length in.	lbs.
QT-7003	25	520	1.1	15	2.4	0.35	1.3 × 10 <sup>-2</sup>	7.73	5.25	1.94	10.3
QT-6401	26	657	1.01	18.7	3.3	0.40	1.2 × 10 <sup>-2</sup>	7.75	4.25	2.10	12.6
T-7250	27.5	582	1.14	15	6.5	0.21	2.3 × 10 <sup>-2</sup>	9.00	5.16	2.94	22.5
T-15603	30	450	1.41	11	3.6	0.35	0.14	16.50	13.88	1.84	22
T-10036	35	740	1.28	16	3.5	0.5	6.0 × 10 <sup>-2</sup>	13.70	3.50	3.62	52.5
QT-6207	40	655	1.56	12	3.0	0.60	2.0 × 10 <sup>-2</sup>	7.20	3.95	3.49	24
T-9902	40	512	1.77	9.5	6.3	0.65	5.0 × 10 <sup>-2</sup>	12.00	8.00	2.50	32.3
QT-7801	46	800	1.63	12.8	3.8	0.50	2.8 × 10 <sup>-2</sup>	9.00	5.16	2.40	20
QT-11301	50	331	2.76	4.9	1.2	1.6	6.0 × 10 <sup>-2</sup>	11.97	10.05	2.40	17.5
QT-17301	54	386	2.75	5.3	1.56	1.2	0.13	18.25	15.75	1.30	18
QT-7809	60	615	2.42	7.5	4.36	0.83	4.1 × 10 <sup>-2</sup>	9.00	5.16	3.40	31
T-9908	70	720	2.61	7.8	6.4	0.6	0.11	12.00	7.75	3.65	50
T-10020	100	930	3.3	7	7.5	2	0.18	13.70	3.50	6.12	110
T-10035	100	1040	3.10	7.7	5.77	1.0	0.178	13.25	3.38	5.31	95.5
QT-11303	100	499	4.5	3.6	0.76	2.5	0.11	12.25	10.05	4.60	39
QT-12506	123	794	4.36	4.8	3.24	1.2	0.17	14.00	10.50	3.00	42
T-10071	150	1470	3.9	7.2	6.6	1.8	0.22	13.70	3.50	7.45	145
QT-12505	200	1095	6.04	4	3.78	1.6	0.27	14.00	10.50	4.48	67
T-12008	201	2628	3.93	9.6	8.33	1.0	0.50	16.06	6.00	7.50	194
T-18002	300	1452	7.85	3.6	20.0	3.0	1.40	23.69	10.35	5.94	300
QT-23502	700	1310	19	1.4	4.8	7.0	2.9	25.45	20.59	6.00	230
T-18004	900	3435	15.3	2.8	25.0	4.0	3.10	23.56	9.38	10.56	650
T-24005	1000	7000	12	5	12.5	5	8	30.00	18.00	8.00	730
T-36010	1500	4900	21	2.4	14	10	15	41.75	27.75	6.75	820
T-18031	1600	5600	21.4	2.5	23	6	4.2	23.51	9.38	14.75	850
T-36001	3000	6300	37.8	1.6	22	12	26	41.75	25.62	10.25	1360

# NT-0786

2.8 oz. in.

PEAK TORQUE



**NOTES:**

- MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. **CAUTION:** DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .0015 (.003 T.I.R.) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
- GOLD PLATED COMMUTATOR.

**LEADS:**

#28 AWG TYPE 'ET' TEFLON COATED PER MIL W-16878, 23" MIN. LG.  
(FREE TO EXIT FACE AND/OR O.D.)

## SIZE CONSTANTS

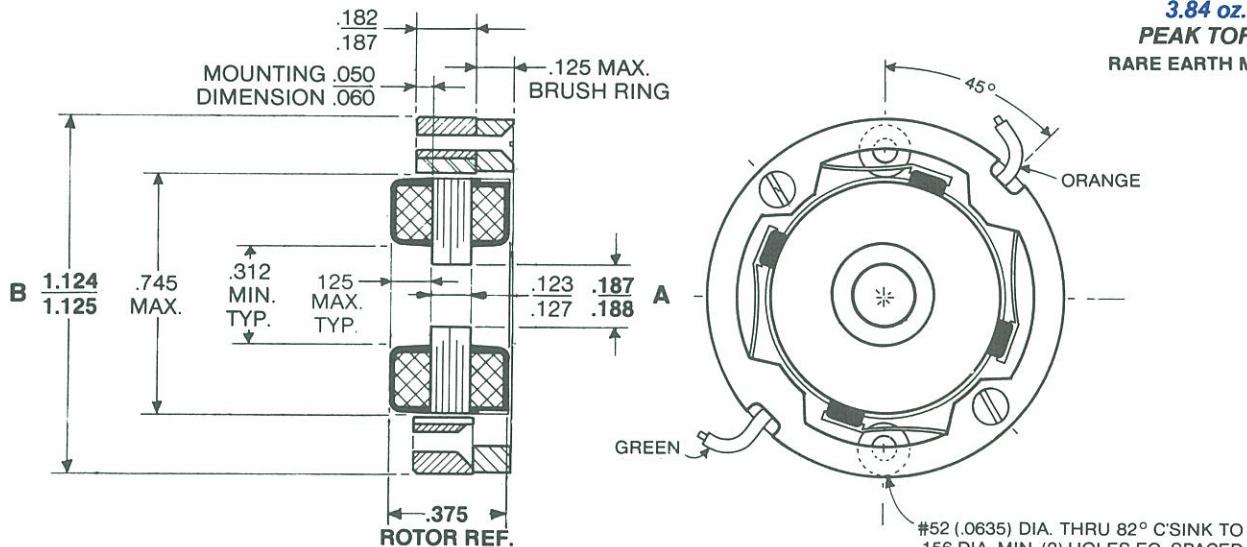
### Value      Units

Peak Torque Rating - $T_p$	2.8	OZ. IN.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	46	WATTS
Motor Constant - $K_m$	0.41	OZ.IN./√WATT
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	2300	RAD/S
Electrical Time Constant - $\tau_e$	0.13	MS
Static Friction (Max.) - $T_f$	0.20	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	$1.2 \times 10^{-3}$ $6.0 \times 10^{-5}$
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - TPR	45	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	7	PERCENT
Ripple Frequency (Fundamental)	13	CYCLES/REV.
Number of Poles	4	
Rotor Inertia - $J_m$	$4.5 \times 10^{-5}$	OZ.IN.S <sup>2</sup>
Motor Weight	1.4	OZ.

## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	11.8	18.8	29.6	37.5			
Peak Current - $I_p$	AMPERES	Rated	3.93	2.50	1.56	1.25			
Torque Sensitivity - $K_t$	OZ.IN./AMP.	±10%	0.712	1.12	1.79	2.24			
Back EMF Constant - $K_b$	V per RAD/S	±10%	0.005	0.008	0.013	0.016			
DC Resistance (25°C) - $R_m$	OHMS	±12.5%	3.00	7.50	19.0	30.0			
Inductance - $L_m$	mH	±30%	0.40	1.0	2.5	4.0			

**NOTES:**

- MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .0015(.003 T.I.R.) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
- GOLD PLATED COMMUTATOR.

**LEADS:**

#28 AWG TYPE "ET" TEFLON COATED PER MIL W-16878, 23" MIN. LENGTH (FREE TO EXIT FACE AND/OR O.D.)

**SIZE CONSTANTS****Value****Units**

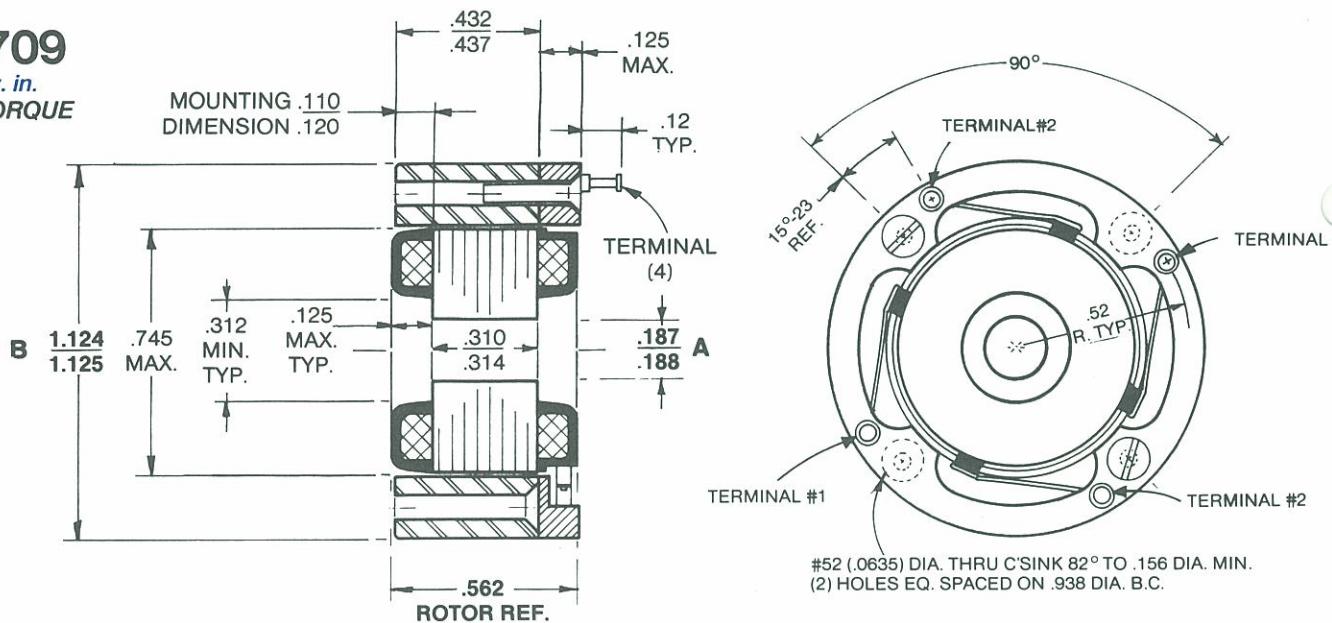
Peak Torque Rating - $T_p$	3.84	OZ. IN.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	53	WATTS
Motor Constant - $K_m$	0.529	OZ.IN./√WATT
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	1940	RAD/S
Electrical Time Constant - $\tau_e$	0.120	MS
Static Friction (Max.) - $T_f$	0.25	OZ. IN.
Viscous Damping Coefficients	$F_0$	OZ. IN. PER RAD/S
	$F_1$	OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - TPR	45	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	7	PERCENT
Ripple Frequency (Fundamental)	13	CYCLES/REV.
Number of Poles	4	
Rotor Inertia - $J_m$	$4.50 \times 10^{-5}$	OZ.IN.S <sup>2</sup>
Motor Weight	1.4	OZ.

**WINDING CONSTANTS****Winding Designation**

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	19.9	50.3	25.1	9.93	31.4		
Peak Current - $I_p$	AMPERES	Rated	2.65	1.06	2.11	5.20	1.68		
Torque Sensitivity - $K_t$	OZ.IN./AMP	±10%	1.45	3.64	1.82	0.738	2.29		
Back EMF Constant - $K_b$	V per RAD/S	±10%	0.010	0.026	0.013	0.005	0.016		
DC Resistance (25°C) - $R_m$	OHMS	±12.5%	7.50	47.5	11.9	1.91	18.7		
Inductance - $L_m$	mH	±30%	0.90	5.7	1.4	0.23	2.2		

# T-0709

6.6 oz. in.  
PEAK TORQUE



**NOTES:**

- MOTOR TO BE SUPPLIED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. **CAUTION:** DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002(.004 T.I.R.) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO TERMINALS #1, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
- GOLD PLATED COMMUTATOR.

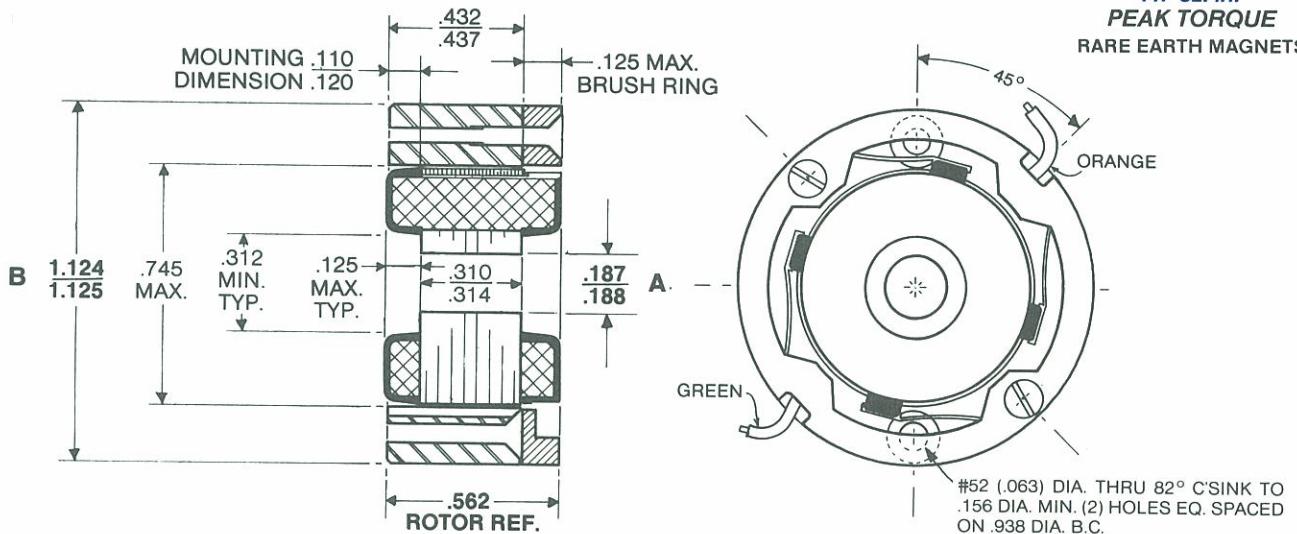
## SIZE CONSTANTS

		Value	Units
Peak Torque Rating - $T_p$		6.6	OZ. IN.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$		60	WATTS
Motor Constant - $K_m$		0.85	OZ.IN./√WATT
No Load Speed, Theoretical @ $V_p - \omega_{NL}$		1300	RAD/S
Electrical Time Constant - $\tau_e$		0.26	MS
Static Friction (Max.) - $T_f$		0.25	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.005	OZ. IN. PER RAD/S
	Infinite Impedance - $F_i$	$1.4 \times 10^{-4}$	OZ. IN. PER RAD/S
Maximum Winding Temperature		155	°C
Temperature Rise per Watt - $TPR$		34	°C/WATT
Ripple Torque (Average to Peak) - $T_r$		7	PERCENT
Ripple Frequency - (Fundamental)		13	CYCLES/REV.
Number of Poles		4	
Rotor Inertia - $J_m$		$1.1 \times 10^{-4}$	OZ.IN.S <sup>2</sup>
Motor Weight		1.6	oz.

## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	27.6	13.9	17.5	20.6	35.5	44.9	
Peak Current - $I_p$	AMPERES	Rated	2.12	3.93	3.44	2.77	1.74	1.33	
Torque Sensitivity - $K_t$	OZ.IN./AMP.	±10%	3.12	1.68	1.92	2.4	3.8	4.95	
Back EMF Constant - $K_b$	V per RAD/S	±10%	0.022	0.012	0.014	0.017	0.027	0.035	
DC Resistance (25°C) - $R_m$	OHMS	±12.5%	13.0	3.5	5.1	7.4	20.4	33.8	
Inductance - $L_m$	mH	±30%	3.4	0.95	1.4	2.2	4.9	8.5	

**NOTES:**

- MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .0015,.003 T.I.R.) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REVS.
- GOLD PLATED COMMUTATOR.

**LEADS:**

#26 AWG TYPE "ET" TEFLON COATED PER MIL W-16878, 23" MIN. LENGTH. (FREE TO EXIT FACE AND/OR O.D.)

**SIZE CONSTANTS****Value****Units**

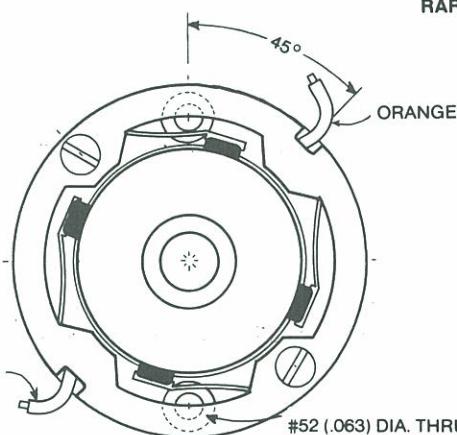
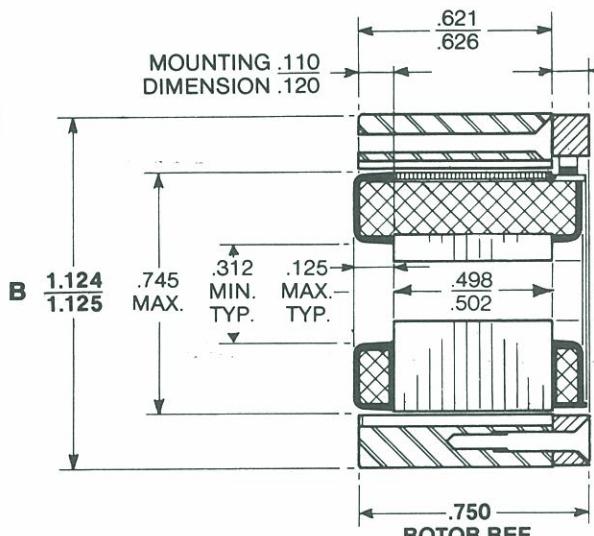
Peak Torque Rating - $T_p$	7.7	OZ.IN.						
Power Input, Stalled at $T_p$ (25°C) - $P_p$	50	WATTS						
Motor Constant - $K_m$	1.09	OZ.IN./√WATT						
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	925	RAD/S						
Electrical Time Constant - $\tau_e$	0.25	MS						
Static Friction (Max.) - $T_f$	0.30	OZ.IN.						
Viscous Damping Coefficients	<table> <tr> <td>Zero Impedance - <math>F_0</math></td> <td>0.0083</td> <td>OZ.IN. PER RAD/S</td> </tr> <tr> <td>Infinite Impedance - <math>F_i</math></td> <td>0.0001</td> <td>OZ.IN. PER RAD/S</td> </tr> </table>	Zero Impedance - $F_0$	0.0083	OZ.IN. PER RAD/S	Infinite Impedance - $F_i$	0.0001	OZ.IN. PER RAD/S	
Zero Impedance - $F_0$	0.0083	OZ.IN. PER RAD/S						
Infinite Impedance - $F_i$	0.0001	OZ.IN. PER RAD/S						
Maximum Winding Temperature	155	°C						
Temperature Rise per Watt - $TPR$	33	°C/WATT						
Ripple Torque (Average to Peak) - $T_R$	10	PERCENT						
Ripple Frequency - (Fundamental)	13	CYCLES/REV.						
Number of Poles	4							
Rotor Inertia - $J_m$	$1.1 \times 10^{-4}$	OZ.IN.S <sup>2</sup>						
Motor Weight	1.6	OZ.						

**WINDING CONSTANTS****Winding Designation**

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	33.3	26.6	21.0	16.5	13.3	10.5	8.32
Peak Current - $I_p$	AMPERES	Rated	1.50	1.90	2.39	3.00	3.79	4.78	5.86
Torque Sensitivity - $K_t$	OZ.IN./AMP	± 10%	5.13	4.06	3.22	2.57	2.03	1.61	1.31
Back EMF Constant - $K_b$	V per RAD/S	± 10%	0.036	0.029	0.023	0.018	0.014	0.012	0.009
DC Resistance (25°C) - $R_m$	OHMS	± 12.5%	22.2	14.0	8.80	5.50	3.50	2.20	1.42
Inductance - $L_m$	mH	± 30%	5.5	3.4	2.2	1.4	0.85	0.55	0.36

# NT-0796

10.6 oz. in.  
PEAK TORQUE

**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY. STATOR ASSEMBLY MUST BE MOUNTED WITH MAGNETIC STEEL SCREWS.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .0015(.003 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE  $\times 10^7$  REVS.
5. — GOLD PLATED COMMUTATOR.

**LEADS:**

#26 AWG TYPE "ET" TEFLON COATED  
PER MIL W-16878, 23" MIN. LENGTH.  
(FREE TO EXIT FACE AND/OR O.D.)

**SIZE CONSTANTS****Value****Units**

Peak Torque Rating - $T_p$	12.3	OZ.IN.
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	63	WATTS
Motor Constant - $K_m$	1.55	OZ.IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p \cdot \omega_{NL}$	725	RAD/S
Electrical Time Constant - $\tau_e$	0.315	MS
Static Friction (Max.) - $T_f$	0.40	OZ.IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_\infty$	0.017      0.0002
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	25	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	10	PERCENT
Ripple Frequency - (Fundamental)	13	CYCLES/REV.
Number of Poles	4	
Rotor Inertia - $J_m$	$1.6 \times 10^{-4}$	OZ.IN.S <sup>2</sup>
Motor Weight	2.5	OZ.

**WINDING CONSTANTS****Winding Designation**

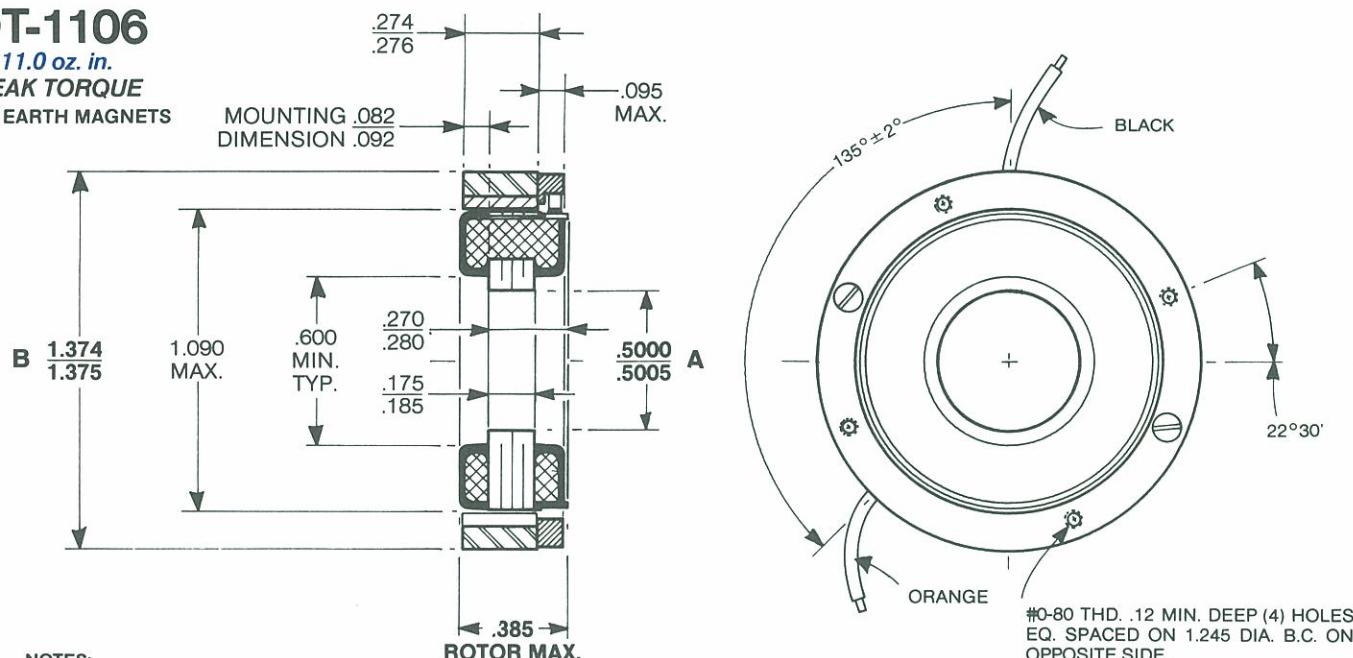
	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	42.0	33.4	26.5	21.0	16.7	10.5	52.8
Peak Current - $I_p$	AMPERES	Rated	1.50	1.90	2.39	3.00	3.79	6.14	1.19
Torque Sensitivity - $K_t$	OZ.IN./AMP	$\pm 10\%$	8.20	6.50	5.16	4.10	3.25	2.00	10.3
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.058	0.046	0.036	0.029	0.023	0.014	0.073
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	28.0	17.6	11.1	7.00	4.40	1.71	44.4
Inductance - $L_m$	mH	$\pm 30\%$	8.8	5.6	3.53	2.2	1.4	0.52	14

# QT-1106

11.0 oz. in.

PEAK TORQUE

RARE EARTH MAGNETS



**NOTES:**

1. — MOTOR TO BE SUPPLIED AS THREE SEPARATE COMPONENTS: STATOR ASSEMBLY, ROTOR ASSEMBLY, AND BRUSH RING ASSEMBLY.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO BLACK LEAD WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

#0-80 THD, .12 MIN. DEEP (4) HOLES  
EQ. SPACED ON 1.245 DIA. B.C. ON  
OPPOSITE SIDE.

**LEADS:**  
#26 AWG PER MIL W-16878/7, 12" MIN.  
LENGTH.

## SIZE CONSTANTS

**Value**

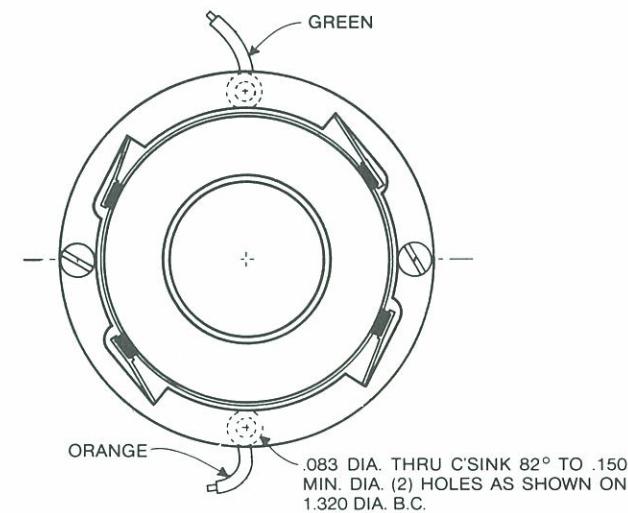
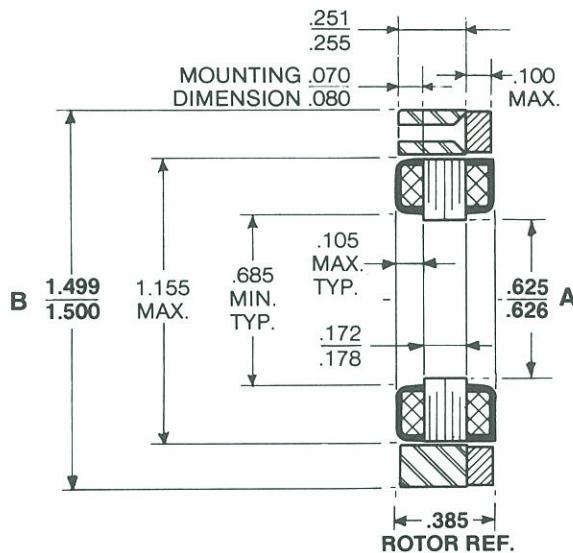
**Units**

Peak Torque Rating - $T_p$	11.0	OZ. IN.
Power Input, Stalled at $T_p$ (25°C) - $P_p$	49	WATTS
Motor Constant - $K_m$	1.57	OZ.IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	636	RAD/S
Electrical Time Constant - $\tau_e$	0.139	MS
Static Friction (Max.) - $T_f$	0.60	OZ. IN.
Viscous Damping Coefficients	$Zero \text{ Impedance} - F_0$ $Infinite \text{ Impedance} - F_i$	$1.73 \times 10^{-2}$ $1.00 \times 10^{-3}$
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	19	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	6.0	PERCENT
Ripple Frequency - (Fundamental)	29	CYCLES/REV.
Number of Poles	8	
Rotor Inertia - $J_m$	$3.20 \times 10^{-4}$	OZ.IN.S <sup>2</sup>
Motor Weight	1.5	OZ.

## WINDING CONSTANTS

*Winding Designation*

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ (25°C) - $V_p$	VOLTS	Nom.	19.8						
Peak Current - $I_p$	AMPERES	Rated	2.50						
Torque Sensitivity - $K_t$	OZ.IN./AMP	$\pm 10\%$	4.40						
Back EMF Constant - $K_b$	V PER RAD/S	$\pm 10\%$	0.0311						
DC Resistance (25°C) - $R_m$	OHMS	$\pm 12.5\%$	7.90						
Inductance - $L_m$	mH	$\pm 30\%$	1.1						

**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**LEADS:**#26 AWG TYPE "E" TEFLON COATED,  
16" MIN. LENGTH.**SIZE CONSTANTS****Value      Units**

Peak Torque Rating - $T_p$	11	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	57	WATTS	
Motor Constant - $K_m$	1.46	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p \cdot \omega_{NL}$	732	RAD/S	
Electrical Time Constant - $\tau_e$	0.11	MS	
Static Friction (Max.) - $T_f$	0.6	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_1$	0.015      0.001	OZ. IN. PER RAD/S      OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	25	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	7	PERCENT	
Ripple Frequency (Fundamental)	29	CYCLES/REV.	
Number of Poles	6		
Rotor Inertia - $J_m$	$4.2 \times 10^{-4}$	OZ.IN.S <sup>2</sup>	
Motor Weight	1.65	OZ.	

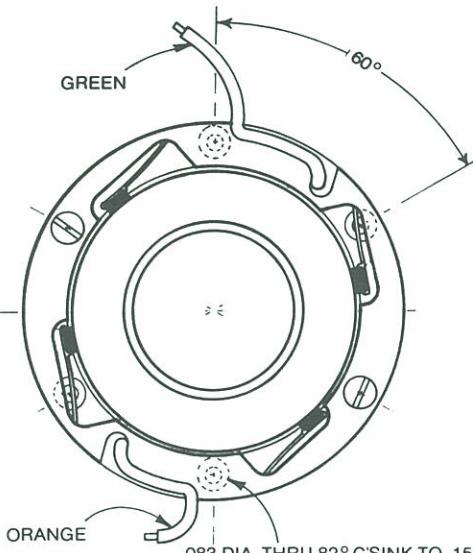
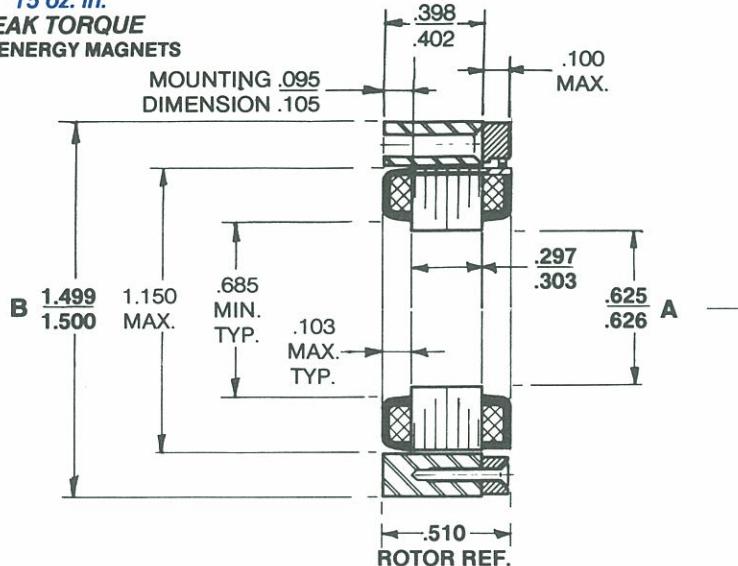
**WINDING CONSTANTS****Winding Designation**

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	18.3	29.0	9.15				
Peak Current - $I_p$	AMPERES	Rated	3.10	1.97	6.20				
Torque Sensitivity - $K_t$	OZ.IN/AMP	$\pm 10\%$	3.56	5.59	1.78				
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.025	0.039	0.013				
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	5.9	14.7	1.48				
Inductance - $L_m$	mH	$\pm 30\%$	0.65	1.6	0.16				

# T-1218

15 oz. in.

**PEAK TORQUE**  
HIGH ENERGY MAGNETS



**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. **CAUTION:** DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002(.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**LEADS:**

#26 AWG TYPE 'E' TEFLON COATED  
16" MIN. LG.

## SIZE CONSTANTS

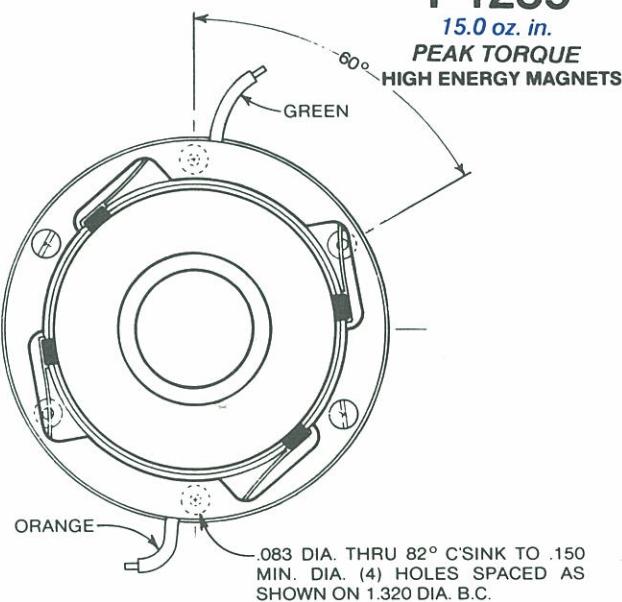
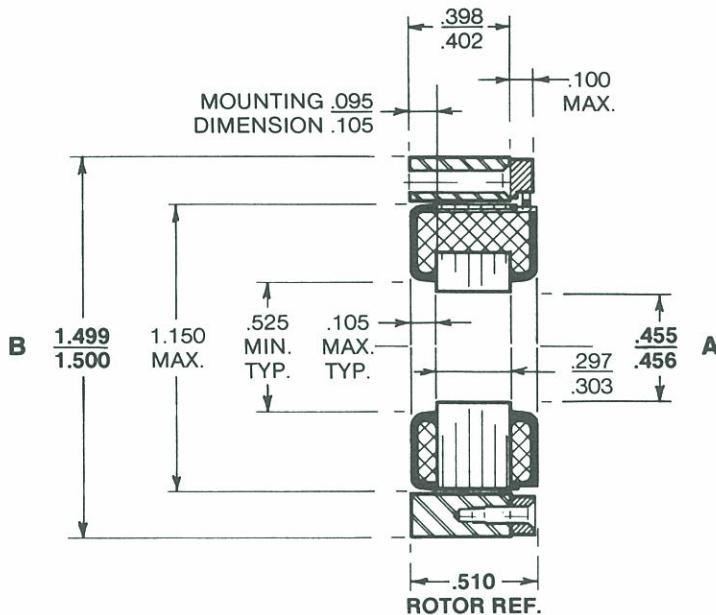
	<b>Value</b>	<b>Units</b>	
Peak Torque Rating - $T_p$	15	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	63	WATTS	
Motor Constant - $K_m$	1.9	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p - \omega_{NL}$	580	RAD/S	
Electrical Time Constant - $\tau_e$	0.31	MS	
Static Friction (Max.) - $T_f$	0.5	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.025	OZ. IN. PER RAD/S
	Infinite Impedance - $F_\infty$	0.002	OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - TPR	19	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	7	PERCENT	
Ripple Frequency - (Fundamental)	29	CYCLES/REV.	
Number of Poles	6		
Rotor Inertia - $J_m$	$6 \times 10^{-4}$	OZ.IN.S <sup>2</sup>	
Motor Weight	2.3	OZ.	

## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	50.0	26.1	64.0	20.1	16.0	12.5	79.0
Peak Current - $I_p$	AMPERES	Rated	1.25	2.75	1.0	3.1	3.8	5.0	0.79
Torque Sensitivity - $K_t$	OZ.IN/AMP.	$\pm 10\%$	12	5.5	15.1	4.8	4.0	3.0	19.0
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.085	0.039	0.107	0.034	0.028	0.021	0.134
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	40.0	9.5	64.0	6.5	4.2	2.5	100
Inductance - $L_m$	mH	$\pm 30\%$	12.3	2.9	20.0	2.0	1.3	0.77	32.0

**T-1259**  
15.0 oz. in.  
**PEAK TORQUE**  
**HIGH ENERGY MAGNETS**



**NOTES:**

- MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. **CAUTION:** DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002(.004 T.I.R.) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**LEADS:**

#26 AWG TYPE "E" TEFLON COATED PER MIL W-16878, 16" MIN. LG.

### SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>	
Peak Torque Rating - $T_p$	15.0	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	40	WATTS	
Motor Constant - $K_m$	2.4	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	374	RAD/S	
Electrical Time Constant - $\tau_e$	0.50	MS	
Static Friction (Max.) - $F_f$	.50	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.041	OZ. IN. PER RAD/S
	Infinite Impedance - $F_\infty$	0.002	OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	19	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	7	PERCENT	
Ripple Frequency - (Fundamental)	29	CYCLES/REV.	
Number of Poles	6		
Rotor Inertia - $J_m$	.00057	OZ.IN.S <sup>2</sup>	
Motor Weight	2.4	OZ.	

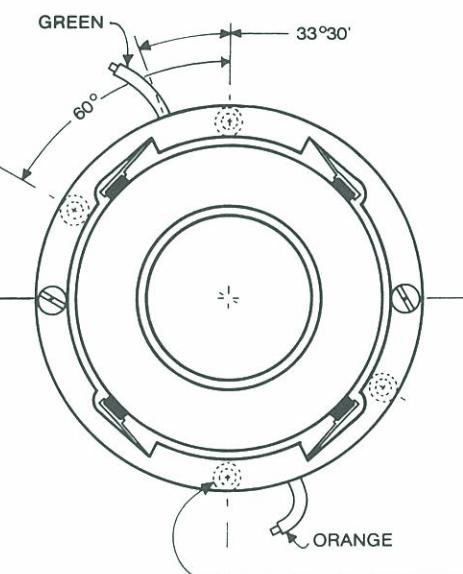
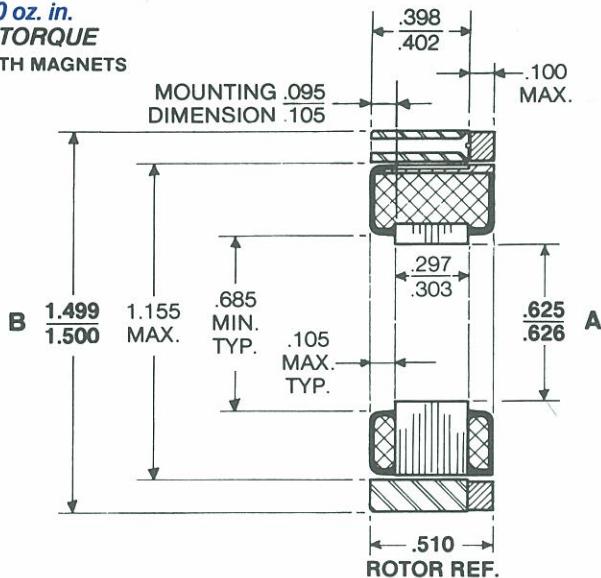
### WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	20.1	25.4	40.2				
Peak Current - $I_p$	AMPERES	Rated	1.97	1.56	0.985				
Torque Sensitivity - $K_t$	OZ.IN./AMP.	± 10%	7.60	9.6	15.2				
Back EMF Constant - $K_b$	V per RAD/S	± 10%	0.0537	0.068	0.107				
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	± 12.5%	10.2	16.3	40.8				
Inductance - $L_m$	mH	± 30%	5.10	8.2	20.4				

# QT-1207

**20.0 oz. in.  
PEAK TORQUE  
RARE EARTH MAGNETS**



#### NOTES:

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

.083 DIA. THRU C'SINK 82° TO .150  
MIN. DIA. (4) HOLES AS SHOWN ON  
1.320 BASIC DIA. B.C.

#### LEADS:

#26 AWG TYPE "E" TEFLON COATED,  
16" MIN. LENGTH.

## SIZE CONSTANTS

**Value      Units**

Peak Torque Rating - $T_p$	20.0	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	81.8	WATTS	
Motor Constant - $K_m$	2.21	OZ.IN./√ WATT	
No Load Speed, Theoretical @ $V_p$ , $\omega_{NL}$	580	RAD/S	
Electrical Time Constant - $\tau_e$	0.20	MS	
Static Friction (Max.) - $T_f$	0.70	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.035	OZ. IN. PER RAD/S
	Infinite Impedance - $F_i$	0.002	OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	19	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	7.0	PERCENT	
Ripple Frequency (Fundamental)	29	CYCLES/REV.	
Number of Poles	6		
Rotor Inertia - $J_m$	$6.0 \times 10^{-4}$	OZ.IN.S <sup>2</sup>	
Motor Weight	2.3	OZ.	

## WINDING CONSTANTS

## Winding Designation

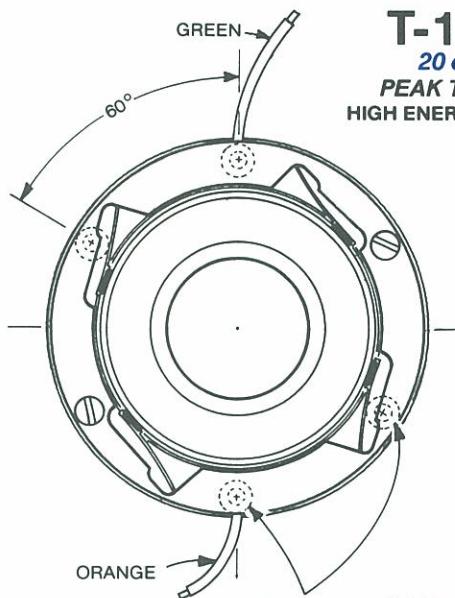
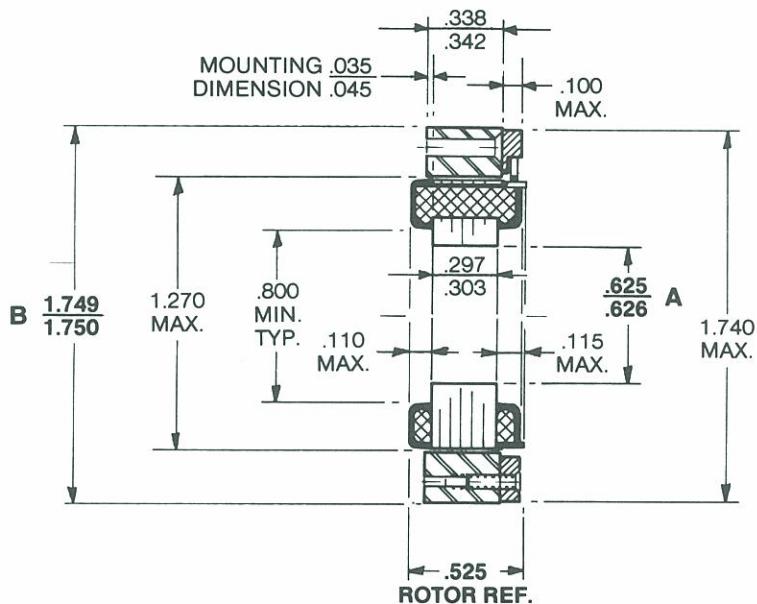
	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	57.3	45.0	36.4	28.6	22.5	17.9	14.3
Peak Current - $I_p$	AMPERES	Rated	1.43	1.80	2.29	2.86	3.52	4.36	5.72
Torque Sensitivity - $K_t$	OZ.IN./AMP	±10%	14.0	11.1	8.75	7.00	5.68	4.59	3.50
Back EMF Constant - $K_b$	V per RAD/S	±10%	.099	.078	.062	.049	.040	.032	.025
DC Resistance (25°C) - $R_m$	OHMS	±12.5%	40.0	25.0	15.9	10.0	6.40	4.10	2.50
Inductance - $L_m$	mH	±30%	7.9	5.0	3.1	2.0	1.3	0.85	0.49

**T-1292**

20 oz. in.

PEAK TORQUE

HIGH ENERGY MAGNETS

**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: ROTOR ASSEMBLY, BRUSH RING ASSEMBLY, AND STATOR WITH KEEPER. **CAUTION:** DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH A POSITIVE VOLTAGE APPLIED TO GREEN LEAD WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
5. — GOLD PLATED COMMUTATOR.

**LEADS:**#26 AWG TYPE "E" TEFILON COATED  
36" MIN. LENGTH.**SIZE CONSTANTS****Value****Units**

Peak Torque Rating - $T_p$	20	OZ. IN.
Power Input, Stalled at $T_p$ (25°C) - $P_p$	64	WATTS
Motor Constant - $K_m$	2.51	OZ.IN./√ WATT
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	450	RAD/S
Electrical Time Constant - $\tau_e$	0.369	MS
Static Friction (Max.) - $T_f$	0.55	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_\infty$	0.0445 $2.20 \times 10^{-3}$
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	17	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	7	PERCENT
Ripple Frequency - (Fundamental)	31	CYCLES/REV.
Number of Poles	6	
Rotor Inertia - $J_m$	$9.00 \times 10^{-4}$	OZ.IN.S <sup>2</sup>
Motor Weight	2.8	OZ.

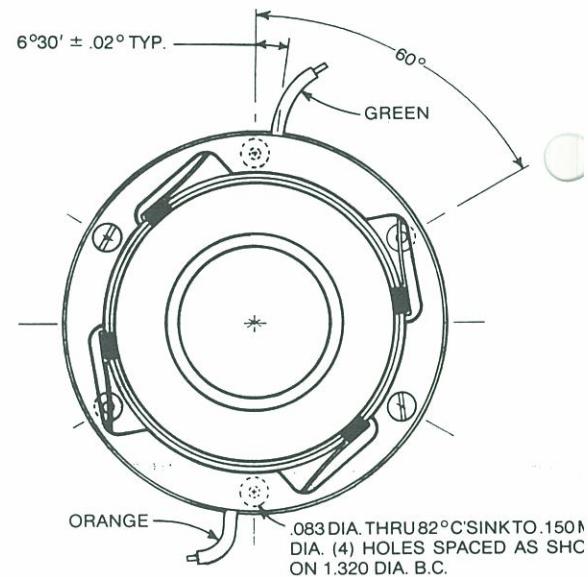
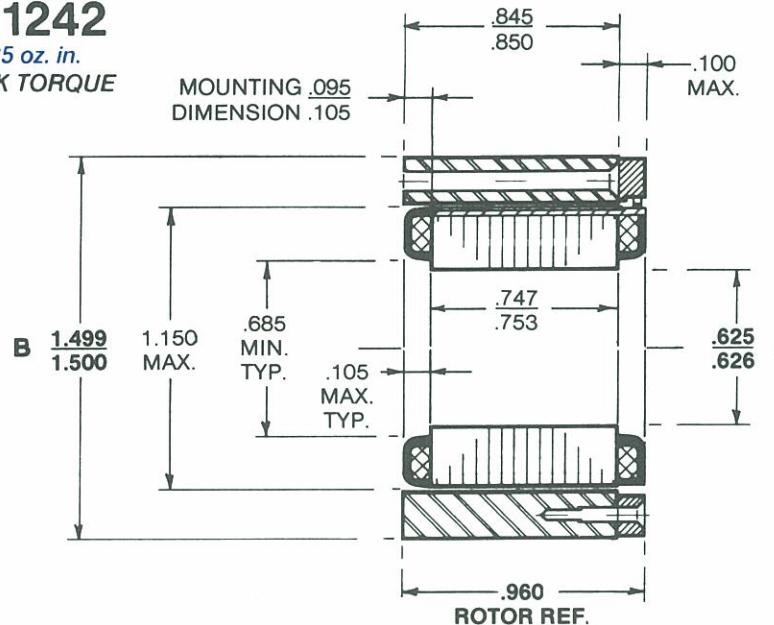
**WINDING CONSTANTS****Winding Designation**

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ (25°C) - $V_p$	VOLTS	Nom.	20.3	25.7					
Peak Current - $I_p$	AMPERES	Rated	3.13	2.52					
Torque Sensitivity - $K_t$	OZ.IN./AMP	±10%	6.40	7.94					
Back EMF Constant - $K_b$	V PER RAD/S	±10%	0.0452	0.0561					
DC Resistance (25°C) - $R_m$	OHMS	±12.5%	6.50	10.2					
Inductance - $L_m$	mH	±30%	2.4	3.7					

# T-1242

25 oz. in.

PEAK TORQUE



**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. CAUTION: DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002(.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**LEADS:**

#26 AWG TYPE "E" TEFLON COATED PER MIL W-16878 16" MIN. LG.

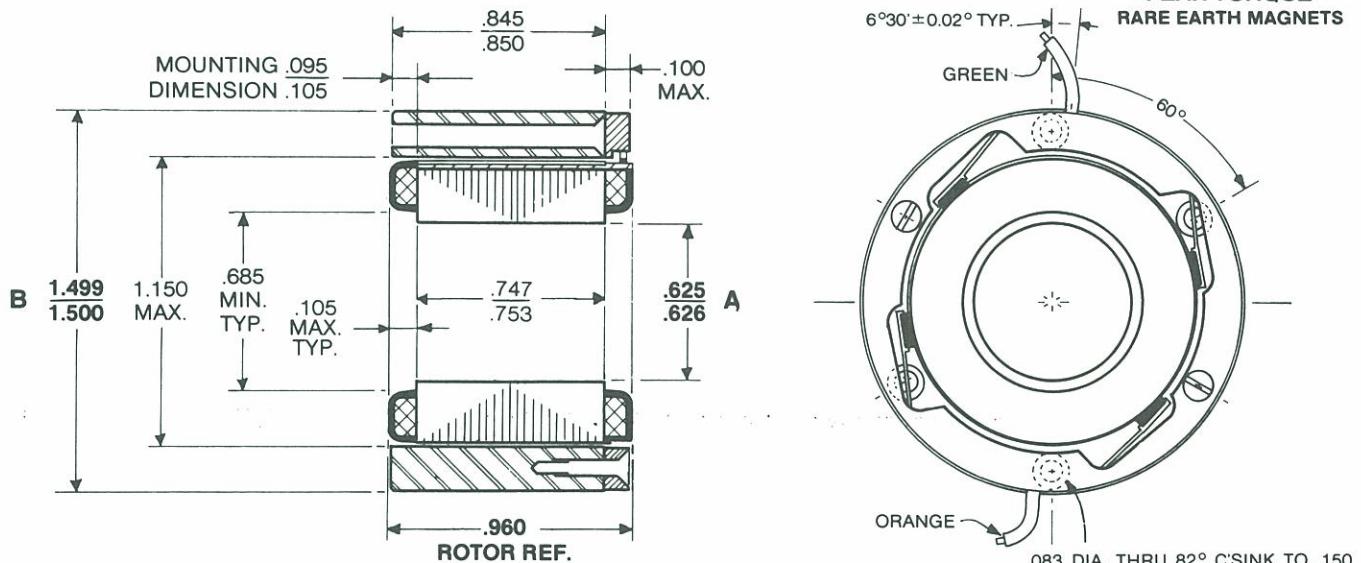
## SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>	
Peak Torque Rating - $T_p$	25	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	55	WATTS	
Motor Constant - $K_m$	3.4	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p - \omega_{NL}$	307	RAD/S	
Electrical Time Constant - $\tau_e$	0.68	MS	
Static Friction (Max.) - $T_f$	1.1	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.082	OZ. IN. PER RAD/S
	Infinite Impedance - $F_\infty$	0.005	OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - TPR	12	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	7	PERCENT	
Ripple Frequency - (Fundamental)	29	CYCLES/REV.	
Number of Poles	6		
Rotor Inertia - $J_m$	0.0015	OZ.IN.S <sup>2</sup>	
Motor Weight	5.5	oz.	

## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	22.8	35.1	29.0	44.9			
Peak Current - $I_p$	AMPERES	Rated	2.40	1.50	1.95	1.20			
Torque Sensitivity - $K_t$	OZ.IN./AMP.	±10%	10.5	16.5	12.9	21.0			
Back EMF Constant - $K_b$	V per RAD/S	±10%	0.074	0.117	0.091	0.148			
DC Resistance (25°C) - $R_m$	OHMS	±12.5%	9.50	23.4	14.9	37.4			
Inductance - $L_m$	mH	±30%	6.5	16	9.8	26			

**NOTES:**

- MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**LEADS:**

#26 AWG TYPE "E" TEFLON COATED  
PER MIL W-16878, 16" MIN. LENGTH.

**SIZE CONSTANTS****Value****Units**

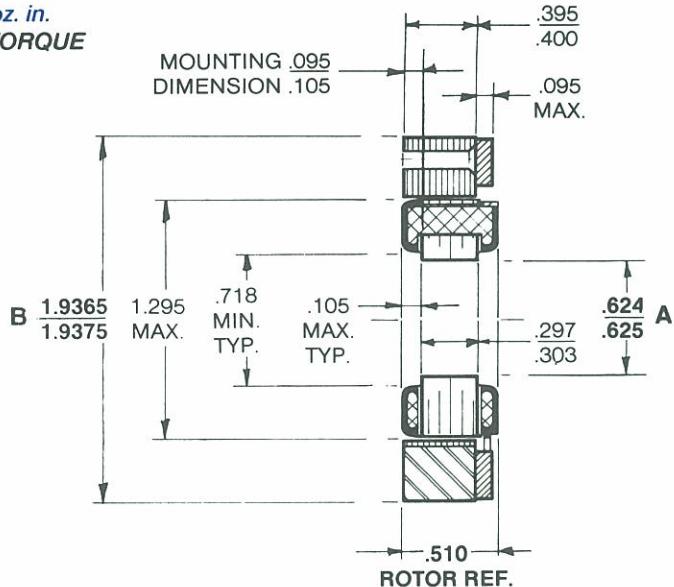
Peak Torque Rating - $T_p$	50	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	165	WATTS	
Motor Constant - $K_m$	3.9	OZ.IN./√WATT	
No Load Speed, Theoretical @ $V_p$ , $\omega_{NL}$	467	RAD/S	
Electrical Time Constant - $\tau_e$	0.38	MS	
Static Friction (Max.) - $T_f$	1.1	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.11	OZ. IN. PER RAD/S
	Infinite Impedance - $F_1$	0.003	OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	12	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	7	PERCENT	
Ripple Frequency (Fundamental)	29	CYCLES/REV.	
Number of Poles	6		
Rotor Inertia - $J_m$	0.0015	OZ.IN.S <sup>2</sup>	
Motor Weight	5.5	OZ.	

**WINDING CONSTANTS****Winding Designation**

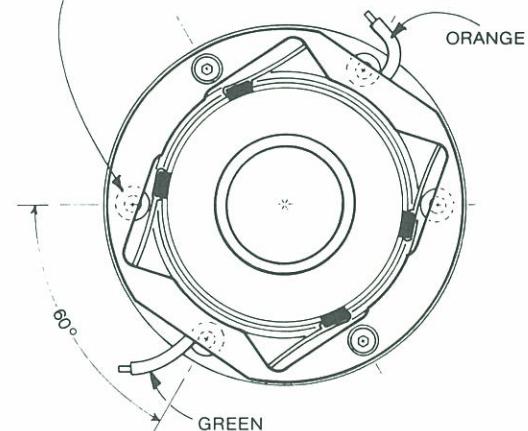
	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	33.0	20.8					
Peak Current - $I_p$	AMPERES	Rated	5.00	7.85					
Torque Sensitivity - $K_t$	OZ.IN./AMP	± 10%	10.0	6.36					
Back EMF Constant - $K_b$	V per RAD/S	± 10%	0.0706	0.045					
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	± 12.5%	6.60	2.65					
Inductance - $L_m$	mH	± 30%	2.5	1.0					

# T-1352

20 oz. in.  
PEAK TORQUE



.096 DIA. THRU CSINK 82° TO .170  
DIA. MIN. (4) HOLES SPACED AS  
SHOWN ON 1.687 DIA. B.C.



#### NOTES:

- MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. CAUTION: DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002(.004T.I.R.) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

#### LEADS:

#28 AWG TYPE 'E' TEFLON COATED PER  
MIL W-16878 10" MIN. LG.

## SIZE CONSTANTS

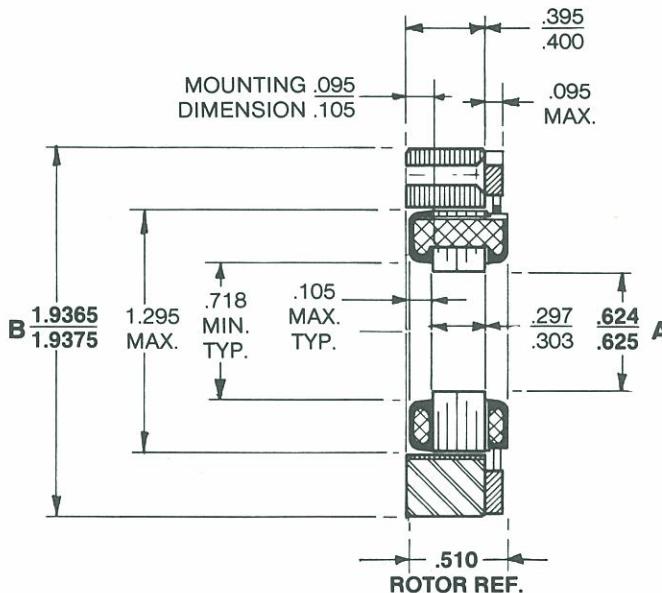
## Value      Units

Peak Torque Rating - $T_p$	20	OZ. IN.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	60	WATTS
Motor Constant - $K_m$	2.58	OZ.IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	400	RAD/S
Electrical Time Constant - $\tau_e$	0.34	MS
Static Friction (Max.) - $T_f$	0.7	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.049 OZ. IN. PER RAD/S
	Infinite Impedance - $F_i$	$4.6 \times 10^{-3}$ OZ. IN. PER RAD/S
Maximum Winding Temperature	105	°C
Temperature Rise per Watt - $TPR$	15.6	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	7	PERCENT
Ripple Frequency - (Fundamental)	31	CYCLES/REV.
Number of Poles	6	
Rotor Inertia - $J_m$	$8.8 \times 10^{-4}$	OZ.IN.S <sup>2</sup>
Motor Weight	4.3	OZ.

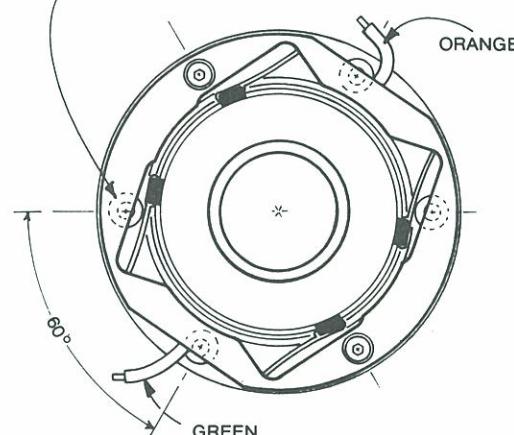
## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	26.0	31.0	40.6	49.4	63.7	79.6	97.8
Peak Current - $I_p$	AMPERES	Rated	2.3	1.8	1.5	1.2	0.90	0.73	0.60
Torque Sensitivity - $K_t$	OZ.IN./AMP	±10%	8.7	11.0	13.7	16.5	22.3	27.5	33.6
Back EMF Constant - $K_b$	V per RAD/S	±10%	0.061	0.078	0.097	0.116	0.157	0.194	0.237
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	±12.5%	11.3	17.2	27.1	41.2	70.8	109	163
Inductance - $L_m$	mH	±30%	4.0	6.0	10.0	13.0	24.0	36.0	54.0



.096 DIA. THRU C'SINK 82° TO .170  
DIA. MIN. (4) HOLES SPACED AS  
SHOWN ON 1.687 DIA. B.C.



## NOTES:

- MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. CAUTION: DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
- TYPICAL BRUSH LIFE > 107 REV.
- HIGH PERMEABILITY LAMINATION MATERIAL.

## LEADS:

#28 AWG TYPE "E" TEFLON COATED  
10" MIN. LG.

## SIZE CONSTANTS

## Value

## Units

Peak Torque Rating - $T_p$	24	OZ. IN.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	64	WATTS
Motor Constant - $K_m$	3.0	OZ.IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	375	RAD/S
Electrical Time Constant - $\tau_e$	0.29	MS
Static Friction (Max.) - $T_f$	0.8	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.064 OZ. IN. PER RAD/S
	Infinite Impedance - $F_i$	0.005 OZ. IN. PER RAD/S
Maximum Winding Temperature	105	°C
Temperature Rise per Watt - TPR	15.6	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT
Ripple Frequency - (Fundamental)	31	CYCLES/REV.
Number of Poles	6	
Rotor Inertia - $J_m$	$8.8 \times 10^{-4}$	OZ.IN.S <sup>2</sup>
Motor Weight	4.3	OZ.

## WINDING CONSTANTS

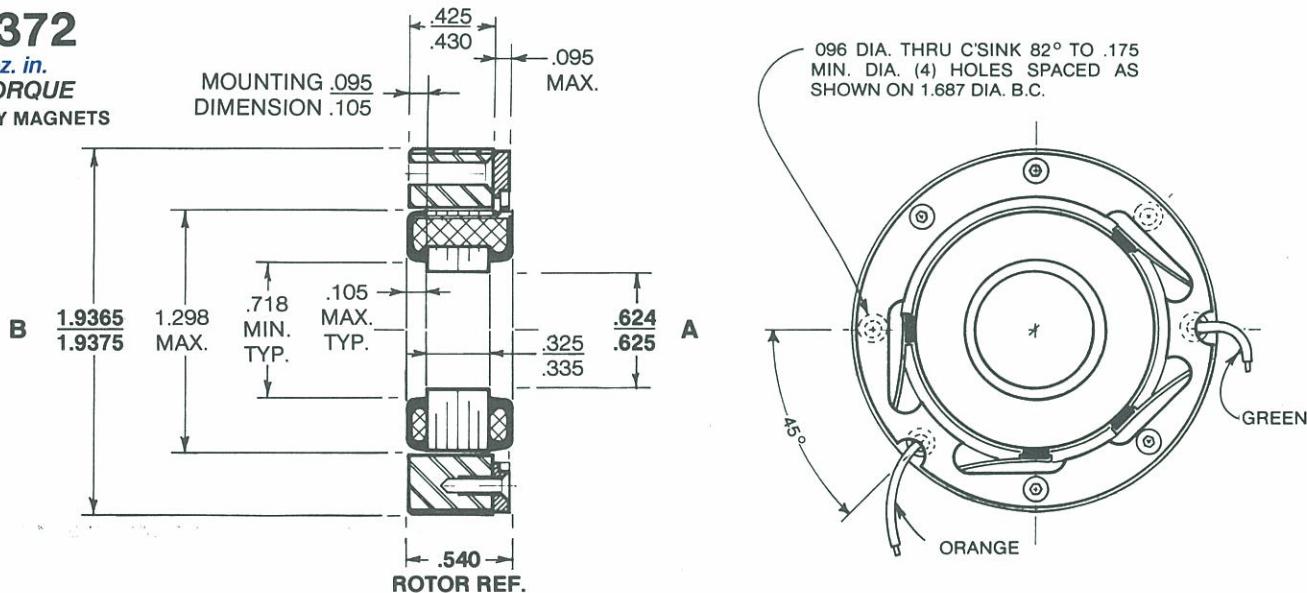
## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	27.6	21.5	17.2	34.4	55.2		
Peak Current - $I_p$	AMPERES	Rated	2.3	2.95	3.73	1.86	1.15		
Torque Sensitivity - $K_t$	OZ.IN./AMP.	± 10%	10.5	8.15	6.45	12.9	21.0		
Back EMF Constant - $K_b$	V per RAD/S	± 10%	0.074	0.058	0.046	0.091	0.148		
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	± 12.5%	12.0	7.30	4.60	18.5	48.0		
Inductance - $L_m$	mH	± 30%	3.5	2.1	1.32	5.3	14		

# NT-1372

30.0 oz. in.  
PEAK TORQUE

HIGH ENERGY MAGNETS



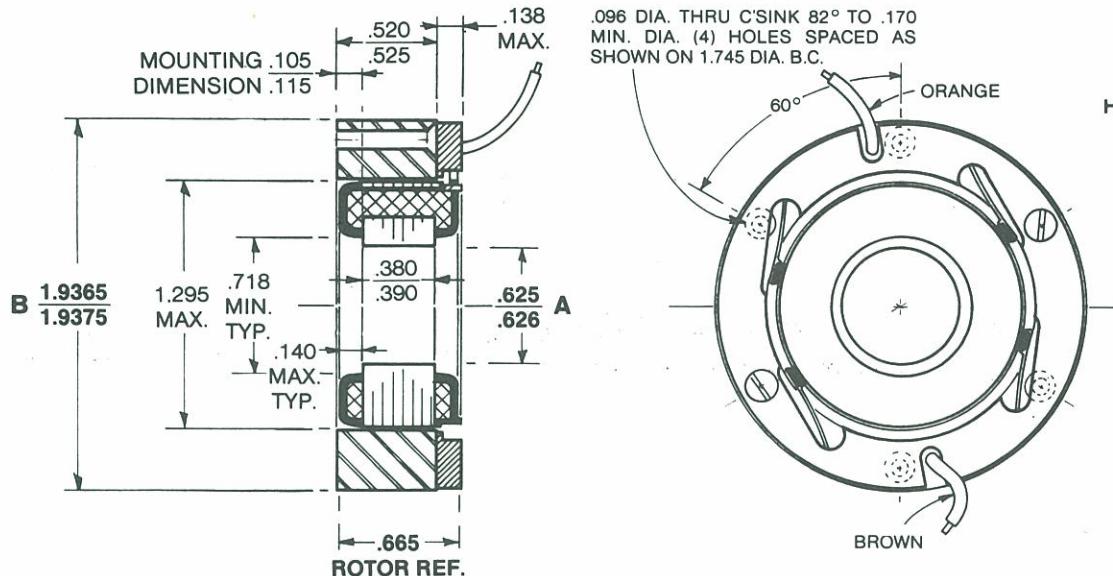
## SIZE CONSTANTS

		Value	Units
Peak Torque Rating - $T_p$		30.0	OZ. IN.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$		52	WATTS
Motor Constant - $K_m$		4.15	OZ.IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p \cdot \omega_{NL}$		245	RAD/S
Electrical Time Constant - $\tau_e$		0.3	MS
Static Friction (Max.) - $T_f$		1.8	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_1$	0.122 $4 \times 10^{-3}$	OZ. IN. PER RAD/S
Maximum Winding Temperature		155	°C
Temperature Rise per Watt - TPR		15.6	°C/WATT
Ripple Torque (Average to Peak) - $T_r$		7	PERCENT
Ripple Frequency - (Fundamental)		31	CYCLES/REV.
Number of Poles		8	
Rotor Inertia - $J_m$		$9.0 \times 10^{-4}$	OZ.IN.S <sup>2</sup>
Motor Weight		4.4	OZ.

## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	17.4	13.7	21.8	27.4	10.9		
Peak Current - $I_p$	AMPERES	Rated	3.0	3.8	2.4	1.9	4.81		
Torque Sensitivity - $K_t$	OZ. IN./AMP.	$\pm 10\%$	10.0	7.92	12.5	15.8	6.24		
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.0706	0.056	0.088	0.112	0.044		
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	5.8	3.6	9.1	14.4	2.26		
Inductance - $L_m$	mH	$\pm 30\%$	1.7	1.1	2.7	4.4	0.69		



**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. CAUTION: DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002(.004 T.I.R) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO BROWN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
5. — GOLD PLATED COMMUTATOR.
6. — HIGH PERMEABILITY LAMINATION MATERIAL.

**LEADS:**

#24 AWG TYPE "E" TEFLON COATED PER MIL W-16878 6" MIN. L.G.

### SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>
Peak Torque Rating - $T_p$	32	OZ. IN.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	83	WATTS
Motor Constant - $K_m$	3.5	OZ.IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	368	RAD/S
Electrical Time Constant - $\tau_e$	0.5	MS
Static Friction (Max.) - $T_f$	1.0	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	0.087      0.015
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	14.7	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	10	PERCENT
Ripple Frequency - (Fundamental)	31	CYCLES/REV.
Number of Poles	6	
Rotor Inertia - $J_m$	$1.1 \times 10^{-3}$	OZ.IN.S <sup>2</sup>
Motor Weight	6	OZ.

### WINDING CONSTANTS

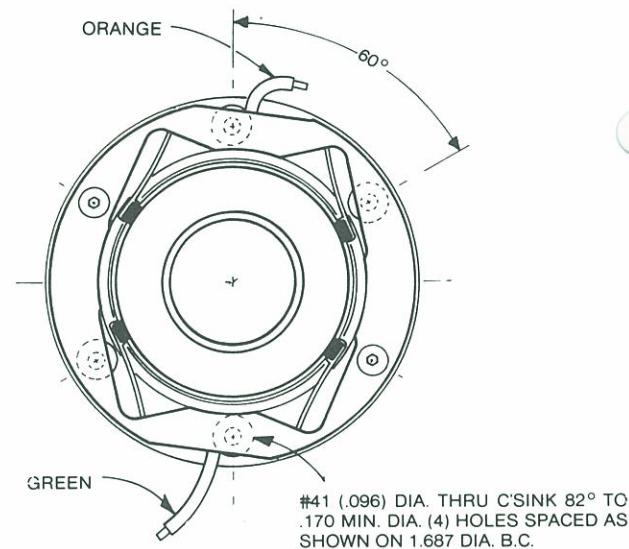
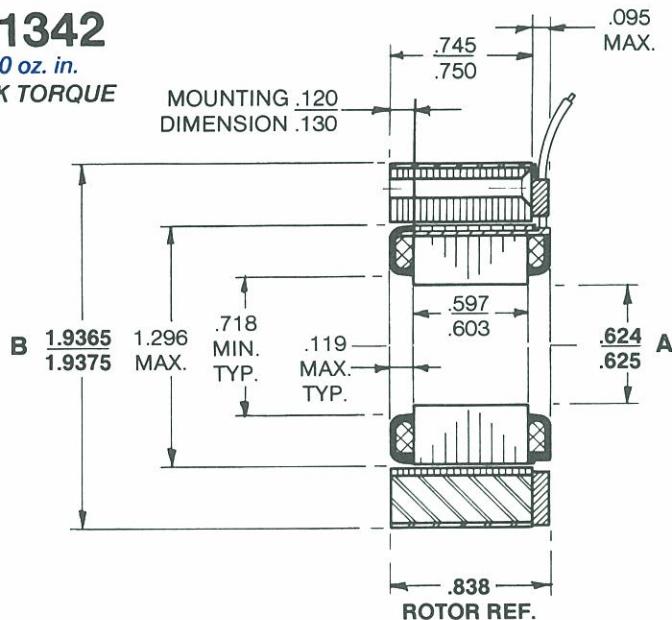
### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	32.0	25.3	20.1	40.3			
Peak Current - $I_p$	AMPERES	Rated	2.60	3.34	4.26	2.08			
Torque Sensitivity - $K_t$	OZ.IN./AMP.	$\pm 10\%$	12.3	9.60	7.52	15.4			
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.087	0.068	0.053	0.109			
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	12.3	7.60	4.73	19.4			
Inductance - $L_m$	mH	$\pm 30\%$	6.0	3.6	2.2	9.4			

# T-1342

40 oz. in.

PEAK TORQUE



**NOTES:**

- MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. **CAUTION:** DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**LEADS:**  
#28 AWG TYPE "E" TEFLON COATED  
10" MIN. LG.

## SIZE CONSTANTS

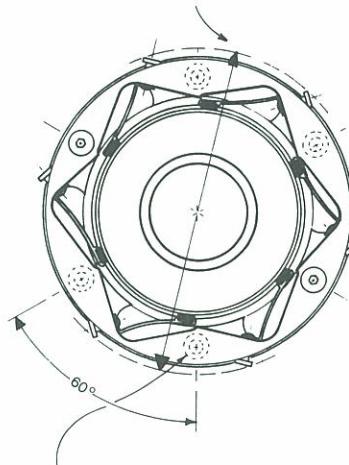
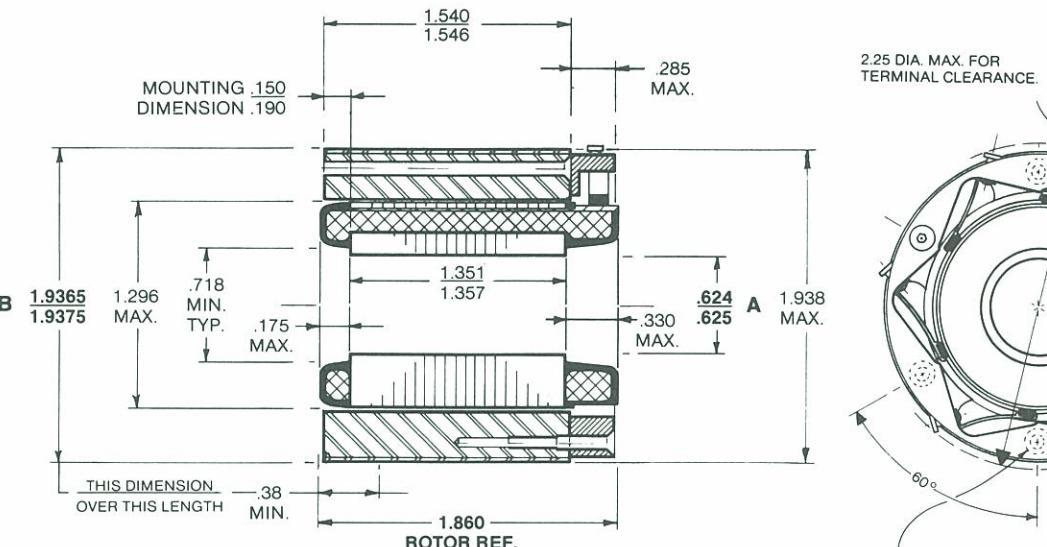
### Value      Units

Peak Torque Rating - $T_p$	40	OZ. IN.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	98	WATTS
Motor Constant - $K_m$	4.05	OZ.IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p - \omega_{NL}$	340	RAD/S
Electrical Time Constant - $\tau_e$	0.30	MS
Static Friction (Max.) - $T_f$	1.0	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.12 OZ. IN. PER RAD/S
	Infinite Impedance - $F_1$	0.007 OZ. IN. PER RAD/S
Maximum Winding Temperature	105	°C
Temperature Rise per Watt - $TPR$	13.4	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	7	PERCENT
Ripple Frequency - (Fundamental)	31	CYCLES/REV.
Number of Poles	6	
Rotor Inertia - $J_m$	$1.6 \times 10^{-3}$	OZ.IN.S <sup>2</sup>
Motor Weight	7.6	OZ.

## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	12.8	29.5	37.2	47.0	59.2	74.8	94.7
Peak Current - $I_p$	AMPERES	Rated	7.6	3.31	2.62	2.1	1.65	1.3	1.0
Torque Sensitivity - $K_t$	OZ.IN./AMP.	$\pm 10\%$	5.24	12.1	15.2	19.2	24.2	30.5	38.5
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.037	0.086	0.11	0.14	0.17	0.22	0.27
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	1.67	8.9	14.2	22.6	35.9	57.2	91.0
Inductance - $L_m$	mH	$\pm 30\%$	0.5	3.0	4.8	7.6	12	19	31



**NOTES:**

1. - MOTOR TO BE SHIPPED AS TWO SEPARATE COMPONENTS: STATOR ASSEMBLY WITH ROTOR IN PLACE AND BRUSH RING ASSEMBLY. REMOVE MYLAR SHIMS FROM AIR GAP AFTER ROTOR AND STATOR ARE SECURELY MOUNTED. **CAUTION:** DO NOT REMOVE ROTOR FROM STATOR AT ANY TIME.
2. - MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" MUST BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. - WITH POSITIVE CURRENT APPLIED TO #1 TERMINALS WITH RESPECT TO #2 TERMINALS, ROTATION SHALL BE C.W. FACING BRUSHRING END. MAXIMUM SOLDER TEMPERATURE 400°F.
4. - TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
5. - FULL COMPLEMENT OF BRUSHES FOR IMPROVED HIGH CURRENT OPERATION.

## SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>
Peak Torque Rating - $T_p$	90	OZ. IN.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	255	WATTS
Motor Constant - $K_m$	5.65	OZ.IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	407	RAD/S
Electrical Time Constant - $\tau_E$	0.40	MS
Static Friction (Max.) - $T_f$	3.0	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.22 OZ. IN. PER RAD/S
	Infinite Impedance - $F_i$	0.019 OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	9	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	7	PERCENT
Ripple Frequency - (Fundamental)	31	CYCLES/REV.
Number of Poles	6	
Rotor Inertia - $J_m$	$3.5 \times 10^{-3}$	OZ.IN.S <sup>2</sup>
Motor Weight	16.1	OZ.

## WINDING CONSTANTS

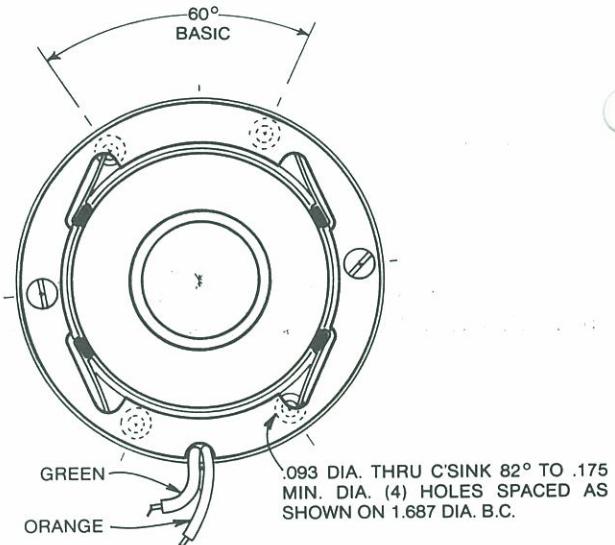
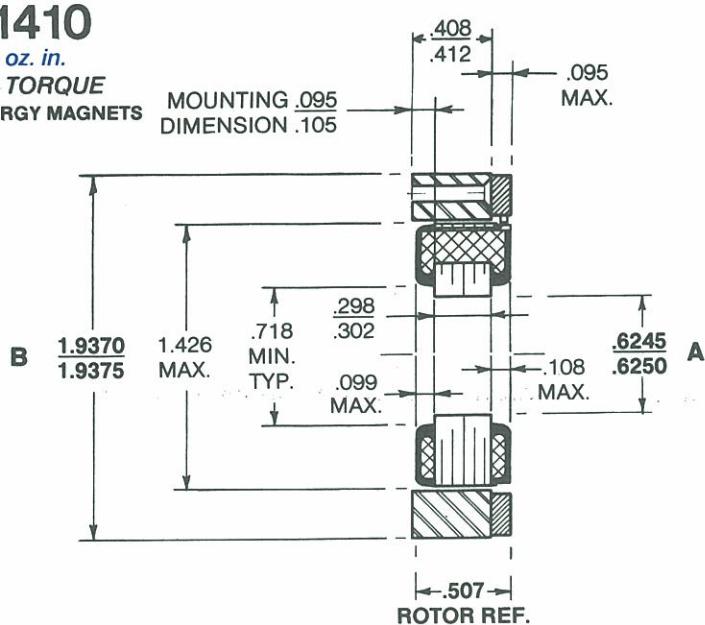
### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	22.0	28.8					
Peak Current - $I_p$	AMPERES	Rated	11.6	9.3					
Torque Sensitivity - $K_t$	OZ.IN./AMP.	$\pm 10\%$	7.8	9.70					
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.055	0.069					
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	1.9	3.1					
Inductance - $L_m$	mH	$\pm 30\%$	0.78	1.22					

# T-1410

21 oz. in.

**PEAK TORQUE**  
HIGH ENERGY MAGNETS



**NOTES:**

- MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. CAUTION: DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002(.004 T.I.R.) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**LEADS:**

#28 AWG TYPE "E" TEFLON COATED  
12" MIN. LG.

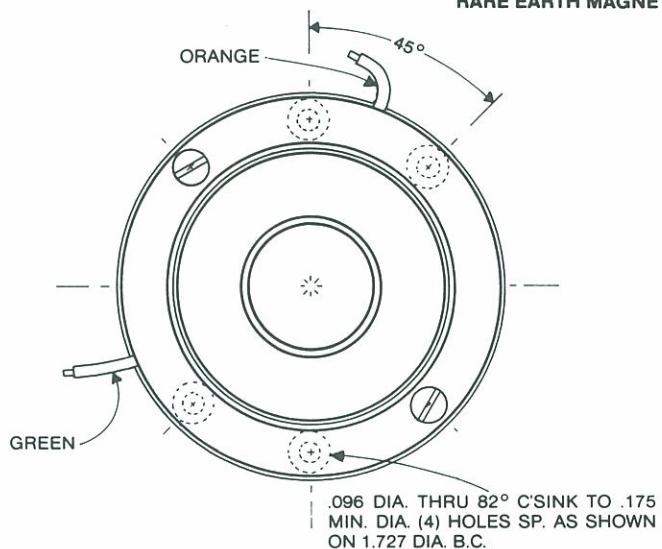
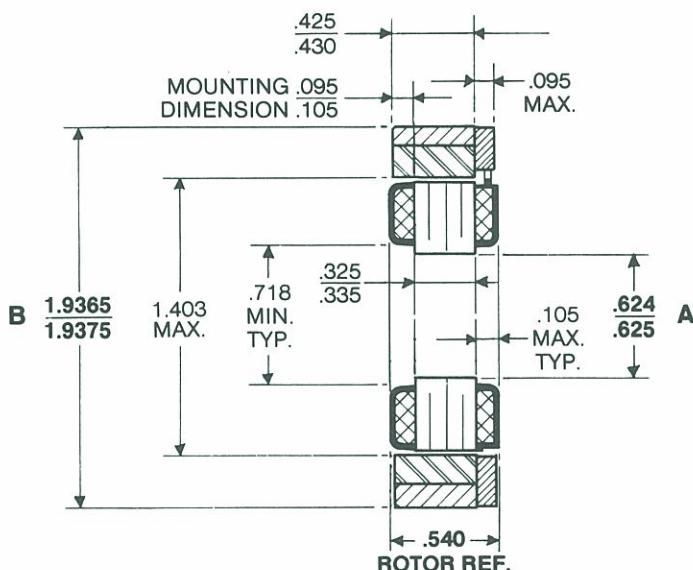
## SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>
Peak Torque Rating - $T_p$	21	OZ. IN.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	49	WATTS
Motor Constant - $K_m$	3.0	OZ.IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	360	RAD/S
Electrical Time Constant - $\tau_e$	.31	MS
Static Friction (Max.) - $T_f$	.7	OZ. IN.
Viscous Damping Coefficients	.064	OZ. IN. PER RAD/S
Zero Impedance - $F_0$	.004	OZ. IN. PER RAD/S
Infinite Impedance - $F_\infty$		
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - TPR	15	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	6	PERCENT
Ripple Frequency - (Fundamental)	37	CYCLES/REV.
Number of Poles	6	
Rotor Inertia - $J_m$	.0015	OZ.IN.S <sup>2</sup>
Motor Weight	5	OZ.

## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	28.0	35.6					
Peak Current - $I_p$	AMPERES	Rated	1.75	1.40					
Torque Sensitivity - $K_t$	OZ.IN./AMP.	±10%	12.0	15.0					
Back EMF Constant - $K_b$	V per RAD/S	±10%	.085	.107					
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	±12.5%	16.0	25.4					
Inductance - $L_m$	mH	±30%	5.0	7.9					

**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**LEADS:**

#28 AWG TYPE "E" TEFLON COATED  
PER MIL W-16878 10" MIN. LENGTH.

**SIZE CONSTANTS****Value      Units**

Peak Torque Rating - $T_p$	55	OZ. IN.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	217	WATTS
Motor Constant - $K_M$	3.74	OZ.IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p, \omega_{NL}$	557	RAD/S
Electrical Time Constant - $\tau_E$	0.21	MS
Static Friction (Max.) - $T_f$	1.8	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.100 OZ. IN. PER RAD/S
	Infinite Impedance - $F_i$	$4.0 \times 10^{-3}$ OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	15	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	7	PERCENT
Ripple Frequency (Fundamental)	31	CYCLES/REV.
Number of Poles	8	
Rotor Inertia - $J_M$	$1.3 \times 10^{-3}$	OZ.IN.S <sup>2</sup>
Motor Weight	4.4	OZ.

**WINDING CONSTANTS****Winding Designation**

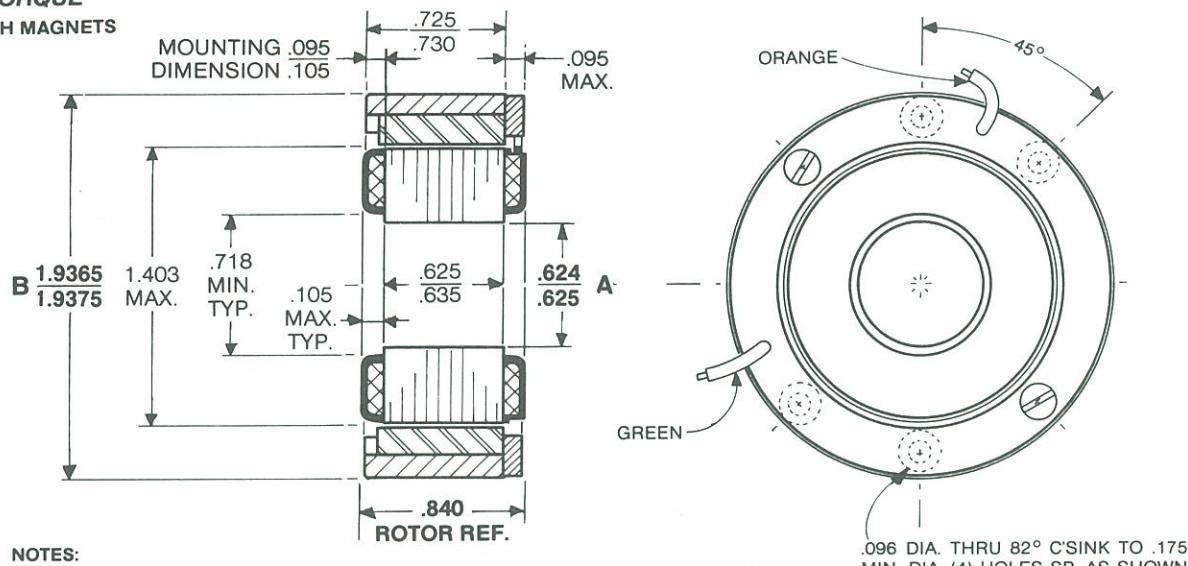
	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	35.4	28.1	22.3	17.7			
Peak Current - $I_p$	AMPERES	Rated	6.11	7.72	9.78	12.2			
Torque Sensitivity - $K_t$	OZ.IN./AMP	$\pm 10\%$	9.00	7.13	5.63	4.50			
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.0636	0.050	0.040	0.0318			
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	5.80	3.64	2.28	1.45			
Inductance - $L_m$	mH	$\pm 30\%$	1.2	0.75	0.47	0.30			

# QT-1404

65 oz. in.

PEAK TORQUE

RARE EARTH MAGNETS



NOTES:

- MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

LEADS:

#28 AWG TYPE "E" TEFLOL COATED PER MIL W-16878, 10" MIN. LENGTH.

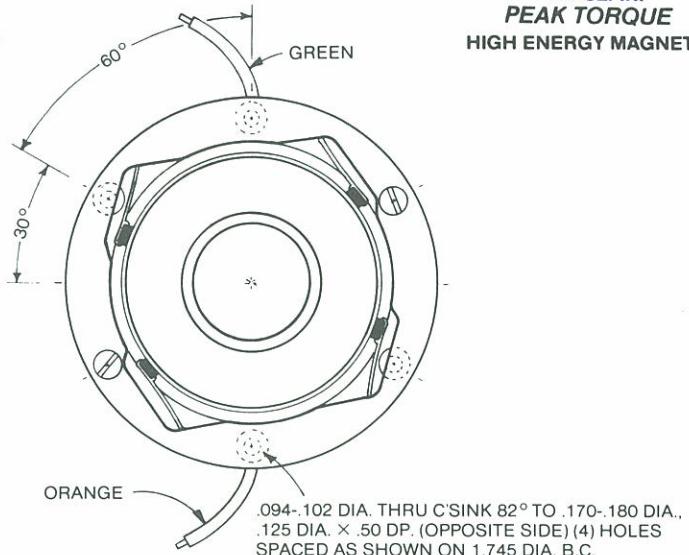
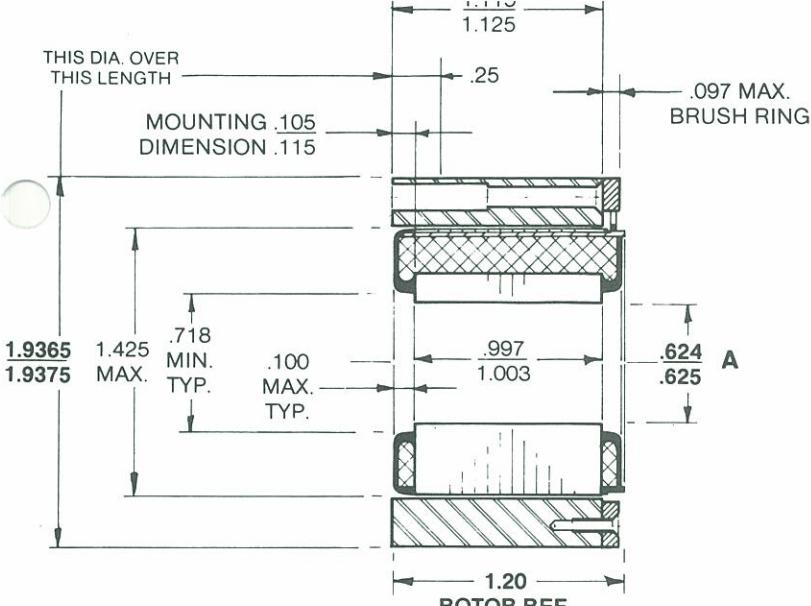
## SIZE CONSTANTS

		Value	Units
Peak Torque Rating - $T_p$		65	OZ. IN.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$		98	WATTS
Motor Constant - $K_m$		6.55	OZ.IN./√WATT
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$		214	RAD/S
Electrical Time Constant - $\tau_e$		0.238	MS
Static Friction (Max.) - $T_f$		3.0	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_\infty$	0.303      0.012	OZ. IN. PER RAD/S      OZ. IN. PER RAD/S
Maximum Winding Temperature		155	°C
Temperature Rise per Watt - TPR		13	°C/WATT
Ripple Torque (Average to Peak) - $T_r$		7	PERCENT
Ripple Frequency (Fundamental)		31	CYCLES/REV.
Number of Poles		8	
Rotor Inertia - $J_m$		$2.55 \times 10^{-3}$	OZ.IN.S <sup>2</sup>
Motor Weight		8.4	OZ.

## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	13.6	17.1	27.2				
Peak Current - $I_p$	AMPERES	Rated	7.20	5.76	3.60				
Torque Sensitivity - $K_t$	OZ.IN./AMP	±10%	9.00	11.3	18.0				
Back EMF Constant - $K_b$	V per RAD/S	±10%	0.064	0.080	0.128				
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	±12.5%	1.89	2.98	7.56				
Inductance - $L_m$	mH	±30%	0.45	0.70	1.8				

**NOTES:**

1. - MOTOR SUPPLIED AS TWO SEPARATE COMPONENTS: STATOR ASSEMBLY WITH ROTOR ASSEMBLY IN PLACE (HELD BY MYLAR SHIMS) AND BRUSH RING ASSEMBLY. REMOVE MYLAR SHIMS AFTER ROTOR AND STATOR ARE SECURELY MOUNTED. **DO NOT REMOVE ROTOR FROM STATOR AT ANY TIME.**
2. - MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002/.004 T.I.R. WHEN MOUNTED.
3. - WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. - TYPICAL BRUSH LIFE  $\times 10^7$  REV.
5. - GOLD PLATED COMMUTATOR.

**SIZE CONSTANTS****Value      Units**

Peak Torque Rating - $T_p$	77.4	OZ. IN.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	112	WATTS
Motor Constant - $K_M$	7.31	OZ.IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p - \omega_{NL}$	205	RAD/S
Electrical Time Constant - $\tau_E$	0.55	MS
Static Friction (Max.) - $T_f$	2.0	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.38 OZ. IN. PER RAD/S
	Infinite Impedance - $F_\infty$	0.01 OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	10	°C/WATT
Ripple Torque (Average to Peak) - $T_R$	5	PERCENT
Ripple Frequency - (Fundamental)	37	CYCLES/REV.
Number of Poles	6	
Rotor Inertia - $J_M$	$2.3 \times 10^{-3}$	OZ.IN.S <sup>2</sup>
Motor Weight	15	OZ.

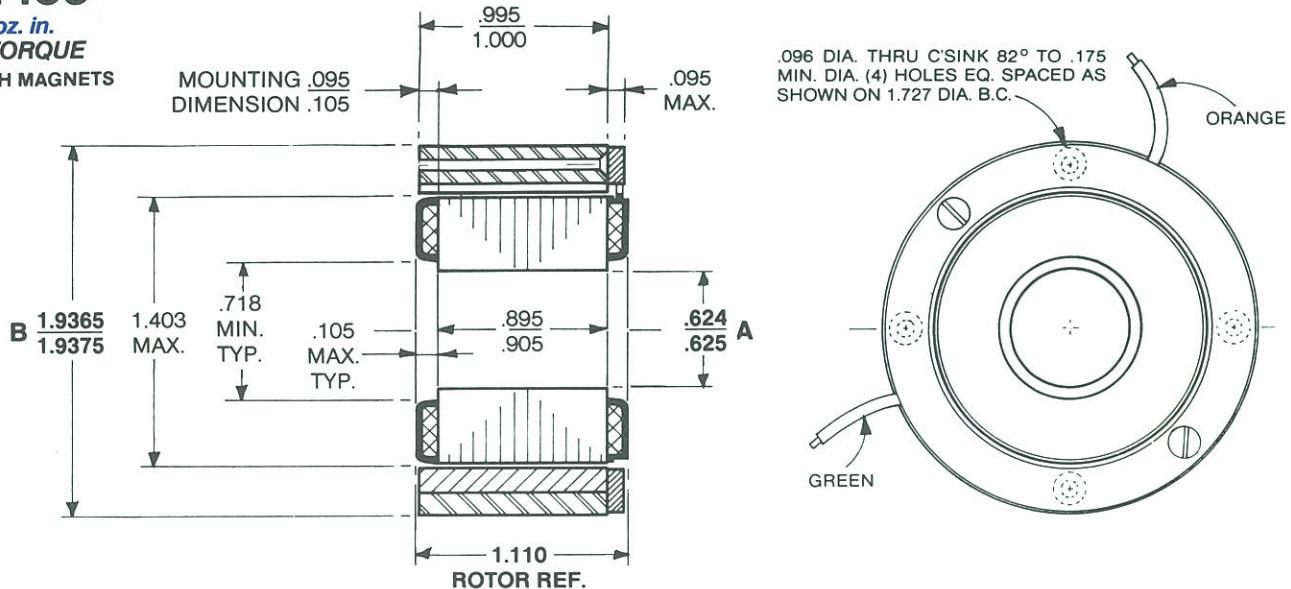
**WINDING CONSTANTS****Winding Designation**

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	24.8						
Peak Current - $I_p$	AMPERES	Rated	4.5						
Torque Sensitivity - $K_T$	OZ.IN./AMP.	$\pm 10\%$	17.2						
Back EMF Constant - $K_B$	V per RAD/S	$\pm 10\%$	0.121						
DC Resistance ( $25^\circ\text{C}$ ) - $R_M$	OHMS	$\pm 12.5\%$	5.5						
Inductance - $L_M$	mH	$\pm 30\%$	3.0						

# QT-1406

**157 oz. in.  
PEAK TORQUE**

RARE EARTH MAGNETS



**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY AND STATOR ASSEMBLY.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**LEADS:**

#28 AWG TYPE "E" TEFLON COATED PER MIL W-16878, 10" MIN. LENGTH.

## SIZE CONSTANTS

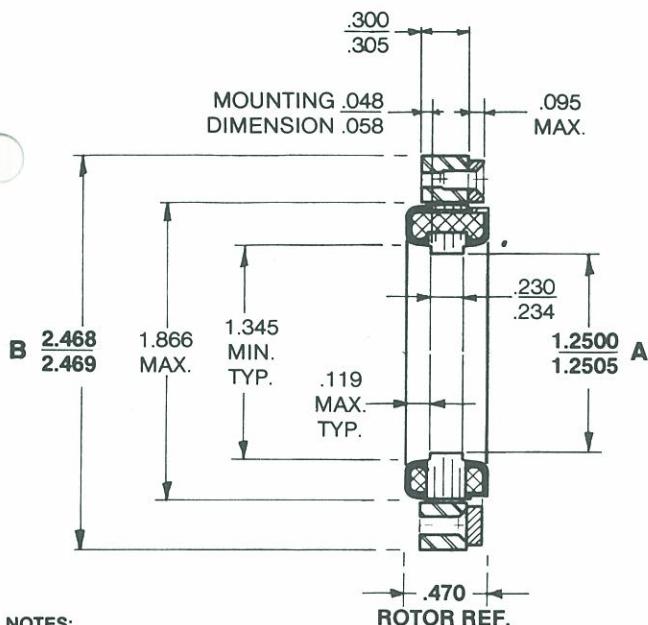
**Value      Units**

Peak Torque Rating - $T_p$	157	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	347	WATTS	
Motor Constant - $K_m$	8.42	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	313	RAD/S	
Electrical Time Constant - $\tau_e$	0.277	MS	
Static Friction (Max.) - $T_f$	3.5	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.501	OZ. IN. PER RAD/S
	Infinite Impedance - $F_i$	0.020	OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	10	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	7	PERCENT	
Ripple Frequency (Fundamental)	31	CYCLES/REV.	
Number of Poles	8		
Rotor Inertia - $J_m$	$3.73 \times 10^{-3}$	OZ.IN.S <sup>2</sup>	
Motor Weight	12	OZ.	

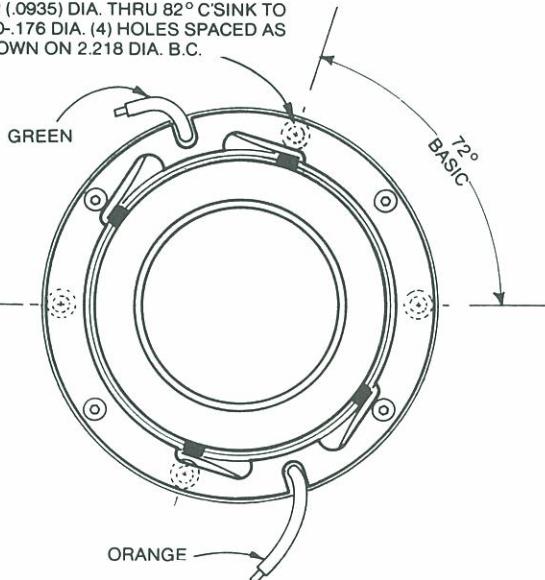
## WINDING CONSTANTS

**Winding Designation**

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	35.4	28.2	44.5				
Peak Current - $I_p$	AMPERES	Rated	9.80	12.3	7.73				
Torque Sensitivity - $K_t$	OZ.IN./AMP	$\pm 10\%$	16.0	12.8	20.3				
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.113	0.090	0.143				
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	3.61	2.29	5.76				
Inductance - $L_m$	mH	$\pm 30\%$	1.0	0.64	1.6				



#42 (.0935) DIA. THRU 82° C'SINK TO .170-.176 DIA. (4) HOLES SPACED AS SHOWN ON 2.218 DIA. B.C.



**NOTES:**

- MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. **CAUTION:** DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**LEADS:**

#28 AWG TYPE 'E' TEFLON COATED PER MIL W-16878 12" MIN. LG.

### SIZE CONSTANTS

**Value      Units**

Peak Torque Rating - $T_p$	24	OZ. IN.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	36	WATTS
Motor Constant - $K_m$	4.0	OZ.IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p - \omega_{NL}$	209	RAD/S
Electrical Time Constant - $\tau_e$	0.22	MS
Static Friction (Max.) - $T_f$	1.9	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.115 OZ. IN. PER RAD/S
	Infinite Impedance - $F_i$	0.003 OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	15	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	4	PERCENT
Ripple Frequency - (Fundamental)	41	CYCLES/REV.
Number of Poles	10	
Rotor Inertia - $J_m$	0.004	OZ.IN.S <sup>2</sup>
Motor Weight	5	OZ.

### WINDING CONSTANTS

### Winding Designation

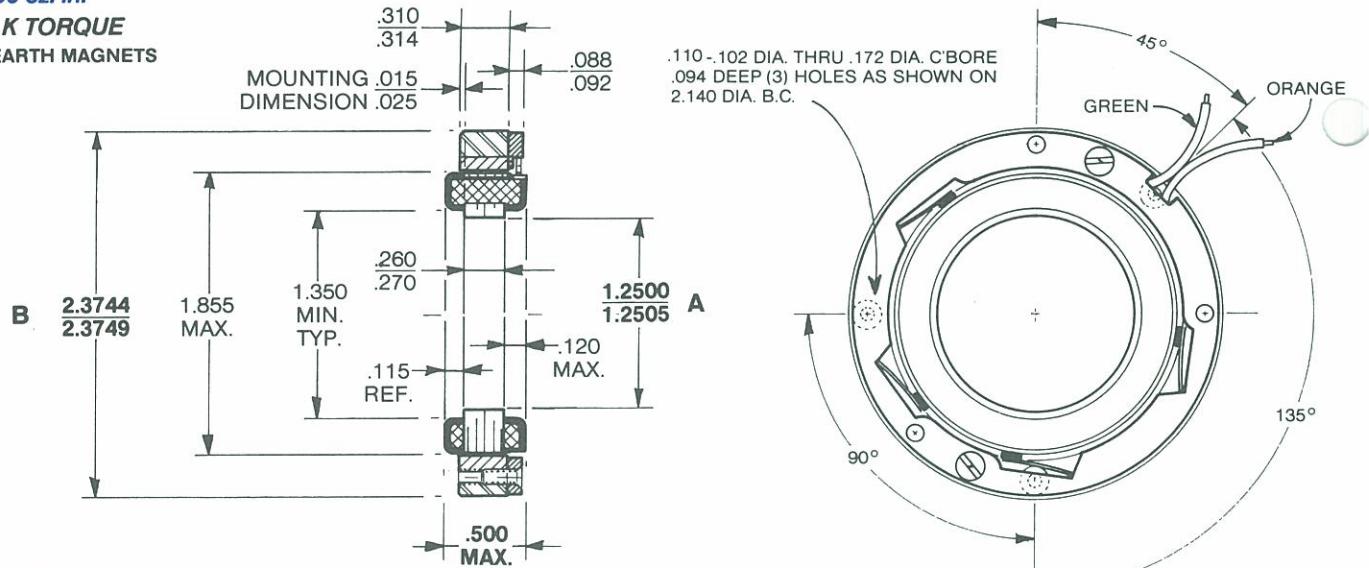
	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	39.6	19.8	12.6	9.80	24.9		
Peak Current - $I_p$	AMPERES	Rated	0.90	1.80	2.79	3.58	1.44		
Torque Sensitivity - $K_t$	OZ.IN./AMP.	$\pm 10\%$	26.8	13.4	8.60	6.70	16.7		
Back EMF Constant - $K_b$	V per RAD/s	$\pm 10\%$	0.189	0.095	0.061	0.047	0.118		
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	44.0	11.0	4.50	2.75	17.3		
Inductance - $L_m$	mH	$\pm 30\%$	9.8	2.4	1.0	0.60	3.8		

# QT-1906

50 oz. in.

PEAK TORQUE

RARE EARTH MAGNETS



**NOTES:**

- MOTOR SHIPPED AS THREE SEPARATE COMPONENTS: ROTOR ASSEMBLY, BRUSH RING ASSEMBLY, AND STATOR ASSEMBLY.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .0025 (.005 T.I.R.) WHEN MOUNTED.
- WITH A POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH END.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
- GOLD PLATED COMMUTATOR.

LEADS:  
#26 AWG TYPE "ET" TEFLON COATED  
PER MIL W-16878, 24" MIN. LG.

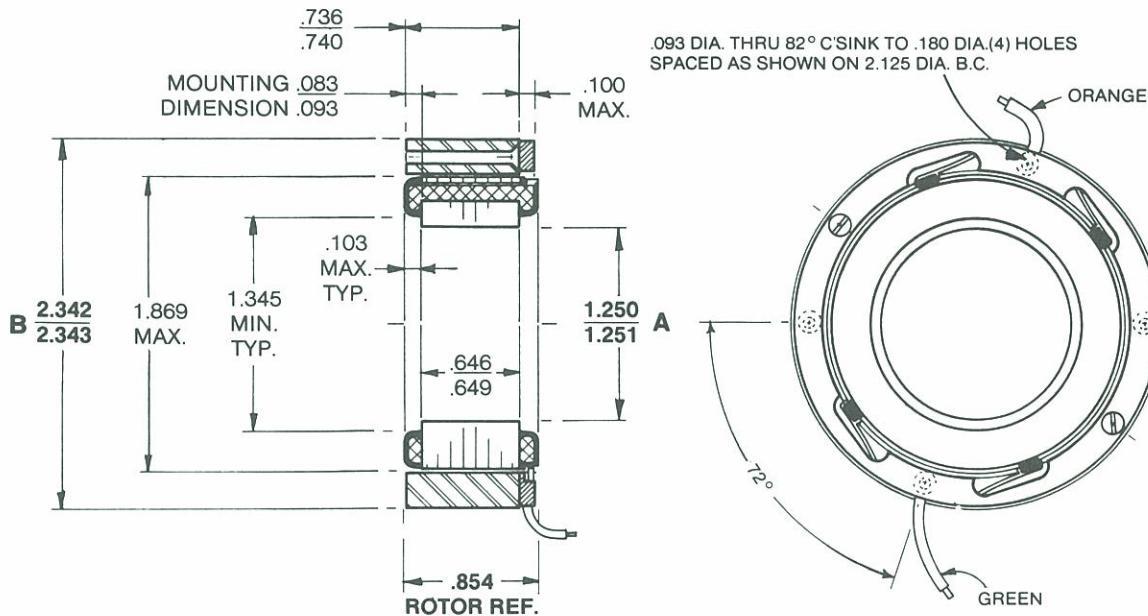
## SIZE CONSTANTS

	Value	Units	
Peak Torque Rating - $T_p$	50	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	115	WATTS	
Motor Constant - $K_m$	4.66	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	326	RAD/S	
Electrical Time Constant - $\tau_e$	0.174	MS	
Static Friction (Max.) - $T_f$	1.0	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.154	OZ. IN. PER RAD/S
	Infinite Impedance - $F_\infty$	0.010	OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	14	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT	
Ripple Frequency - (Fundamental)	37	CYCLES/REV.	
Number of Poles	8		
Rotor Inertia - $J_m$	$3.4 \times 10^{-3}$	OZ.IN.S <sup>2</sup>	
Motor Weight	5	OZ.	

## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	23.0	58.0	36.9				
Peak Current - $I_p$	AMPERES	Rated	5.00	2.00	3.13				
Torque Sensitivity - $K_t$	OZ.IN./AMP.	$\pm 10\%$	10.0	25.0	16.0				
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.0706	0.177	0.113				
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	4.60	29.0	11.8				
Inductance - $L_m$	mH	$\pm 30\%$	0.80	5.0	2.0				



**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. **CAUTION:** DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002(.004 T.I.R) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
5. — GOLD PLATED COMMUTATOR.

**LEADS:**  
#24 AWG TYPE 'E' TEFLON COATED  
6" MIN. LG.

### SIZE CONSTANTS

**Value      Units**

Peak Torque Rating - $T_p$	60	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	60	WATTS	
Motor Constant - $K_m$	7.75	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p - \omega_{NL}$	143	RAD/S	
Electrical Time Constant - $\tau_e$	0.40	MS	
Static Friction (Max.) - $T_f$	2.5	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.424	OZ. IN. PER RAD/S
	Infinite Impedance - $F_\infty$	0.05	OZ. IN. PER RAD/S
Maximum Winding Temperature	105	°C	
Temperature Rise per Watt - $TPR$	10	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT	
Ripple Frequency - (Fundamental)	41	CYCLES/REV.	
Number of Poles	10		
Rotor Inertia - $J_m$	$8.8 \times 10^{-3}$	OZ.IN.S <sup>2</sup>	
Motor Weight	9.5	OZ.	

### WINDING CONSTANTS

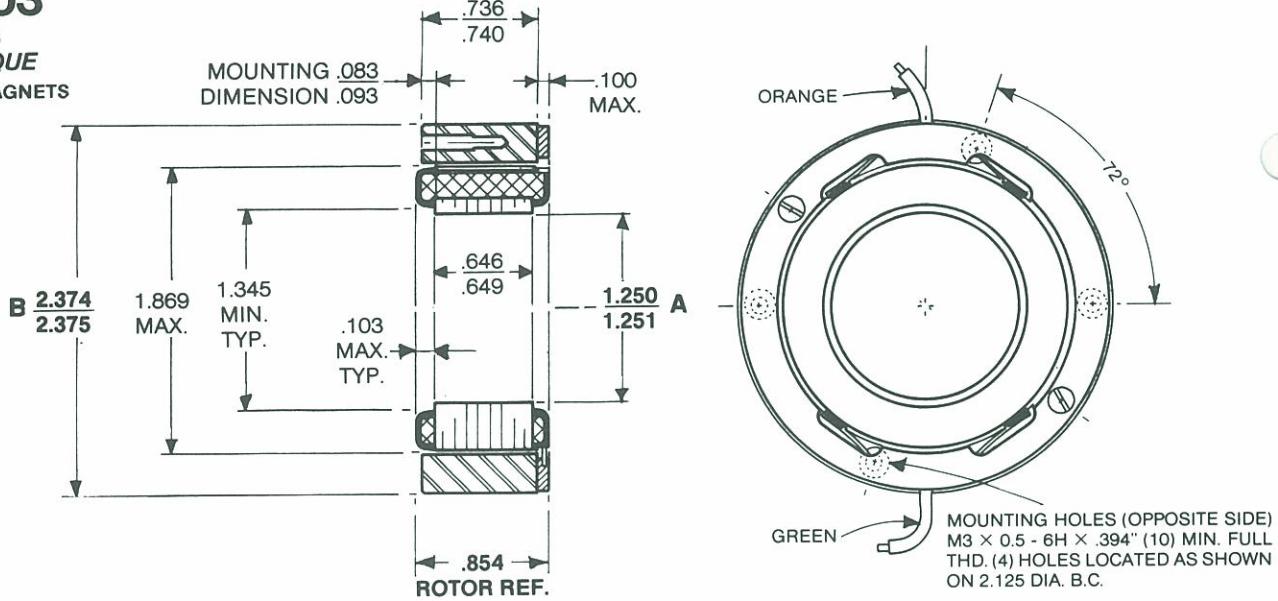
### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	60.0	31.2	19.5	15.2	24.0		
Peak Current - $I_p$	AMPERES	Rated	1.00	2.00	3.20	4.00	2.55		
Torque Sensitivity - $K_t$	OZ.IN./AMP.	$\pm 10\%$	60.0	30.0	19.0	15.0	23.5		
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.424	0.212	0.134	0.106	0.166		
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	60.0	15.6	6.10	3.80	9.40		
Inductance - $L_m$	mH	$\pm 30\%$	24	6.0	2.4	1.5	3.7		

# QT-1903

90 oz. in.

PEAK TORQUE  
RARE EARTH MAGNETS



**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002(.004 T.I.R) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
5. — GOLD PLATED COMMUTATOR.

**LEADS:**  
#24 AWG TYPE "E" TEFLON COATED 6" MIN. LENGTH.

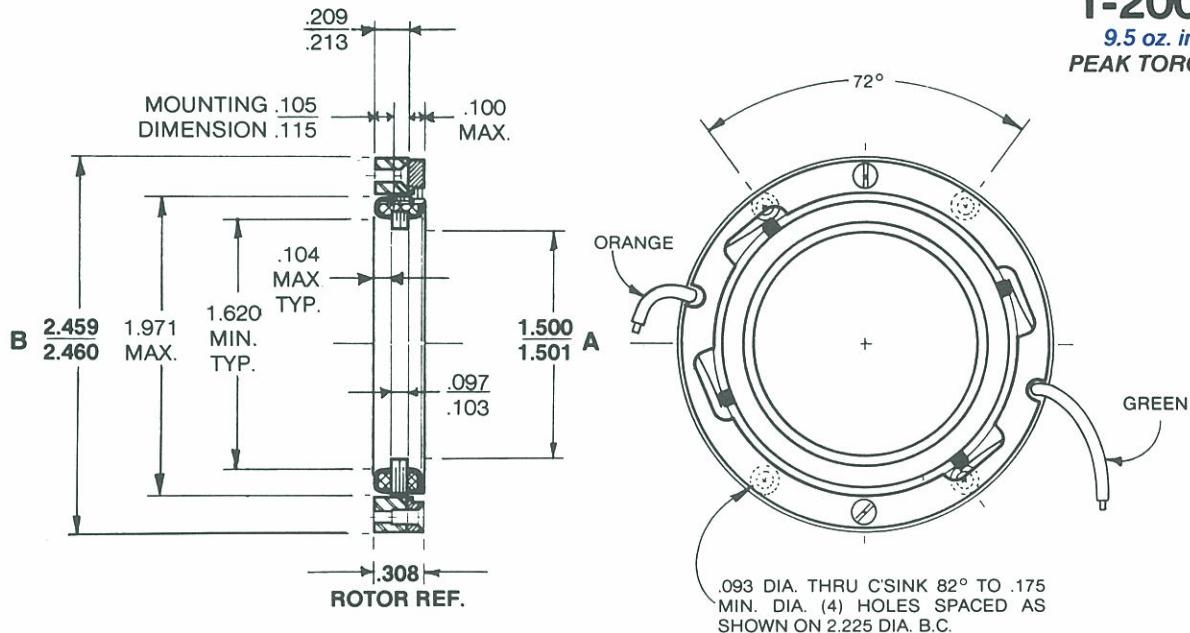
## SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>	
Peak Torque Rating - $T_p$	90	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	107	WATTS	
Motor Constant - $K_M$	8.7	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	167	RAD/S	
Electrical Time Constant - $\tau_E$	0.22	MS	
Static Friction (Max.) - $T_f$	2.8	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.539	OZ. IN. PER RAD/S
	Infinite Impedance - $F_\infty$	0.03	OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - TPR	10	°C/WATT	
Ripple Torque (Average to Peak) - $T_R$	5	PERCENT	
Ripple Frequency (Fundamental)	41	CYCLES/REV.	
Number of Poles	10		
Rotor Inertia - $J_M$	$8.8 \times 10^{-3}$	OZ.IN.S <sup>2</sup>	
Motor Weight	9.5	OZ.	

## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	30.3	24.1	12.1	60.5			
Peak Current - $I_p$	AMPERES	Rated	3.52	4.40	8.82	1.76			
Torque Sensitivity - $K_T$	OZ.IN./AMP.	± 10%	25.6	20.5	10.2	51.2			
Back EMF Constant - $K_B$	V per RAD/S	± 10%	0.181	0.145	0.072	0.362			
DC Resistance ( $25^\circ\text{C}$ ) - $R_M$	OHMS	± 12.5%	8.60	5.5	1.37	34.4			
Inductance - $L_M$	mH	± 30%	1.9	1.2	0.3	7.6			



**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. **CAUTION:** DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

LEADS:  
#28 AWG TYPE 'E' TEFLON COATED  
12" MIN. LG.

### SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>	
Peak Torque Rating - $T_p$	9.5	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	41	WATTS	
Motor Constant - $K_m$	1.48	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p - \omega_{NL}$	610	RAD/S	
Electrical Time Constant - $\tau_e$	0.10	MS	
Static Friction (Max.) - $T_f$	0.40	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	0.0156 0.005	OZ. IN. PER RAD/S OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - TPR	20	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT	
Ripple Frequency - (Fundamental)	46	CYCLES/REV.	
Number of Poles	10		
Rotor Inertia - $J_m$	$1.6 \times 10^{-3}$	OZ.IN.S <sup>2</sup>	
Motor Weight	2.5	OZ.	

### WINDING CONSTANTS

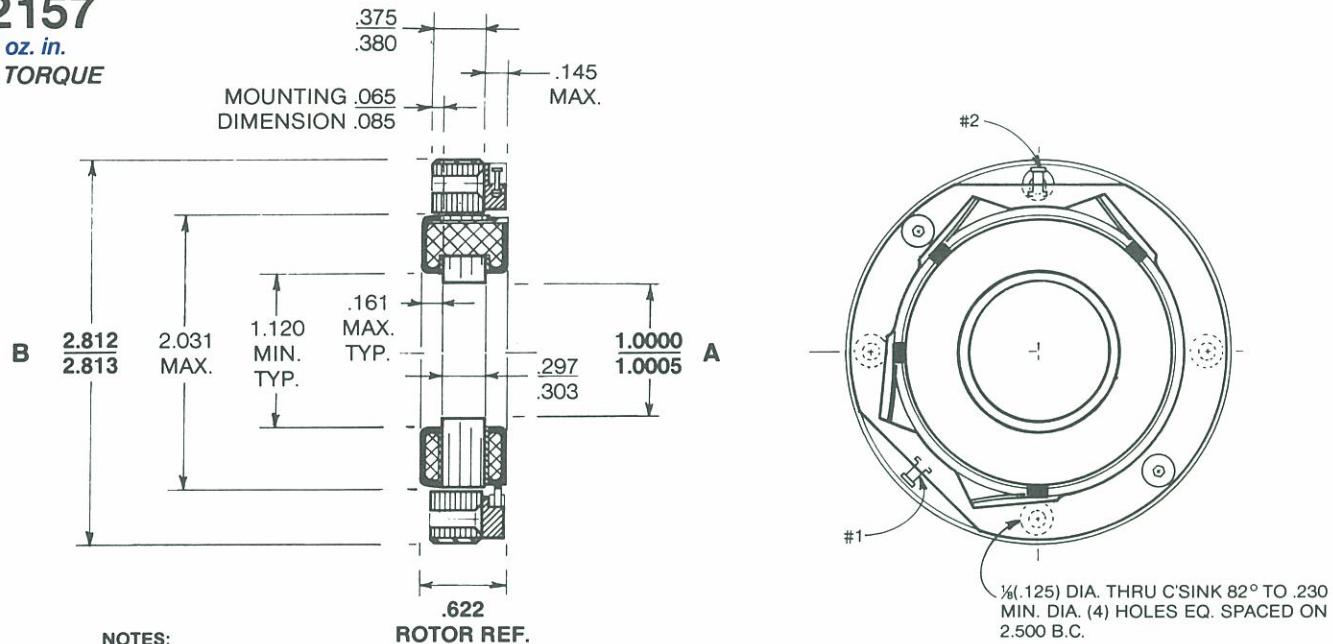
### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	32.9	26.4					
Peak Current - $I_p$	AMPERES	Rated	1.25	1.60					
Torque Sensitivity - $K_t$	OZ.IN./AMP.	± 10%	7.6	5.9					
Back EMF Constant - $K_b$	V per RAD/S	± 10%	0.054	0.042					
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	± 12.5%	26.3	16.5					
Inductance - $L_m$	mH	± 30%	2.7	1.6					

# T-2157

35 oz. in.

PEAK TORQUE



NOTES:

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. CAUTION: DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002(.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO TERMINAL #1, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

## SIZE CONSTANTS

## Value

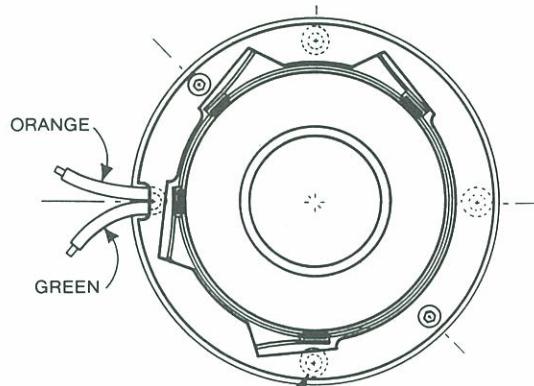
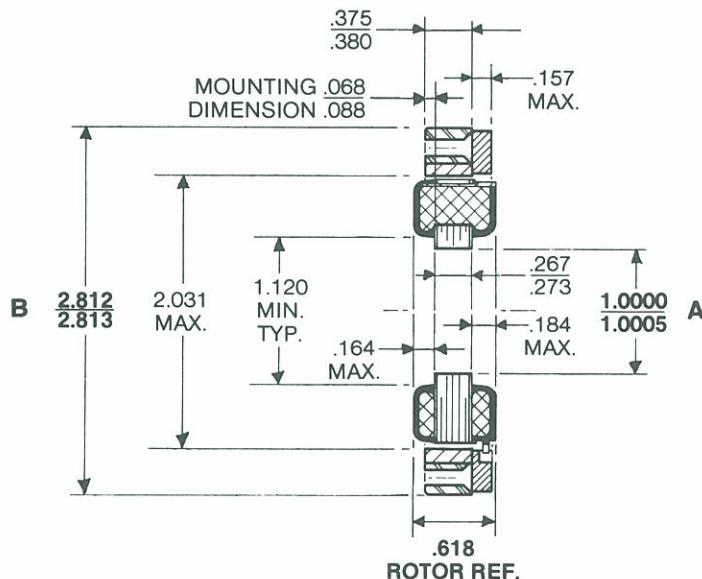
## Units

Peak Torque Rating - $T_p$	35	OZ.IN.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	41	WATTS
Motor Constant - $K_m$	5.45	OZ.IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p - \omega_{NL}$	160	RAD/S
Electrical Time Constant - $\tau_e$	0.60	MS
Static Friction (Max.) - $T_f$	1.1	OZ.IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.21 OZ.IN. PER RAD/S
	Infinite Impedance - $F_i$	$3.6 \times 10^{-2}$ OZ.IN. PER RAD/S
Maximum Winding Temperature	105	°C
Temperature Rise per Watt - $TPR$	9.0	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	6	PERCENT
Ripple Frequency - (Fundamental)	33	CYCLES/REV.
Number of Poles	8	
Rotor Inertia - $J_m$	$6.2 \times 10^{-3}$	OZ.IN.S <sup>2</sup>
Motor Weight	8.8	OZ.

## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	6.4	10.0	12.1	18.9	23.8	29.8	61.6
Peak Current - $I_p$	AMPERES	Rated	6.4	4.0	3.2	2.0	1.6	1.3	0.65
Torque Sensitivity - $K_t$	OZ.IN./AMP.	$\pm 10\%$	5.5	8.8	11.0	17.5	22.0	27.5	54.0
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.04	0.06	0.08	0.12	0.16	0.19	0.38
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	1.0	2.5	3.8	9.5	15.0	23.4	95
Inductance - $L_m$	mH	$\pm 30\%$	0.6	1.5	2.4	6.0	10	15	60



(.125) DIA. THRU C'SINK 82° TO .230  
MIN. DIA. (4) HOLES EQ. SPACED ON  
2.500 DIA. B.C.

#### NOTES:

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10' REV.

#### LEADS:

#24 AWG TYPE "E" TEFLOX COATED  
PER MIL W-16878, 18" MIN. LENGTH.

## SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>
Peak Torque Rating - $T_p$	48	OZ. IN.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	39	WATTS
Motor Constant - $K_m$	7.7	OZ.IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	114	RAD/S
Electrical Time Constant - $\tau_E$	0.50	MS
Static Friction (Max.) - $T_f$	1.8	OZ. IN.
Viscous Damping Coefficients	0.42	OZ. IN. PER RAD/S
Zero Impedance - $F_0$	0.04	OZ. IN. PER RAD/S
Infinite Impedance - $F_i$		
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	9	°C/WATT
Ripple Torque (Average to Peak) - $T_R$	6	PERCENT
Ripple Frequency (Fundamental)	33	CYCLES/REV.
Number of Poles	8	
Rotor Inertia - $J_m$	0.006	OZ.IN.S <sup>2</sup>
Motor Weight	9.2	OZ.

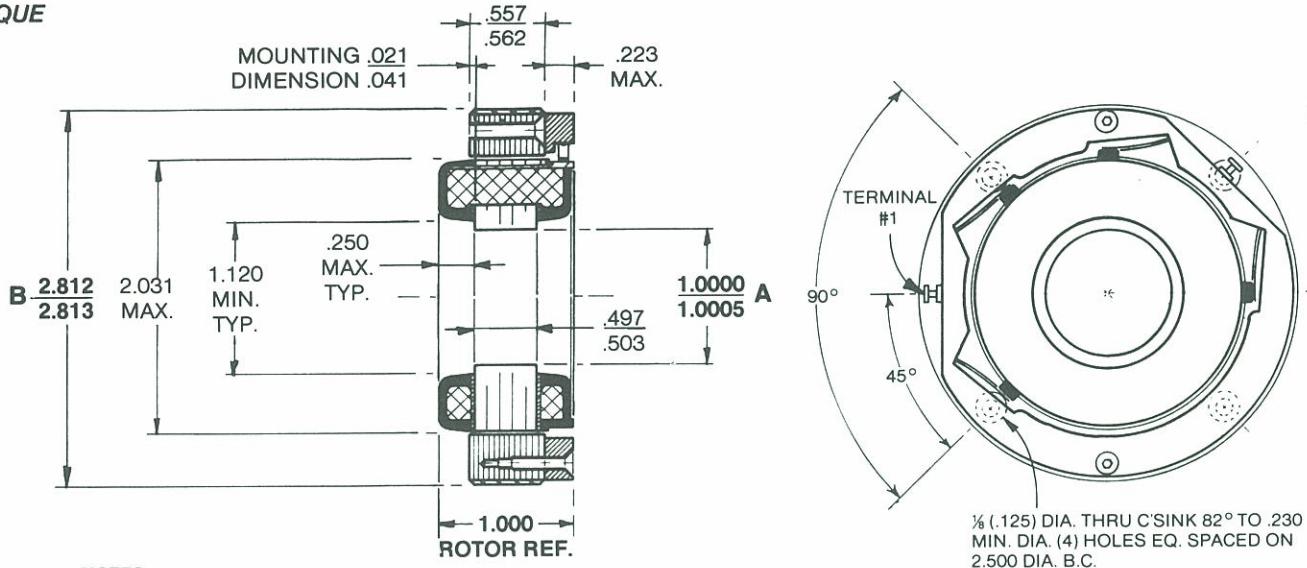
## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	17.6	22.3	56.0				
Peak Current - $I_p$	AMPERES	Rated	2.20	1.74	0.695				
Torque Sensitivity - $K_t$	OZ.IN./AMP	±10%	21.8	27.6	69.1				
Back EMF Constant - $K_b$	V per RAD/S	±10%	0.154	0.195	0.488				
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	±12.5%	8.00	12.8	80.6				
Inductance - $L_m$	mH	±30%	4.0	6.4	40				

# T-2170

60 oz. in.  
PEAK TORQUE



**NOTES:**

- MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. CAUTION: DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002-.004T.I.R. WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO TERMINAL #1 ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

## SIZE CONSTANTS

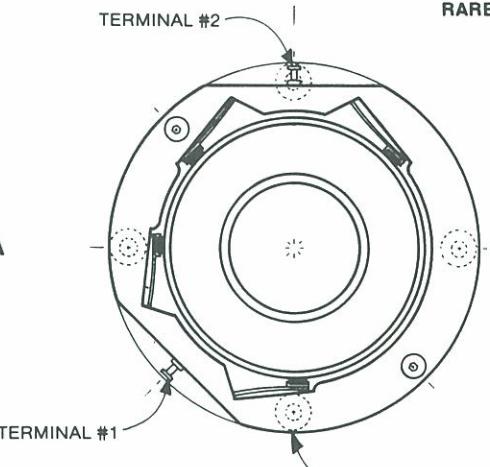
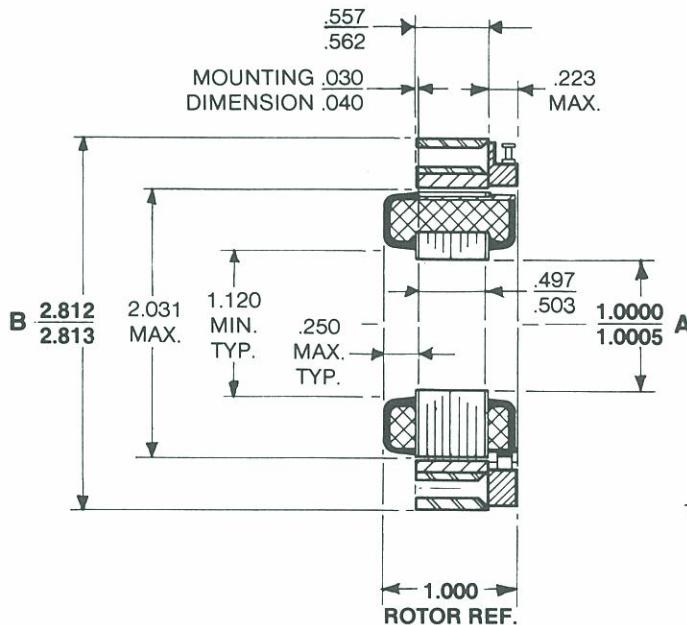
### Value      Units

Peak Torque Rating - $T_p$	60	OZ. IN.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	33.8	WATTS
Motor Constant - $K_m$	10.5	OZ.IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	79	RAD/S
Electrical Time Constant - $\tau_e$	0.91	MS
Static Friction (Max.) - $T_f$	1.5	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_\infty$	0.76      0.04
Maximum Winding Temperature	105	°C
Temperature Rise per Watt - TPR	7.8	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	6	PERCENT
Ripple Frequency - (Fundamental)	33	CYCLES/REV.
Number of Poles	8	
Rotor Inertia - $J_m$	$1.1 \times 10^{-2}$	OZ.IN.S <sup>2</sup>
Motor Weight	13.8	oz.

## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	10.6	16.5	20.3	25.6	49.9	59.0	80.0
Peak Current - $I_p$	AMPERES	Rated	3.2	2.0	1.6	1.3	0.61	0.49	0.42
Torque Sensitivity - $K_t$	OZ.IN./AMP.	$\pm 10\%$	18.9	30.5	38.4	46.8	98.0	123	144
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.13	0.22	0.27	0.33	0.69	0.87	1.0
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	3.3	8.4	13.0	20.0	81.5	121	191
Inductance - $L_m$	mH	$\pm 30\%$	3.0	8.0	12	19	80	120	170

**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO TERMINAL #1, WITH RESPECT TO TERMINAL #2, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

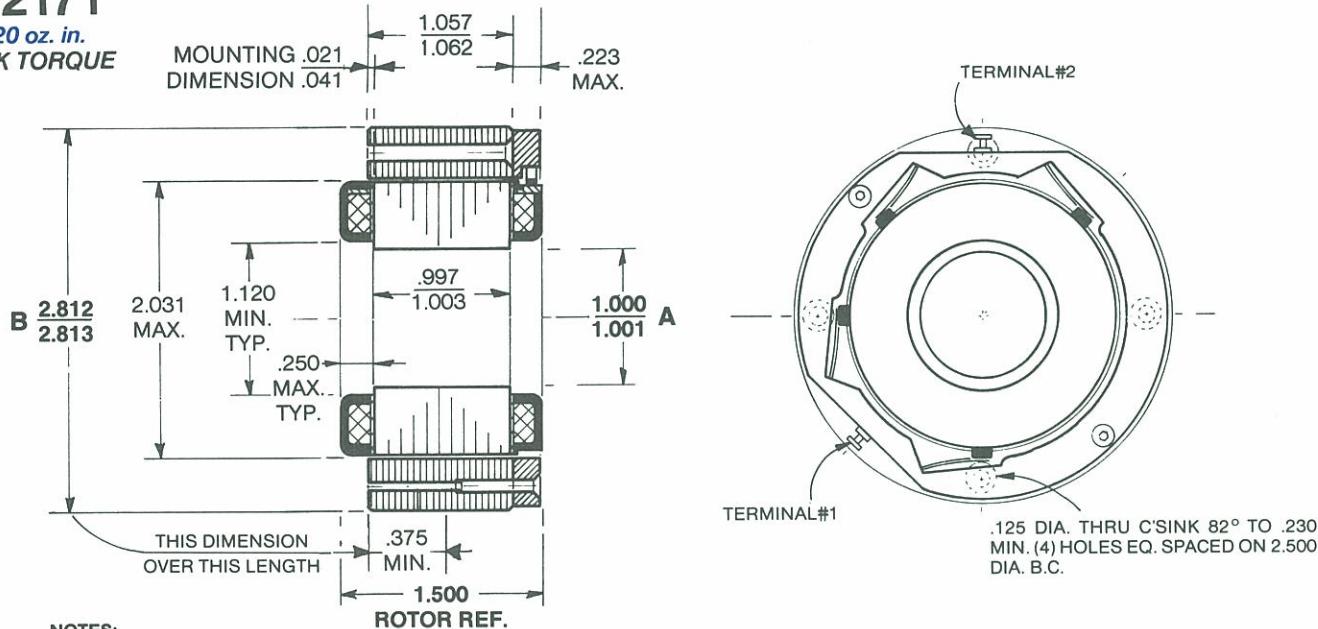
**SIZE CONSTANTS**

	<b>Value</b>	<b>Units</b>	
Peak Torque Rating - $T_p$	75	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	35	WATTS	
Motor Constant - $K_m$	12.8	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p - \omega_{NL}$	65	RAD/S	
Electrical Time Constant - $\tau_e$	0.77	MS	
Static Friction (Max.) - $T_f$	3.0	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	1.16	OZ. IN. PER RAD/S
	Infinite Impedance - $F_i$	0.04	OZ. IN. PER RAD/S
Maximum Winding Temperature	105	°C	
Temperature Rise per Watt - TPR	7.8	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	6	PERCENT	
Ripple Frequency (Fundamental)	33	CYCLES/REV.	
Number of Poles	8		
Rotor Inertia - $J_m$	$1.1 \times 10^{-2}$	OZ.IN.S <sup>2</sup>	
Motor Weight	13.5	OZ.	

**WINDING CONSTANTS****Winding Designation**

	<b>UNITS</b>	<b>TOLERANCES</b>	<b>A</b>	<b>B</b>	<b>C</b>	<b>D</b>	<b>E</b>	<b>F</b>	<b>G</b>
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	<b>VOLTS</b>	Nom.	21.2	33.0	26.1				
Peak Current - $I_p$	<b>AMPERES</b>	Rated	1.63	1.03	1.22				
Torque Sensitivity - $K_t$	<b>OZ.IN./AMP</b>	$\pm 10\%$	46.1	72.7	61.2				
Back EMF Constant - $K_b$	<b>V per RAD/S</b>	$\pm 10\%$	0.326	0.513	0.432				
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	<b>OHMS</b>	$\pm 12.5\%$	13.0	32.0	21.4				
Inductance - $L_m$	<b>mH</b>	$\pm 30\%$	10	25	17.6				

**T-2171**  
120 oz. in.  
PEAK TORQUE



**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR WITH (2) KEEPERs. CAUTION: DO NOT REMOVE KEEPERs UNTIL ROTOR IS FULLY IN PLACE.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .003(.006 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO TERMINAL #1, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REVs.

**SIZE CONSTANTS**

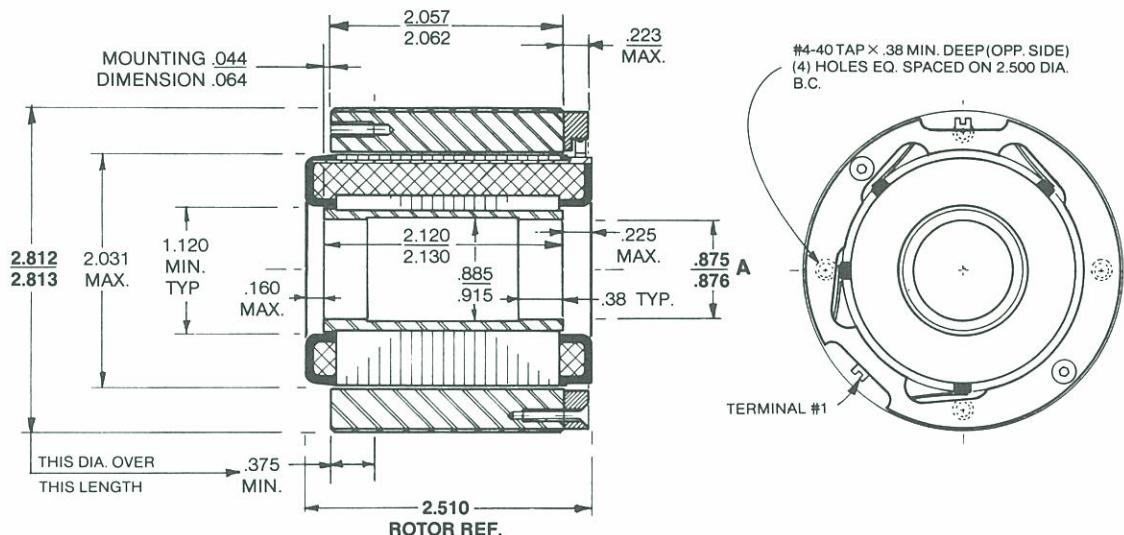
**Value      Units**

Peak Torque Rating - $T_p$	120	OZ. IN.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	50	WATTS
Motor Constant - $K_m$	17.0	OZ.IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p - \omega_{NL}$	57	RAD/S
Electrical Time Constant - $\tau_e$	1.5	MS
Static Friction (Max.) - $T_f$	3.0	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_1$	2.2      0.08
Maximum Winding Temperature	105	°C
Temperature Rise per Watt - $TPR$	5.4	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	6	PERCENT
Ripple Frequency - (Fundamental)	33	CYCLES/REV.
Number of Poles	8	
Rotor Inertia - $J_m$	0.019	OZ.IN.S <sup>2</sup>
Motor Weight	25	OZ.

**WINDING CONSTANTS**

**Winding Designation**

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	7.5	11.3	18.1	22.9	28.9	35.1	57.4
Peak Current - $I_p$	AMPERES	Rated	6.8	4.2	2.7	2.1	1.7	1.4	0.84
Torque Sensitivity - $K_t$	OZ.IN./AMP.	± 10%	17.7	28.6	44.9	57.2	70.8	88.4	143
Back EMF Constant - $K_b$	V per RAD/S	± 10%	0.125	0.202	0.317	0.404	0.50	0.624	1.00
DC Resistance (25°C) - $R_m$	OHMS	± 12.5%	1.1	2.7	6.7	10.9	17.0	25.1	68.4
Inductance - $L_m$	mH	± 30%	1.6	4.0	10.0	17.0	26.0	40.0	100



1. — MOTOR TO BE SHIPPED AS TWO SEPARATE COMPONENTS: STATOR ASSEMBLY WITH ROTOR IN PLACE AND BRUSH RING ASSEMBLY. REMOVE MYLAR SHIMS FROM AIR GAP AFTER ROTOR AND STATOR ARE SECURELY MOUNTED. CAUTION: DO NOT REMOVE ROTOR FROM STATOR AT ANY TIME.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .003(.006 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO TERMINAL #1 ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

## SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>
Peak Torque Rating - $T_p$	1.25	LB. FT.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	75	WATTS
Motor Constant - $K_m$	0.15	LB.FT./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p - \omega_{NL}$	42.1	RAD/S
Electrical Time Constant - $\tau_e$	1.5	MS
Static Friction (Max.) - $T_f$	0.040	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	0.03      0.0004
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	9.0	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	6	PERCENT
Ripple Frequency - (Fundamental)	33	CYCLES/REV.
Number of Poles	8	
Rotor Inertia - $J_m$	$1.4 \times 10^{-4}$	LB.FT.S <sup>2</sup>
Motor Weight	3.0	LB.

## WINDING CONSTANTS

### Winding Designation

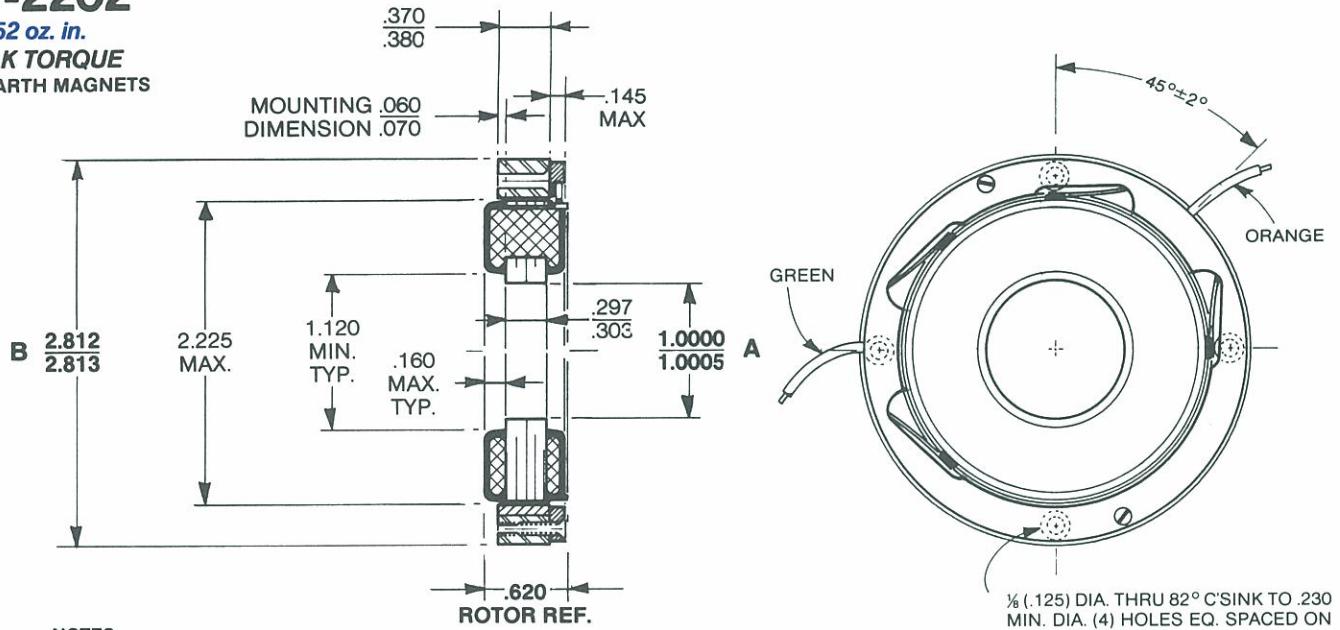
	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	14.2	17.9	27.9	88.0	44.2		
Peak Current - $I_p$	AMPERES	Rated	5.25	4.17	2.66	0.830	1.66		
Torque Sensitivity - $K_t$	LB.FT./AMP.	$\pm 10\%$	0.242	0.30	0.470	1.50	0.755		
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.327	0.41	0.637	2.03	1.02		
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	2.7	4.2	10.5	106	26.6		
Inductance - $L_m$	mH	$\pm 30\%$	4.1	6.3	16	160	41		

# QT-2202

52 oz. in.

PEAK TORQUE

RARE EARTH MAGNETS



**NOTES:**

1. — MOTOR TO BE SUPPLIED AS THREE SEPARATE COMPONENTS: ROTOR ASSEMBLY, STATOR ASSEMBLY, AND BRUSH RING ASSEMBLY.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002(.004 T.I.R.) WHEN MOUNTED.
3. — WITH A POSITIVE CURRENT APPLIED TO GREEN LEAD WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**LEADS:**  
#22 AWG TYPE "EE" TEFLOM COATED  
PER MIL W-16878, 12" MIN. LG.

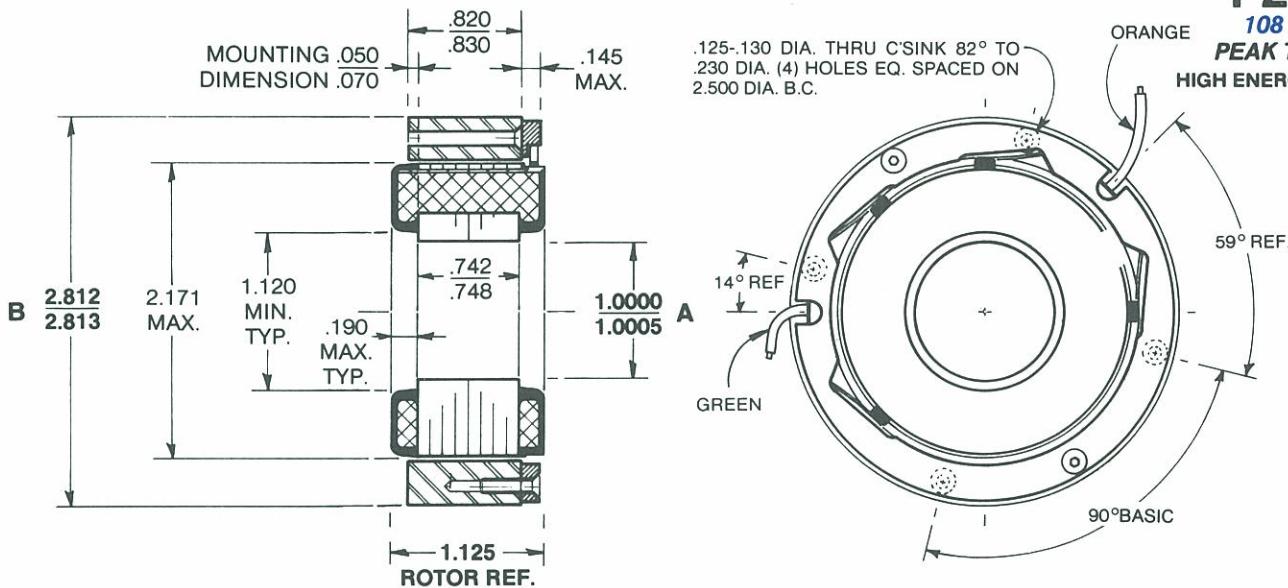
## SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>	
Peak Torque Rating - $T_p$	52	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	40	WATTS	
Motor Constant - $K_m$	8.28	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	107	RAD/S	
Electrical Time Constant - $\tau_e$	0.844	MS	
Static Friction (Max.) - $T_f$	2.5	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	0.484 0.024	OZ. IN. PER RAD/S OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	9	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	6	PERCENT	
Ripple Frequency - (Fundamental)	33	CYCLES/REV	
Number of Poles	8		
Rotor Inertia - $J_m$	$8.5 \times 10^{-3}$	OZ.IN.S <sup>2</sup>	
Motor Weight	11	OZ.	

## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	24.6						
Peak Current - $I_p$	AMPERES	Rated	1.60						
Torque Sensitivity - $K_t$	OZ.IN./AMP	$\pm 10\%$	32.5						
Back EMF Constant - $K_b$	V per RAD/s	$\pm 10\%$	0.230						
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	15.4						
Inductance - $L_m$	mH	$\pm 30\%$	13						



**NOTES:**

- MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. **CAUTION:** DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002(.004 T.I.R.) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REVS.

**LEADS:**  
#22 AWG TYPE "EE" TEFILON COATED PER MIL W-16878, 12" MIN. LG.

### SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>	
Peak Torque Rating - $T_p$	108	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	41	WATTS	
Motor Constant - $K_m$	16.9	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	54	RAD/S	
Electrical Time Constant - $\tau_e$	1.74	MS	
Static Friction (Max.) - $T_f$	3.3	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	2.0	OZ. IN. PER RAD/S
	Infinite Impedance - $F_i$	0.042	OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	6	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	4.5	PERCENT	
Ripple Frequency - (Fundamental)	41	CYCLES/REV.	
Number of Poles	8		
Rotor Inertia - $J_m$	0.017	OZ.IN.S <sup>2</sup>	
Motor Weight	20	OZ.	

### WINDING CONSTANTS

### Winding Designation

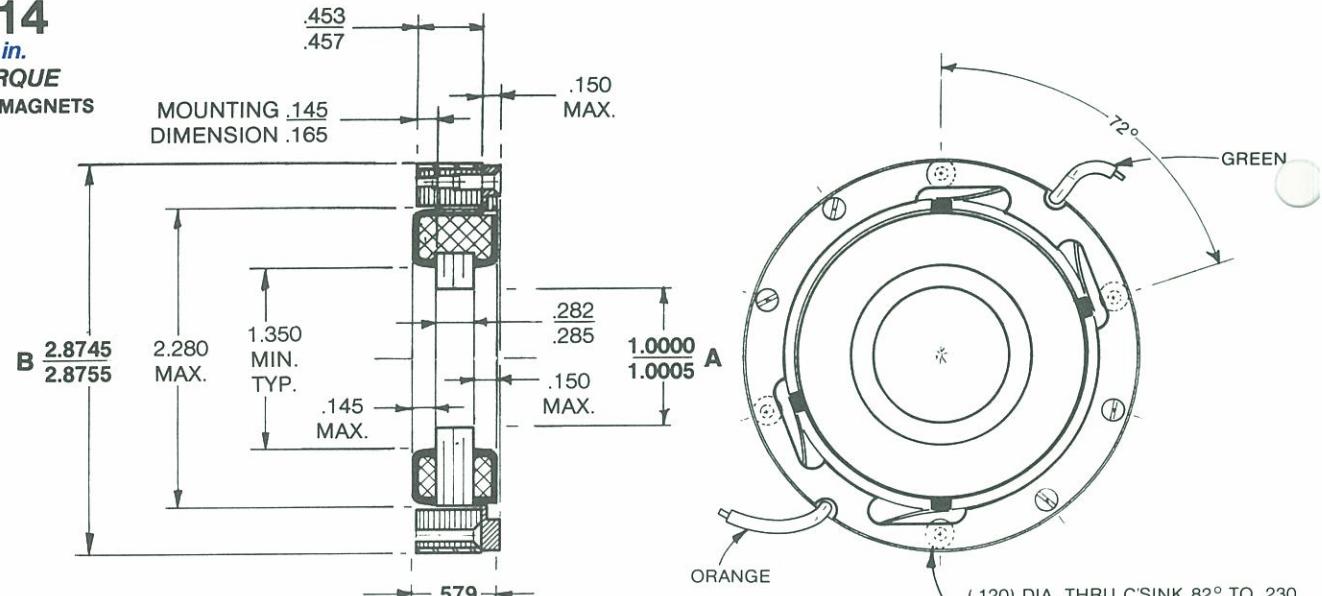
	<b>UNITS</b>	<b>TOLERANCES</b>	<b>A</b>	<b>B</b>	<b>C</b>	<b>D</b>	<b>E</b>	<b>F</b>	<b>G</b>
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	<b>VOLTS</b>	Nom.	18.9	12.0	24.1	48.1			
Peak Current - $I_p$	<b>AMPERES</b>	Rated	2.2	3.54	1.77	0.885			
Torque Sensitivity - $K_t$	<b>OZ.IN./AMP.</b>	$\pm 10\%$	49	30.5	61.0	122			
Back EMF Constant - $K_b$	<b>V per RAD/S</b>	$\pm 10\%$	0.35	0.215	0.431	0.861			
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	<b>OHMS</b>	$\pm 12.5\%$	8.6	3.40	13.60	54.4			
Inductance - $L_m$	<b>mH</b>	$\pm 30\%$	15	5.8	23	93			

# T-2314

54 oz. in.

**PEAK TORQUE**

HIGH ENERGY MAGNETS



**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. **CAUTION:** DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002(.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
5. — GOLD PLATED COMMUTATOR.

**LEADS:**

#26 AWG TYPE 'EE' TEFLON COATED PER MIL W-16878, 12" MIN. LG.

## SIZE CONSTANTS

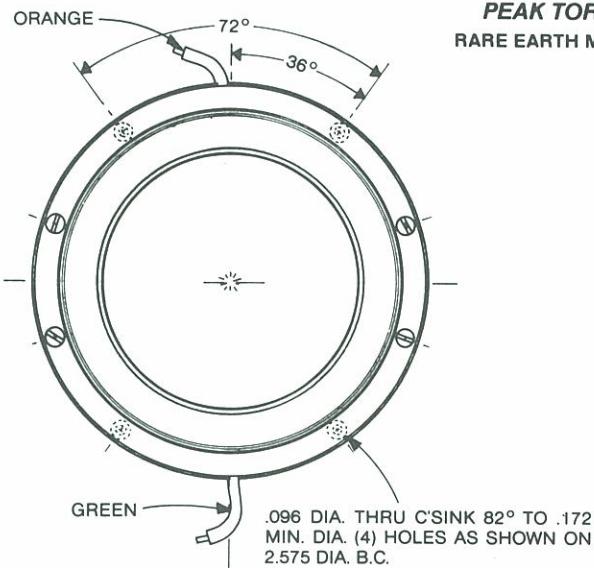
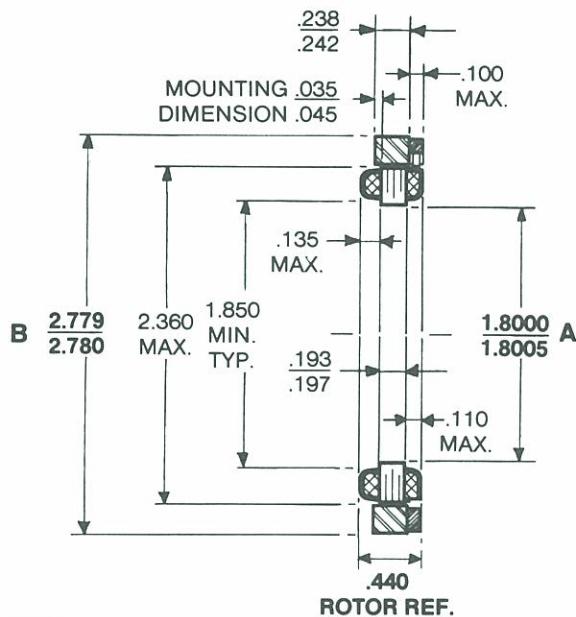
### Value      Units

Peak Torque Rating - $T_p$	54	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	57.5	WATTS	
Motor Constant - $K_m$	7.1	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	150	RAD/S	
Electrical Time Constant - $\tau_e$	0.66	MS	
Static Friction (Max.) - $T_f$	1.7	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.36	OZ. IN. PER RAD/S
	Infinite Impedance - $F_\infty$	0.013	OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	8	°C/WATT	
Ripple Torque (Average to Peak) - $T_R$	6	PERCENT	
Ripple Frequency - (Fundamental)	41	CYCLES/REV.	
Number of Poles	10		
Rotor Inertia - $J_m$	0.009	OZ.IN.S <sup>2</sup>	
Motor Weight	11	OZ.	

## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	40.9	25.4	20.4	50.6			
Peak Current - $I_p$	AMPERES	Rated	1.41	2.25	2.86	1.12			
Torque Sensitivity - $K_t$	OZ.IN./AMP.	± 10%	38.4	24.1	18.9	48.2			
Back EMF Constant - $K_b$	V per RAD/S	± 10%	0.271	0.170	0.133	0.340			
DC Resistance (25°C) - $R_m$	OHMS	± 12.5%	29.0	11.3	7.15	45.2			
Inductance - $L_m$	mH	± 30%	19	7.5	4.6	30			

**NOTES:**

- MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002(.004 T.I.R) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
- TYPICAL BRUSH LIFE  $\times 10^7$  REV.
- GOLD PLATED COMMUTATOR.

**LEADS:**#24 AWG TYPE "E" PER MIL W-16878/7  
18" MIN. LENGTH.**SIZE CONSTANTS****Value      Units**

Peak Torque Rating - $T_p$	30.0	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	53.5	WATTS	
Motor Constant - $K_m$	4.1	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	250	RAD/S	
Electrical Time Constant - $\tau_e$	0.13	MS	
Static Friction (Max.) - $T_f$	1.8	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.12	OZ. IN. PER RAD/S
	Infinite Impedance - $F_i$	0.008	OZ. IN. PER RAD/S
Maximum Winding Temperature	155	$^\circ\text{C}$	
Temperature Rise per Watt - $TPR$	10	$^\circ\text{C}/\text{WATT}$	
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT	
Ripple Frequency (Fundamental)	46	CYCLES/REV.	
Number of Poles	10		
Rotor Inertia - $J_m$	$5.4 \times 10^{-3}$	OZ.IN.S <sup>2</sup>	
Motor Weight	3.85	OZ.	

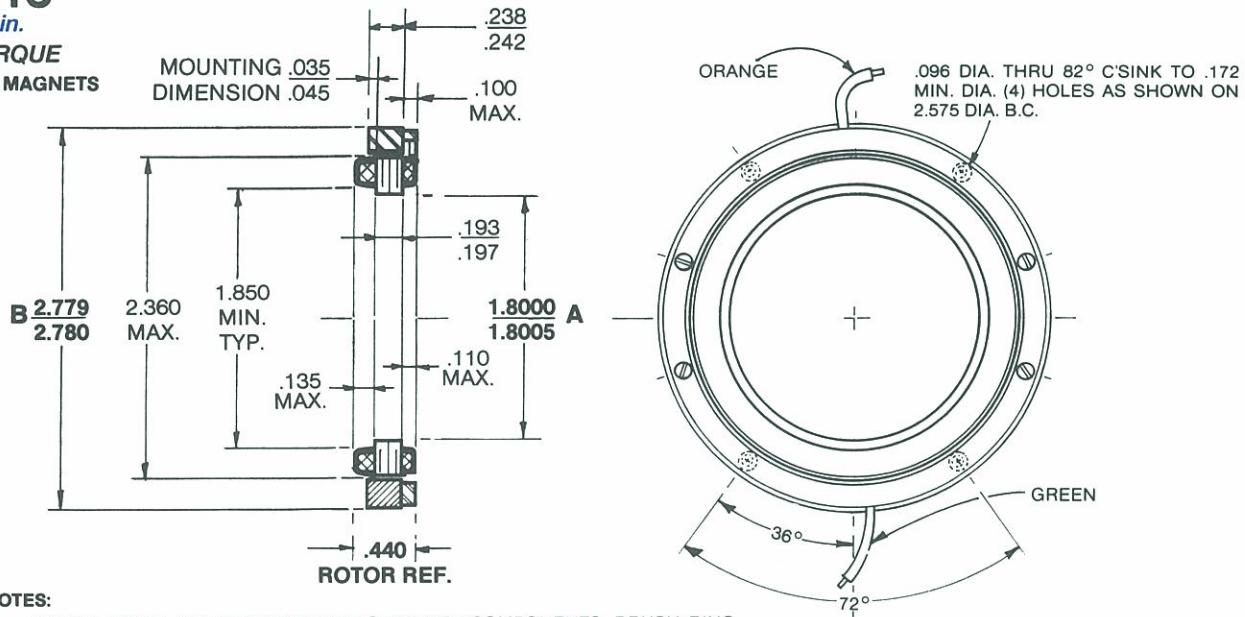
**WINDING CONSTANTS****Winding Designation**

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	34.1	27.4	15.2				
Peak Current - $I_p$	AMPERES	Rated	1.57	1.97	3.49				
Torque Sensitivity - $K_t$	OZ.IN./AMP	$\pm 10\%$	19.1	15.2	8.60				
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.135	0.107	0.0607				
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	21.7	13.9	4.35				
Inductance - $L_m$	mH	$\pm 30\%$	2.9	2.0	0.59				

# T-2413

30 oz. in.

**PEAK TORQUE**  
HIGH ENERGY MAGNETS



**NOTES:**

- MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. **CAUTION:** DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002/.004 T.I.R. WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
- GOLD PLATED COMMUTATOR.

**LEADS:**

#24 AWG TYPE 'E' TEFLON COATED  
18" MIN. LG.

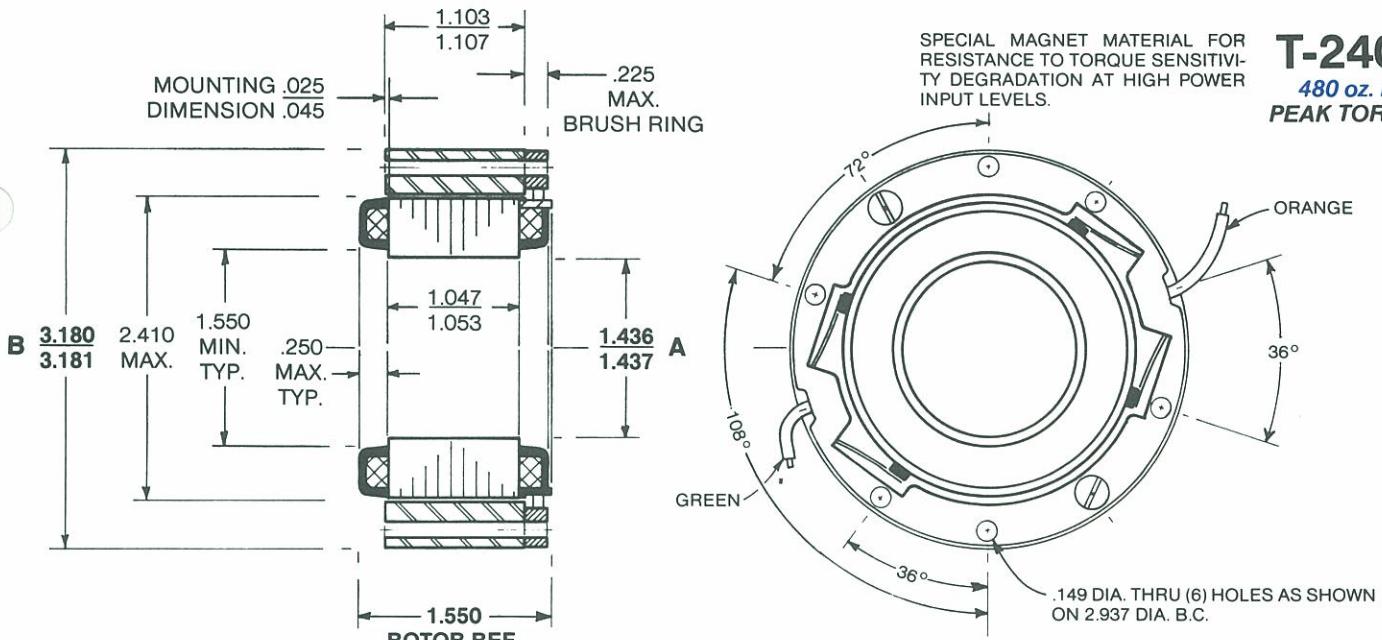
## SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>	
Peak Torque Rating - $T_p$	30	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	50.5	WATTS	
Motor Constant - $K_m$	4.22	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	238	RAD/S	
Electrical Time Constant - $\tau_e$	0.20	MS	
Static Friction (Max.) - $T_f$	1.7	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_\infty$	0.126      0.002	OZ. IN. PER RAD/S      OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - TPR	10	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT	
Ripple Frequency - (Fundamental)	46	CYCLES/REV.	
Number of Poles	10		
Rotor Inertia - $J_m$	0.006	OZ.IN.S <sup>2</sup>	
Motor Weight	4	OZ.	

## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	32.2	25.6					
Peak Current - $I_p$	AMPERES	Rated	1.57	1.97					
Torque Sensitivity - $K_t$	OZ.IN./AMP.	$\pm 10\%$	19.1	15.2					
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.135	0.107					
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	20.5	13.0					
Inductance - $L_m$	mH	$\pm 30\%$	4.3	2.6					



**NOTES:**

- MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. **CAUTION:** DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002(.004 T.I.R.) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**LEADS:**

#20 AWG TYPE "E" 41/36 STRANDING TEFLON COATED PER MIL W-16878, 24" MIN. LG.

### SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>
Peak Torque Rating - $T_p$	480	OZ. IN.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	285	WATTS
Motor Constant - $K_m$	28.4	OZ.IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	84	RAD/S
Electrical Time Constant - $\tau_e$	1.75	MS
Static Friction (Max.) - $T_f$	10	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	5.71      0.1
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	5	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	7	PERCENT
Ripple Frequency - (Fundamental)	41	CYCLES/REV.
Number of Poles	10	
Rotor Inertia - $J_m$	0.031	OZ.IN.S <sup>2</sup>
Motor Weight	31	OZ.

### WINDING CONSTANTS

### Winding Designation

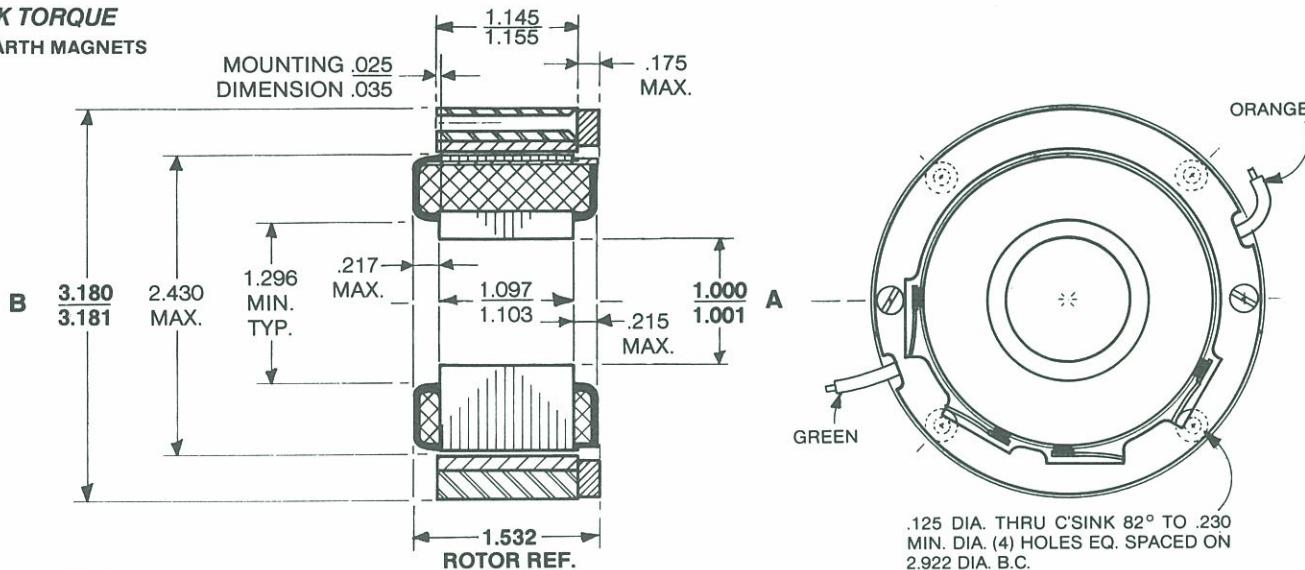
	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	28.5	24.3	45.4	57.0			
Peak Current - $I_p$	AMPERES	Rated	10.0	12.8	6.40	5.00			
Torque Sensitivity - $K_t$	OZ.IN./AMP.	$\pm 10\%$	48.0	37.5	75.1	96.0			
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.339	0.265	0.530	0.678			
DC Resistance( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	2.85	1.9	7.10	11.4			
Inductance - $L_m$	mH	$\pm 30\%$	5.0	3.1	12	20			

# QT-2404

3.0 lb. ft.

## PEAK TORQUE

RARE EARTH MAGNETS



### NOTE:

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

### LEADS:

#20 AWG TYPE "E" 41/36 STRANDING  
TEFLON COATED PER MIL W-16878,  
24" MIN. LENGTH.

## SIZE CONSTANTS

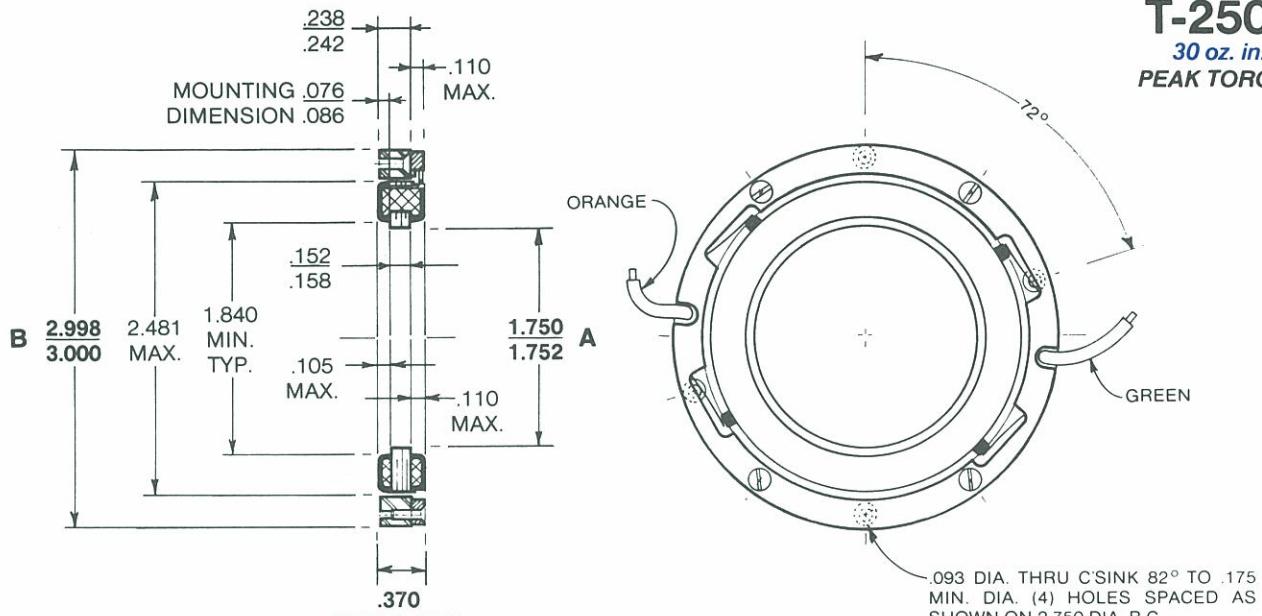
### Value      Units

Peak Torque Rating - $T_p$	3.0	LB. FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	260	WATTS	
Motor Constant - $K_m$	0.19	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	64	RAD/S	
Electrical Time Constant - $\tau_e$	1.04	MS	
Static Friction (Max.) - $T_f$	0.062	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.047	LB. FT. PER RAD/S
	Infinite Impedance - $F_\infty$	$7.0 \times 10^{-4}$	LB. FT. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	5	°C/WATT	
Ripple Torque (Average to Peak) - $T_R$	7	PERCENT	
Ripple Frequency (Fundamental)	41	CYCLES/REV.	
Number of Poles	12		
Rotor Inertia - $J_m$	$2.0 \times 10^{-4}$	LB.FT.S <sup>2</sup>	
Motor Weight	2.4	LB.	

## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	26.0	20.6	32.8	41.4	52.0		
Peak Current - $I_p$	AMPERES	Rated	10.0	12.2	7.86	6.29	5.00		
Torque Sensitivity - $K_t$	LB.FT./AMP	±10%	0.30	0.245	0.382	0.477	0.600		
Back EMF Constant - $K_b$	V per RAD/S	±10%	0.407	0.333	0.518	0.647	0.814		
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	±12.5%	2.60	1.69	4.17	6.58	10.4		
Inductance - $L_m$	mH	±30%	2.7	1.8	4.4	6.8	11		



**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. **CAUTION:** DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002(.004 T.I.R) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
5. — GOLD PLATED COMMUTATOR.

LEADS:  
#28 AWG TYPE "E" TEFLON COATED  
12" MIN. LG.

### SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>	
Peak Torque Rating - $T_p$	30	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	48	WATTS	
Motor Constant - $K_m$	4.33	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	220	RAD/S	
Electrical Time Constant - $\tau_e$	0.25	MS	
Static Friction (Max.) - $T_f$	1.0	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.134	OZ. IN. PER RAD/S
	Infinite Impedance - $F_i$	0.01	OZ. IN. PER RAD/S
Maximum Winding Temperature	105	°C	
Temperature Rise per Watt - $TPR$	9.0	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT	
Ripple Frequency - (Fundamental)	59	CYCLES/REV.	
Number of Poles	10		
Rotor Inertia - $J_m$	0.006	OZ.IN.S <sup>2</sup>	
Motor Weight	4.5	OZ.	

### WINDING CONSTANTS

### Winding Designation

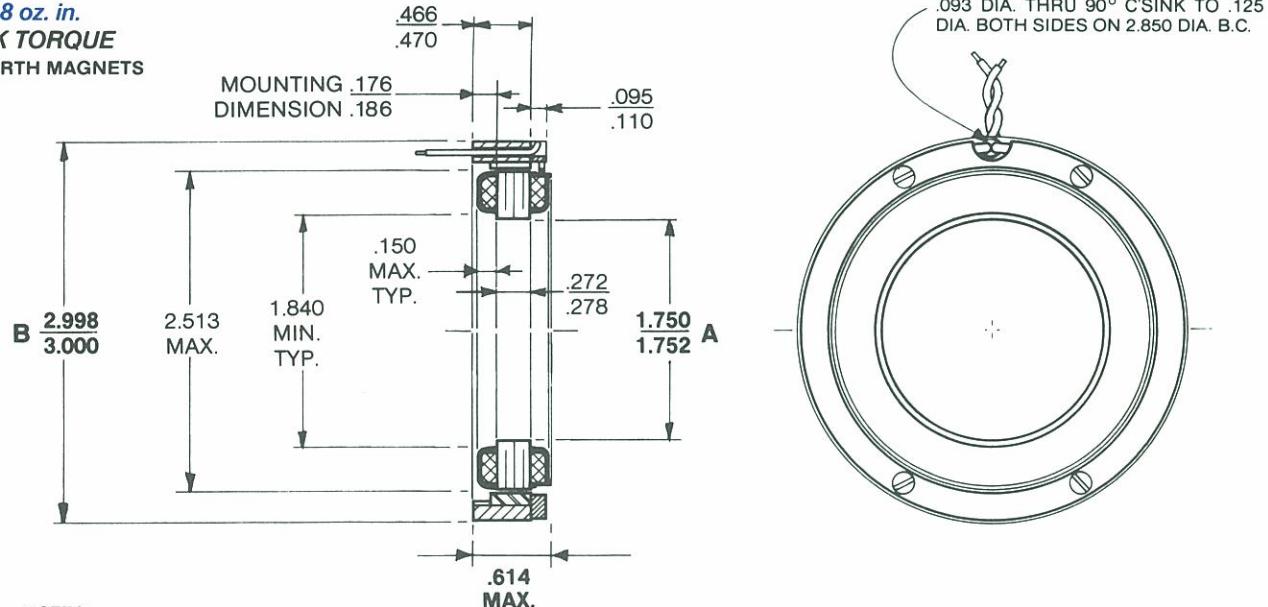
	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	30.8	19.1	12.7	38.5			
Peak Current - $I_p$	AMPERES	Rated	1.54	2.42	3.85	1.21			
Torque Sensitivity - $K_t$	OZ.IN./AMP.	± 10%	19.5	12.4	7.83	24.8			
Back EMF Constant - $K_b$	V per RAD/S	± 10%	0.138	0.088	0.055	0.175			
DC Resistance( $25^\circ\text{C}$ ) - $R_m$	OHMS	± 12.5%	20.0	7.9	3.3	31.8			
Inductance - $L_m$	mH	± 30%	5.0	2.0	0.79	8.0			

# QT-2502

48 oz. in.

PEAK TORQUE

RARE EARTH MAGNETS



**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002(.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO ORANGE LEAD, WITH RESPECT TO BLACK LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
5. — GOLD PLATED COMMUTATOR.

**LEADS:**

#26 AWG TYPE "E" TEFLON COATED PER MIL W-16878, 6" MIN. LENGTH.

## SIZE CONSTANTS

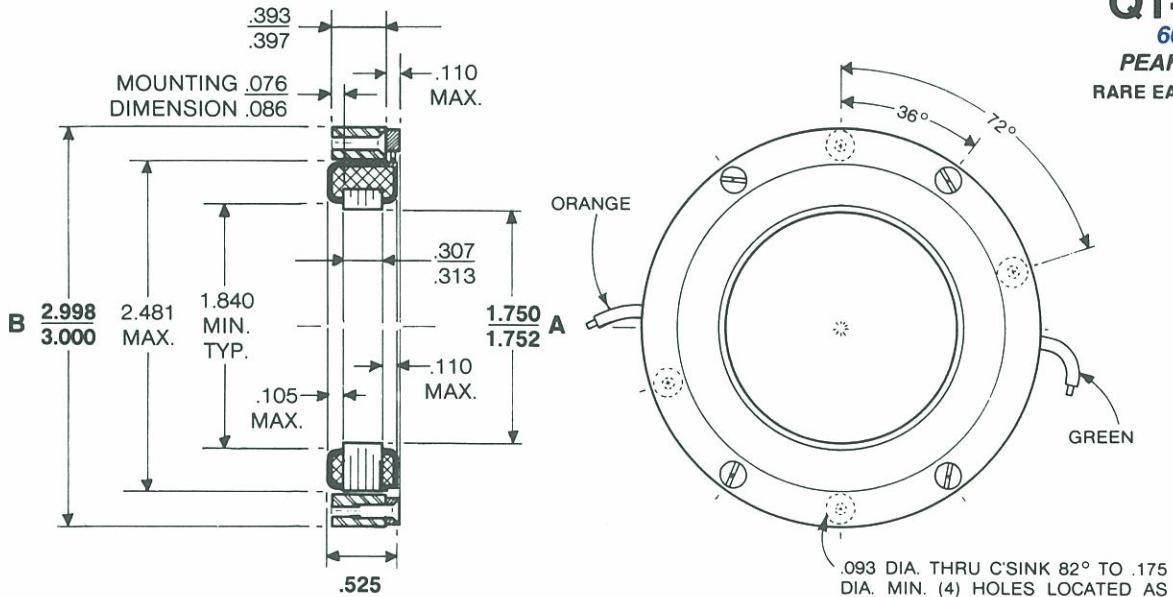
### Value      Units

Peak Torque Rating - $T_p$	48	OZ. IN.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	27	WATTS
Motor Constant - $K_m$	9.25	OZ.IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ , $\omega_{NL}$	79	RAD/S
Electrical Time Constant - $\tau_e$	0.184	MS
Static Friction (Max.) - $T_f$	2.5	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.604 OZ. IN. PER RAD/S
	Infinite Impedance - $F_\infty$	0.033 OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	7.0	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT
Ripple Frequency - (Fundamental)	59	CYCLES/REV.
Number of Poles	12	
Rotor Inertia - $J_m$	$1.05 \times 10^{-2}$	OZ.IN.S <sup>2</sup>
Motor Weight	9.0	oz.

## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	19.0						
Peak Current - $I_p$	AMPERES	Rated	1.40						
Torque Sensitivity - $K_t$	OZ. IN./AMP.	±10%	34.1						
Back EMF Constant - $K_b$	V per RAD/S	±10%	0.241						
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	±12.5%	13.6						
Inductance - $L_m$	mH	±30%	2.5						



**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002-.004T.I.R. WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
5. — GOLD PLATED COMMUTATOR.

**LEADS:**  
#28 AWG TYPE "E" TEFLON COATED  
12" MIN. LENGTH.

### SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>
Peak Torque Rating - $T_p$	60	OZ. IN.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	55	WATTS
Motor Constant - $K_m$	8.1	OZ.IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	128	RAD/S
Electrical Time Constant - $\tau_e$	0.29	MS
Static Friction (Max.) - $T_f$	1.8	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.47 OZ. IN. PER RAD/S
	Infinite Impedance - $F_i$	0.02 OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	7	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT
Ripple Frequency (Fundamental)	59	CYCLES/REV.
Number of Poles	10	
Rotor Inertia - $J_m$	0.011	OZ.IN.S <sup>2</sup>
Motor Weight	8	OZ.

### WINDING CONSTANTS

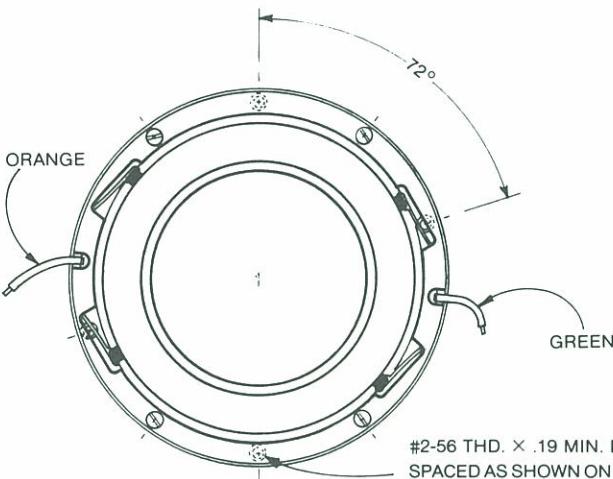
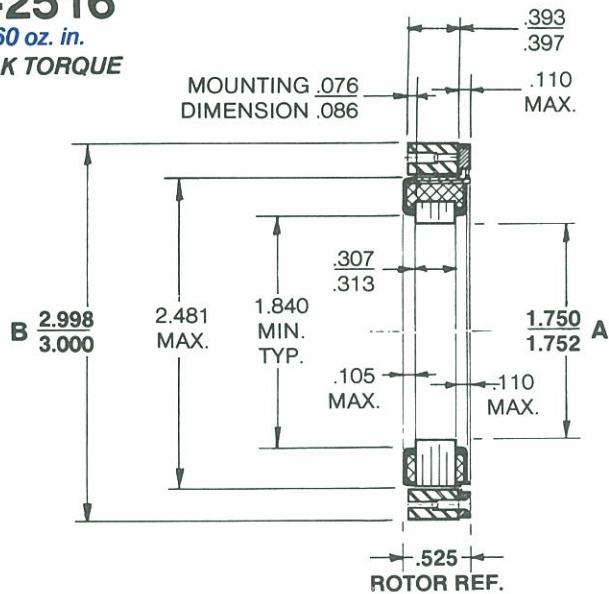
### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	22.4	45.0	56.6				
Peak Current - $I_p$	AMPERES	Rated	2.43	1.22	0.962				
Torque Sensitivity - $K_t$	OZ.IN./AMP	±10%	24.7	49.4	62.4				
Back EMF Constant - $K_b$	V per RAD/S	±10%	0.174	0.349	0.441				
DC Resistance (25°C) - $R_m$	OHMS	±12.5%	9.23	36.9	58.8				
Inductance - $L_m$	mH	±30%	2.7	11	17				

# T-2516

60 oz. in.

PEAK TORQUE



#2-56 THD. X .19 MIN. DP. (4) HOLES  
SPACED AS SHOWN ON 2.750 DIA. B.C.  
(OPPOSITE SIDE)

**NOTES:**

1. - MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. CAUTION: DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
2. - MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002(.004 T.I.R) WHEN MOUNTED.
3. - WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. - TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
5. - GOLD PLATED COMMUTATOR.

**LEADS:**

#28 AWG TYPE 'E' TEFLON COATED  
12" MIN. LG.

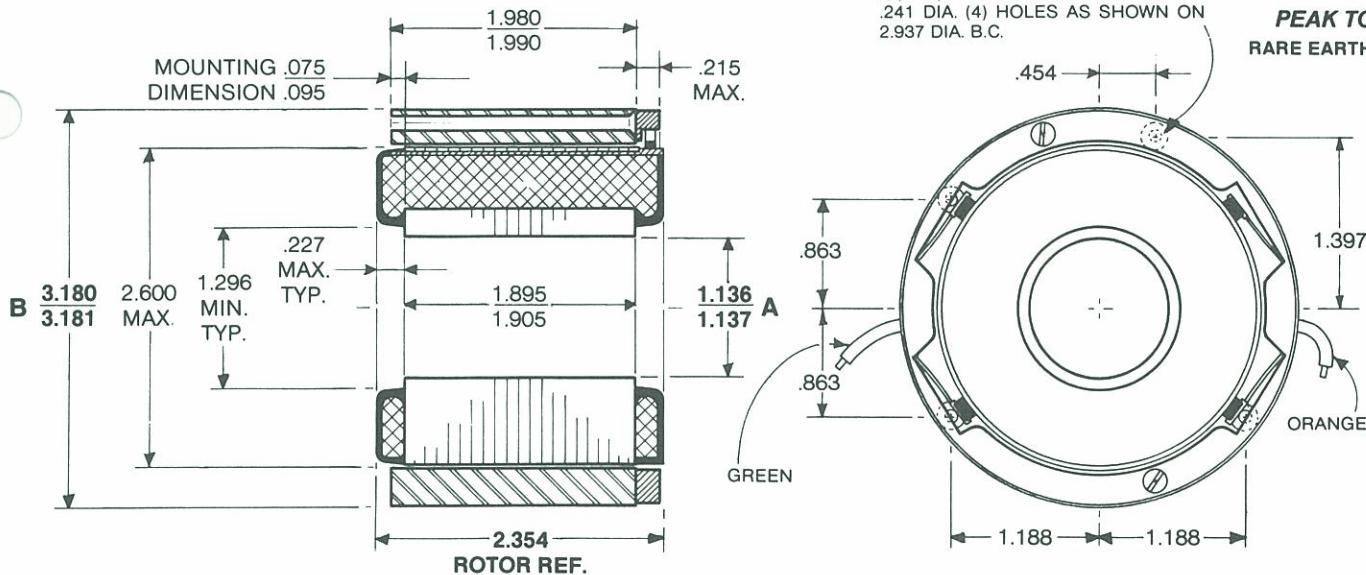
## SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>	
Peak Torque Rating - $T_p$	60	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	55	WATTS	
Motor Constant - $K_m$	8.1	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	127	RAD/S	
Electrical Time Constant - $\tau_e$	0.43	MS	
Static Friction (Max.) - $T_f$	1.8	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.47	OZ. IN. PER RAD/S
	Infinite Impedance - $F_1$	0.02	OZ. IN. PER RAD/S
Maximum Winding Temperature	105	°C	
Temperature Rise per Watt - $TPR$	7.0	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT	
Ripple Frequency - (Fundamental)	59	CYCLES/REV.	
Number of Poles	10		
Rotor Inertia - $J_m$	0.011	OZ.IN.S <sup>2</sup>	
Motor Weight	8.0	OZ.	

## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	35.6	22.6	17.9	14.1	28.4		
Peak Current - $I_p$	AMPERES	Rated	1.54	2.45	3.08	3.85	1.93		
Torque Sensitivity - $K_t$	OZ.IN./AMP.	±10%	39.0	24.7	19.5	15.6	31.2		
Back EMF Constant - $K_b$	V per RAD/S	±10%	0.28	0.174	0.138	0.110	0.220		
DC Resistance (25°C) - $R_m$	OHMS	±12.5%	23.1	9.20	5.80	3.67	14.7		
Inductance - $L_m$	mH	±30%	10	4.0	2.5	1.6	6.4		

**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**LEADS:**

#20 AWG TYPE "E" TEFLON COATED  
PER MIL W-16878, 6" MIN. LENGTH.

<b>SIZE CONSTANTS</b>	<b>Value</b>	<b>Units</b>
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Peak Torque Rating - $T_p$	5	LB. FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	313	WATTS	
Motor Constant - $K_m$	0.28	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	46	RAD/S	
Electrical Time Constant - $\tau_e$	2.1	MS	
Static Friction (Max.) - $T_f$	0.10	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.108	LB. FT. PER RAD/S
	Infinite Impedance - $F_i$	0.0014	LB. FT. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	4.3	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT	
Ripple Frequency (Fundamental)	39	CYCLES/REV.	
Number of Poles	10		
Rotor Inertia - $J_m$	$4.0 \times 10^{-4}$	LB.FT.S <sup>2</sup>	
Motor Weight	3.5	L.B.	

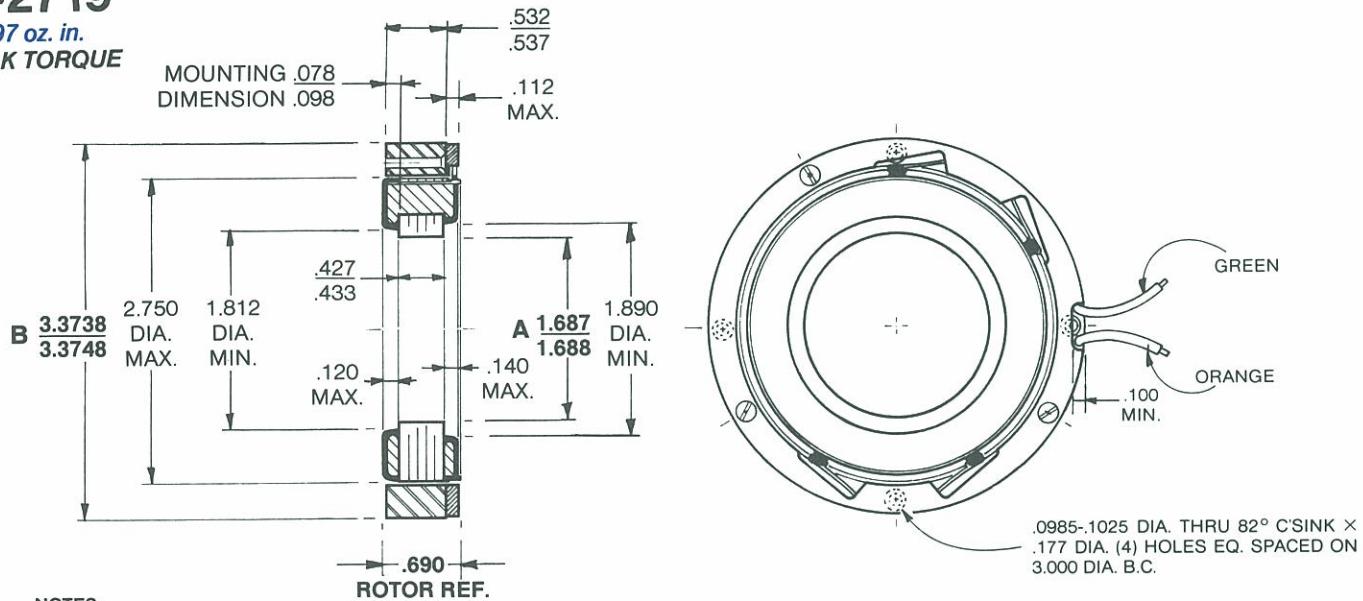
**WINDING CONSTANTS****Winding Designation**

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	50.0	19.8	39.7	31.5	25.0	63.2	
Peak Current - $I_p$	AMPERES	Rated	6.25	16.1	8.04	9.78	12.5	4.90	
Torque Sensitivity - $K_t$	LB.FT./AMP	± 10%	0.800	0.310	0.622	0.511	0.400	1.02	
Back EMF Constant - $K_b$	V per RAD/S	± 10%	1.08	0.420	0.842	0.693	0.542	1.38	
DC Resistance (25°C) - $R_m$	OHMS	± 12.5%	8.00	1.23	4.94	3.22	2.00	12.9	
Inductance - $L_m$	mH	± 30%	17	2.6	10	6.9	4.2	27	

# T-2719

97 oz. in.

PEAK TORQUE



**NOTES:**

- MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. CAUTION: DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
- GOLD PLATED COMMUTATOR.

**LEADS:**

#30 AWG TYPE 'E' TEFLON COATED 7-STRAND MIN. 12" MIN. LG.

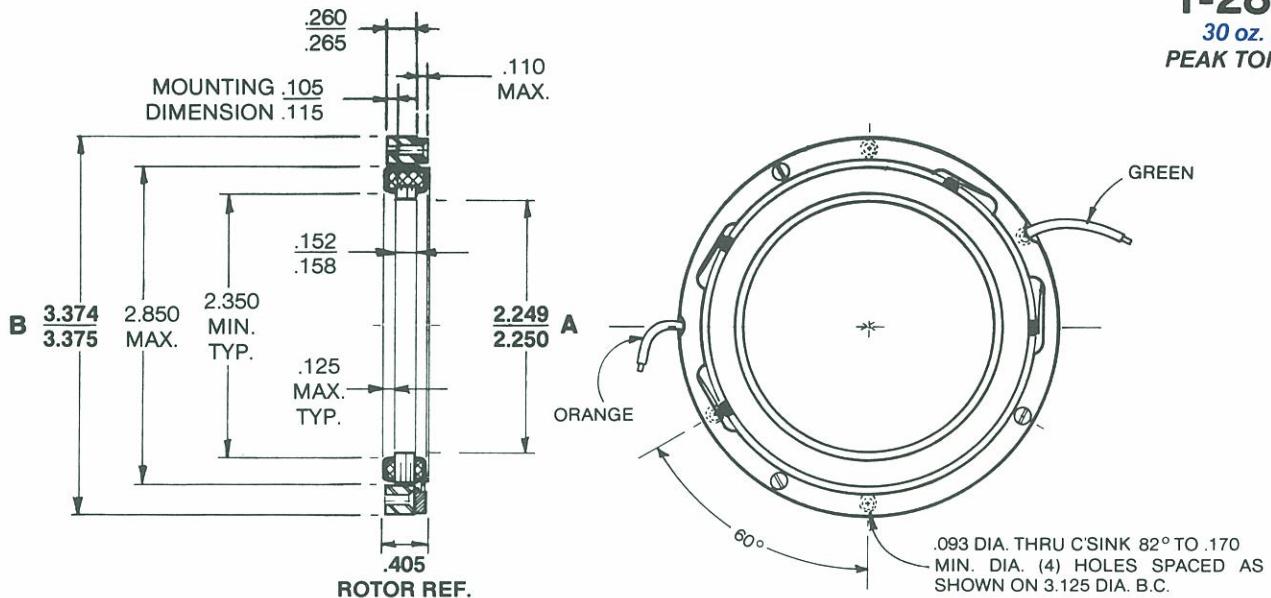
## SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>	
Peak Torque Rating - $T_p$	97	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	37.5	WATTS	
Motor Constant - $K_m$	15.8	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	54	RAD/S	
Electrical Time Constant - $\tau_e$	0.77	MS	
Static Friction (Max.) - $T_f$	4.25	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	1.78	OZ. IN. PER RAD/S
	Infinite Impedance - $F_\infty$	0.038	OZ. IN. PER RAD/S
Maximum Winding Temperature	105	°C	
Temperature Rise per Watt - $TPR$	5.0	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT	
Ripple Frequency - (Fundamental)	61	CYCLES/REV.	
Number of Poles	12		
Rotor Inertia - $J_m$	0.022	OZ.IN.S <sup>2</sup>	
Motor Weight	15	oz.	

## WINDING CONSTANTS

## Winding Designation

	<b>UNITS</b>	<b>TOLERANCES</b>	<b>A</b>	<b>B</b>	<b>C</b>	<b>D</b>	<b>E</b>	<b>F</b>	<b>G</b>
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	<b>VOLTS</b>	Nom.	31.2	19.6	12.4	62.4	15.6		
Peak Current - $I_p$	<b>AMPERES</b>	Rated	1.20	1.92	3.03	0.600	2.40		
Torque Sensitivity - $K_t$	<b>OZ.IN./AMP.</b>	±10%	81.0	50.6	32.0	162	40.5		
Back EMF Constant - $K_b$	<b>V per RAD/S</b>	±10%	0.57	0.36	0.226	1.14	0.286		
DC Resistance (25°C) - $R_m$	<b>OHMS</b>	±12.5%	26.0	10.2	4.10	104	6.50		
Inductance - $L_m$	<b>mH</b>	±30%	20	7.8	3.1	80	5.0		



**NOTES:**

- MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. CAUTION: DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002(.004 T.I.R.) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REVS.

**LEADS:**

#28 AWG TYPE 'EE' TEFLON COATED PER MIL W-16878, 6" MIN. LG.

### SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>
Peak Torque Rating - $T_p$	30	OZ. IN.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	67	WATTS
Motor Constant - $K_m$	3.66	OZ.IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	320	RAD/S
Electrical Time Constant - $\tau_e$	0.30	MS
Static Friction (Max.) - $T_f$	1.5	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	0.095      0.005
Maximum Winding Temperature	105	°C
Temperature Rise per Watt - $TPR$	7.9	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	7	PERCENT
Ripple Frequency - (Fundamental)	67	CYCLES/REV.
Number of Poles	12	
Rotor Inertia - $J_m$	$8.6 \times 10^{-3}$	OZ.IN.S <sup>2</sup>
Motor Weight	5.1	OZ.

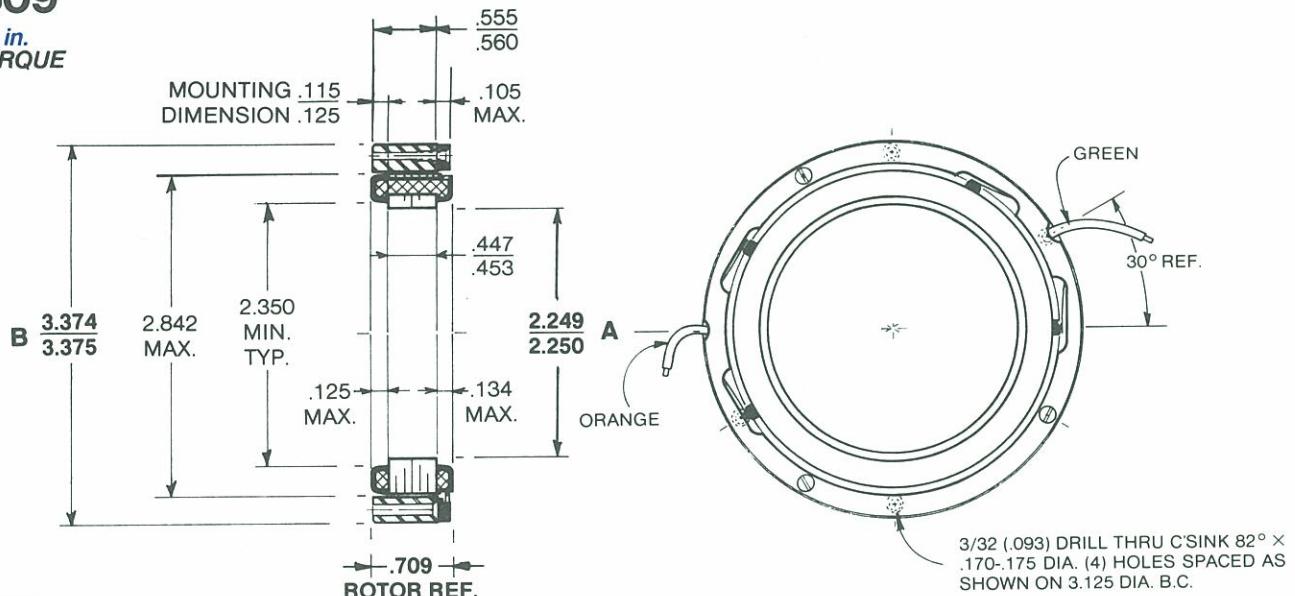
### WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	45.3	56.2	71.2	92.4	115	28.6	33.4
Peak Current - $I_p$	AMPERES	Rated	1.48	1.2	0.95	0.74	0.59	2.34	2.13
Torque Sensitivity - $K_t$	OZ.IN./AMP.	$\pm 10\%$	20.2	25.0	31.7	40.4	50.5	12.8	14.1
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.14	0.18	0.22	0.29	0.36	0.09	0.10
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	30.6	46.8	74.9	125	195	12.2	15.7
Inductance - $L_m$	mH	$\pm 30\%$	9.0	14	22	36	56	3.6	4.4

# T-2809

85 oz. in.  
PEAK TORQUE



#### NOTES:

- MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. CAUTION: DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
- GOLD PLATED COMMUTATOR.

#### LEADS:

#28 AWG TYPE 'EE' TEFLON COATED PER MIL W-16878, 18" MIN. LG.

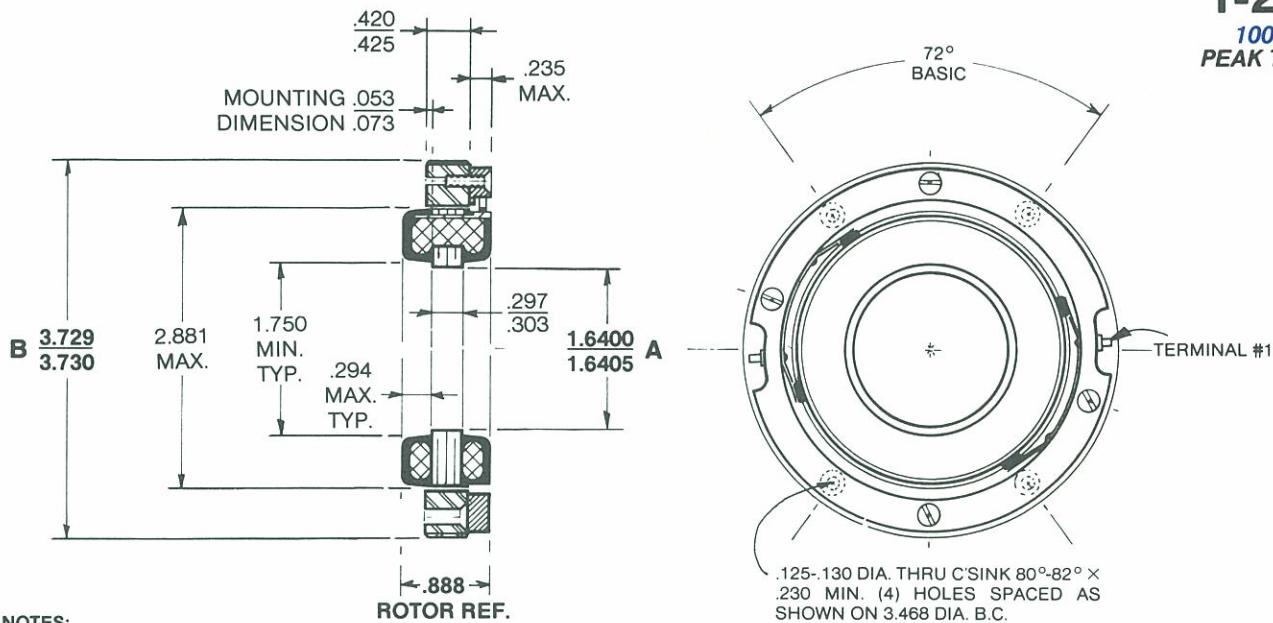
SIZE CONSTANTS	Value	Units
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Peak Torque Rating - $T_p$	85	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	103	WATTS	
Motor Constant - $K_m$	8.4	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	170	RAD/S	
Electrical Time Constant - $\tau_e$	0.300	MS	
Static Friction (Max.) - $T_f$	3.5	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.49	OZ. IN. PER RAD/S
	Infinite Impedance - $F_\infty$	0.015	OZ. IN. PER RAD/S
Maximum Winding Temperature	105	°C	
Temperature Rise per Watt - $TPR$	3.1	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	7	PERCENT	
Ripple Frequency - (Fundamental)	67	CYCLES/REV.	
Number of Poles	12		
Rotor Inertia - $J_m$	0.02	OZ.IN.S <sup>2</sup>	
Motor Weight	11	OZ.	

#### WINDING CONSTANTS

#### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	40.6	32.2	64.4	81.3			
Peak Current - $I_p$	AMPERES	Rated	2.54	3.22	1.61	1.27			
Torque Sensitivity - $K_t$	OZ.IN./AMP.	$\pm 10\%$	33.4	26.4	52.8	66.8			
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.236	0.186	0.373	0.472			
DC Resistance (25°C) - $R_m$	OHMS	$\pm 12.5\%$	16.0	10.0	40.0	64.0			
Inductance - $L_m$	mH	$\pm 30\%$	4.8	3.0	12	19.2			



**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. **CAUTION:** DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002(.004 T.I.R.) WHEN MOUNTED.
3. — WITH A POSITIVE CURRENT APPLIED TO TERMINAL #1, ROTATION SHALL BE C.C.W. FACING THE BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

### SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>	
Peak Torque Rating - $T_p$	100	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	67.5	WATTS	
Motor Constant - $K_m$	12.2	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	95	RAD/S	
Electrical Time Constant - $\tau_e$	1.2	MS	
Static Friction (Max.) - $T_f$	3.5	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	1.04	OZ. IN. PER RAD/S
	Infinite Impedance - $F_i$	0.055	OZ. IN. PER RAD/S
Maximum Winding Temperature	105	°C	
Temperature Rise per Watt - $TPR$	5.6	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT	
Ripple Frequency - (Fundamental)	41	CYCLES/REV.	
Number of Poles	10		
Rotor Inertia - $J_m$	0.035	OZ.IN.S <sup>2</sup>	
Motor Weight	17.5	OZ.	

### WINDING CONSTANTS

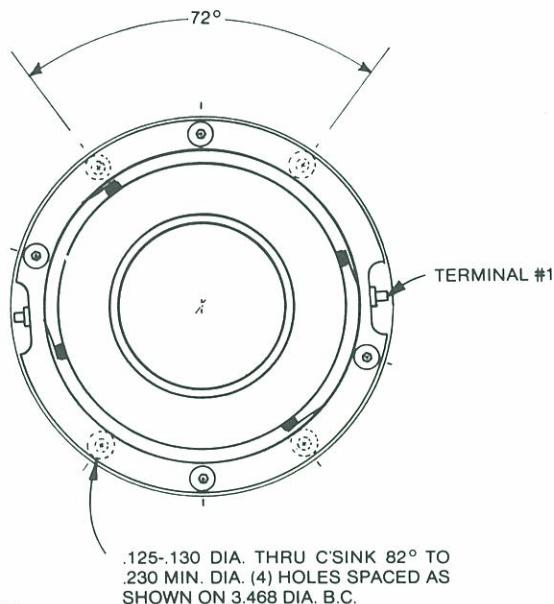
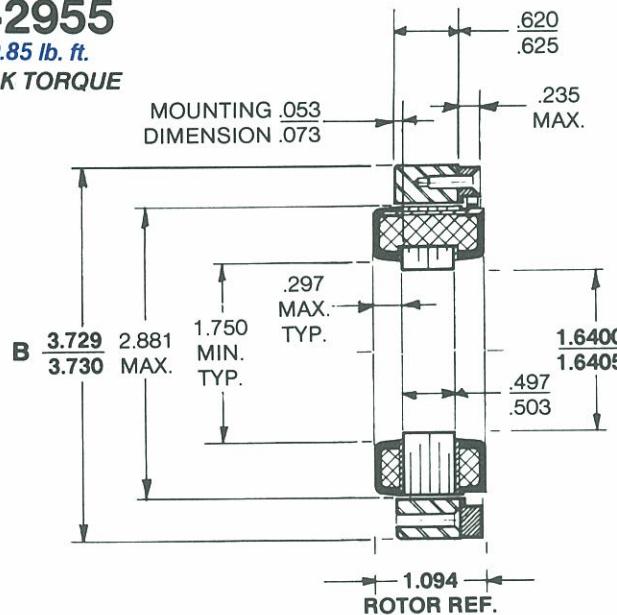
### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	21.4	27.2	34.1	11.0	13.5	8.9	53.8
Peak Current - $I_p$	AMPERES	Rated	3.15	2.5	1.97	6.3	5.0	8.1	1.25
Torque Sensitivity - $K_t$	OZ.IN./AMP.	$\pm 10\%$	31.7	40.2	50.8	15.85	20.0	12.4	80.4
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.224	0.284	0.359	0.112	0.141	0.0876	0.568
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	6.8	10.9	17.3	1.75	2.7	1.1	43.0
Inductance - $L_m$	mH	$\pm 30\%$	8.0	13.0	21.0	2.0	3.2	1.2	52

# T-2955

0.85 lb. ft.

PEAK TORQUE



**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. **CAUTION:** DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002(.004T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO TERMINAL #1, ROTATION SHALL BE C.C.W. WHEN VIEWED FROM BRUSH RING SIDE.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

## SIZE CONSTANTS

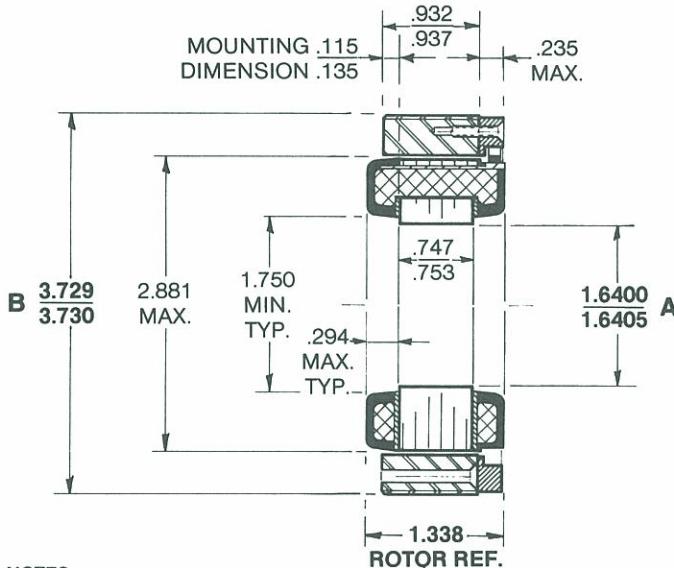
### Value      Units

Peak Torque Rating - $T_p$	0.85	LB. FT.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	77	WATTS
Motor Constant - $K_m$	0.097	LB.FT./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p - \omega_{NL}$	67	RAD/S
Electrical Time Constant - $\tau_e$	1.6	MS
Static Friction (Max.) - $T_f$	0.013	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	0.013 $5 \times 10^{-3}$
Maximum Winding Temperature	105	°C
Temperature Rise per Watt - TPR	5	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT
Ripple Frequency - (Fundamental)	41	CYCLES/REV.
Number of Poles	10	
Rotor Inertia - $J_m$	$2.3 \times 10^{-4}$	LB.FT.S <sup>2</sup>
Motor Weight	1.5	LB.

## WINDING CONSTANTS

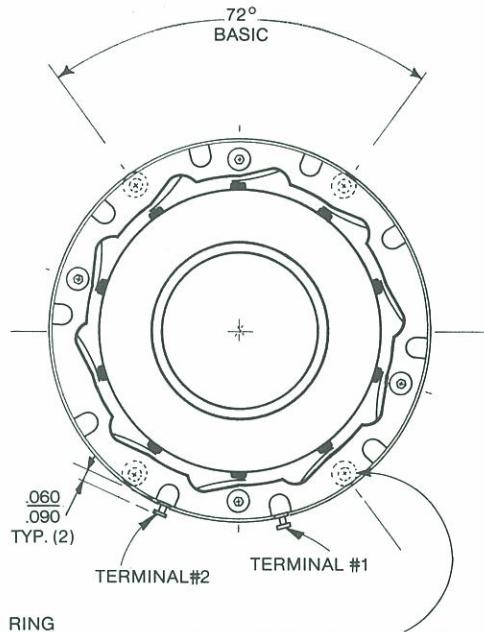
### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	12.2	14.9	22.8	28.2	34.5	56.7	89.2
Peak Current - $I_p$	AMPERES	Rated	6.8	5.5	3.4	2.74	2.13	1.36	0.85
Torque Sensitivity - $K_t$	LB.FT./AMP.	± 10%	0.125	0.155	0.25	0.31	0.40	0.63	1.0
Back EMF Constant - $K_b$	V per RAD/S	± 10%	0.17	0.21	0.34	0.42	0.54	0.85	1.36
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	± 12.5%	1.8	2.7	6.7	10.3	16.2	41.7	105
Inductance - $L_m$	mH	± 30%	2.7	4.1	11	17	27	68	175



**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. **CAUTION:** DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO TERMINAL #1, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
5. — FULL COMPLEMENT OF BRUSHES FOR IMPROVED COMMUTATION AT SUBSTANTIAL SPEEDS AND LOADS.



.125-.130 DIA. THRU CSINK 80°-82° X .230 MIN. (4) HOLES SPACED AS SHOWN ON 3.468 DIA. B.C.

### SIZE CONSTANTS

### Value      Units

Peak Torque Rating - $T_p$	1.10	LB. FT.
Power Input, Stalled at $T_p$ (25°C) - $P_p$	113	WATTS
Motor Constant - $K_m$	0.104	LB. FT./√WATT
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	75	RAD/S
Electrical Time Constant - $\tau_e$	2.13	MS
Static Friction (Max.) - $T_f$	$3.0 \times 10^{-2}$	LB. FT.
Viscous Damping Coefficients	$1.46 \times 10^{-2}$	LB. FT. PER RAD/S
Zero Impedance - $F_0$	$5.0 \times 10^{-4}$	LB. FT. PER RAD/S
Infinite Impedance - $F_i$		
Maximum Winding Temperature	105	°C
Temperature Rise per Watt - $TPR$	2.5	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT
Ripple Frequency - (Fundamental)	41	CYCLES/REV.
Number of Poles	10	
Rotor Inertia - $J_m$	$3.2 \times 10^{-4}$	LB.FT.S <sup>2</sup>
Motor Weight	2.0	LB.

### WINDING CONSTANTS

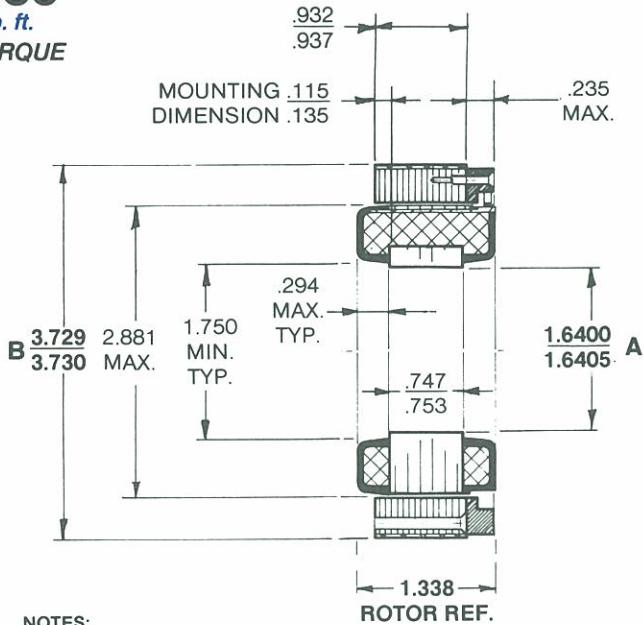
### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ (25°C) - $V_p$	VOLTS	Nom.	14.6	12			18.6	29.7	37.2
Peak Current - $I_p$	AMPERES	Rated	7.7	10			6.0	3.75	3.00
Torque Sensitivity - $K_t$	LB.FT./AMP.	±10%	0.143	0.110			0.183	0.294	0.366
Back EMF Constant - $K_b$	V per RAD/S	±10%	0.195	0.150			0.248	0.400	0.500
DC Resistance (25°C) - $R_m$	OHMS	±12.5%	1.90	1.2			3.1	7.9	12.4
Inductance - $L_m$	mH	±30%	4.05	2.4			6.5	16.5	26

# T-2950

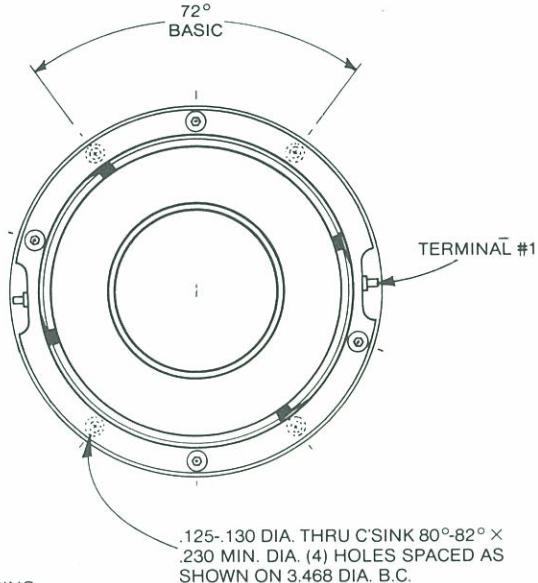
1.20 lb. ft.

PEAK TORQUE



NOTES:

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. CAUTION: DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITH .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH A POSITIVE CURRENT APPLIED TO TERMINAL #1. ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.



## SIZE CONSTANTS

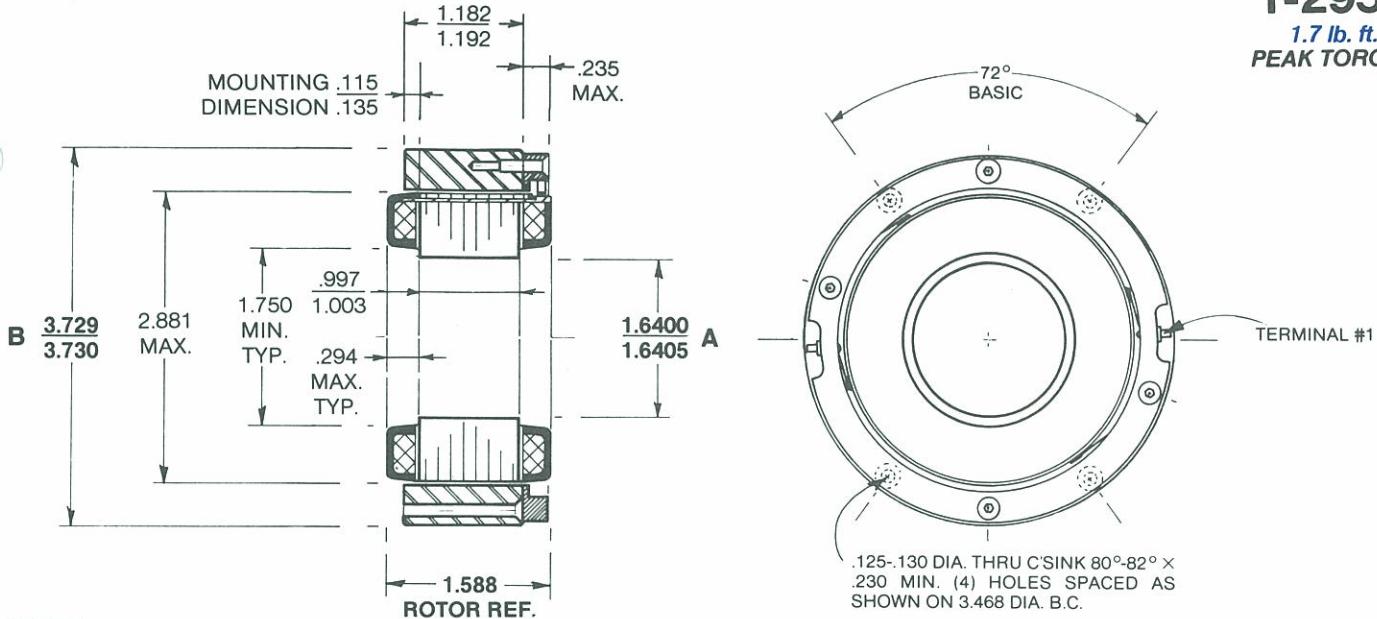
**Value      Units**

Peak Torque Rating - $T_p$	1.20	LB. FT.						
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	79	WATTS						
Motor Constant - $K_M$	0.135	LB.FT./ $\sqrt{\text{WATT}}$						
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	48	RAD/S						
Electrical Time Constant - $\tau_E$	2.13	MS						
Static Friction (Max.) - $T_f$	0.017	LB. FT.						
Viscous Damping Coefficients	<table border="0"> <tr> <td>Zero Impedance - <math>F_0</math></td> <td>0.025</td> </tr> <tr> <td>Infinite Impedance - <math>F_1</math></td> <td><math>8.0 \times 10^{-4}</math></td> </tr> </table>	Zero Impedance - $F_0$	0.025	Infinite Impedance - $F_1$	$8.0 \times 10^{-4}$	<table border="0"> <tr> <td>LB. FT. PER RAD/S</td> </tr> <tr> <td>LB. FT. PER RAD/S</td> </tr> </table>	LB. FT. PER RAD/S	LB. FT. PER RAD/S
Zero Impedance - $F_0$	0.025							
Infinite Impedance - $F_1$	$8.0 \times 10^{-4}$							
LB. FT. PER RAD/S								
LB. FT. PER RAD/S								
Maximum Winding Temperature	105	°C						
Temperature Rise per Watt - TPR	4.3	°C/WATT						
Ripple Torque (Average to Peak) - $T_R$	5	PERCENT						
Ripple Frequency - (Fundamental)	41	CYCLES/REV.						
Number of Poles	10							
Rotor Inertia - $J_M$	$2.9 \times 10^{-4}$	LB.FT.S <sup>2</sup>						
Motor Weight	2.15	LB.						

## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	24.4	53.7	12.0	15.1	30.2	38.4	60.6
Peak Current - $I_p$	AMPERES	Rated	3.25	1.43	6.3	5.2	2.6	2.0	1.3
Torque Sensitivity - $K_T$	LB.FT./AMP.	±10%	0.37	0.84	0.19	0.23	0.46	0.60	0.92
Back EMF Constant - $K_B$	V per RAD/S	±10%	0.50	1.14	0.26	0.31	0.63	0.81	1.25
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	±12.5%	7.5	37.5	1.9	2.9	11.6	19.2	46.7
Inductance - $L_M$	mH	±30%	16	82	4.1	6.2	25	41	100



**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. **CAUTION:** DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002(.004 T.I.R.) WHEN MOUNTED.
3. — WITH A POSITIVE CURRENT APPLIED TO TERMINAL #1, ROTATION SHALL BE C.C.W. FACING THE BRUSH RING SIDE.
4. — TYPICAL BRUSH LIFE > 10' REV.

### SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>
Peak Torque Rating - $T_p$	1.7	LB. FT.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	110	WATTS
Motor Constant - $K_M$	0.16	LB.FT./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	47	RAD/S
Electrical Time Constant - $\tau_E$	2.5	MS
Static Friction (Max.) - $T_F$	0.026	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	0.035      0.001
Maximum Winding Temperature	105	°C
Temperature Rise per Watt - $TPR$	4.0	°C/WATT
Ripple Torque (Average to Peak) - $T_R$	5	PERCENT
Ripple Frequency - (Fundamental)	41	CYCLES/REV.
Number of Poles	10	
Rotor Inertia - $J_M$	$3.3 \times 10^{-4}$	LB.FT.S <sup>2</sup>
Motor Weight	2.5	LB.

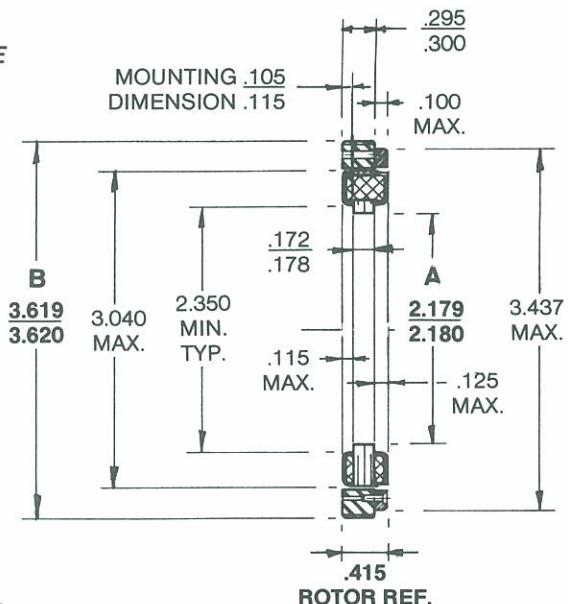
### WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	15.6	95.0	30.4	24.8	19.3		
Peak Current - $I_p$	AMPERES	Rated	7.1	1.12	3.55	4.5	5.67		
Torque Sensitivity - $K_T$	LB.FT./AMP.	± 10%	0.24	1.52	0.475	0.38	0.30		
Back EMF Constant - $K_B$	V per RAD/S	± 10%	0.325	2.06	0.65	0.52	0.40		
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	± 12.5%	2.2	85.0	8.55	5.5	3.4		
Inductance - $L_m$	mH	± 30%	5.5	220	22.0	13.6	8.4		

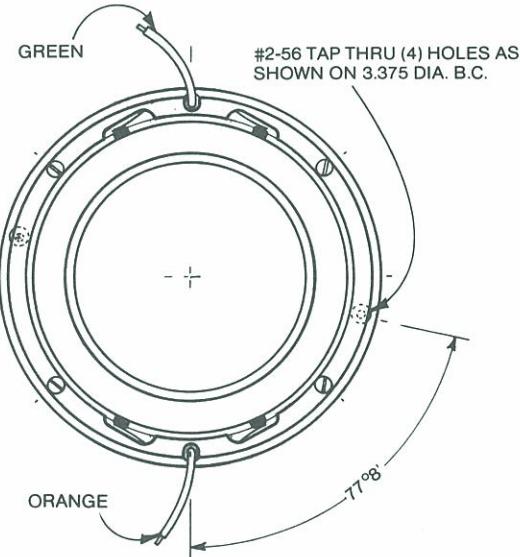
# T-3001

26.5 oz. in.  
PEAK TORQUE



NOTES:

- MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. CAUTION: DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002(.004 T.I.R.) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
- GOLD PLATED COMMUTATOR.



LEADS:

#28 AWG TYPE "EE" 7-STRAND TEF-LON COATED PER MIL W-16878/SA  
12" MIN. LG.

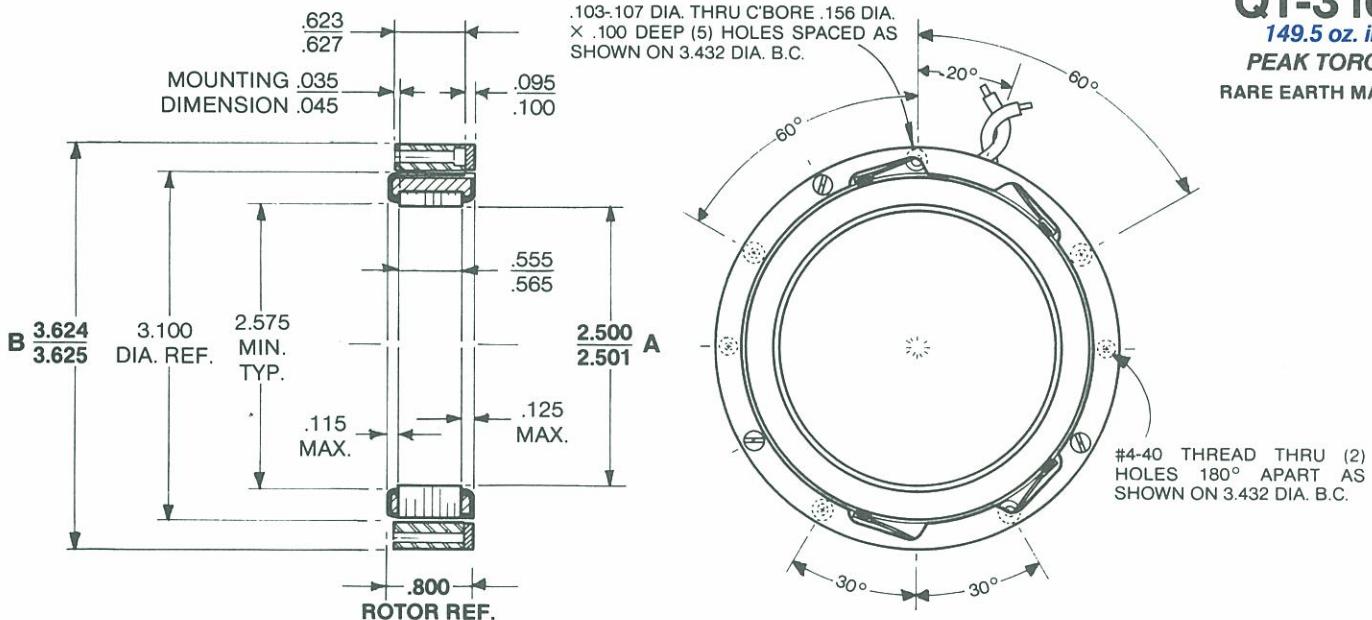
## SIZE CONSTANTS

	Value	Units	
Peak Torque Rating - $T_p$	26.5	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	9.6	WATTS	
Motor Constant - $K_M$	8.55	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p - \omega_{NL}$	51	RAD/S	
Electrical Time Constant - $\tau_E$	0.23	MS	
Static Friction (Max.) - $T_f$	2.8	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.52	OZ. IN. PER RAD/S
	Infinite Impedance - $F_\infty$	$3.4 \times 10^{-3}$	OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	6	°C/WATT	
Ripple Torque (Average to Peak) - $T_R$	5	PERCENT	
Ripple Frequency - (Fundamental)	71	CYCLES/REV.	
Number of Poles	14		
Rotor Inertia - $J_M$	0.015	OZ.IN.S <sup>2</sup>	
Motor Weight	8	OZ.	

## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	14.1	35.4	22.4				
Peak Current - $I_p$	AMPERES	Rated	0.68	0.27	0.43				
Torque Sensitivity - $K_T$	OZ.IN./AMP.	±10%	39.0	98.0	61.5				
Back EMF Constant - $K_B$	V per RAD/S	±10%	0.275	0.692	0.43				
DC Resistance (25°C) - $R_M$	OHMS	±12.5%	20.7	131	52				
Inductance - $L_M$	mH	±30%	4.8	30.4	12				



**NOTES:**

- MOTOR TO BE SUPPLIED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .003-.006T.I.R. WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
- TYPICAL BRUSH LIFE >  $10^7$  REV.

**LEADS:**

#26 AWG TYPE "E" TEFLON COATED  
PER MIL W-16878, 24" MIN. LENGTH  
TWISTED.

### SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>	
Peak Torque Rating - $T_p$	149.5	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	97.2	WATTS	
Motor Constant - $K_m$	15.2	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	92	RAD/S	
Electrical Time Constant - $\tau_e$	0.38	MS	
Static Friction (Max.) - $T_f$	3.0	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	1.62	OZ. IN. PER RAD/S
	Infinite Impedance - $F_i$	0.06	OZ. IN. PER RAD/S
Maximum Winding Temperature	155	$^\circ\text{C}$	
Temperature Rise per Watt - $TPR$	5	$^\circ\text{C}/\text{WATT}$	
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT	
Ripple Frequency (Fundamental)	61	CYCLES/REV.	
Number of Poles	12		
Rotor Inertia - $J_m$	0.034	OZ.IN.S <sup>2</sup>	
Motor Weight	14	OZ.	

### WINDING CONSTANTS

### Winding Designation

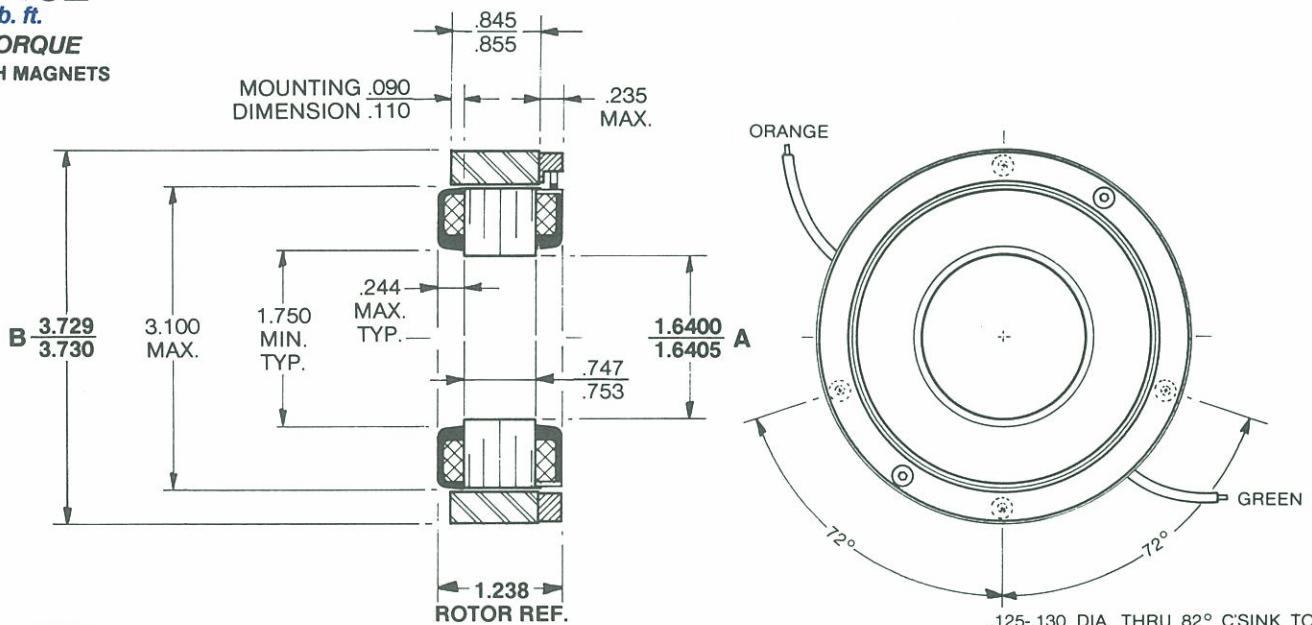
	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	26.3	29.6	41.7	37.3	13.2		
Peak Current - $I_p$	AMPERES	Rated	3.70	3.29	2.37	2.57	7.40		
Torque Sensitivity - $K_t$	OZ.IN/AMP	$\pm 10\%$	40.4	45.5	63.1	58.1	20.2		
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.285	0.321	0.446	0.410	0.143		
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	7.10	9.0	17.6	14.5	1.78		
Inductance - $L_m$	mH	$\pm 30\%$	2.7	3.4	6.6	5.6	0.68		

# QT-3102

2.5 lb. ft.

PEAK TORQUE

RARE EARTH MAGNETS



**NOTES:**

1. — MOTOR SUPPLIED AS THREE SEPARATE COMPONENTS: BRUSH RING, ROTOR AND STATOR.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH A POSITIVE CURRENT APPLIED TO GREEN LEAD WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

.125-.130 DIA. THRU 82° C'SINK TO .230 DIA. MIN. (4) HOLES SPACED AS SHOWN ON 3.468 DIA. B.C.

**LEADS:**

#20 AWG TYPE "E" TEFLON COATED PER MIL-W-16878 24" MIN. LENGTH.

## SIZE CONSTANTS

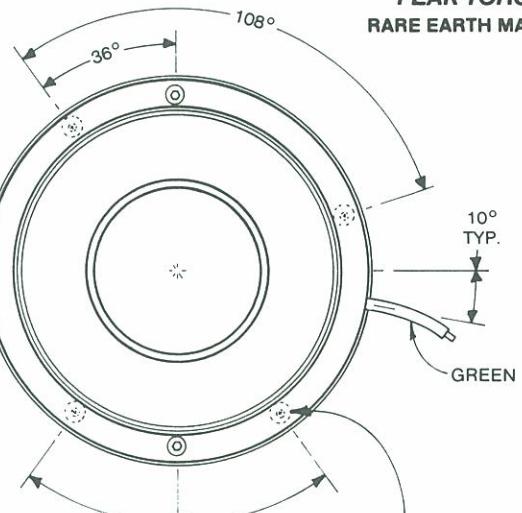
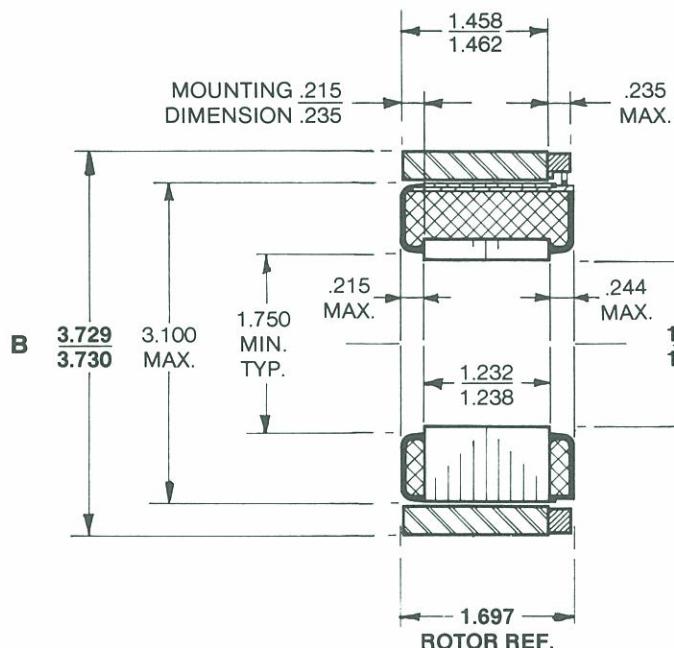
### Value      Units

Peak Torque Rating - $T_p$	2.5	LB. FT.
Power Input, Stalled at $T_p$ (25°C) - $P_p$	263	WATTS
Motor Constant - $K_m$	0.154	LB.FT./ $\sqrt{WATT}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	77	RAD/S
Electrical Time Constant - $\tau_e$	1.2	MS
Static Friction (Max.) - $T_f$	0.041	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	0.032 $2.5 \times 10^{-4}$
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	4	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT
Ripple Frequency - (Fundamental)	39	CYCLES/REV.
Number of Poles	10	
Rotor Inertia - $J_m$	$4.10 \times 10^{-4}$	LB.FT.S <sup>2</sup>
Motor Weight	2	LB.

## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ (25°C) - $V_p$	VOLTS	Nom.	47.3	19.9	9.90	16.2			
Peak Current - $I_p$	AMPERES	Rated	5.56	13.7	29.1	18.0			
Torque Sensitivity - $K_t$	LB.FT./AMP	± 10%	0.450	0.182	0.086	0.139			
Back EMF Constant - $K_b$	V PER RAD/S	± 10%	0.610	0.247	0.116	0.188			
DC Resistance (25°C) - $R_m$	OHMS	± 12.5%	8.50	1.45	0.34	0.90			
Inductance - $L_m$	mH	± 30%	10	1.6	0.36	0.90			



.123-.128 DIA. THRU C'SINK 100° TO  
.225-.241 DIA. (4) HOLES AS SHOWN  
ON 3.468 DIA. B.C.

NOTES:

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

LEADS:

#20 AWG TYPE "E" TEFLON COATED  
PER MIL W-16878 12" MIN. LENGTH.

### SIZE CONSTANTS

**Value      Units**

Peak Torque Rating - $T_p$	3.31	LB. FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	190	WATTS	
Motor Constant - $K_M$	0.240	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ , $\omega_{NL}$	39	RAD/S	
Electrical Time Constant - $\tau_E$	1.52	MS	
Static Friction (Max.) - $T_f$	0.057	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.078	LB. FT. PER RAD/S
	Infinite Impedance - $F_i$	$7.3 \times 10^{-4}$	LB. FT. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	3.8	°C/WATT	
Ripple Torque (Average to Peak) - $T_R$	5	PERCENT	
Ripple Frequency - (Fundamental)	39	CYCLES/REV.	
Number of Poles	10		
Rotor Inertia - $J_M$	$5.7 \times 10^{-4}$	LB.FT.S <sup>2</sup>	
Motor Weight	3.1	LB.	

### WINDING CONSTANTS

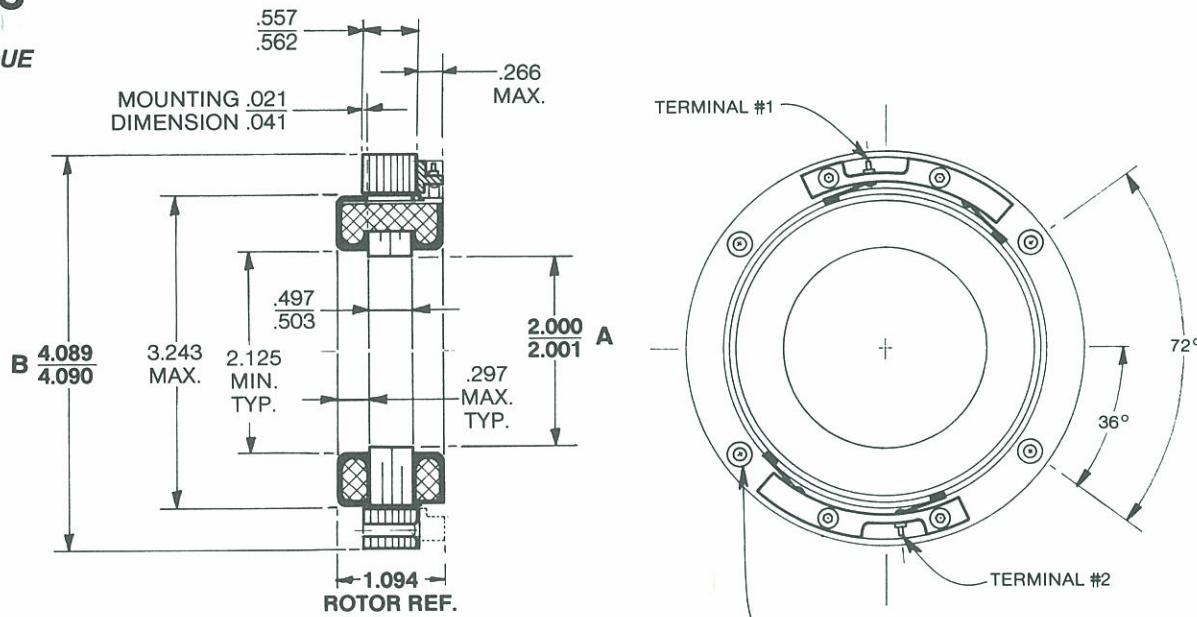
### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	54.8	27.4	22.1	17.2			
Peak Current - $I_p$	AMPERES	Rated	3.47	6.94	8.83	11.4			
Torque Sensitivity - $K_T$	LB. FT./AMP.	±10%	0.953	0.477	0.375	0.290			
Back EMF Constant - $K_B$	V per RAD/S	±10%	1.29	0.647	0.508	0.393			
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	±12.5%	15.8	3.95	2.50	1.51			
Inductance - $L_m$	mH	±30%	24	6.0	3.7	2.2			

# T-3203

1.0 lb. ft.

PEAK TORQUE



**NOTES:**

- MOTOR SUPPLIED AS THREE SEPARATE COMPONENTS: ROTOR ASSEMBLY, BRUSH ASSEMBLY, AND STATOR WITH KEEPER. CAUTION: DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .003 (.006 T.I.R.) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO TERMINAL #1 THE ROTATION SHALL BE C.C.W. FACING THE BRUSH RING SIDE.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

(.125) DIA. THRU 82° C'SINK TO .230 DIA. MIN. (4) HOLES SP. AS SHOWN ON 3.750 DIA. B.C.

## SIZE CONSTANTS

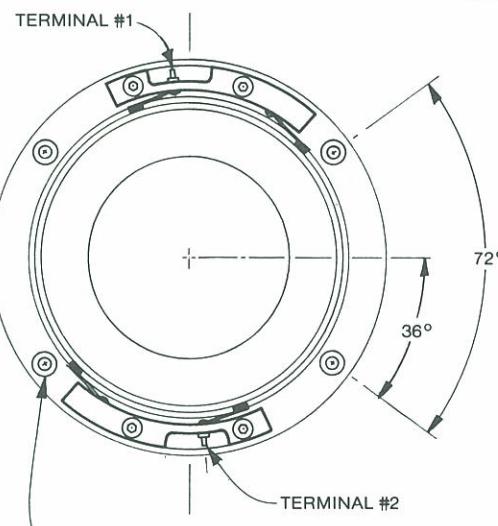
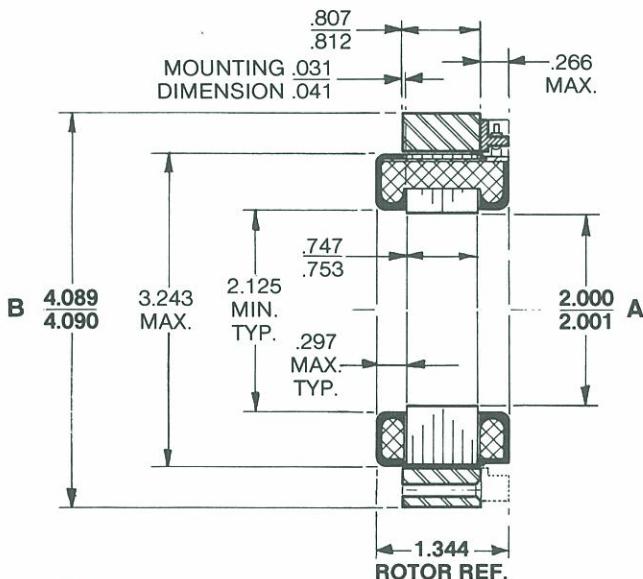
### Value      Units

Peak Torque Rating - $T_p$	1.0	LB. FT.						
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	87	WATTS						
Motor Constant - $K_m$	0.107	LB.FT./ $\sqrt{\text{WATT}}$						
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	63	RAD/S						
Electrical Time Constant - $\tau_e$	2.3	MS						
Static Friction (Max.) - $T_f$	0.02	LB. FT.						
Viscous Damping Coefficients	<table border="0"> <tr> <td>Zero Impedance - <math>F_0</math></td> <td>0.016</td> <td>LB. FT. PER RAD/S</td> </tr> <tr> <td>Infinite Impedance - <math>F_i</math></td> <td><math>0.6 \times 10^{-3}</math></td> <td>LB. FT. PER RAD/S</td> </tr> </table>	Zero Impedance - $F_0$	0.016	LB. FT. PER RAD/S	Infinite Impedance - $F_i$	$0.6 \times 10^{-3}$	LB. FT. PER RAD/S	
Zero Impedance - $F_0$	0.016	LB. FT. PER RAD/S						
Infinite Impedance - $F_i$	$0.6 \times 10^{-3}$	LB. FT. PER RAD/S						
Maximum Winding Temperature	105	°C						
Temperature Rise per Watt - $TPR$	3.4	°C/WATT						
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT						
Ripple Frequency - (Fundamental)	46	CYCLES/REV.						
Number of Poles	10							
Rotor Inertia - $J_m$	$3.5 \times 10^{-4}$	LB.FT.S <sup>2</sup>						
Motor Weight	1.6	LB.						

## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	12.1	15	18.7	30.6	38.9	48.8	77.0
Peak Current - $I_p$	AMPERES	Rated	7.1	5.55	4.35	2.86	2.22	1.75	1.12
Torque Sensitivity - $K_t$	LB.FT./AMP.	$\pm 10\%$	0.14	0.18	0.23	0.35	0.45	0.57	0.89
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.19	0.24	0.31	0.48	0.61	0.77	1.2
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	1.7	2.7	4.3	10.7	17.5	27.9	68.8
Inductance - $L_m$	mH	$\pm 30\%$	4.0	6.0	10	24	40	64	160

**NOTES:**

- MOTOR SUPPLIED AS THREE SEPARATE COMPONENTS: ROTOR ASSEMBLY, BRUSH ASSEMBLY, AND STATOR WITH KEEPER. CAUTION: DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO TERMINAL #1 WITH RESPECT TO TERMINAL #2 ROTATION SHALL BE C.C.W. FACING THE BRUSH RING SIDE.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**SIZE CONSTANTS****Value      Units**

Peak Torque Rating - $T_p$	1.5	LB. FT.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	113	WATTS
Motor Constant - $K_m$	0.14	LB.FT./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	56	RAD/S
Electrical Time Constant - $\tau_e$	3.0	MS
Static Friction (Max.) - $T_f$	0.027	LB. FT.
Viscous Damping Coefficients	$2.7 \times 10^{-2}$	LB. FT. PER RAD/S
Zero Impedance - $F_0$	$1.0 \times 10^{-3}$	LB. FT. PER RAD/S
Infinite Impedance - $F_i$		
Maximum Winding Temperature	105	°C
Temperature Rise per Watt - $TPR$	2.5	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT
Ripple Frequency - (Fundamental)	46	CYCLES/REV.
Number of Poles	10	
Rotor Inertia - $J_m$	$4 \times 10^{-4}$	LB.FT.S <sup>2</sup>
Motor Weight	2.4	LB.

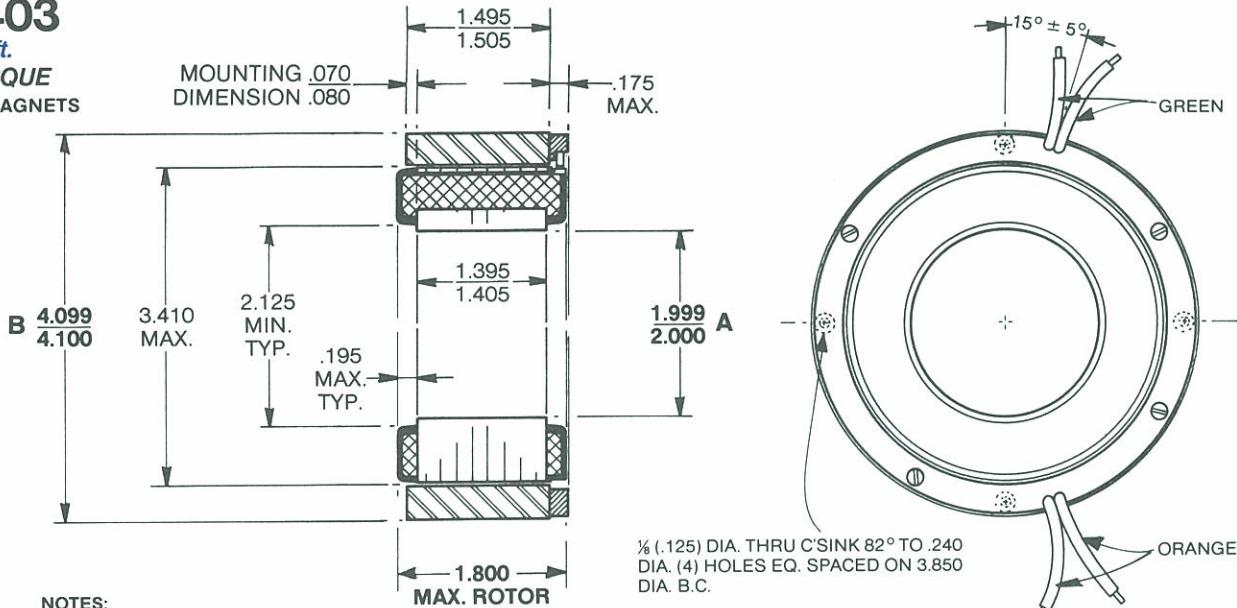
**WINDING CONSTANTS****Winding Designation**

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	15.0	95	19.2	23.9	30.0		
Peak Current - $I_p$	AMPERES	Rated	7.5	1.15	6.0	4.69	3.75		
Torque Sensitivity - $K_t$	LB.FT./AMP	±10%	0.20	1.30	0.25	0.320	0.400		
Back EMF Constant - $K_b$	V per RAD/S	±10%	0.27	1.76	0.34	0.434	0.540		
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	±12.5%	2.0	82.5	3.2	5.10	8.00		
Inductance - $L_m$	mH	±30%	6.0	250	9.4	15	24		

# QT-3403

4.0 lb. ft.

PEAK TORQUE  
RARE EARTH MAGNETS



NOTES:

- MOTOR SUPPLIED AS THREE SEPARATE COMPONENTS: STATOR, ROTOR, & BRUSH RING ASSEMBLY.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO GREEN LEADS, WITH RESPECT TO ORANGE LEADS, ROTATION SHALL BE C.C.W. FACING BRUSH RING SIDE.
- CONNECT GREEN LEADS TOGETHER AND ORANGE LEADS TOGETHER FOR PROPER OPERATION.
- GOLD PLATED COMMUTATOR.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

LEADS:

#22 AWG TYPE "ET" TEFLON COATED PER MIL W-16878, 18" MIN. LENGTH.

## SIZE CONSTANTS

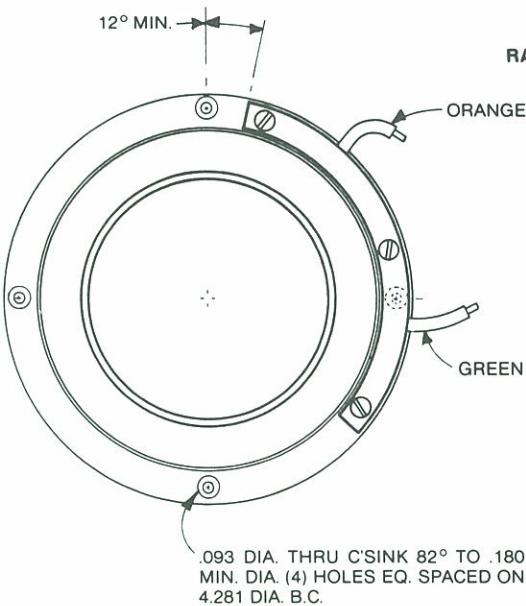
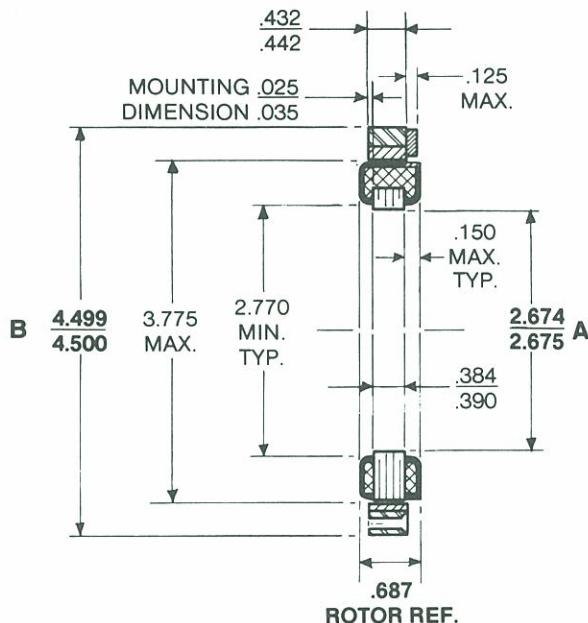
## Value      Units

Peak Torque Rating - $T_p$	4.0	LB. FT.	
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	126	WATTS	
Motor Constant - $K_M$	0.357	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	23.2	RAD/S	
Electrical Time Constant - $\tau_E$	2.1	MS	
Static Friction (Max.) - $T_f$	0.10	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.173	LB. FT. PER RAD/S
	Infinite Impedance - $F_i$	$3.0 \times 10^{-3}$	LB. FT. PER RAD/S
Maximum Winding Temperature		$155^\circ\text{C}$	$^\circ\text{C}$
Temperature Rise per Watt - TPR	2.0	$^\circ\text{C}/\text{WATT}$	
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT	
Ripple Frequency - (Fundamental)	49	CYCLES/REV.	
Number of Poles	12		
Rotor Inertia - $J_M$	$9.8 \times 10^{-4}$	LB.FT.S <sup>2</sup>	
Motor Weight	4	LB.	

## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	22.0	55.6					
Peak Current - $I_p$	AMPERES	Rated	5.71	2.29					
Torque Sensitivity - $K_T$	LB.FT./AMP	$\pm 10\%$	0.700	1.75					
Back EMF Constant - $K_B$	V PER RAD/S	$\pm 10\%$	0.949	2.37					
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	3.85	24.3					
Inductance - $L_m$	mH	$\pm 30\%$	8.2	51					



**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH SEGMENT ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**LEADS:**  
#24 AWG TEFLON COATED PER MIL  
W-16878, 12" MIN. LENGTH.

### SIZE CONSTANTS

**Value      Units**

Peak Torque Rating - $T_p$	2.40	LB. FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	187	WATTS	
Motor Constant - $K_m$	0.175	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	57.5	RAD/S	
Electrical Time Constant - $\tau_e$	0.577	MS	
Static Friction (Max.) - $T_f$	0.05	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_\infty$	0.042 $1.0 \times 10^{-3}$	LB. FT. PER RAD/S      LB. FT. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	3.3	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	6	PERCENT	
Ripple Frequency (Fundamental)	89	CYCLES/REV.	
Number of Poles	20		
Rotor Inertia - $J_M$	$3.60 \times 10^{-4}$	LB.FT.S <sup>2</sup>	
Motor Weight	1.3	LB.	

### WINDING CONSTANTS

### Winding Designation

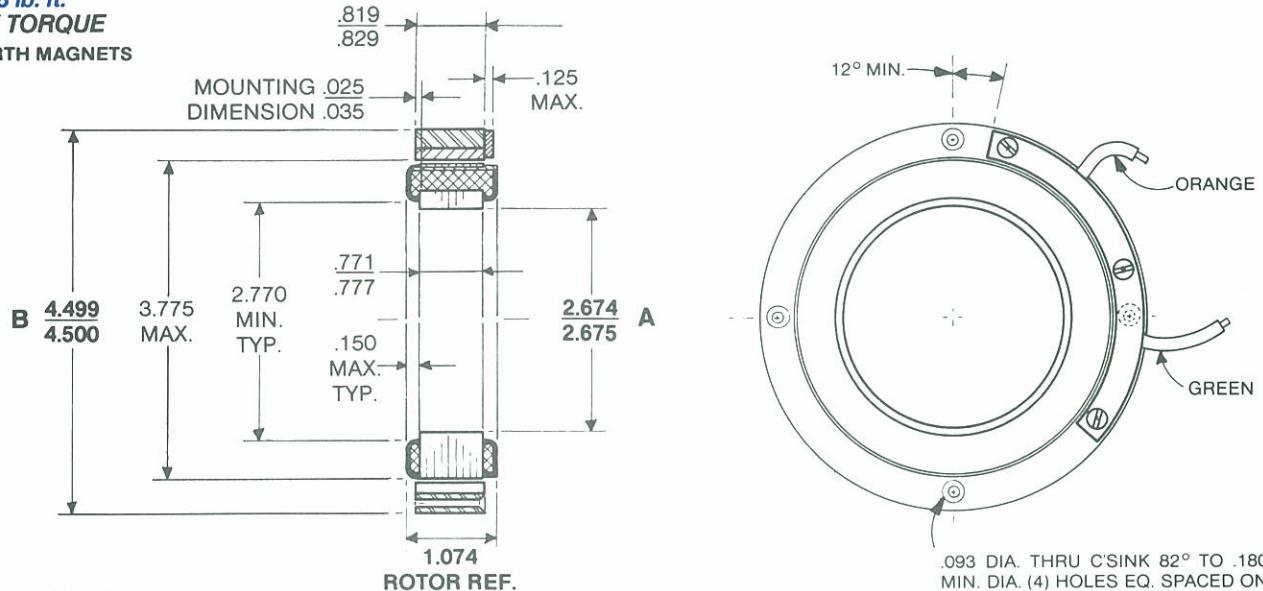
	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	62.4	31.2	55.4	24.8	19.6	15.6	
Peak Current - $I_p$	AMPERES	Rated	3.00	6.00	3.38	7.77	9.41	12.0	
Torque Sensitivity - $K_t$	LB.FT./AMP	$\pm 10\%$	0.800	0.400	0.710	0.309	0.255	0.200	
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	1.08	0.542	0.963	0.419	0.346	0.271	
DC Resistance (25°C) - $R_M$	OHMS	$\pm 12.5\%$	20.8	5.20	16.4	3.19	2.08	1.30	
Inductance - $L_M$	mH	$\pm 30\%$	12	3.0	9.4	1.8	1.2	0.75	

# QT-3802

4.8 lb. ft.

PEAK TORQUE

RARE EARTH MAGNETS



**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH SEGMENT ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

.093 DIA. THRU CSINK 82° TO .180  
MIN. DIA. (4) HOLES EQ. SPACED ON  
4.281 DIA. B.C.

**LEADS:**

#24 AWG TEFLON COATED PER MIL  
W-16878, 12" MIN. LENGTH.

## SIZE CONSTANTS

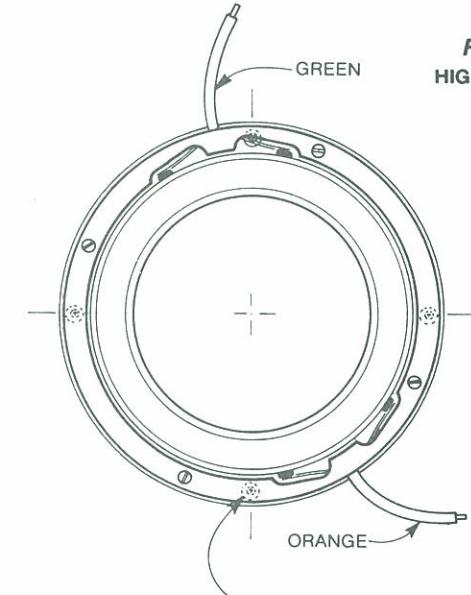
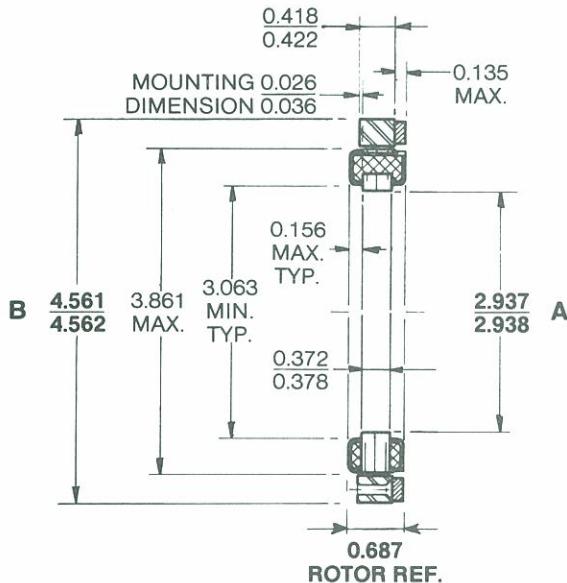
**Value      Units**

Peak Torque Rating - $T_p$	4.8	LB. FT.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	256	WATTS
Motor Constant - $K_M$	0.30	LB.FT./√WATT
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	39.3	RAD/S
Electrical Time Constant - $\tau_e$	0.84	MS
Static Friction (Max.) - $T_f$	0.10	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_1$	0.122 $2.0 \times 10^{-3}$
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	2.64	°C/WATT
Ripple Torque (Average to Peak) - $T_R$	6	PERCENT
Ripple Frequency (Fundamental)	89	CYCLES/REV.
Number of Poles	20	
Rotor Inertia - $J_M$	$7.2 \times 10^{-4}$	LB.FT.S <sup>2</sup>
Motor Weight	2.6	LB.

## WINDING CONSTANTS

*Winding Designation*

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	42.7	33.9	68.0				
Peak Current - $I_p$	AMPERES	Rated	6.00	7.77	3.78				
Torque Sensitivity - $K_T$	LB.FT./AMP	± 10%	0.800	0.618	1.27				
Back EMF Constant - $K_B$	V per RAD/S	± 10%	1.085	0.838	1.72				
DC Resistance ( $25^\circ\text{C}$ ) - $R_M$	OHMS	± 12.5%	7.11	4.36	18.0				
Inductance - $L_M$	mH	± 30%	6.0	3.6	15				

**NOTES:**

1. — MOTOR SUPPLIED AS THREE SEPARATE COMPONENTS: ROTOR ASSEMBLY, BRUSH RING ASSEMBLY, AND STATOR WITH KEEPER. CAUTION: DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH A POSITIVE CURRENT APPLIED TO GREEN LEAD WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING THE BRUSH RING SIDE.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
5. — GOLD PLATED COMMUTATOR.

(0.125) DIA. THRU CSINK 82° TO 0.260  
MIN. DIA. (4) HOLES EQ. SPACED ON  
4.188 DIA. B.C.

**LEADS:**  
#24 AWG TYPE "E"TEFLON COATED,  
6" MIN. LENGTH.

**SIZE CONSTANTS****Value      Units**

Peak Torque Rating - $T_p$	1.0	LB. FT.	
Power Input, Stalled at $T_p$ (25°C) - $P_p$	50	WATTS	
Motor Constant - $K_M$	0.14	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	36	RAD/S	
Electrical Time Constant - $\tau_E$	0.84	MS	
Static Friction (Max.) - $T_f$	0.042	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.027	LB. FT. PER RAD/S
	Infinite Impedance - $F_i$	$7.3 \times 10^{-4}$	LB. FT. PER RAD/S
Maximum Winding Temperature	105	°C	
Temperature Rise per Watt - $TPR$	5.9	°C/WATT	
Ripple Torque (Average to Peak) - $T_R$	5	PERCENT	
Ripple Frequency - (Fundamental)	79	CYCLES/REV.	
Number of Poles	16		
Rotor Inertia - $J_M$	$3.4 \times 10^{-4}$	LB.FT.S <sup>2</sup>	
Motor Weight	1.1	LB.	

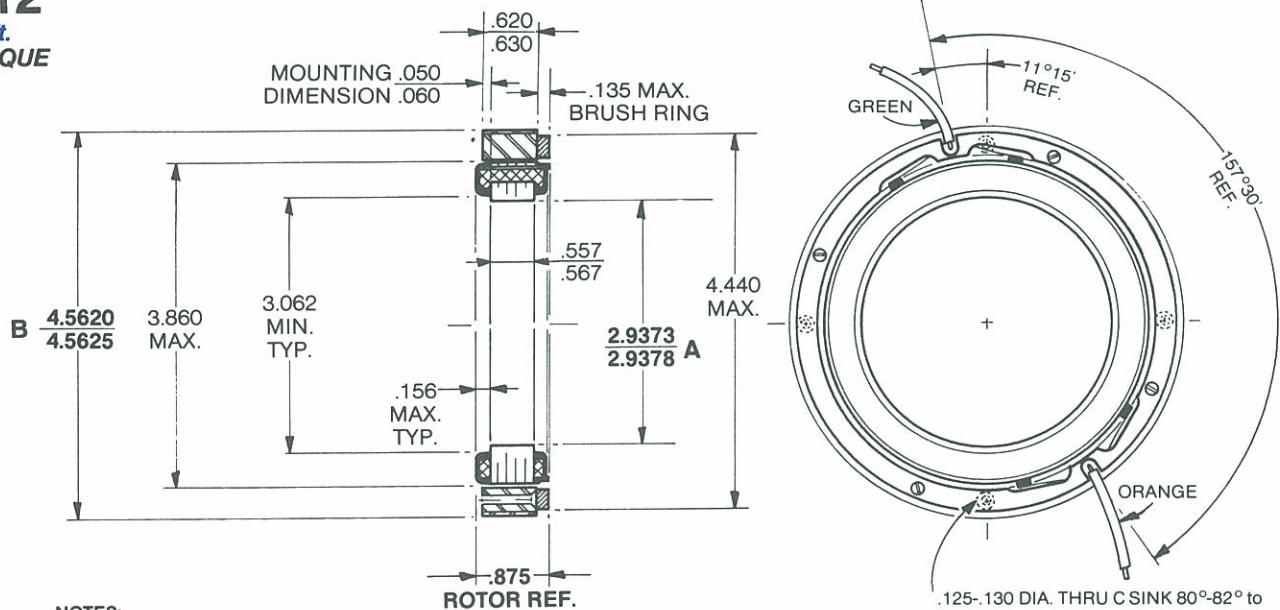
**WINDING CONSTANTS****Winding Designation**

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ (25°C) - $V_p$	VOLTS	Nom.	55.5	34.6	85.9	76.3	42.9	21.8	13.9
Peak Current - $I_p$	AMPERES	Rated	0.893	1.42	0.565	0.641	1.13	2.25	3.63
Torque Sensitivity - $K_T$	LB.FT./AMP	± 10%	1.12	0.703	1.77	1.56	0.885	0.444	0.275
Back EMF Constant - $K_B$	V per RAD/S	± 10%	1.52	0.953	2.40	2.11	1.20	0.602	0.373
DC Resistance (25°C) - $R_m$	OHMS	± 12.5%	62.2	24.4	152	119	38.0	9.70	3.82
Inductance - $L_M$	mH	± 30%	52	20	130	103	32	8.0	3.1

# T-3912

1.2 lb. ft.

PEAK TORQUE



**NOTES:**

1. — MOTOR SUPPLIED AS THREE SEPARATE COMPONENTS: ROTOR ASSEMBLY, STATOR WITH-KEEPER, AND BRUSH RING ASSEMBLY. **CAUTION:** DO NOT REMOVE KEEPER UNLESS ROTOR IS FULLY IN PLACE.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH A POSITIVE CURRENT APPLIED TO GREEN LEAD WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. WHEN VIEWED FROM BRUSH SIDE.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
5. — GOLD PLATED COMMUTATOR.

.125-.130 DIA. THRU C SINK 80°-82° to  
.26-.28 DIA. (4) HOLES EQ. SPACED ON  
4.188 DIA. B.C.

**LEADS:**  
#24 AWG TYPE "E" TEFLON COATED  
8" MIN. LENGTH.

## SIZE CONSTANTS

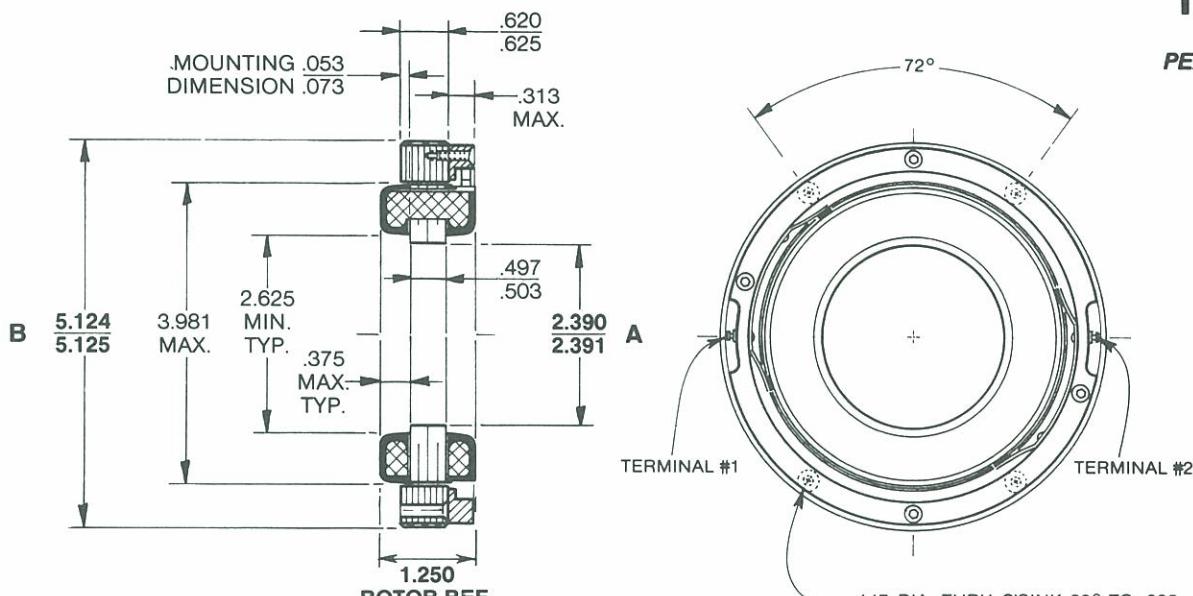
**Value      Units**

Peak Torque Rating - $T_p$	1.2	LB. FT.
Power Input, Stalled at $T_p$ (25°C) - $P_p$	34.8	WATTS
Motor Constant - $K_M$	0.201	LB.FT./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	21.6	RAD/S
Electrical Time Constant - $\tau_E$	1.25	MS
Static Friction (Max.) - $T_f$	0.05	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_1$	0.055      0.0027
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - TPR	4.6	°C/WATT
Ripple Torque (Average to Peak) - $T_R$	5.0	PERCENT
Ripple Frequency - (Fundamental)	79	CYCLES/REV.
Number of Poles	16	
Rotor Inertia - $J_M$	$6.11 \times 10^{-4}$	LB.FT.S <sup>2</sup>
Motor Weight	1.9	LB.

## WINDING CONSTANTS

*Winding Designation*

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ (25°C) - $V_p$	VOLTS	Nom.	10.6	21.2	42.6	85.1	33.8	26.9	
Peak Current - $I_p$	AMPERES	Rated	3.3	1.67	0.833	0.417	1.06	1.33	
Torque Sensitivity - $K_T$	LB.FT./AMP	± 10%	0.36	0.72	1.44	2.88	1.13	0.90	
Back EMF Constant - $K_B$	V PER RAD/S	± 10%	0.49	0.98	1.95	3.90	1.53	1.22	
DC Resistance (25°C) - $R_M$	OHMS	± 12.5%	3.2	12.8	51.2	204	31.9	20.2	
Inductance - $L_M$	mH	± 30%	4.0	16.0	64	250	39	25	



**NOTES:**

1. — MOTOR SUPPLIED AS THREE SEPARATE COMPONENTS: ROTOR ASSEMBLY, BRUSH ASSEMBLY, AND STATOR WITH KEEPER. **CAUTION:** DO NOT REMOVE KEEPER UNLESS ROTOR IS FULLY IN PLACE.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO TERMINAL #1 ROTATION SHALL BE C.C.W. WHEN VIEWED FROM THE BRUSH RING SIDE.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

### SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>
Peak Torque Rating - $T_p$	1.8	LB. FT.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	87.8	WATTS
Motor Constant - $K_m$	0.19	LB.FT./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	36	RAD/S
Electrical Time Constant - $\tau_e$	1.79	MS
Static Friction (Max.) - $F_f$	0.035	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	0.049      0.001
Maximum Winding Temperature	105	°C
Temperature Rise per Watt - $TPR$	3.3	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT
Ripple Frequency - (Fundamental)	56	CYCLES/REV.
Number of Poles	10	
Rotor Inertia - $J_m$	$8.7 \times 10^{-4}$	LB.FT.S <sup>2</sup>
Motor Weight	2.9	LB.

### WINDING CONSTANTS

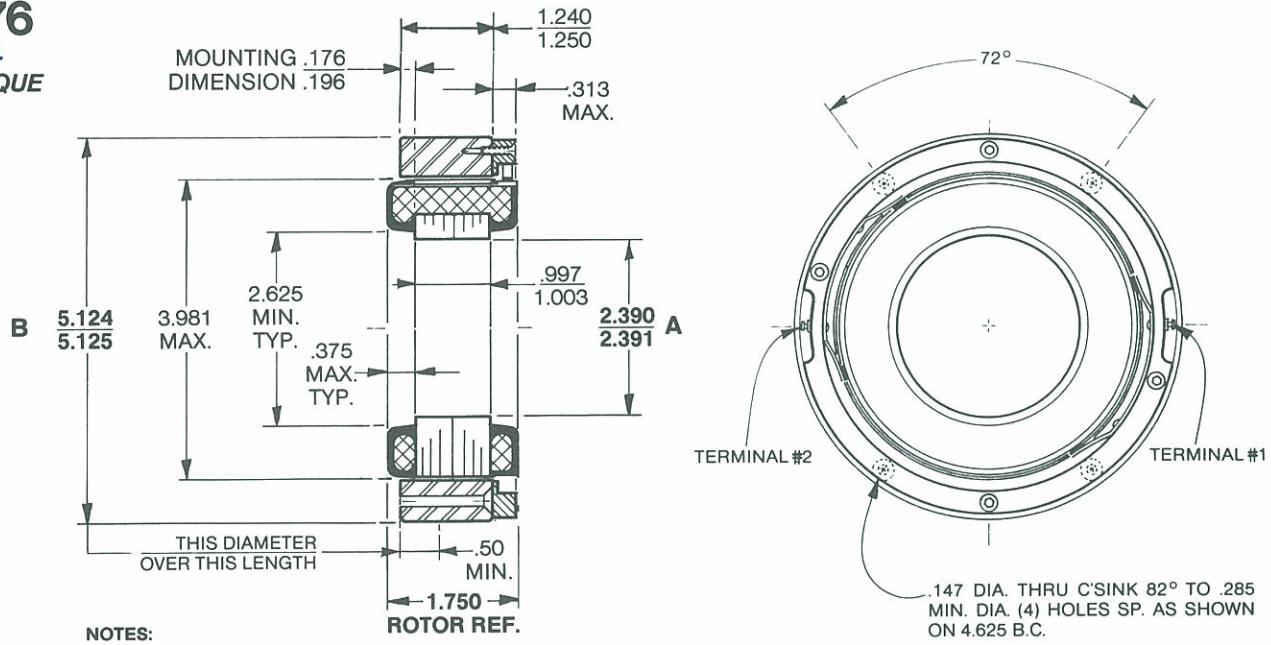
### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	15.7	19.7	25.3	31.4	39.4	50.6	100
Peak Current - $I_p$	AMPERES	Rated	5.60	4.60	3.70	2.90	2.30	1.80	0.90
Torque Sensitivity - $K_t$	LB.FT./AMP	$\pm 10\%$	0.320	0.390	0.490	0.630	0.790	1.00	2.00
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.434	0.530	0.660	0.850	1.10	1.36	2.70
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5$	2.80	4.30	6.90	11.0	17.3	28.1	111
Inductance - $L_m$	mH	$\pm 30\%$	5.0	8.0	13	21	33	52	210

# T-4076

3.6 lb. ft.

PEAK TORQUE



NOTES:

- MOTOR SUPPLIED AS THREE SEPARATE COMPONENTS: ROTOR ASSEMBLY, BRUSH RING ASSEMBLY, AND STATOR WITH (8) KEEPERS. **CAUTION:** DO NOT REMOVE KEEPERS UNLESS ROTOR IS FULLY IN PLACE.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO TERMINAL #1 ROTATION SHALL BE C.C.W. WHEN VIEWED FROM THE BRUSH RING SIDE.
- TYPICAL BRUSH LIFE > 107 REV.
- GOLD PLATED COMMUTATOR.

## SIZE CONSTANTS

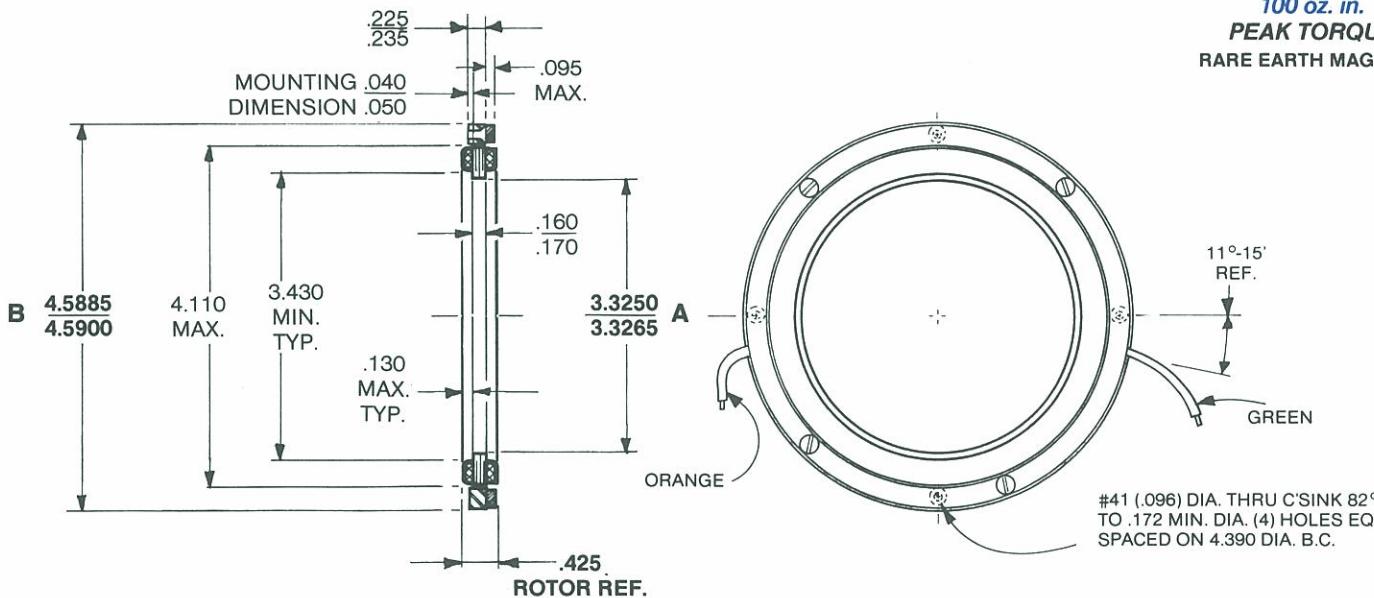
**Value      Units**

Peak Torque Rating - $T_p$	3.6	LB. FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	127	WATTS	
Motor Constant - $K_m$	0.32	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	26	RAD/S	
Electrical Time Constant - $\tau_e$	2.7	MS	
Static Friction (Max.) - $T_f$	.052	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	0.137      .002	LB. FT. PER RAD/S      LB. FT. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - TPR	1.2	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT	
Ripple Frequency - (Fundamental)	56	CYCLES/REV.	
Number of Poles	10		
Rotor Inertia - $J_m$	.0014	LB.FT.S <sup>2</sup>	
Motor Weight	5.6	LB.	

## WINDING CONSTANTS

*Winding Designation*

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	27.7	22.0	17.5	69.7	55.2		
Peak Current - $I_p$	AMPERES	Rated	4.7	5.8	7.60	1.82	2.30		
Torque Sensitivity - $K_t$	LB.FT./AMP	±10%	0.77	0.62	0.474	1.98	1.57		
Back EMF Constant - $K_b$	V per RAD/S	±10%	1.05	0.84	0.643	2.68	2.13		
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	±12.5%	5.9	3.8	2.30	38.3	24.0		
Inductance - $L_m$	mH	±30%	16	10.4	6.1	100	66		



**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .004 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE  $\times 10^7$  REV.

**LEADS:**

#26 AWG TEFLON COATED PER MIL W-16878, 12" MIN. LENGTH.

### SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>	
Peak Torque Rating - $T_p$	100	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	76	WATTS	
Motor Constant - $K_m$	11.5	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	107	RAD/S	
Electrical Time Constant - $\tau_E$	0.15	MS	
Static Friction (Max.) - $T_f$	4.0	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.93	OZ. IN. PER RAD/S
	Infinite Impedance - $F_\infty$	0.02	OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	6	°C/WATT	
Ripple Torque (Average to Peak) - $T_R$	6	PERCENT	
Ripple Frequency (Fundamental)	79	CYCLES/REV.	
Number of Poles	16		
Rotor Inertia - $J_M$	0.047	OZ.IN.S <sup>2</sup>	
Motor Weight	9.5	OZ.	

### WINDING CONSTANTS

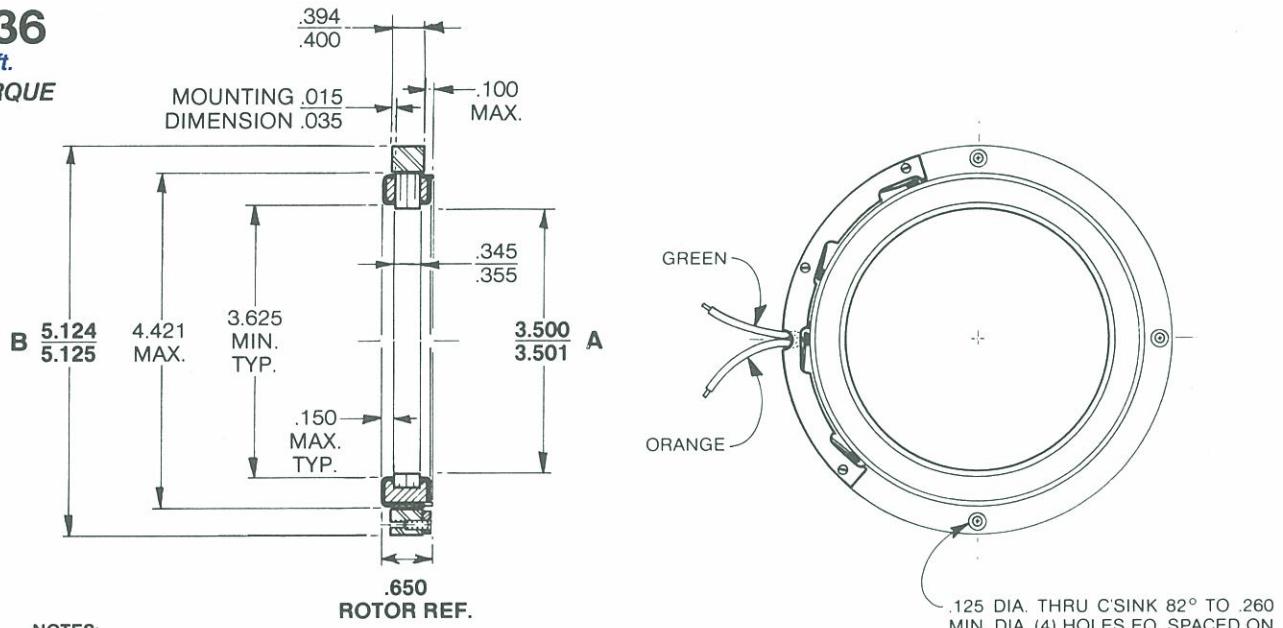
### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	19.7						
Peak Current - $I_p$	AMPERES	Rated	3.97						
Torque Sensitivity - $K_T$	OZ.IN./AMP	$\pm 10\%$	25.2						
Back EMF Constant - $K_B$	V per RAD/S	$\pm 10\%$	0.18						
DC Resistance ( $25^\circ\text{C}$ ) - $R_M$	OHMS	$\pm 12.5\%$	4.95						
Inductance - $L_M$	mH	$\pm 30\%$	0.70						

# T-4436

1.0 lb. ft.

PEAK TORQUE



NOTES:

- MOTOR SUPPLIED AS THREE SEPARATE COMPONENTS: ROTOR ASSEMBLY, BRUSH RING ASSEMBLY, AND STATOR WITH KEEPER. **CAUTION:** DO NOT REMOVE KEEPER UNLESS ROTOR IS FULLY IN PLACE.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .003 (.006 T.I.R.) WHEN MOUNTED.
- WITH A POSITIVE CURRENT APPLIED TO GREEN LEAD ROTATION SHALL BE C.C.W. FACING BRUSH RING SIDE.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
- GOLD PLATED COMMUTATOR.

.125 DIA. THRU CSINK 82° TO .260  
MIN. DIA. (4) HOLES EQ. SPACED ON  
4.750 DIA. B.C.

LEADS:  
#26 AWG TYPE "E" TEFLON COATED  
18" MIN. LENGTH.

## SIZE CONSTANTS

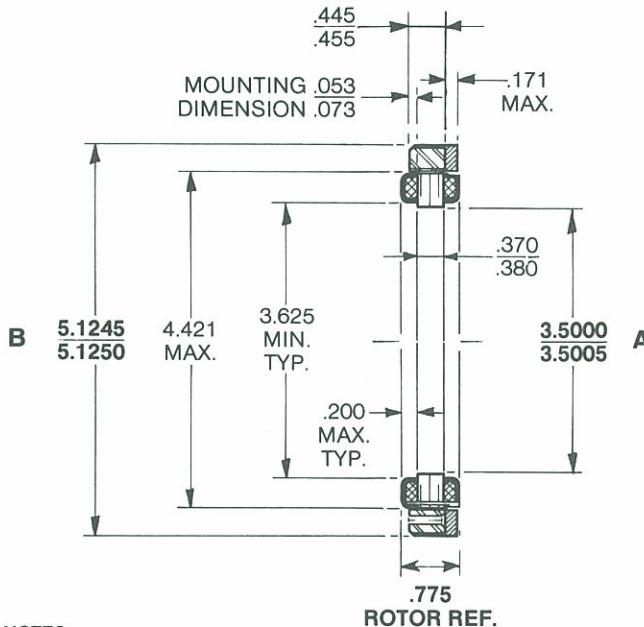
	Value	Units	
Peak Torque Rating - $T_p$	1.0	LB. FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	70	WATTS	
Motor Constant - $K_m$	0.12	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p - \omega_{NL}$	51	RAD/S	
Electrical Time Constant - $\tau_e$	0.70	MS	
Static Friction (Max.) - $T_f$	0.03	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_\infty$	0.02 $4.2 \times 10^{-4}$	LB. FT. PER RAD/S      LB. FT. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	4.0	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	4.5	PERCENT	
Ripple Frequency - (Fundamental)	79	CYCLES/REV.	
Number of Poles	16		
Rotor Inertia - $J_m$	$5.5 \times 10^{-4}$	LB.FT.S <sup>2</sup>	
Motor Weight	1.2	LB.	

## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	*B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	21.0	10.7	12.0	23.6			
Peak Current - $I_p$	AMPERES	Rated	3.33	6.70	6.13	2.96			
Torque Sensitivity - $K_t$	LB.FT./AMP.	±10%	0.300	0.150	0.163	0.338			
Back EMF Constant - $K_b$	V per RAD/S	±10%	0.407	0.203	0.221	0.458			
DC Resistance (25°C) - $R_m$	OHMS	±12.5%	6.30	1.60	1.95	7.96			
Inductance - $L_m$	mH	±30%	4.4	1.1	1.3	5.6			

\*SPECIAL WINDING. HIGH BRUSH CURRENT DENSITY

**NOTES:**

1. MOTOR SUPPLIED AS THREE SEPARATE COMPONENTS: ROTOR ASSEMBLY, BRUSH ASSEMBLY, AND STATOR WITH KEEPER. **CAUTION:** DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
2. MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. WITH POSITIVE CURRENT APPLIED TO BLACK LEAD ROTATION SHALL BE C.C.W. FACING THE BRUSH RING SIDE.
4. TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

.125 DIA. THRU C'SINK 82° TO .260  
MIN. DIA. (4) HOLES SPACED AS  
SHOWN ON 4.750 DIA. R.C.

**LEADS:**  
#24 AWG TEFLON COATED TYPE "EE"  
12" MIN. LENGTH.

**SIZE CONSTANTS****Value      Units**

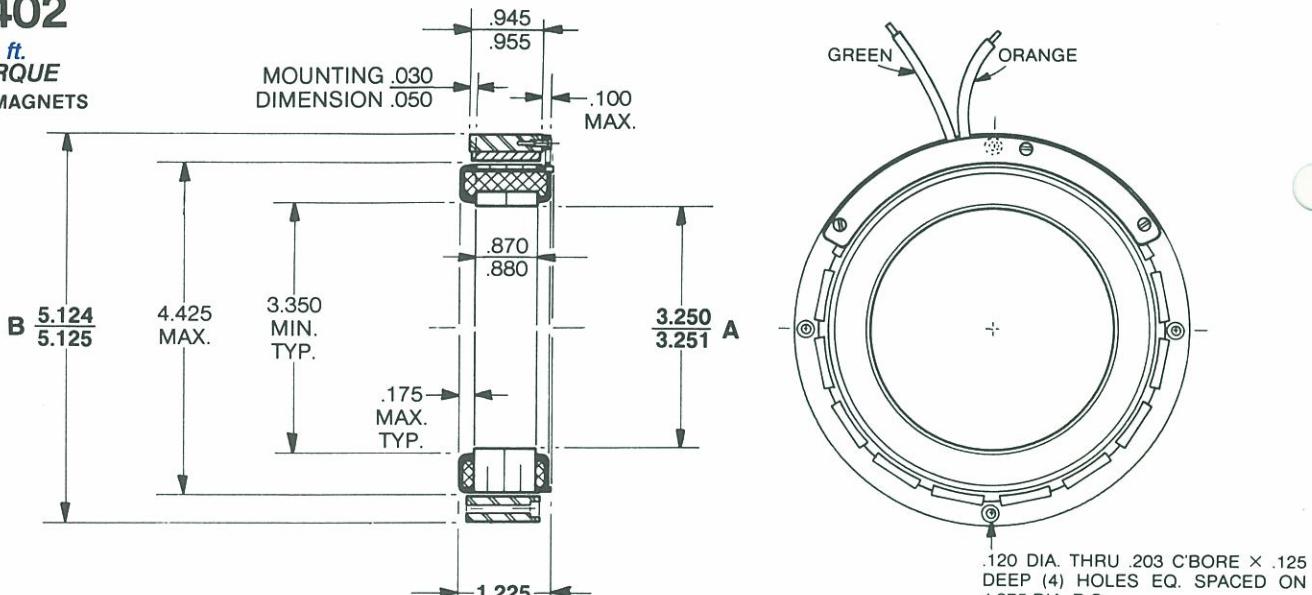
Peak Torque Rating - $T_p$	1.52	LB. FT.						
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	120	WATTS						
Motor Constant - $K_M$	0.139	LB.FT./ $\sqrt{\text{WATT}}$						
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	58	RAD/S						
Electrical Time Constant - $\tau_E$	0.84	MS						
Static Friction (Max.) - $T_f$	0.04	LB. FT.						
Viscous Damping Coefficients	<table style="width: 100%; border-collapse: collapse;"> <tr> <td style="width: 30%;">Zero Impedance - <math>F_0</math></td> <td style="width: 70%;">2.6 × 10<sup>-2</sup></td> </tr> <tr> <td>Infinite Impedance - <math>F_i</math></td> <td>0.001</td> </tr> </table>	Zero Impedance - $F_0$	2.6 × 10 <sup>-2</sup>	Infinite Impedance - $F_i$	0.001	<table style="width: 100%; border-collapse: collapse;"> <tr> <td style="width: 30%;">LB. FT. PER RAD/S</td> <td style="width: 70%;">LB. FT. PER RAD/S</td> </tr> </table>	LB. FT. PER RAD/S	LB. FT. PER RAD/S
Zero Impedance - $F_0$	2.6 × 10 <sup>-2</sup>							
Infinite Impedance - $F_i$	0.001							
LB. FT. PER RAD/S	LB. FT. PER RAD/S							
Maximum Winding Temperature	105	°C						
Temperature Rise per Watt - $TPR$	2.9	°C/WATT						
Ripple Torque (Average to Peak) - $T_R$	5	PERCENT						
Ripple Frequency - (Fundamental)	71	CYCLES/REV.						
Number of Poles	16							
Rotor Inertia - $J_M$	6.2 × 10 <sup>-4</sup>	LB.FT.S <sup>2</sup>						
Motor Weight	1.5	LB.						

**WINDING CONSTANTS****Winding Designation**

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	31.5	40.8	50.7	62.7	84.0	105	24.8
Peak Current - $I_p$	AMPERES	Rated	3.80	3.00	2.40	1.90	1.60	1.30	4.55
Torque Sensitivity - $K_T$	LB.FT./AMP	±10%	0.400	0.500	0.630	0.780	0.950	1.20	0.330
Back EMF Constant - $K_B$	V per RAD/S	±10%	0.542	0.680	0.850	1.10	1.30	1.60	0.450
DC Resistance (25°C) - $R_M$	OHMS	±12.5%	8.30	13.6	21.3	32.7	53.2	84.1	5.45
Inductance - $L_M$	mH	±30%	7.0	11	18	27	44	69	5.0

# QT-4402

**4.24 lb. ft.**  
**PEAK TORQUE**  
RARE EARTH MAGNETS



#### NOTES:

1. — MOTOR SUPPLIED AS THREE SEPARATE COMPONENTS: ROTOR ASSEMBLY, STATOR, AND BRUSH SEGMENT ASSEMBLY.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH A POSITIVE CURRENT APPLIED TO GREEN LEAD WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.W. FACING BRUSH RING SIDE.
4. — TYPICAL BRUSH LIFE  $\times 10^7$  REV.
5. — GOLD PLATED COMMUTATOR.

#### LEADS:

#24 AWG TYPE "ET" TEFLO COATED  
— 19 STRAND — PER MIL-W-16878 12"  
MIN. LENGTH.

## SIZE CONSTANTS

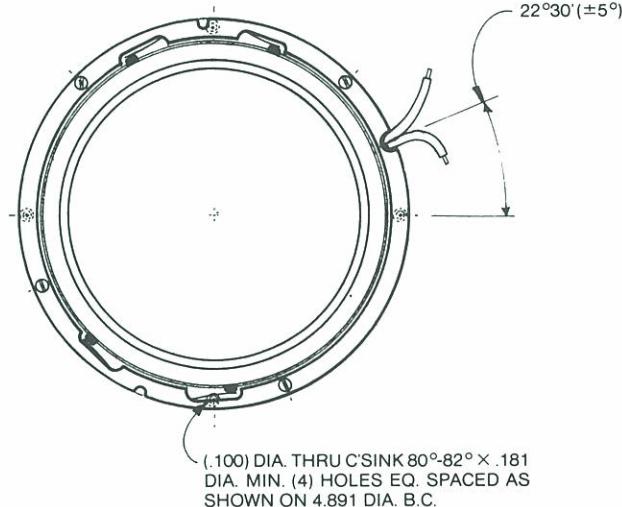
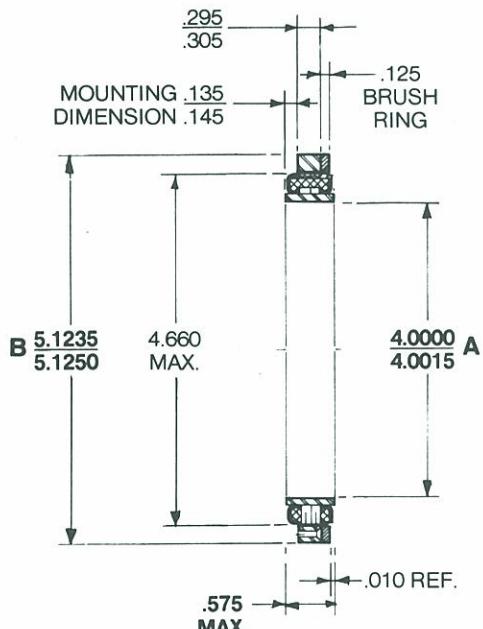
### Value      Units

Peak Torque Rating - $T_p$	4.24	LB. FT.	
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	160	WATTS	
Motor Constant - $K_m$	0.335	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	27.7	RAD/S	
Electrical Time Constant - $\tau_e$	1.10	MS	
Static Friction (Max.) - $T_f$	0.12	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.153	LB. FT. PER RAD/S
	Infinite Impedance - $F_i$	$1.75 \times 10^{-2}$	LB. FT. PER RAD/S
Maximum Winding Temperature	155	$^\circ\text{C}$	
Temperature Rise per Watt - $TPR$	1.9	$^\circ\text{C}/\text{WATT}$	
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT	
Ripple Frequency - (Fundamental)	71	CYCLES/REV.	
Number of Poles	16		
Rotor Inertia - $J_m$	$1.52 \times 10^{-3}$	LB.FT.S <sup>2</sup>	
Motor Weight	3.0	LB.	

## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	40.0						
Peak Current - $I_p$	AMPERES	Rated	4.00						
Torque Sensitivity - $K_t$	LB.FT./AMP	$\pm 10\%$	1.06						
Back EMF Constant - $K_b$	V PER RAD/S	$\pm 10\%$	1.44						
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	10.0						
Inductance - $L_m$	mH	$\pm 30\%$	11						



**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: ROTOR, STATOR WITH KEEPER, AND BRUSH RING ASSEMBLY. CAUTION: DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .0005 in./in.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, ROTATION SHALL BE C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
5. — GOLD PLATED COMMUTATOR.

LEADS:  
#26 AWG TYPE 'E' TEFILON COATED  
PER MIL W-16878, 18" MIN. LG.

### SIZE CONSTANTS

		<b>Value</b>	<b>Units</b>
Peak Torque Rating - $T_p$		0.80	LB. FT.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$		200	WATTS
Motor Constant - $K_m$		0.057	LB.FT./√ WATT
No Load Speed, Theoretical @ $V_p$ , $\omega_{NL}$		184	RAD/S
Electrical Time Constant - $\tau_e$		0.467	MS
Static Friction (Max.) - $T_f$		0.025	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_\infty$	$4.33 \times 10^{-3}$ $3.0 \times 10^{-4}$	LB. FT. PER RAD/S      LB. FT. PER RAD/S
Maximum Winding Temperature		155	°C
Temperature Rise per Watt - $TPR$		4.9	°C/WATT
Ripple Torque (Average to Peak) - $T_r$		5	PERCENT
Ripple Frequency - (Fundamental)		79	CYCLES/REV.
Number of Poles		16	
Rotor Inertia - $J_m$		$4.8 \times 10^{-4}$	LB.FT.S <sup>2</sup>
Motor Weight		0.83	LB.

### WINDING CONSTANTS

### Winding Designation

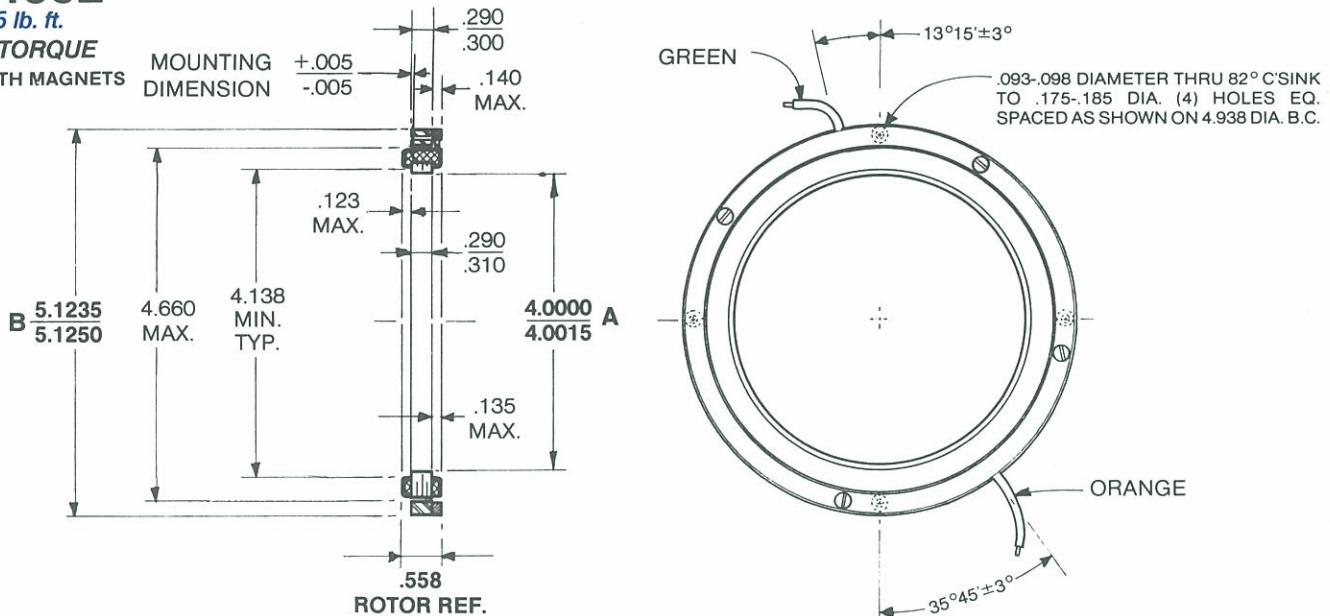
	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	59.9	21.6	39.0	49.7	30.4	17.2	
Peak Current - $I_p$	AMPERES	Rated	3.33	10.0	5.34	4.25	6.45	12.9	
Torque Sensitivity - $K_t$	LB. FT./AMP	± 10%	0.240	0.080	0.150	0.190	0.120	0.062	
Back EMF Constant - $K_b$	V per RAD/S	± 10%	0.325	0.110	0.200	0.260	0.160	0.086	
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	± 12.5%	18.0	2.16	7.30	11.7	4.70	1.33	
Inductance - $L_m$	mH	± 30%	8.4	0.90	3.3	5.1	2.2	0.54	

# QT-4602

0.85 lb. ft.

## PEAK TORQUE

RARE EARTH MAGNETS



### NOTES:

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY AND STATOR ASSEMBLY.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .003 (.006 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

### LEADS:

#22 AWG TYPE "E" TEFLON COATED PER MIL W-16878, 12" MIN. LENGTH.

## SIZE CONSTANTS

### Value

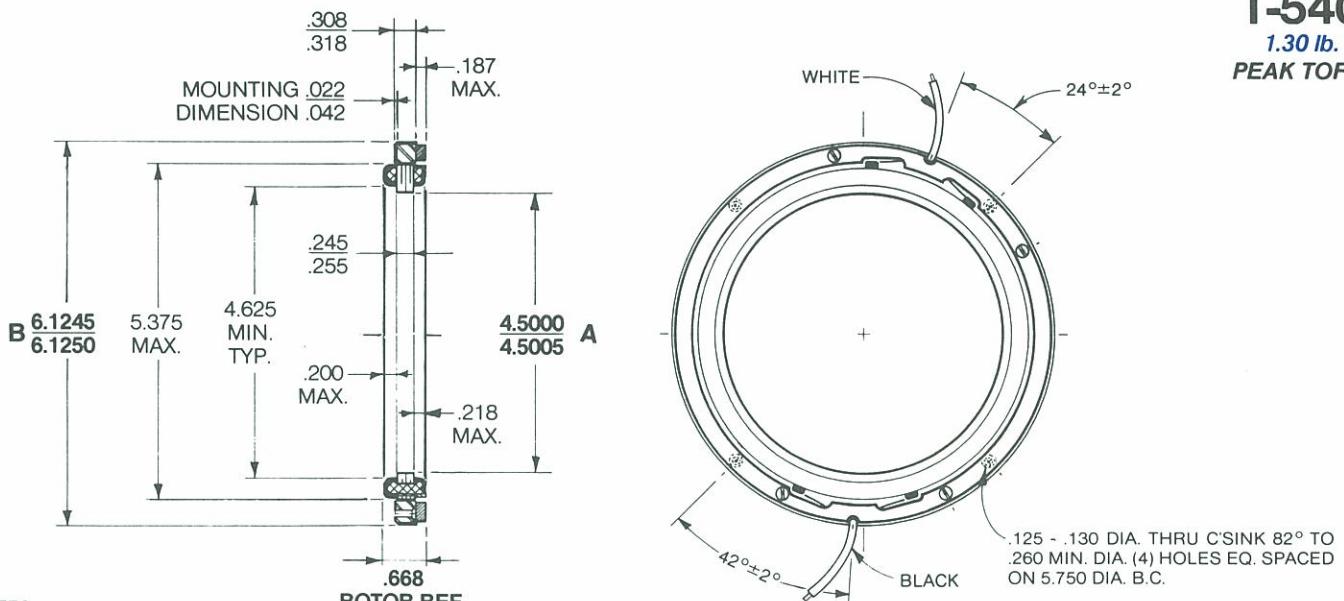
### Units

Peak Torque Rating - $T_p$	0.85	LB. FT.						
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	211	WATTS						
Motor Constant - $K_m$	0.059	LB.FT./ $\sqrt{\text{WATT}}$						
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	183	RAD/S						
Electrical Time Constant - $\tau_e$	0.265	MS						
Static Friction (Max.) - $T_f$	0.026	LB. FT.						
Viscous Damping Coefficients	<table border="0"><tr><td>Zero Impedance - <math>F_0</math></td><td>4.62 × 10<sup>-3</sup></td><td>LB. FT. PER RAD/S</td></tr><tr><td>Infinite Impedance - <math>F_\infty</math></td><td>3.00 × 10<sup>-4</sup></td><td>LB. FT. PER RAD/S</td></tr></table>	Zero Impedance - $F_0$	4.62 × 10 <sup>-3</sup>	LB. FT. PER RAD/S	Infinite Impedance - $F_\infty$	3.00 × 10 <sup>-4</sup>	LB. FT. PER RAD/S	
Zero Impedance - $F_0$	4.62 × 10 <sup>-3</sup>	LB. FT. PER RAD/S						
Infinite Impedance - $F_\infty$	3.00 × 10 <sup>-4</sup>	LB. FT. PER RAD/S						
Maximum Winding Temperature	155	°C						
Temperature Rise per Watt - TPR	5.0	°C/WATT						
Ripple Torque (Average to Peak) - $T_r$	7	PERCENT						
Ripple Frequency (Fundamental)	79	CYCLES/REV.						
Number of Poles	16							
Rotor Inertia - $J_m$	$4.30 \times 10^{-4}$	LB.FT.S <sup>2</sup>						
Motor Weight	0.83	LB.						

## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	49.7	31.3	19.8				
Peak Current - $I_p$	AMPERES	Rated	4.25	6.38	9.92				
Torque Sensitivity - $K_t$	LB.FT./AMP	± 10%	0.200	0.133	0.0857				
Back EMF Constant - $K_b$	V per RAD/S	± 10%	0.271	0.181	0.116				
DC Resistance (25°C) - $R_m$	OHMS		11.7	4.91	2.00				
Inductance - $L_m$	mH	± 30%	3.1	1.4	0.57				



**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: ROTOR, STATOR WITH KEEPER, AND BRUSH RING ASSEMBLY. **CAUTION:** DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002/.004 T.I.R. WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO BLACK LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
5. — GOLD PLATED COMMUTATOR.

**LEADS:**  
#24 AWG TYPE 'E' TEFLON COATED 6"  
MIN. LG.

### SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>	
Peak Torque Rating - $T_p$	1.30	LB. FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	120	WATTS	
Motor Constant - $K_M$	0.119	LB.FT./√ WATT	
No Load Speed, Theoretical @ $V_p \cdot \omega_{NL}$	68	RAD/S	
Electrical Time Constant - $\tau_E$	0.672	MS	
Static Friction (Max.) - $T_f$	0.04	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_\infty$	0.019      0.001	LB. FT. PER RAD/S      LB. FT. PER RAD/S
Maximum Winding Temperature	105	°C	
Temperature Rise per Watt - $TPR$	3.1	°C/WATT	
Ripple Torque (Average to Peak) - $T_R$	5	PERCENT	
Ripple Frequency - (Fundamental)	89	CYCLES/REV.	
Number of Poles	20		
Rotor Inertia - $J_M$	$8.6 \times 10^{-4}$	LB.FT.S <sup>2</sup>	
Motor Weight	1.15	LB.	

### WINDING CONSTANTS

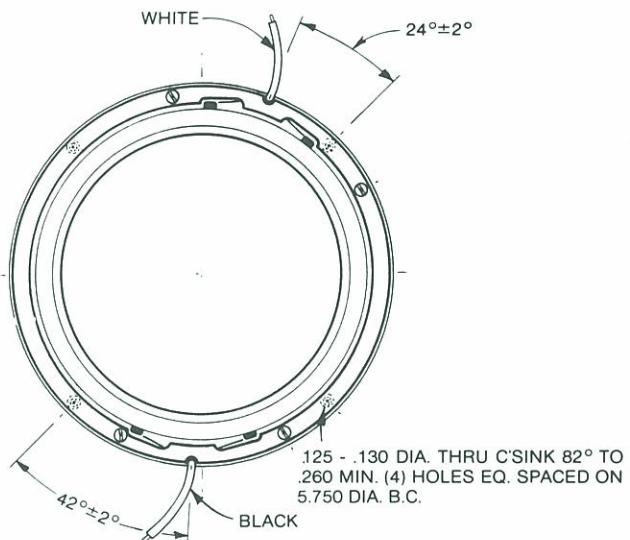
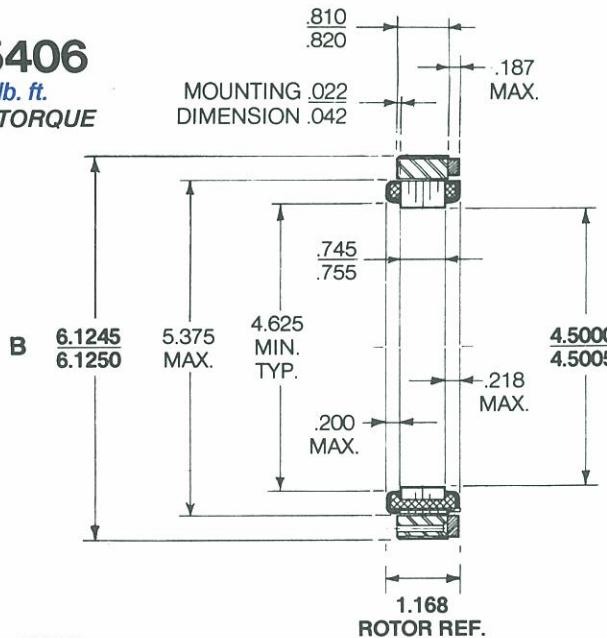
### Winding Designation

	<b>UNITS</b>	<b>TOLERANCES</b>	<b>A</b>	<b>B</b>	<b>C</b>	<b>D</b>	<b>E</b>	<b>F</b>	<b>G</b>
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	<b>VOLTS</b>	Nom.	40.6	51.7	62.4	80.0	102	25.6	19.5
Peak Current - $I_p$	<b>AMPERES</b>	Rated	2.96	2.32	1.88	1.50	1.18	4.64	6.10
Torque Sensitivity - $K_T$	<b>LB. FT./AMP</b>	±10%	0.440	0.560	0.690	0.870	1.10	0.280	0.210
Back EMF Constant - $K_B$	<b>V per RAD/S</b>	±10%	0.597	0.760	0.940	1.20	1.50	0.380	0.280
DC Resistance (25°C) - $R_M$	<b>OHMS</b>	±12.5%	13.7	22.3	33.2	53.5	86.9	5.50	3.20
Inductance - $L_M$	<b>mH</b>	±30%	9.2	15	22	36	58	3.5	2.0

# T-5406

2 lb. ft.

PEAK TORQUE



**NOTES:**

- MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: ROTOR, STATOR WITH KEEPER, AND BRUSH RING ASSEMBLY. **CAUTION:** DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002(.004 T.I.R.) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO BLACK LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
- GOLD PLATED COMMUTATOR.

**LEADS:**  
#24 AWG TYPE 'E' TEFLON COATED  
30" MIN. LG.

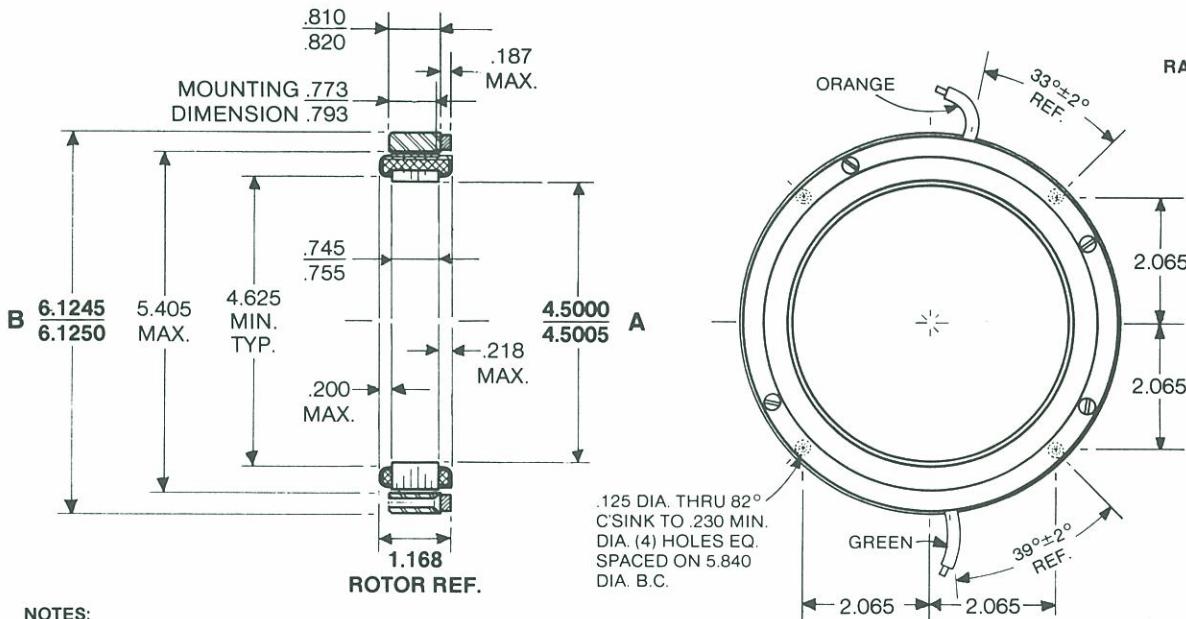
## SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>
Peak Torque Rating - $T_p$	2	LB. FT.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	52	WATTS
Motor Constant - $K_m$	0.28	LB.FT./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p, \omega_{NL}$	19.17	RAD/S
Electrical Time Constant - $\tau_e$	1.5	MS
Static Friction (Max.) - $T_f$	0.12	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	0.100      0.003
Maximum Winding Temperature	105	°C
Temperature Rise per Watt - TPR	2	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	6	PERCENT
Ripple Frequency - (Fundamental)	89	CYCLES/REV.
Number of Poles	20	
Rotor Inertia - $J_m$	$1.5 \times 10^{-3}$	LB.FT.S <sup>2</sup>
Motor Weight	3.0	LB.

## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	26.0	16.3	41.3	52.1			
Peak Current - $I_p$	AMPERES	Rated	2.00	3.28	1.27	1.02			
Torque Sensitivity - $K_t$	LB. FT./AMP	± 10%	1.00	0.610	1.57	1.96			
Back EMF Constant - $K_b$	V per RAD/S	± 10%	1.36	0.827	2.13	2.66			
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	± 12.5%	13.0	4.96	32.5	51.1			
Inductance - $L_m$	mH	± 30%	20	7.4	49	77			

**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**LEADS:**

#20 AWG 19-STRAND TYPE "E" TEF-LON COATED PER MIL W-16878 12" MIN. LG.

**SIZE CONSTANTS**

	<b>Value</b>	<b>Units</b>
Peak Torque Rating - $T_p$	5.0	LB. FT.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	227	WATTS
Motor Constant - $K_M$	0.33	LB.FT./√WATT
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	33	RAD/S
Electrical Time Constant - $\tau_E$	0.60	MS
Static Friction (Max.) - $T_f$	0.15	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	0.15   0.003
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	2.0	°C/WATT
Ripple Torque (Average to Peak) - $T_R$	7	PERCENT
Ripple Frequency (Fundamental)	89	CYCLES/REV.
Number of Poles	20	
Rotor Inertia - $J_M$	$1.9 \times 10^{-3}$	LB.FT.S <sup>2</sup>
Motor Weight	2.9	LB.

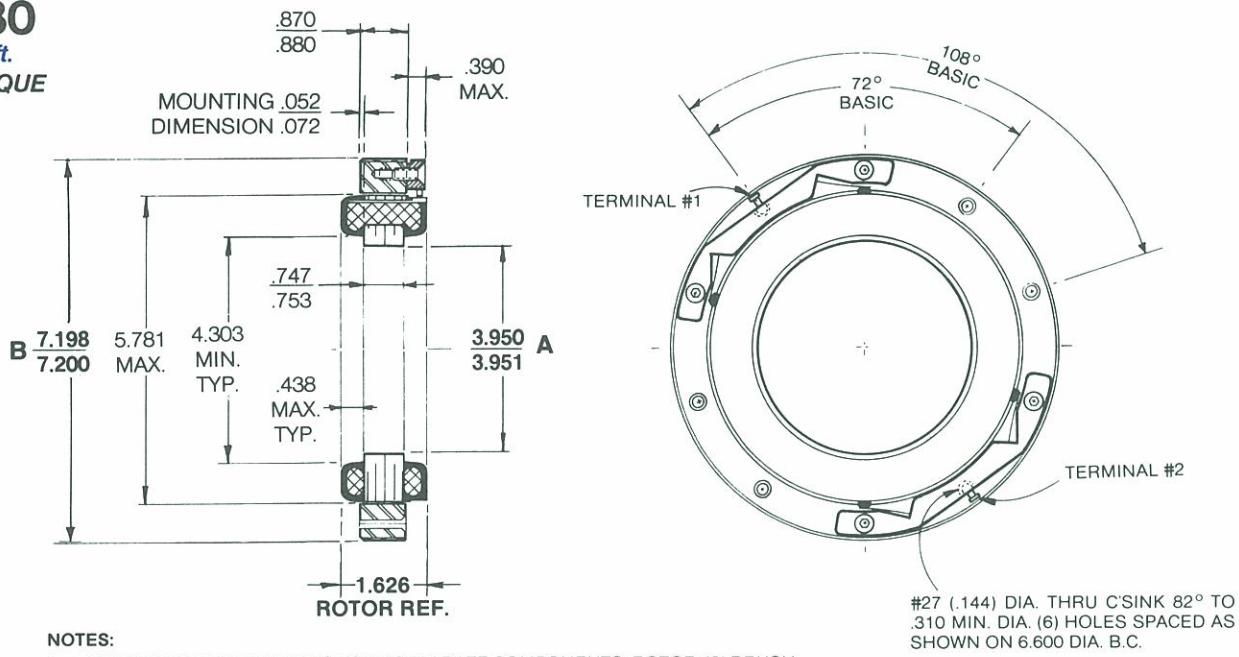
**WINDING CONSTANTS****Winding Designation**

UNITS	TOLERANCES	A	B	C	D	E	F	G
VOLTS	Nom.	18.5	30.8	24.6	64.9	51.6	40.6	
AMPERES	Rated	12.3	6.15	7.94	3.09	3.97	5.00	
LB.FT./AMP	± 10%	0.405	0.810	0.630	1.62	1.26	1.00	
V per RAD/S	± 10%	0.549	1.10	0.854	2.20	1.71	1.36	
OHMS	± 12.5%	1.50	5.00	3.10	21.0	13.0	8.11	
mH	± 30%	0.90	3.6	2.2	14	8.8	5.5	

# T-5730

7.00 lb. ft.

PEAK TORQUE



NOTES:

- MOTOR TO BE SUPPLIED AS FOUR SEPARATE COMPONENTS: ROTOR, (2) BRUSH RING ASSEMBLIES, AND STATOR WITH KEEPER. CAUTION: DO NOT REMOVE KEEPER UNLESS ROTOR IS FULLY IN PLACE.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO TERMINAL #1, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

## SIZE CONSTANTS

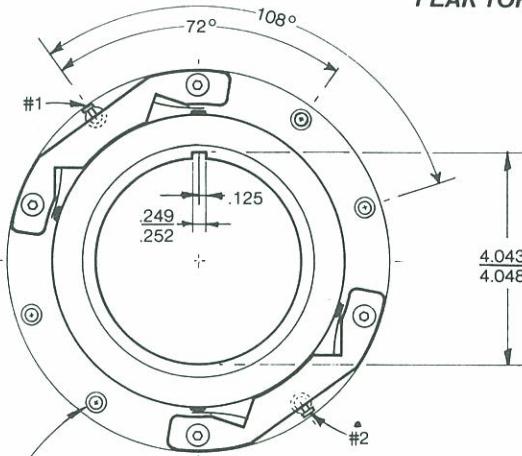
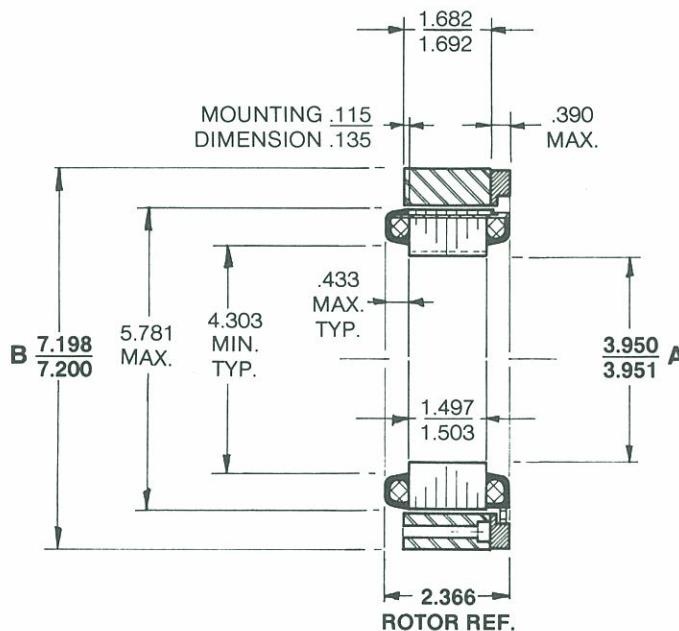
### Value      Units

Peak Torque Rating - $T_p$	7.00	LB. FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	261	WATTS	
Motor Constant - $K_M$	0.433	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p - \omega_{NL}$	28	RAD/S	
Electrical Time Constant - $\tau_E$	3.13	MS	
Static Friction (Max.) - $T_f$	0.09	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_\infty$	0.254      0.003	LB. FT. PER RAD/S      LB. FT. PER RAD/S
Maximum Winding Temperature	105	°C	
Temperature Rise per Watt - TPR	2.0	°C/WATT	
Ripple Torque (Average to Peak) - $T_R$	4	PERCENT	
Ripple Frequency - (Fundamental)	79	CYCLES/REV.	
Number of Poles	10		
Rotor Inertia - $J_M$	$5.0 \times 10^{-3}$	LB.FT.S <sup>2</sup>	
Motor Weight	7.25	LB.	

## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	19.8	30.6	37.8	45.7	57.4	93.0	113
Peak Current - $I_p$	AMPERES	Rated	13.2	8.76	7.00	5.38	4.38	2.70	2.12
Torque Sensitivity - $K_T$	LB. FT./AMP	$\pm 10\%$	0.530	0.800	1.00	1.30	1.60	2.60	3.30
Back EMF Constant - $K_B$	V per RAD/S	$\pm 10\%$	0.719	1.09	1.36	1.77	2.17	3.53	4.48
DC Resistance ( $25^\circ\text{C}$ ) - $R_M$	OHMS	$\pm 12.5\%$	1.50	3.50	5.40	8.50	13.1	34.3	53.5
Inductance - $L_M$	mH	$\pm 30\%$	4.7	10.6	17.2	27.4	40.0	110	174



#15 (.180) DIA. THRU (.297) DIA. C'BORE X .188 DEEP(6) HOLES SPACED AS SHOWN ON 6.600 DIA. B.C.

**NOTES:**

1. — MOTOR TO BE SHIPPED AS **FOUR** SEPARATE COMPONENTS: ROTOR, (2) BRUSH SEGMENT ASSEMBLIES, AND STATOR WITH (2) KEEPERs. **CAUTION:** DO NOT REMOVE KEEPERs UNTIL ROTOR IS FULLY IN PLACE
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002(.004 T.I.R.) WHEN MOUNTED.
3. — WITH A POSITIVE CURRENT APPLIED TO TERMINAL #1 ROTATION SHALL BE C.C.W. FACING THE BRUSH RING END.
4. — TYPICAL BRUSH LIFE >  $10^7$  REVs.

## SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>	
Peak Torque Rating - $T_p$	14.0	LB. FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	357	WATTS	
Motor Constant - $K_m$	0.74	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	18.75	RAD/S	
Electrical Time Constant - $\tau_e$	5.3	MS	
Static Friction (Max.) - $T_f$	0.15	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.75	LB. FT. PER RAD/S
	Infinite Impedance - $F_i$	0.01	LB. FT. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	1.3	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	4	PERCENT	
Ripple Frequency - (Fundamental)	79	CYCLES/REV.	
Number of Poles	10		
Rotor Inertia - $J_m$	0.008	LB.FT.S <sup>2</sup>	
Motor Weight	15	LB.	

## WINDING CONSTANTS

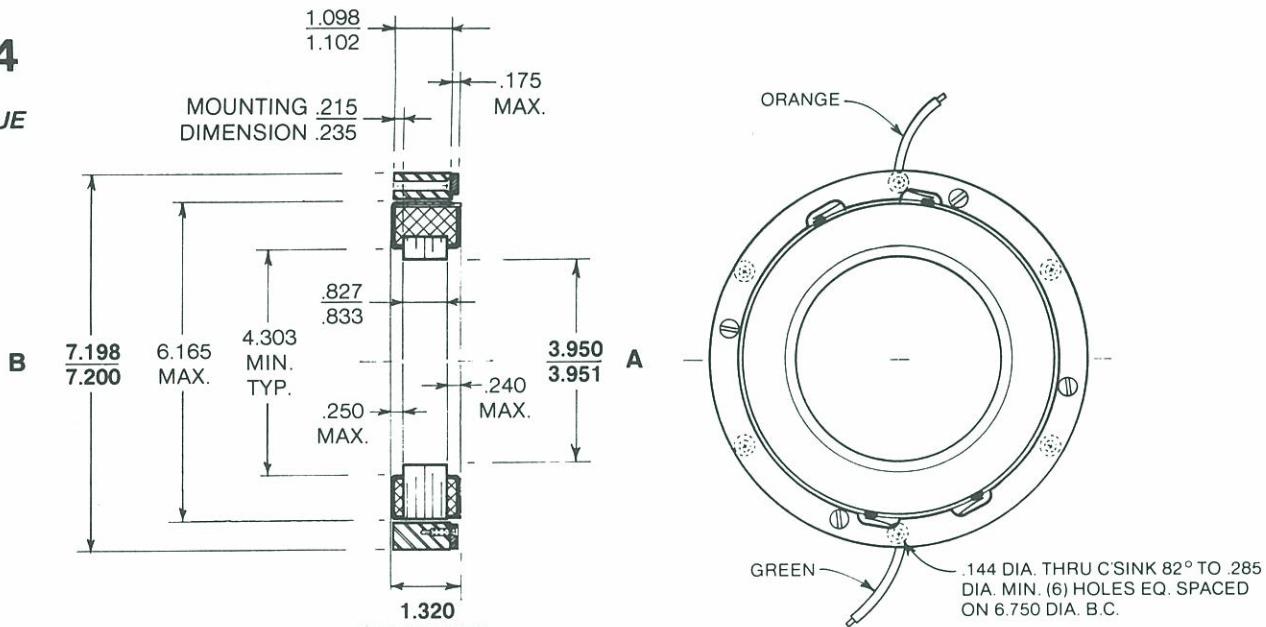
### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	21.1	49.3	13.2	33.6	26.7	123	
Peak Current - $I_p$	AMPERES	Rated	16.9	6.75	28.0	10.5	13.0	2.68	
Torque Sensitivity - $K_t$	LB.FT./AMP.	± 10%	0.83	2.07	0.5	1.33	1.08	5.22	
Back EMF Constant - $K_b$	V per RAD/S	± 10%	1.125	2.81	0.68	1.8	1.46	7.08	
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	± 12.5%	1.25	7.3	0.47	3.2	2.05	45.9	
Inductance - $L_m$	mH	± 30%	6.6	41.2	2.4	16.9	11.2	260	

# T-6204

6.0 lb. ft.

PEAK TORQUE



NOTES:

- MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. CAUTION: DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002(.004 T.I.R.) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
- GOLD PLATED COMMUTATOR.

LEADS:

#20 AWG TYPE "EE" TEFLON COATED PER MIL W-16878 24"MIN. LG.

## SIZE CONSTANTS

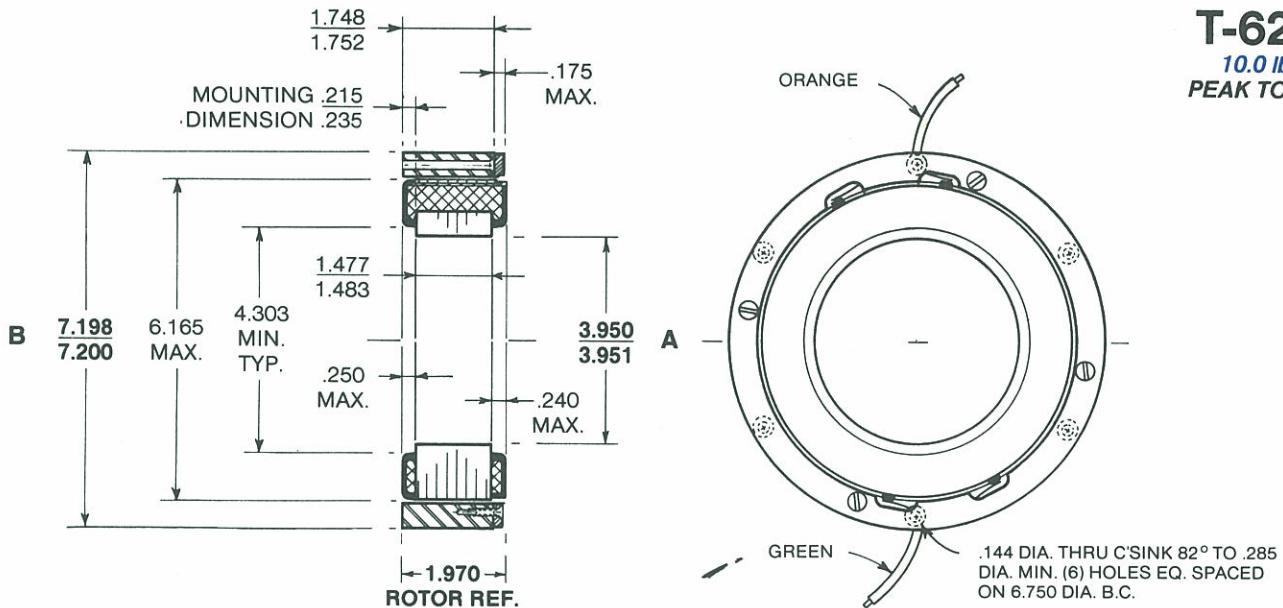
**Value      Units**

Peak Torque Rating - $T_p$	6.0	LB. FT.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	103	WATTS
Motor Constant - $K_M$	0.59	LB.FT./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	12.8	RAD/S
Electrical Time Constant - $\tau_E$	2.49	MS
Static Friction (Max.) - $T_f$	0.15	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_\infty$	0.467      0.006
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	1.8	°C/WATT
Ripple Torque (Average to Peak) - $T_R$	6	PERCENT
Ripple Frequency - (Fundamental)	89	CYCLES/REV.
Number of Poles	18	
Rotor Inertia - $J_M$	0.0065	LB.FT.S <sup>2</sup>
Motor Weight	7.0	LB.

## WINDING CONSTANTS

*Winding Designation*

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	22.5	25.6	11.3	51.2	32.2		
Peak Current - $I_p$	AMPERES	Rated	4.6	3.66	9.65	1.83	2.95		
Torque Sensitivity - $K_T$	LB.FT./AMP.	±10%	1.30	1.64	0.622	3.28	2.04		
Back EMF Constant - $K_B$	V per RAD/S	±10%	1.76	2.23	0.843	4.45	2.75		
DC Resistance ( $25^\circ\text{C}$ ) - $R_M$	OHMS	±12.5%	4.90	7.00	1.17	28.0	10.9		
Inductance - $L_M$	mH	±30%	12	19	2.8	77	29		



**NOTES:**

1. - MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. **CAUTION:** DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
2. - MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002-.004 T.I.R. WHEN MOUNTED.
3. - WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. - TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
5. - GOLD PLATED COMMUTATOR.

**LEADS:**  
#20 AWG TYPE "EE" TEFLON COATED PER MIL W-16878 24" MIN. LG.

### SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>
Peak Torque Rating - $T_p$	10.0	LB. FT.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	125	WATTS
Motor Constant - $K_m$	0.87	LB.FT./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	9.2	RAD/S
Electrical Time Constant - $\tau_e$	2.6	MS
Static Friction (Max.) - $T_f$	.35	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_\infty$	1.09      .009
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	1.5	°C/WATT
Ripple Torque (Average to Peak) - $T_R$	6	PERCENT
Ripple Frequency - (Fundamental)	89	CYCLES/REV.
Number of Poles	18	
Rotor Inertia - $J_m$	0.009	LB.FT.S <sup>2</sup>
Motor Weight	10	LB.

### WINDING CONSTANTS

### Winding Designation

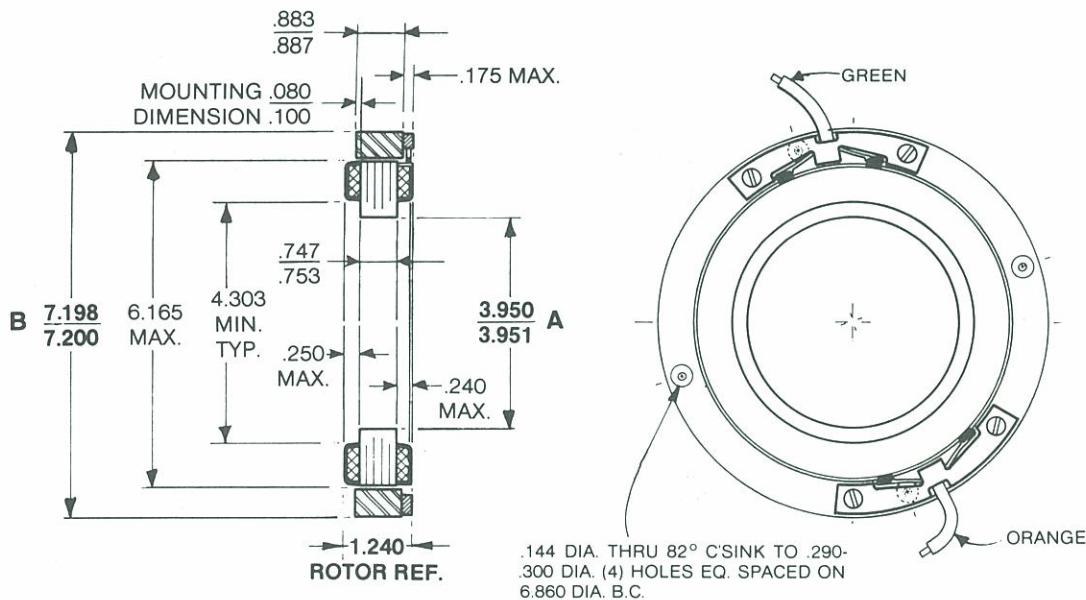
	<b>UNITS</b>	<b>TOLERANCES</b>	<b>A</b>	<b>B</b>	<b>C</b>	<b>D</b>	<b>E</b>	<b>F</b>	<b>G</b>
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	<b>VOLTS</b>	Nom.	20.2	14.0	35.4	71.0	17.8		
Peak Current - $I_p$	<b>AMPERES</b>	Rated	5.60	9.10	3.47	1.74	7.75		
Torque Sensitivity - $K_t$	<b>LB.FT./AMP.</b>	±10%	1.79	1.10	2.88	5.76	1.29		
Back EMF Constant - $K_b$	<b>V per RAD/S</b>	±10%	2.43	1.48	3.90	7.81	1.75		
DC Resistance (25°C) - $R_m$	<b>OHMS</b>	±12.5%	3.60	1.54	10.2	40.8	2.30		
Inductance - $L_m$	<b>mH</b>	±30%	10	3.9	27	110	5.2		

# QT-6202

11 lb. ft.

PEAK TORQUE

RARE EARTH MAGNETS



**NOTES:**

1. — MOTOR TO BE SHIPPED AS FOUR SEPARATE COMPONENTS: ROTOR ASSEMBLY, STATOR ASSEMBLY, AND (2) BRUSH SEGMENT ASSEMBLIES.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**LEADS:**

#16 AWG TYPE "EE" TEFLOX COATED 12" MIN. LENGTH.

## SIZE CONSTANTS

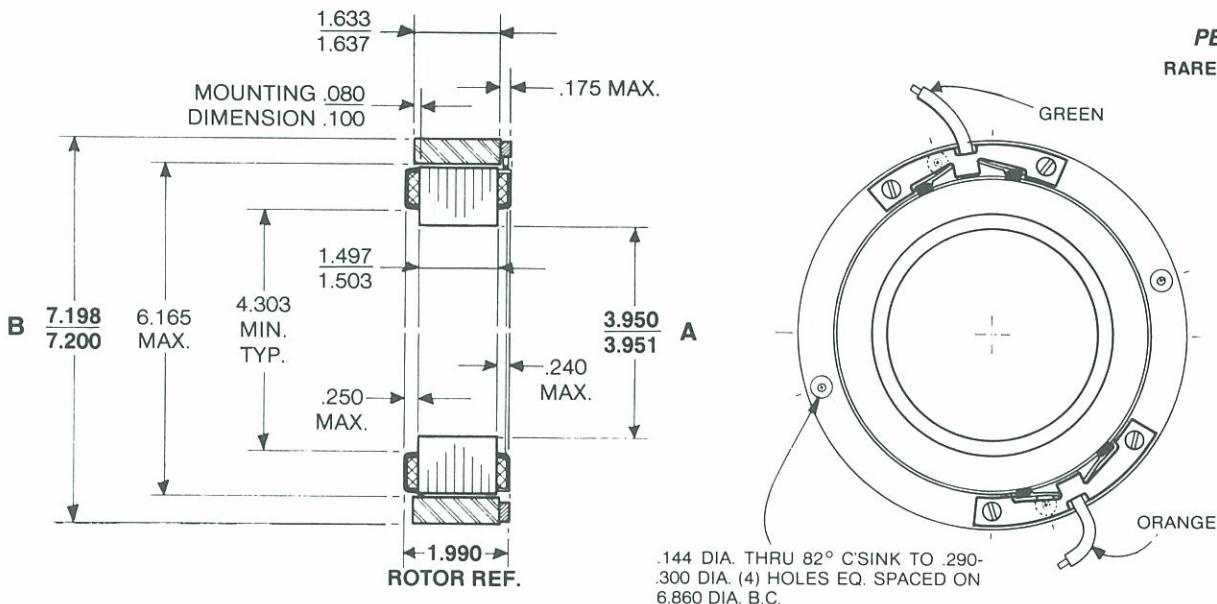
## Value      Units

Peak Torque Rating - $T_p$	11	LB. FT.						
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	330	WATTS						
Motor Constant - $K_m$	0.61	LB.FT./ $\sqrt{\text{WATT}}$						
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	22	RAD/S						
Electrical Time Constant - $\tau_e$	1.8	MS						
Static Friction (Max.) - $F_f$	0.18	LB. FT.						
Viscous Damping Coefficients	<table border="0"> <tr> <td>Zero Impedance - <math>F_0</math></td> <td>0.50</td> </tr> <tr> <td>Infinite Impedance - <math>F_\infty</math></td> <td><math>2.6 \times 10^{-3}</math></td> </tr> </table>	Zero Impedance - $F_0$	0.50	Infinite Impedance - $F_\infty$	$2.6 \times 10^{-3}$	<table border="0"> <tr> <td>LB. FT. PER RAD/S</td> </tr> <tr> <td>LB. FT. PER RAD/S</td> </tr> </table>	LB. FT. PER RAD/S	LB. FT. PER RAD/S
Zero Impedance - $F_0$	0.50							
Infinite Impedance - $F_\infty$	$2.6 \times 10^{-3}$							
LB. FT. PER RAD/S								
LB. FT. PER RAD/S								
Maximum Winding Temperature	155	°C						
Temperature Rise per Watt - $TPR$	2.0	°C/WATT						
Ripple Torque (Average to Peak) - $T_r$	4	PERCENT						
Ripple Frequency (Fundamental)	89	CYCLES/REV.						
Number of Poles	20							
Rotor Inertia - $J_m$	0.0058	LB.FT.S <sup>2</sup>						
Motor Weight	6.2	LB.						

## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	34.5	43.5	27.3	21.6			
Peak Current - $I_p$	AMPERES	Rated	9.57	7.60	12.95	16.9			
Torque Sensitivity - $K_t$	LB.FT./AMP	$\pm 10\%$	1.15	1.45	0.850	0.650			
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	1.56	1.97	1.15	0.881			
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	3.60	5.72	2.11	1.28			
Inductance - $L_m$	mH	$\pm 30\%$	6.5	10	3.6	2.1			

**NOTES:**

1. — MOTOR TO BE SUPPLIED AS FOUR SEPARATE COMPONENTS: ROTOR ASSEMBLY, STATOR ASSEMBLY, AND (2) BRUSH SEGMENT ASSEMBLIES.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**LEADS:**

#16 AWG TYPE "EE" TEFLON COATED,  
12" MIN. LENGTH.

**SIZE CONSTANTS****Value      Units**

Peak Torque Rating - $T_p$	25	LB. FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	627	WATTS	
Motor Constant - $K_m$	1.0	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	18.5	RAD/S	
Electrical Time Constant - $\tau_e$	2.41	MS	
Static Friction (Max.) - $T_f$	0.35	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	1.35	LB. FT. PER RAD/S
	Infinite Impedance - $F_\infty$	0.005	LB. FT. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	1.5	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	4	PERCENT	
Ripple Frequency (Fundamental)	89	CYCLES/REV.	
Number of Poles	20		
Rotor Inertia - $J_m$	0.01	LB.FT.S <sup>2</sup>	
Motor Weight	12	LB.	

**WINDING CONSTANTS****Winding Designation**

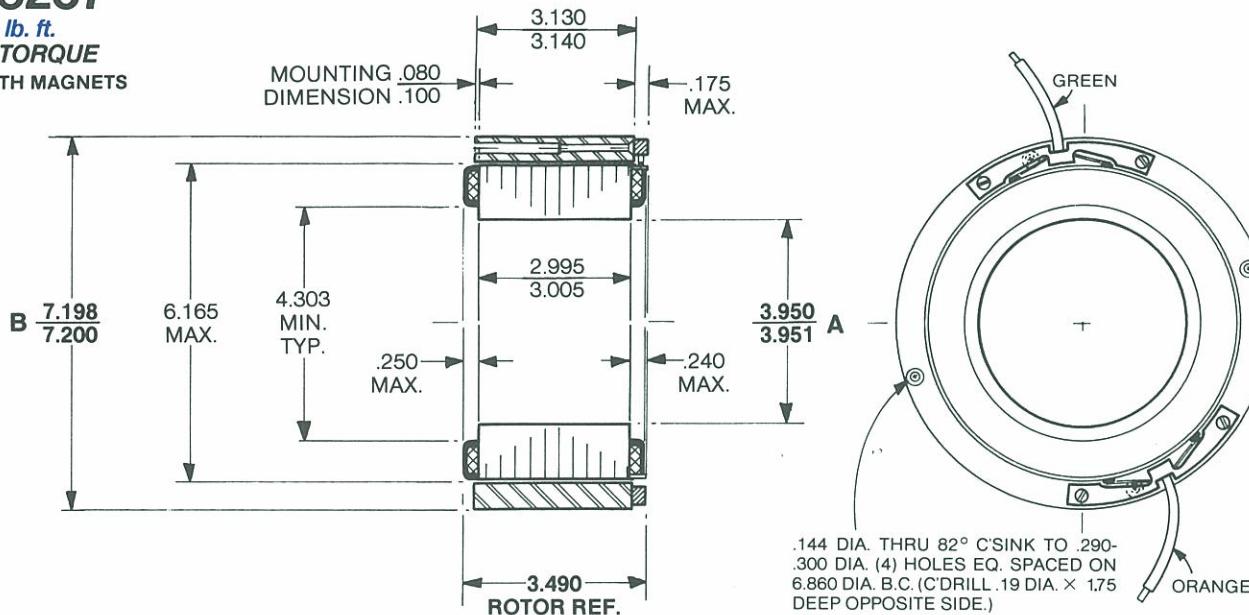
	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	30.2	48.8	60.3	24.0	38.4		
Peak Current - $I_p$	AMPERES	Rated	20.8	13.2	10.4	27.8	16.7		
Torque Sensitivity - $K_t$	LB.FT./AMP	± 10%	1.20	1.90	2.40	0.90	1.50		
Back EMF Constant - $K_b$	V per RAD/S	± 10%	1.63	2.58	3.25	1.22	2.03		
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	± 12.5%	1.45	3.70	5.80	0.863	2.30		
Inductance - $L_m$	mH	± 30%	3.5	8.8	14	2.0	5.5		

# QT-6207

40 lb. ft.

PEAK TORQUE

RARE EARTH MAGNETS



**NOTES:**

- MOTOR SUPPLIED AS FOUR SEPARATE COMPONENTS: ROTOR ASSEMBLY, STATOR ASSEMBLY, AND (2) BRUSH RING SEGMENT ASSEMBLIES.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
- WITH A POSITIVE CURRENT APPLIED TO GREEN LEAD WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. WHEN VIEWED FROM BRUSH SIDE.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REVS.

**LEADS:**

#16 AWG TYPE "EE" TEFLOX COATED  
12" MIN. LENGTH.

## SIZE CONSTANTS

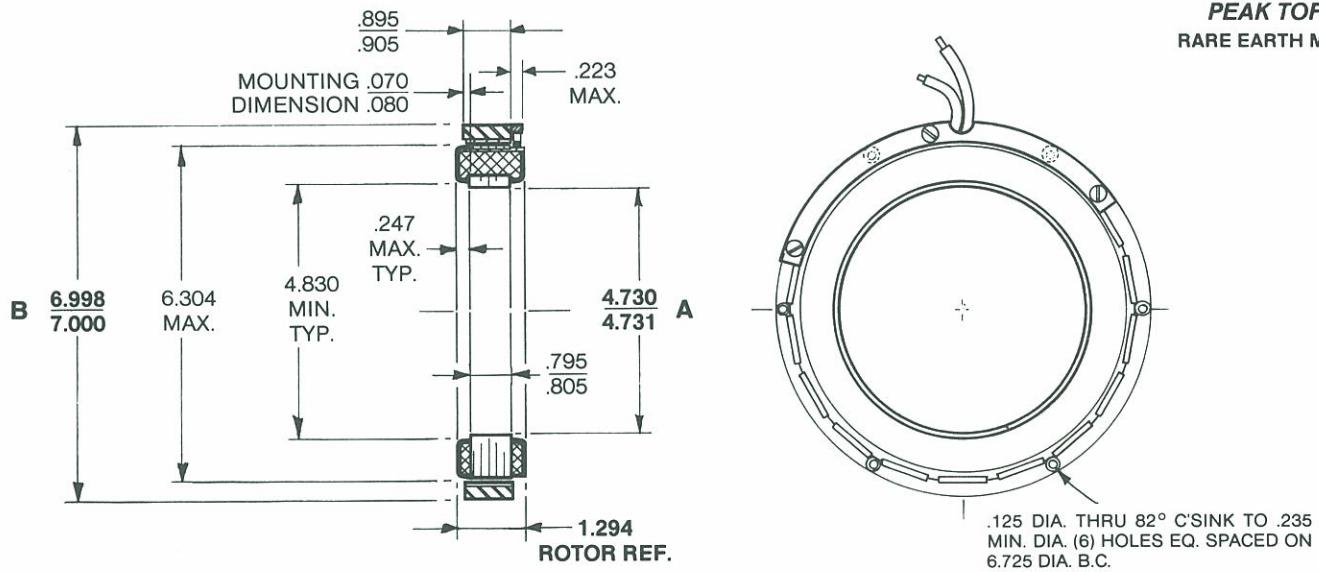
### Value      Units

Peak Torque Rating - $T_p$	40	LB. FT.	
Power Input, Stalled at $T_p$ (25°C) - $P_p$	655	WATTS	
Motor Constant - $K_m$	1.56	LB.FT./ $\sqrt{WATT}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	12	RAD/S	
Electrical Time Constant - $\tau_e$	3.0	MS	
Static Friction (Max.) - $T_f$	0.60	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	3.32      0.01	LB. FT. PER RAD/S      LB. FT. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - TPR	0.75	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	4	PERCENT	
Ripple Frequency - (Fundamental)	89	CYCLES/REV.	
Number of Poles	20		
Rotor Inertia - $J_m$	0.02	LB.FT.S <sup>2</sup>	
Motor Weight	24	LB.	

## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ (25°C) - $V_p$	VOLTS	Nom.	39.2						
Peak Current - $I_p$	AMPERES	Rated	16.7						
Torque Sensitivity - $K_t$	LB.FT./AMP	± 10%	2.40						
Back EMF Constant - $K_b$	V PER RAD/S	± 10%	3.25						
DC Resistance (25°C) - $R_m$	OHMS	± 12.5%	2.35						
Inductance - $L_m$	mH	± 30%	7.0						



**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH SEGMENT ASSEMBLY, ROTOR ASSEMBLY AND STATOR ASSEMBLY.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**LEADS:**  
#22 AWG TYPE "E" TEFLON COATED PER MIL W-16878, 12" MIN. LENGTH.

### SIZE CONSTANTS

**Value      Units**

Peak Torque Rating - $T_p$	800	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	67	WATTS	
Motor Constant - $K_m$	97.7	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	12	RAD/S	
Electrical Time Constant - $\tau_e$	1.44	MS	
Static Friction (Max.) - $T_f$	30	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	67.6	OZ. IN. PER RAD/S
	Infinite Impedance - $F_\infty$	0.75	OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	2.0	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT	
Ripple Frequency (Fundamental)	89	CYCLES/REV.	
Number of Poles	18		
Rotor Inertia - $J_m$	1.2	OZ.IN.S <sup>2</sup>	
Motor Weight	100	OZ.	

### WINDING CONSTANTS

*Winding Designation*

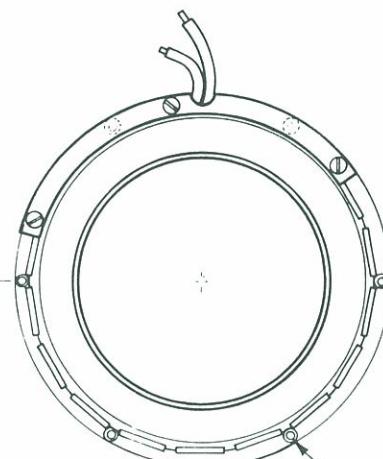
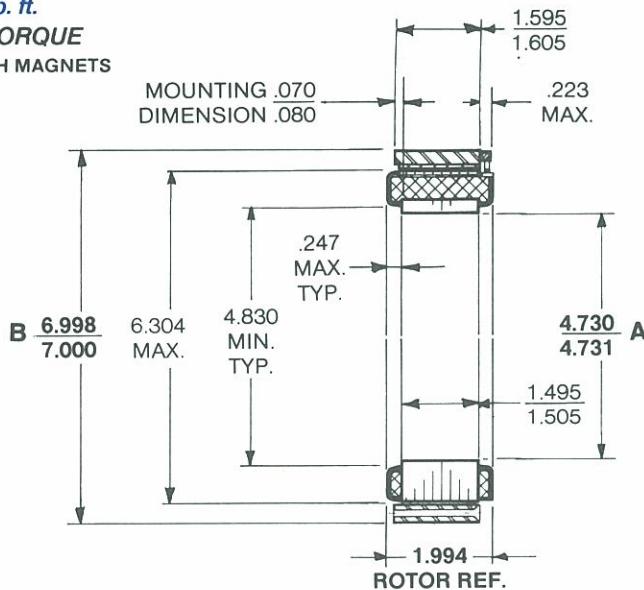
	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	21.5						
Peak Current - $I_p$	AMPERES	Rated	3.10						
Torque Sensitivity - $K_t$	OZ.IN./AMP	±10%	258						
Back EMF Constant - $K_b$	V per RAD/S	±10%	1.82						
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	±12.5%	6.95						
Inductance - $L_m$	mH	±30%	10						

# QT-6301

20 lb. ft.

PEAK TORQUE

RARE EARTH MAGNETS



125 DIA. THRU 82° C SINK TO  
235 MIN DIA. (6) HOLES  
EQ. SPACED ON 6.725 DIA. B.C.

**NOTES:**

- MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH SEGMENT ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002/.004 T.I.R. WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**LEADS:**

#22 AWG TYPE "E" TEFLON COATED  
PER MIL W-16878, 12" MIN. LENGTH.

## SIZE CONSTANTS

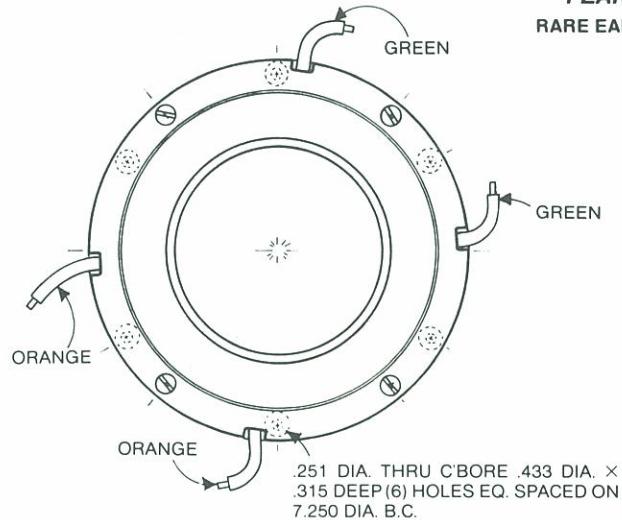
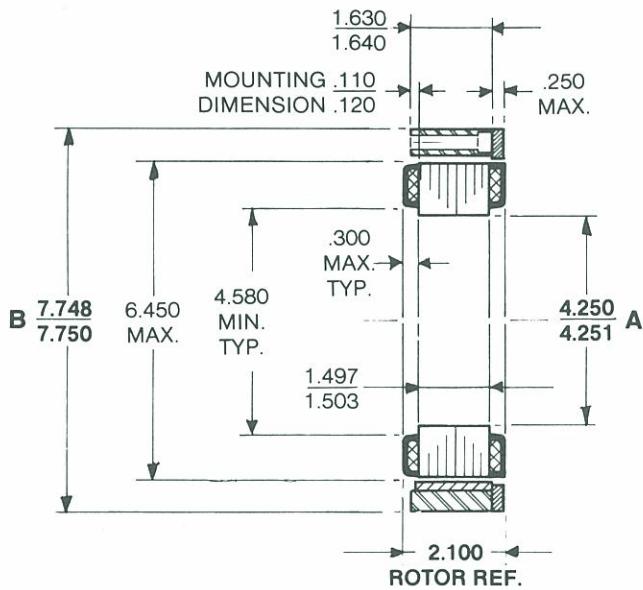
### Value      Units

Peak Torque Rating - $T_p$	20	LB. FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	576	WATTS	
Motor Constant - $K_M$	0.83	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	21	RAD/S	
Electrical Time Constant - $\tau_E$	2.1	MS	
Static Friction (Max.) - $T_f$	0.25	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.94	LB. FT. PER RAD/S
	Infinite Impedance - $F_i$	0.007	LB. FT. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	1.0	°C/WATT	
Ripple Torque (Average to Peak) - $T_R$	5	PERCENT	
Ripple Frequency (Fundamental)	89	CYCLES/REV.	
Number of Poles	18		
Rotor Inertia - $J_M$	0.010	LB.FT.S <sup>2</sup>	
Motor Weight	9	LB.	

## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	45.1						
Peak Current - $I_p$	AMPERES	Rated	12.4						
Torque Sensitivity - $K_T$	LB.FT./AMP	± 10%	1.61						
Back EMF Constant - $K_B$	V per RAD/S	± 10%	2.18						
DC Resistance (25°C) - $R_M$	OHMS	± 12.5%	3.64						
Inductance - $L_M$	mH	± 30%	7.8						



**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITH-. IN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEADS, WITH RESPECT TO ORANGE LEADS, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — CONNECT (2) GREEN LEADS TOGETHER AND (2) ORANGE LEADS TOGETHER FOR PROPER OPERATION.
5. — TYPICAL BRUSH LIFE >  $10^7$  REV.

**LEADS:**

#16 AWG TYPE "E" TEFLON COATED  
PER MIL W-16878, 12" MIN. LENGTH.

### SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>	
Peak Torque Rating - $T_p$	26	LB. FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	657	WATTS	
Motor Constant - $K_m$	1.01	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	18.7	RAD/S	
Electrical Time Constant - $\tau_e$	3.3	MS	
Static Friction (Max.) - $T_f$	0.40	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	1.39	LB. FT. PER RAD/S
	Infinite Impedance - $F_i$	0.006	LB. FT. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	1.4	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	4	PERCENT	
Ripple Frequency (Fundamental)	91	CYCLES/REV.	
Number of Poles	18		
Rotor Inertia - $J_m$	0.0124	LB.FT.S <sup>2</sup>	
Motor Weight	12.6	LB.	

### WINDING CONSTANTS

### Winding Designation

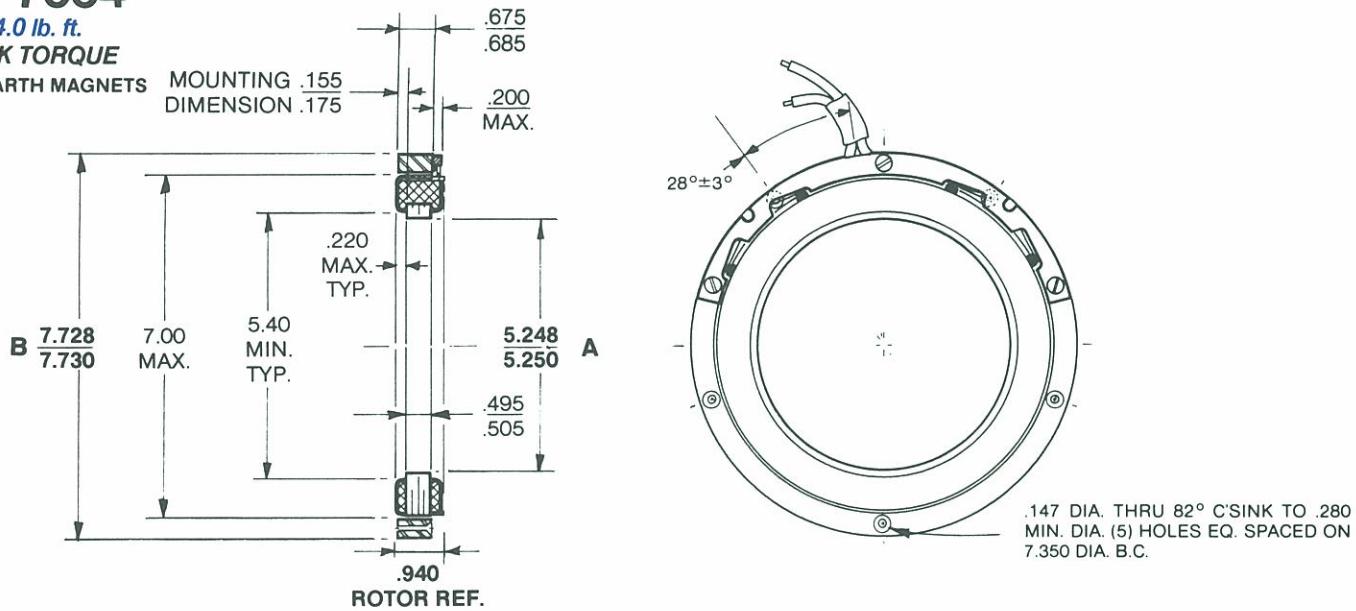
	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	28.1	35.3					
Peak Current - $I_p$	AMPERES	Rated	23.4	18.7					
Torque Sensitivity - $K_t$	LB.FT./AMP	$\pm 10\%$	1.11	1.39					
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	1.50	1.89					
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	1.20	1.89					
Inductance - $L_m$	mH	$\pm 30\%$	4.0	6.3					

# QT-7004

4.0 lb. ft.

PEAK TORQUE

RARE EARTH MAGNETS



**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH SEGMENT ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO BLACK LEAD, WITH RESPECT TO WHITE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**LEADS:**

#20 AWG TYPE "E" TEFLON COATED PER MIL W-16878, 20" MIN. LENGTH.

## SIZE CONSTANTS

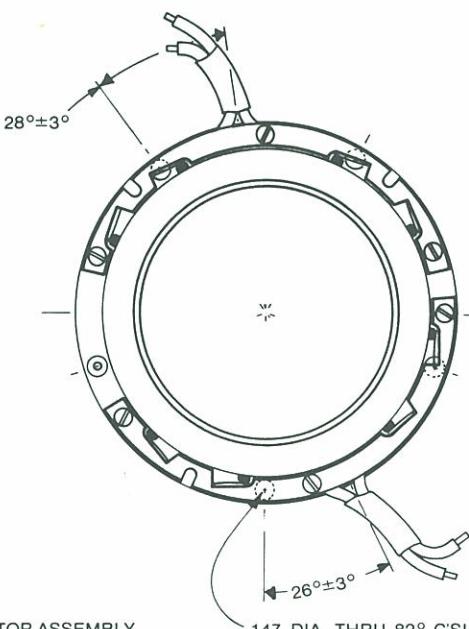
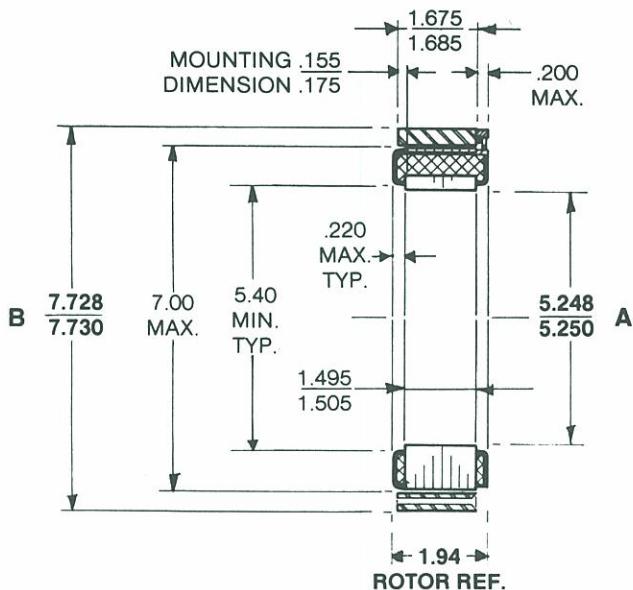
**Value      Units**

Peak Torque Rating - $T_p$	4.0	LB. FT.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	58.2	WATTS
Motor Constant - $K_M$	0.524	LB.FT./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	10.7	RAD/S
Electrical Time Constant - $\tau_E$	2.0	MS
Static Friction (Max.) - $T_f$	0.20	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	0.37 $4.8 \times 10^{-3}$
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	2.0	°C/WATT
Ripple Torque (Average to Peak) - $T_R$	5	PERCENT
Ripple Frequency (Fundamental)	91	CYCLES/REV.
Number of Poles	20	
Rotor Inertia - $J_M$	0.0063	LB.FT.S <sup>2</sup>
Motor Weight	4.2	LB.

## WINDING CONSTANTS

*Winding Designation*

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	26.2	40.9					
Peak Current - $I_p$	AMPERES	Rated	2.22	1.40					
Torque Sensitivity - $K_T$	LB.FT./AMP.	± 10%	1.80	2.86					
Back EMF Constant - $K_B$	V per RAD/S	± 10%	2.44	3.88					
DC Resistance (25°C) - $R_M$	OHMS	± 12.5%	11.8	29.2					
Inductance - $L_M$	mH	± 30%	24	61					

**NOTES:**

1. - MOTOR TO BE SUPPLIED AS FOUR SEPARATE COMPONENTS: ROTOR ASSEMBLY, STATOR ASSEMBLY, AND (2) BRUSH SEGMENT ASSEMBLIES.
2. - MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. - WITH POSITIVE CURRENT APPLIED TO BLACK LEADS, WITH RESPECT TO WHITE LEADS, ROTATION SHALL BE C.C.W FACING BRUSH RING END.
4. - CONNECT (2) BLACK LEADS TOGETHER AND (2) WHITE LEADS TOGETHER FOR PROPER OPERATION.
5. - TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

.147 DIA. THRU 82° CSINK TO .280  
MIN. DIA. (5) HOLES EQ. SPACED ON  
7.350 DIA. B.C.

LEADS:  
#20 AWG TYPE "E" TEFLON COATED  
PER MIL W-16878, 20" MIN. LENGTH.

**SIZE CONSTANTS****Value      Units**

Peak Torque Rating - $T_p$	25	LB. FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	520	WATTS	
Motor Constant - $K_m$	1.1	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	15	RAD/S	
Electrical Time Constant - $\tau_e$	2.4	MS	
Static Friction (Max.) - $T_f$	0.35	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	1.6	LB. FT. PER RAD/S
	Infinite Impedance - $F_i$	$8.0 \times 10^{-3}$	LB. FT. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	1.2	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT	
Ripple Frequency (Fundamental)	91	CYCLES/REV.	
Number of Poles	20		
Rotor Inertia - $J_m$	0.013	LB.FT.S <sup>2</sup>	
Motor Weight	10.3	LB.	

**WINDING CONSTANTS****Winding Designation**

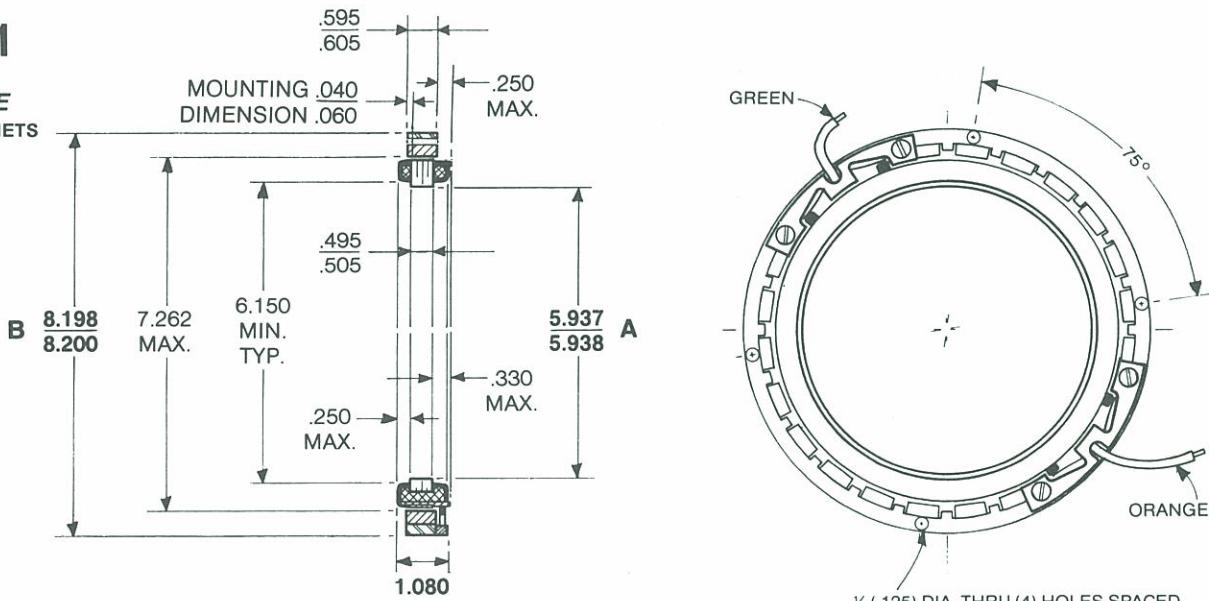
	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	21.0	53.0					
Peak Current - $I_p$	AMPERES	Rated	24.7	9.69					
Torque Sensitivity - $K_t$	LB.FT./AMP	± 10%	1.01	2.58					
Back EMF Constant - $K_b$	V per RAD/S	± 10%	1.37	3.50					
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	± 12.5%	0.849	5.47					
Inductance - $L_m$	mH	± 30%	2.0	13					

# QT-7201

9.0 lb. ft.

PEAK TORQUE

RARE EARTH MAGNETS



**NOTES:**

- MOTOR TO BE SHIPPED AS (3) SEPARATE COMPONENTS: ROTOR ASSEMBLY INSIDE STATOR ASSEMBLY AND (2) BRUSH SEGMENT ASSEMBLIES.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002(.004 T.I.R) WHEN MOUNTED.
- STATOR MOUNTING SCREWS MUST BE NON-MAGNETIC.
- WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**LEADS:**

#18 AWG TEFLON COATED PER MIL W-16878, 24" MIN. LENGTH.

## SIZE CONSTANTS

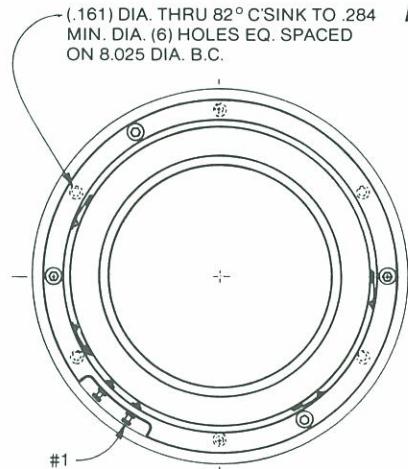
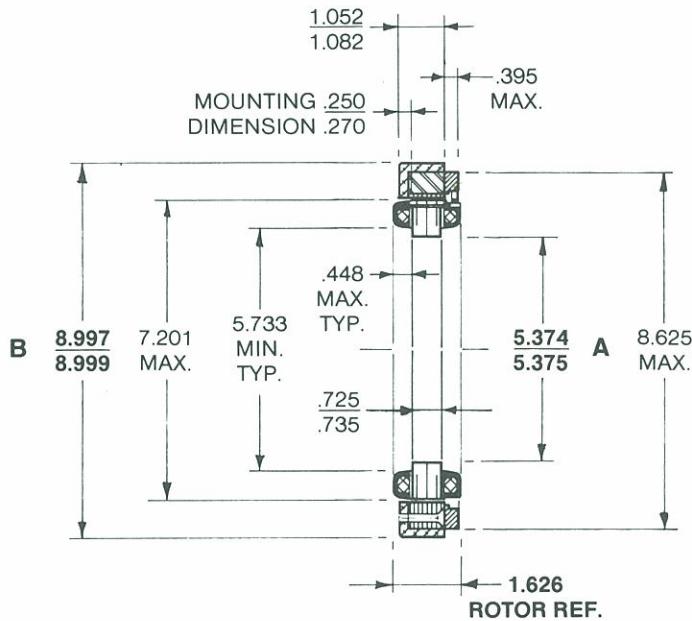
### Value      Units

Peak Torque Rating - $T_p$	9.0	LB. FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	490	WATTS	
Motor Constant - $K_m$	0.41	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	40	RAD/S	
Electrical Time Constant - $\tau_e$	0.79	MS	
Static Friction (Max.) - $T_f$	0.15	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.22	LB. FT. PER RAD/S
	Infinite Impedance - $F_i$	0.0024	LB. FT. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	1.0	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	5.0	PERCENT	
Ripple Frequency (Fundamental)	107	CYCLES/REV.	
Number of Poles	24		
Rotor Inertia - $J_m$	$5.6 \times 10^{-3}$	LB.FT.S <sup>2</sup>	
Motor Weight	4.0	LB.	

## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	30.6						
Peak Current - $I_p$	AMPERES	Rated	16.1						
Torque Sensitivity - $K_t$	LB.FT./AMP	$\pm 10\%$	0.56						
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.759						
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 15\%$	1.90						
Inductance - $L_m$	mH	$\pm 30\%$	1.5						

**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. **CAUTION:** DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO TERMINAL #1, ROTATION SHALL BE C.C.W. FACING THE BRUSH RING SIDE.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**SIZE CONSTANTS****Value      Units**

Peak Torque Rating - $T_p$	11	LB. FT.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	325	WATTS
Motor Constant - $K_m$	0.61	LB.FT./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	22	RAD/S
Electrical Time Constant - $\tau_e$	3.15	MS
Static Friction (Max.) - $T_f$	0.15	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_\infty$	0.5      0.005
Maximum Winding Temperature	105	°C
Temperature Rise per Watt - $TPR$	1.2	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	4	PERCENT
Ripple Frequency - (Fundamental)	97	CYCLES/REV.
Number of Poles	12	
Rotor Inertia - $J_m$	0.010	LB.FT.S <sup>2</sup>
Motor Weight	10.3	LB.

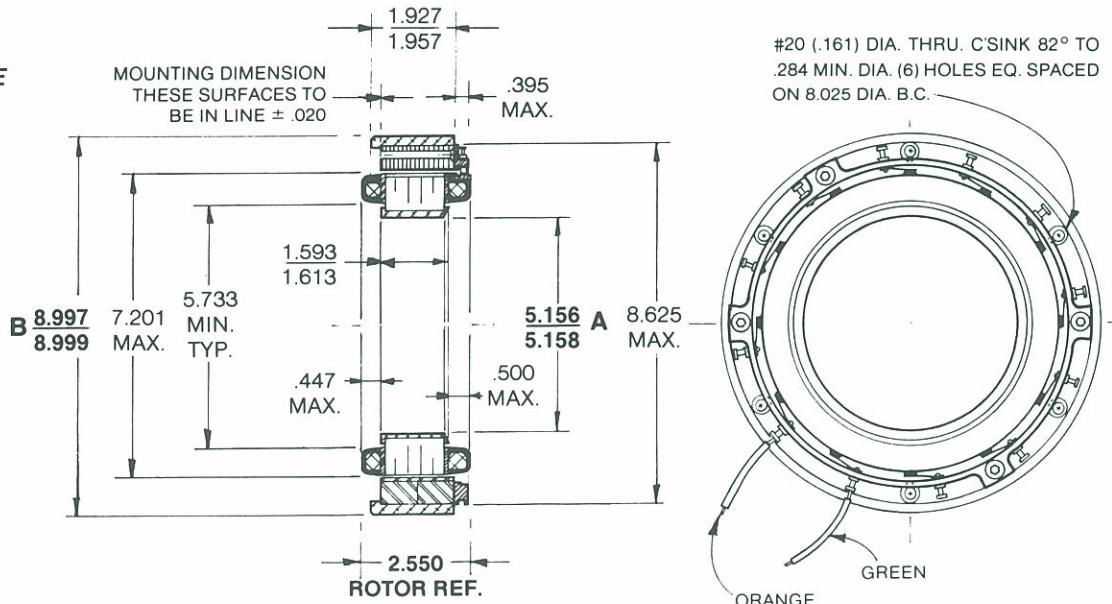
**WINDING CONSTANTS****Winding Designation**

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	29.7	59.5	16.8	19.7	24.2	23.5	47.6
Peak Current - $I_p$	AMPERES	Rated	11.0	5.5	20.8	16.6	15.1	13.8	6.9
Torque Sensitivity - $K_t$	LB.FT./AMP.	±10%	1.0	2.0	0.53	0.66	0.73	0.80	1.6
Back EMF Constant - $K_b$	V per RAD/S	±10%	1.4	2.7	0.72	0.90	0.99	1.1	2.2
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	±12.5%	2.7	10.8	0.81	1.18	1.6	1.7	6.9
Inductance - $L_m$	mH	±30%	8.4	34	2.4	3.7	4.5	5.4	22

# T-7203

22 lb. ft.

PEAK TORQUE



NOTES:

- MOTOR TO BE SUPPLIED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. CAUTION: DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .003 (.006 T.I.R.) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
- FULL COMPLEMENT OF BRUSHES FOR IMPROVED HIGH CURRENT OPERATION.

LEADS:

#18 AWG TYPE "EE" TEFLON COATED PER MIL W-16878 12" MIN. LG.

## SIZE CONSTANTS

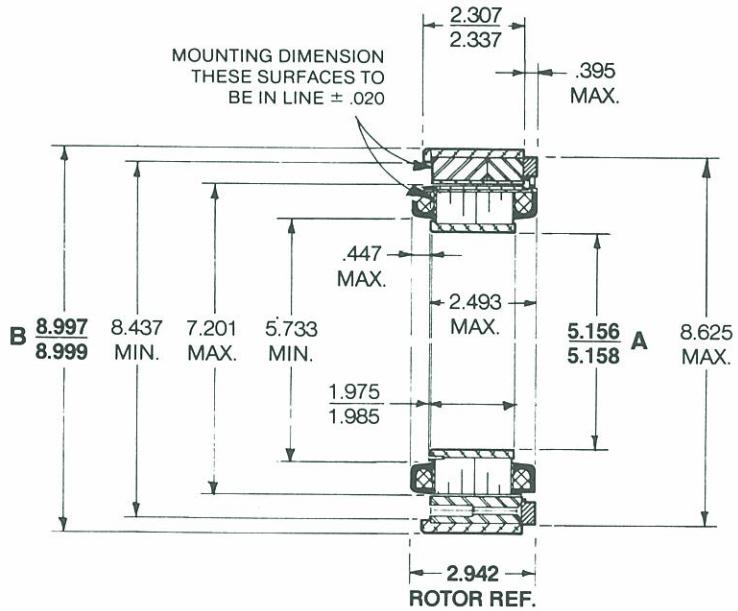
**Value      Units**

Peak Torque Rating - $T_p$	22	LB. FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	530	WATTS	
Motor Constant - $K_m$	0.96	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	18	RAD/S	
Electrical Time Constant - $\tau_e$	5.7	MS	
Static Friction (Max.) - $T_f$	0.25	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	1.25	LB. FT. PER RAD/S
	Infinite Impedance - $F_\infty$	0.013	LB. FT. PER RAD/S
Maximum Winding Temperature	105	°C	
Temperature Rise per Watt - $TPR$	1.1	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	4	PERCENT	
Ripple Frequency - (Fundamental)	97	CYCLES/REV.	
Number of Poles	12		
Rotor Inertia - $J_m$	0.019	LB.FT.S <sup>2</sup>	
Motor Weight	18.3	LB.	

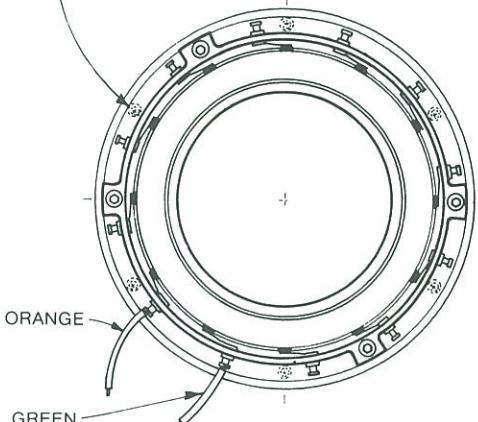
## WINDING CONSTANTS

*Winding Designation*

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	24.5	40.9	23.7	50.1	66.7	105	132
Peak Current - $I_p$	AMPERES	Rated	24.5	12.2	19.0	8.50	7.75	4.75	3.79
Torque Sensitivity - $K_t$	LB.FT./AMP.	±10%	0.90	1.81	1.16	2.60	2.84	4.64	5.80
Back EMF Constant - $K_b$	V per RAD/S	±10%	1.22	2.45	1.57	3.53	3.85	6.29	7.86
DC Resistance (25°C) - $R_m$	OHMS	±12.5%	1.00	3.35	1.25	5.90	8.60	22.2	34.9
Inductance - $L_m$	mH	±30%	5.0	20.0	8.0	40.0	48.0	130	200



#20 (.161) DIA. THRU (.218) DIA. X 1.00  
DP. (OPP. SIDE) 82° C'SINK TO .284  
MIN. DIA. (6) HOLES EQ. SP. ON 8.025  
DIA. B.C.



NOTES:

1. — MOTOR SUPPLIED AS THREE SEPARATE COMPONENTS: ROTOR, STATOR WITH (2) KEEPERs, AND BRUSH RING ASSEMBLY. CAUTION: INSERT ROTOR INTO STATOR PRIOR TO REMOVING KEEPERs.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REVs.
5. — FULL COMPLEMENT OF BRUSHES FOR IMPROVED HIGH CURRENT OPERATION.

LEADS:  
#18 AWG TEFLON COATED TYPE "EE"  
12" MIN. LG.

## SIZE CONSTANTS

	Value	Units	
Peak Torque Rating - $T_p$	27.5	LB. FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	582	WATTS	
Motor Constant - $K_m$	1.14	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p \cdot \omega_{NL}$	15	RAD/S	
Electrical Time Constant - $\tau_e$	6.5	MS	
Static Friction (Max.) - $T_f$	.21	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	1.75 .025	LB. FT. PER RAD/S LB. FT. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	1.0	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	4	PERCENT	
Ripple Frequency - (Fundamental)	97	CYCLES/REV.	
Number of Poles	12		
Rotor Inertia - $J_m$	.023	LB.FT.S <sup>2</sup>	
Motor Weight	22.5	LB.	

## WINDING CONSTANTS

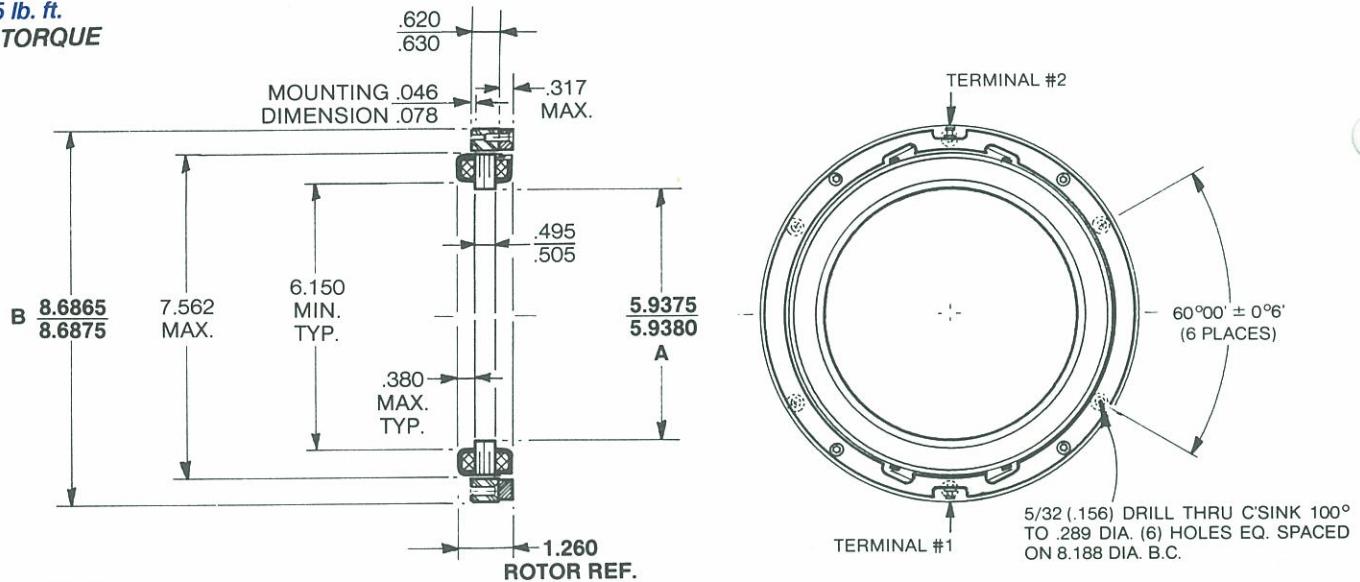
## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	23.8	47.7	60.2	95.2	37.8		
Peak Current - $I_p$	AMPERES	Rated	24.5	12.25	9.55	6.14	15.6		
Torque Sensitivity - $K_t$	LB. FT./AMP	±10%	1.12	2.24	2.88	4.48	1.76		
Back EMF Constant - $K_b$	V per RAD/S	±10%	1.52	3.04	3.90	6.07	2.39		
DC Resistance (25°C) - $R_m$	OHMS	±12.5%	.97	3.88	6.30	15.5	2.42		
Inductance - $L_m$	mH	±30%	6.3	25	41	100	15		

# T-7501

6.5 lb. ft.

PEAK TORQUE



**NOTES:**

1. — MOTOR SUPPLIED AS THREE SEPARATE COMPONENTS: ROTOR ASSEMBLY, BRUSH ASSEMBLY, AND STATOR WITH KEEPER. CAUTION: DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .0015 (.003 T.I.R.) WHEN MOUNTED.
3. — WITH A POSITIVE CURRENT APPLIED TO TERMINAL #1, ROTATION SHALL BE C.C.W. FACING BRUSH RING SIDE.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REVS.

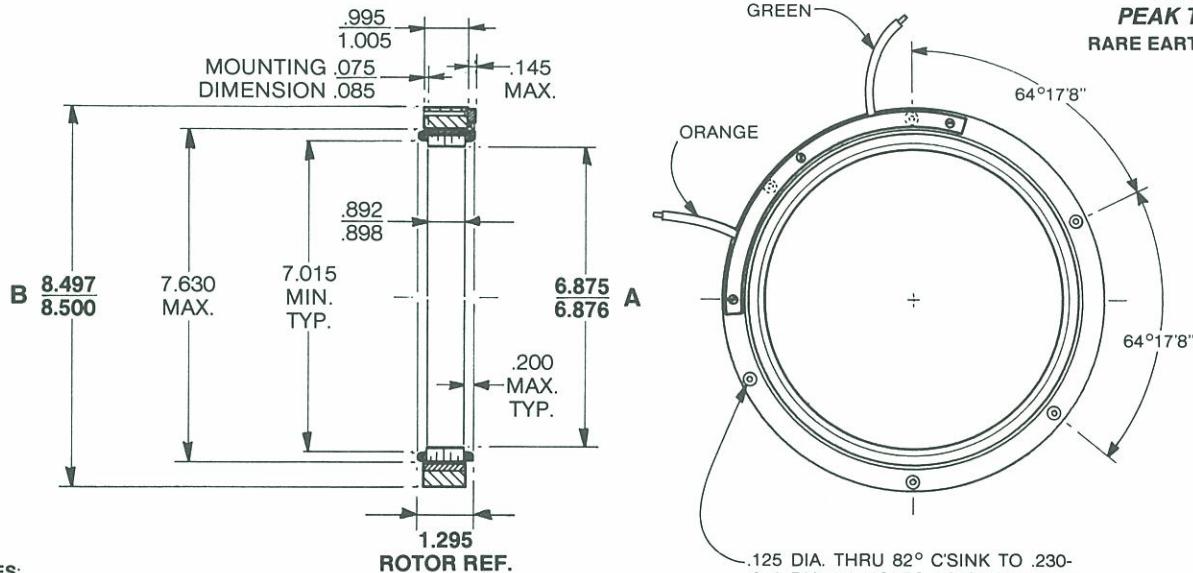
## SIZE CONSTANTS

	Value	Units	
Peak Torque Rating - $T_p$	6.5	LB. FT.	
Power Input, Stalled at $T_p$ (25°C) - $P_p$	177	WATTS	
Motor Constant - $K_m$	0.49	LB.FT./√WATT	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	20	RAD/S	
Electrical Time Constant - $\tau_e$	1.60	MS	
Static Friction (Max.) - $T_f$	0.25	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	0.326 0.003	LB. FT. PER RAD/S LB. FT. PER RAD/S
Maximum Winding Temperature	105	°C	
Temperature Rise per Watt - $TPR$	1.0	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	5.0	PERCENT	
Ripple Frequency - (Fundamental)	107	CYCLES/REV.	
Number of Poles	18		
Rotor Inertia - $J_m$	0.011	LB.FT.S <sup>2</sup>	
Motor Weight	7.5	LB.	

## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ (25°C) - $V_p$	VOLTS	Nom.	42	26	51.4	84.0			
Peak Current - $I_p$	AMPERES	Rated	4.2	6.8	3.38	2.10			
Torque Sensitivity - $K_t$	LB. FT./AMP	±10%	1.55	0.96	1.92	3.10			
Back EMF Constant - $K_b$	V PER RAD/S	±10%	2.1	1.3	2.60	4.2			
DC Resistance (25°C) - $R_m$	OHMS	±12.5%	10.0	3.8	15.2	40.0			
Inductance - $L_m$	mH	±30%	16	6	24	64			

**NOTES:**

1. — MOTOR SUPPLIED AS THREE SEPARATE COMPONENTS: ROTOR, STATOR AND BRUSH RING SEGMENT.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002(.004 T.I.R.) WHEN MOUNTED.
3. — WITH A POSITIVE CURRENT APPLIED TO GREEN LEAD WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING SIDE.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
5. — GOLD PLATED COMMUTATOR.

.125 DIA. THRU 82° C'SINK TO .230-.250 DIA. (6) HOLES AS SHOWN ON 8.100 DIA. B.C.

**LEADS:**  
# 24 AWG TYPE "ET" PER MIL-W 16878,  
18" MIN. LG.

**SIZE CONSTANTS****Value      Units**

Peak Torque Rating - $T_p$	2.1	LB. FT.	
Power Input, Stalled at $T_p$ (25°C) - $P_p$	16.7	WATTS	
Motor Constant - $K_m$	0.514	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	5.88	RAD/S	
Electrical Time Constant - $\tau_e$	0.576	MS	
Static Friction (Max.) - $T_f$	0.30	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.358	LB. FT. PER RAD/S
	Infinite Impedance - $F_i$	0.015	LB. FT. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - TPR	1.0	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT	
Ripple Frequency - (Fundamental)	113	CYCLES/REV.	
Number of Poles	28		
Rotor Inertia - $J_m$	$6.00 \times 10^{-3}$	LB.FT.S <sup>2</sup>	
Motor Weight	7.3	LB.	

**WINDING CONSTANTS****Winding Designation**

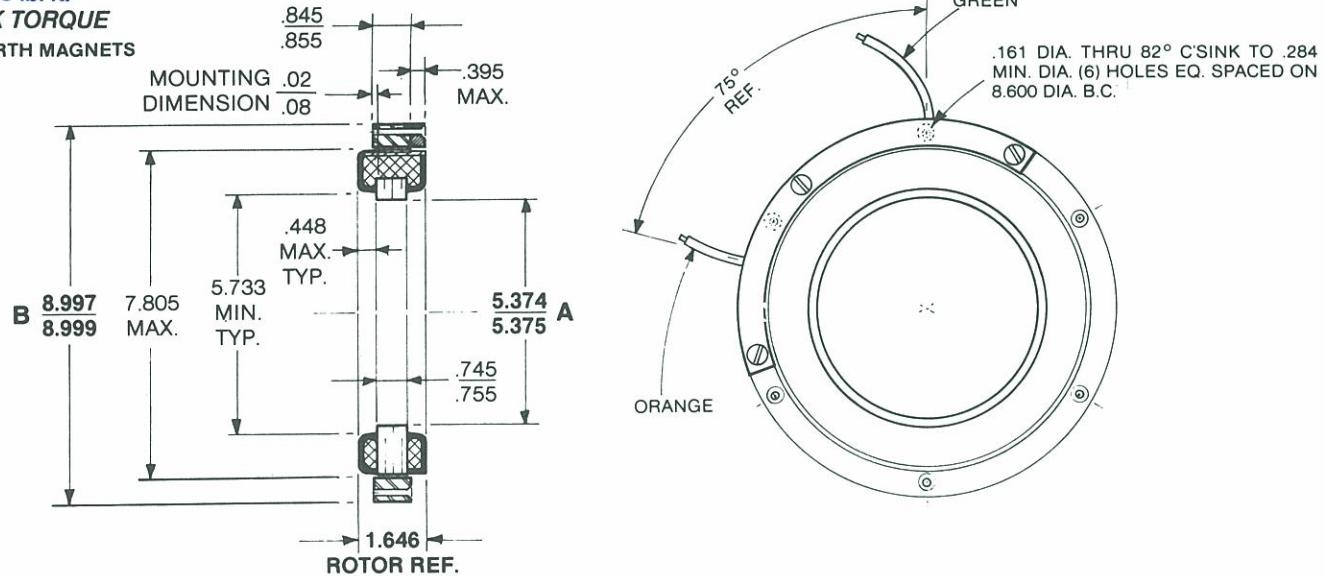
	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ (25°C) - $V_p$	VOLTS	Nom.	23.5						
Peak Current - $I_p$	AMPERES	Rated	0.712						
Torque Sensitivity - $K_t$	LB.FT./AMP	± 10%	2.95						
Back EMF Constant - $K_b$	V PER RAD/S	± 10%	4.00						
DC Resistance (25°C) - $R_m$	OHMS	± 12.5%	33.0						
Inductance - $L_m$	mH	± 30%	19						

# QT-7802

23 lb. ft.

PEAK TORQUE

RARE EARTH MAGNETS



**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH SEGMENT ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**LEADS:**

#16 AWG TYPE "E" TEFLOX COATED PER MIL W-16878, 12" MIN. LENGTH.

## SIZE CONSTANTS

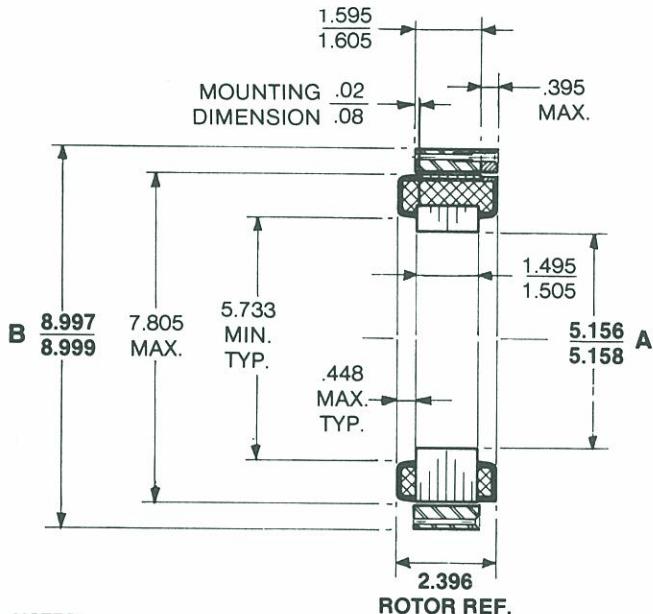
### Value      Units

Peak Torque Rating - $T_p$	23	LB. FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	620	WATTS	
Motor Constant - $K_M$	0.92	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	19.9	RAD/S	
Electrical Time Constant - $\tau_E$	2.45	MS	
Static Friction (Max.) - $T_f$	0.37	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	1.16      0.010	LB. FT. PER RAD/S      LB. FT. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	1.0	°C/WATT	
Ripple Torque (Average to Peak) - $T_R$	5	PERCENT	
Ripple Frequency (Fundamental)	97	CYCLES/REV.	
Number of Poles	24		
Rotor Inertia - $J_M$	0.0155	LB.FT.S <sup>2</sup>	
Motor Weight	10.2	LB.	

## WINDING CONSTANTS

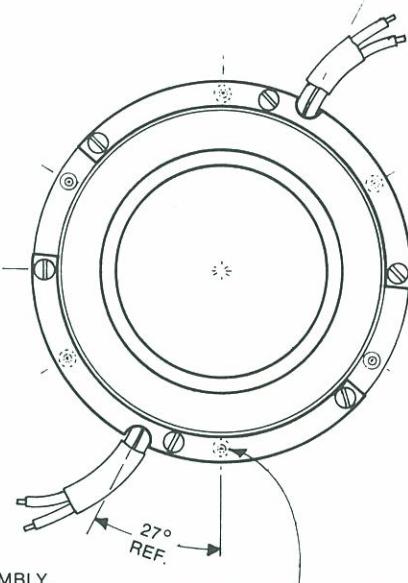
### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	31.0	76.8	39.0	24.7			
Peak Current - $I_p$	AMPERES	Rated	20.0	8.00	15.6	25.7			
Torque Sensitivity - $K_T$	LB.FT./AMP	±10%	1.15	2.88	1.47	0.894			
Back EMF Constant - $K_B$	V per RAD/S	±10%	1.56	3.91	1.99	1.21			
DC Resistance ( $25^\circ\text{C}$ ) - $R_M$	OHMS	±12.5%	1.55	9.60	2.50	0.96			
Inductance - $L_M$	mH	±30%	3.8	24	6.2	2.3			



**NOTES:**

1. — MOTOR TO BE SHIPPED AS FOUR SEPARATE COMPONENTS: ROTOR ASSEMBLY, STATOR ASSEMBLY, AND (2) BRUSH SEGMENT ASSEMBLIES.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — CONNECT (2) GREEN LEADS TOGETHER AND (2) ORANGE LEADS TOGETHER FOR PROPER OPERATION.
5. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.



.161 DIA. THRU 82° C'SINK TO .284  
MIN. DIA. (6) HOLES EQ. SPACED ON  
8.600 DIA. B.C.

LEADS:  
#16 AWG TYPE "E" TEFLON COATED  
PER MIL W-16878, 30" MIN. LENGTH.

## SIZE CONSTANTS

### Value      Units

Peak Torque Rating - $T_p$	46	LB. FT.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	800	WATTS
Motor Constant - $K_M$	1.63	LB.FT./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	12.8	RAD/S
Electrical Time Constant - $\tau_E$	3.80	MS
Static Friction (Max.) - $T_f$	0.50	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	3.59      0.020
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - TPR	0.7	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	4	PERCENT
Ripple Frequency (Fundamental)	97	CYCLES/REV.
Number of Poles	24	
Rotor Inertia - $J_M$	0.028	LB.FT.S <sup>2</sup>
Motor Weight	20	LB.

## WINDING CONSTANTS

### Winding Designation

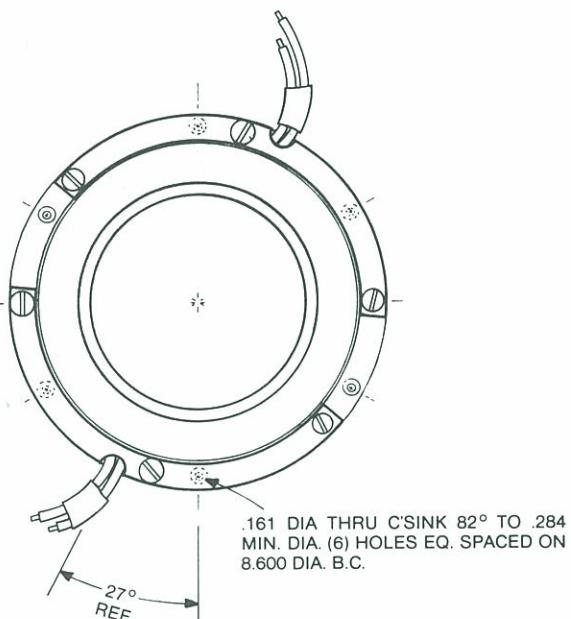
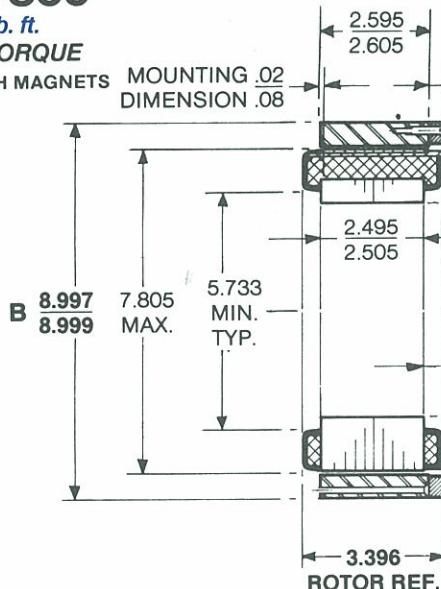
	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	20.0	43.0	63.5	54.3			
Peak Current - $I_p$	AMPERES	Rated	40.0	20.0	12.4	15.7			
Torque Sensitivity - $K_T$	LB.FT./AMP	± 10%	1.15	2.30	3.71	2.94			
Back EMF Constant - $K_B$	V per RAD/S	± 10%	1.56	3.12	5.03	3.99			
DC Resistance ( $25^\circ\text{C}$ ) - $R_M$	OHMS	± 12.5%	0.50	2.15	5.12	3.46			
Inductance - $L_M$	mH	± 30%	1.9	7.6	20	12			

# QT-7809

60 lb. ft.

PEAK TORQUE

RARE EARTH MAGNETS MOUNTING .02  
DIMENSION .08



**NOTES:**

1. — MOTOR TO BE SUPPLIED AS FOUR (4) SEPARATE COMPONENTS: ROTOR ASSEMBLY, STATOR ASSEMBLY, AND (2) BRUSH RING SEGMENTS.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEADS, WITH RESPECT TO ORANGE LEADS, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — CONNECT (2) GREEN LEADS TOGETHER AND (2) ORANGE LEADS TOGETHER FOR PROPER OPERATION.
5. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**LEADS:**

#16 AWG TYPE "E" TEFLON COATED  
PER MIL W-16878, 30" MIN. LENGTH.

## SIZE CONSTANTS

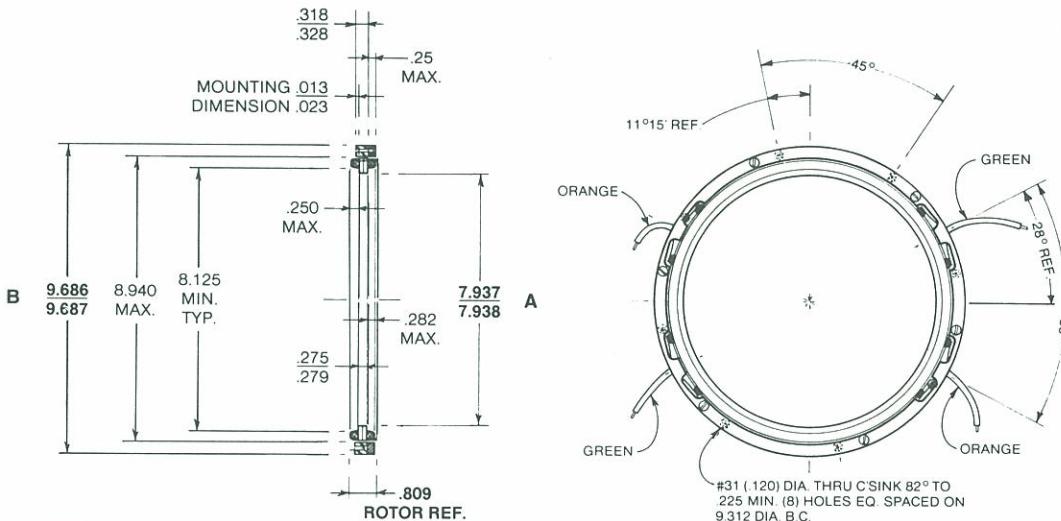
## Value      Units

Peak Torque Rating - $T_p$	60	LB. FT.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	615	WATTS
Motor Constant - $K_m$	2.42	LB.FT./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	7.55	RAD/S
Electrical Time Constant - $\tau_e$	4.36	MS
Static Friction (Max.) - $T_f$	0.83	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	7.95      0.133
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	0.60	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	4	PERCENT
Ripple Frequency (Fundamental)	97	CYCLES/REV.
Number of Poles	24	
Rotor Inertia - $J_m$	0.041	LB.FT.S <sup>2</sup>
Motor Weight	31	LB.

## WINDING CONSTANTS

## Winding Designation

UNITS	TOLERANCES	A	B	C	D	E	F	G
VOLTS	Nom.	31.8	63.7	50.4	40.1	25.3		
AMPERES	Rated	19.3	9.65	12.3	15.0	24.6		
LB.FT./AMP	± 10%	3.11	6.22	4.89	4.00	2.44		
V per RAD/S	± 10%	4.22	8.43	6.63	5.42	3.31		
OHMS	± 12.5%	1.65	6.60	4.10	2.67	1.03		
mH	± 30%	7.2	29	18	12	4.4		



**NOTE:**

1. - MOTOR TO BE SHIPPED AS TWO SEPARATE COMPONENTS: BRUSH RING ASSEMBLY AND ROTOR SECURED INSIDE STATOR WITH SHIPPING CLAMP. CAUTION: DO NOT REMOVE ROTOR FROM STATOR.
2. MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. - WITH POSITIVE CURRENT APPLIED TO GREEN LEADS, WITH RESPECT TO ORANGE LEADS, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. - CONNECT (2) GREEN LEADS TOGETHER AND (2) ORANGE LEADS TOGETHER FOR PROPER OPERATION.
5. - TYPICAL BRUSH LIFE > 10<sup>7</sup> REV'S.

LEADS:  
#24 AWG TYPE "EE" TEFLON COATED  
18" MIN. LG.

<b>SIZE CONSTANTS</b>	<b>Value</b>	<b>Units</b>	
Peak Torque Rating - $T_p$	400	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	61	WATTS	
Motor Constant - $K_M$	51.2	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	21.6	RAD/S	
Electrical Time Constant - $\tau_E$	0.40	MS	
Static Friction (Max.) - $T_f$	10	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	18.7	OZ. IN. PER RAD/S
	Infinite Impedance - $F_i$	0.6	OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	1.5	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	10	PERCENT	
Ripple Frequency - (Fundamental)	143	CYCLES/REV.	
Number of Poles	32		
Rotor Inertia - $J_M$	1.04	OZ.IN.S <sup>2</sup>	
Motor Weight	72	OZ.	

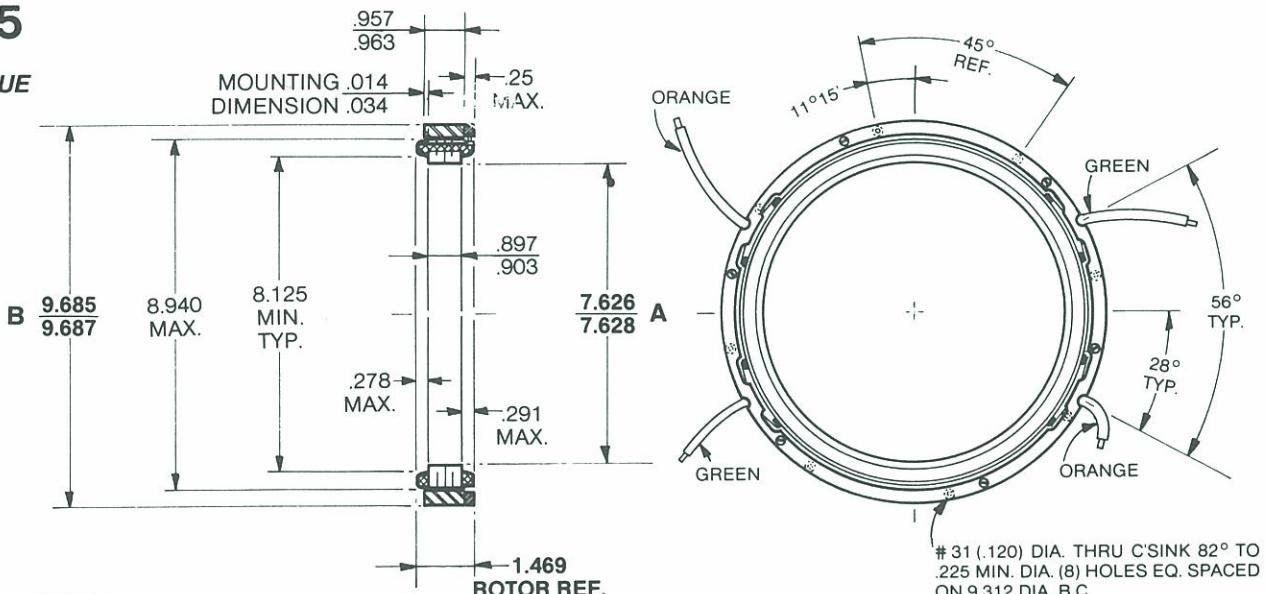
**WINDING CONSTANTS**      **Winding Designation**

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	17.5						
Peak Current - $I_p$	AMPERES	Rated	3.5						
Torque Sensitivity - $K_T$	OZ.IN./AMP.	± 10%	115						
Back EMF Constant - $K_B$	V per RAD/S	± 10%	0.81						
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	± 12.5%	5.0						
Inductance - $L_M$	mH	± 30%	2.0						

# T-8905

13.6 lb. ft.

PEAK TORQUE



NOTES:

1. — MOTOR SUPPLIED AS TWO SEPARATE COMPONENTS: ROTOR ASSEMBLY SECURED INSIDE STATOR WITH SHIPPING CLAMPS, AND BRUSH RING ASSEMBLY. CAUTION: DO NOT REMOVE ROTOR FROM STATOR.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH A POSITIVE VOLTAGE APPLIED TO GREEN LEADS WITH RESPECT TO ORANGE LEADS ROTATION SHALL BE C.C.W. FACING BRUSH RING SIDE.
4. — FOR PROPER OPERATION CONNECT (2) GREEN LEADS TOGETHER AND (2) ORANGE LEADS TOGETHER.
5. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

LEADS:  
#24 AWG TYPE "EE" TEFLON COATED  
PER MIL W-16878, 18" MIN. LG.

## SIZE CONSTANTS

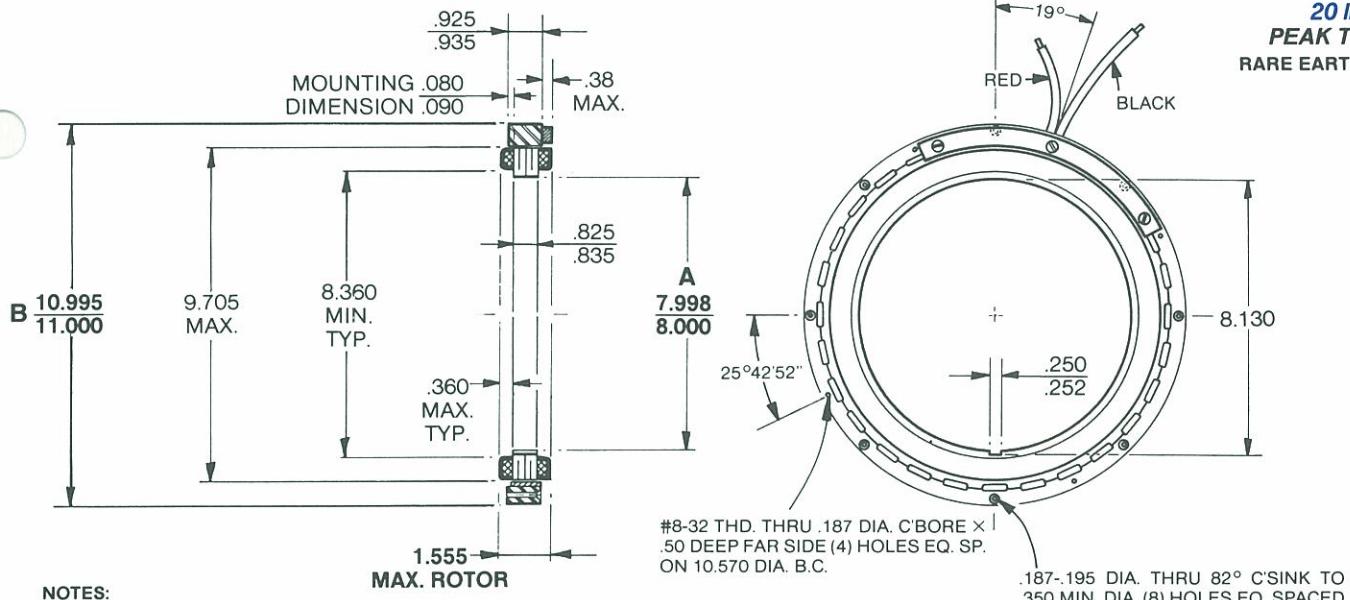
### Value      Units

Peak Torque Rating - $T_p$	13.6	LB. FT.
Power Input, Stalled at $T_p$ (25°C) - $P_p$	666	WATTS
Motor Constant - $K_M$	0.526	LB.FT./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	36.2	RAD/S
Electrical Time Constant - $\tau_E$	1.38	MS
Static Friction (Max.) - $T_f$	0.22	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	0.375      0.011
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - TPR	0.80	°C/WATT
Ripple Torque (Average to Peak) - $T_R$	7	PERCENT
Ripple Frequency - (Fundamental)	143	CYCLES/REV.
Number of Poles	32	
Rotor Inertia - $J_M$	$1.53 \times 10^{-2}$	LB.FT.S <sup>2</sup>
Motor Weight	9.9	LB.

## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ (25°C) - $V_p$	VOLTS	Nom.	47.6						
Peak Current - $I_p$	AMPERES	Rated	14.0						
Torque Sensitivity - $K_t$	LB. FT./AMP	± 10%	0.970						
Back EMF Constant - $K_b$	V PER RAD/S	± 10%	1.32						
DC Resistance (25°C) - $R_m$	OHMS	± 12.5%	3.40						
Inductance - $L_m$	mH	± 30%	4.7						

**NOTES:**

1. — MOTOR SHIPPED AS THREE SEPARATE COMPONENTS: ROTOR ASSEMBLY, BRUSH RING ASSEMBLY, AND STATOR ASSEMBLY.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH A POSITIVE CURRENT APPLIED TO BLACK LEAD WITH RESPECT TO RED LEAD, ROTATION SHALL BE C.C.W. AS VIEWED FROM BRUSH END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
5. — GOLD PLATED COMMUTATOR.

**LEADS:**

#22 AWG TYPE "E" TEFLON COATED  
—19 STRAND— PER MIL-W-16878 12"  
MIN. LENGTH.

**SIZE CONSTANTS****Value      Units**

Peak Torque Rating - $T_p$	20	LB.FT.	
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	235	WATTS	
Motor Constant - $K_M$	1.3	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	8.6	RAD/S	
Electrical Time Constant - $\tau_E$	1.5	MS	
Static Friction (Max.) - $T_f$	0.72	LB.FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	2.31      0.05	LB.FT. PER RAD/S      LB.FT. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	1.0	°C/WATT	
Ripple Torque (Average to Peak) - $T_R$	5	PERCENT	
Ripple Frequency - (Fundamental)	113	CYCLES/REV.	
Number of Poles	28		
Rotor Inertia - $J_M$	0.025	LB.FT.S <sup>2</sup>	
Motor Weight	10.5	LB.	

**WINDING CONSTANTS****Winding Designation**

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	27.0	10.9					
Peak Current - $I_p$	AMPERES	Rated	8.70	21.7					
Torque Sensitivity - $K_T$	LB.FT./AMP	±10%	2.30	0.920					
Back EMF Constant - $K_B$	V PER RAD/S	±10%	3.12	1.25					
DC Resistance ( $25^\circ\text{C}$ ) - $R_M$	OHMS	±12.5%	3.10	0.50					
Inductance - $L_M$	mH	±30%	4.7	0.75					

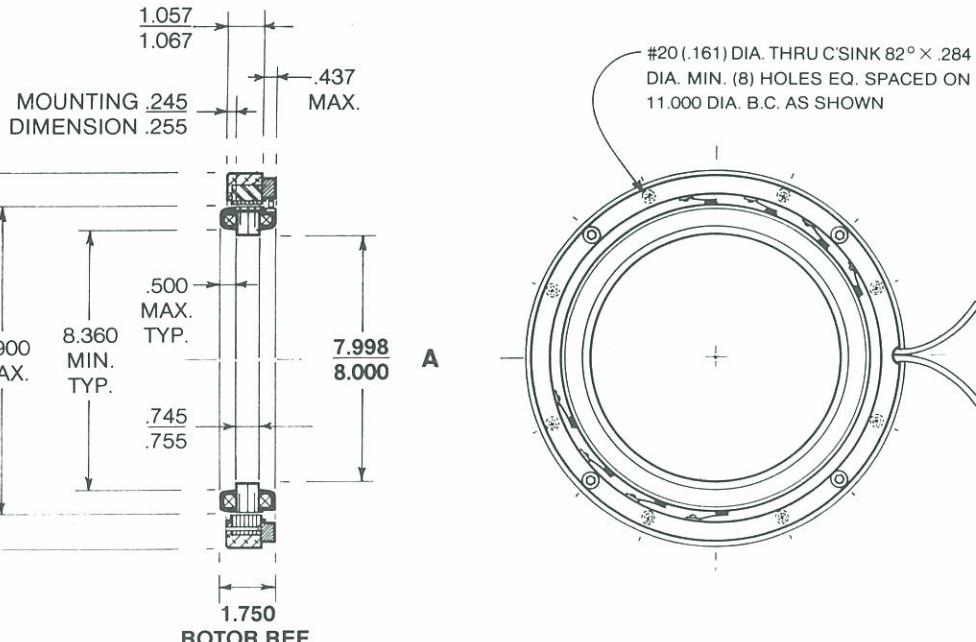
# T-9901

20 lb. ft.

PEAK TORQUE

**NOTES:**

- MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. **CAUTION:** DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .003(.006 T.I.R.) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
- TYPICAL BRUSH LIFE > 10' REV.



**LEADS:**

#16 AWG TYPE "E" TEFLON COATED  
12" MIN. LG.

## SIZE CONSTANTS

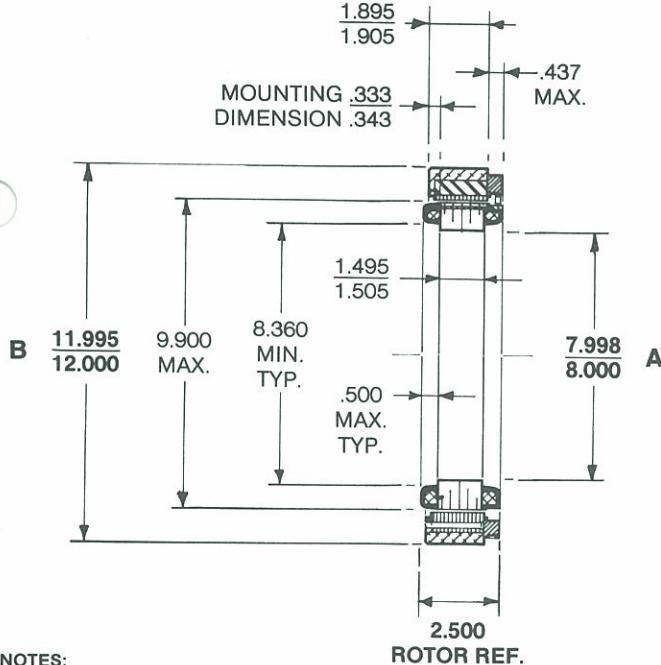
### Value      Units

Peak Torque Rating - $T_p$	20	LB. FT.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	400	WATTS
Motor Constant - $K_m$	1.0	LB.FT./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	14.5	RAD/S
Electrical Time Constant - $\tau_e$	4.0	MS
Static Friction (Max.) - $T_f$	0.25	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_\infty$	1.37      0.015
Maximum Winding Temperature	105	°C
Temperature Rise per Watt - TPR	0.55	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	4	PERCENT
Ripple Frequency - (Fundamental)	143	CYCLES/REV.
Number of Poles	16	
Rotor Inertia - $J_m$	0.025	LB.FT.S <sup>2</sup>
Motor Weight	15	LB.

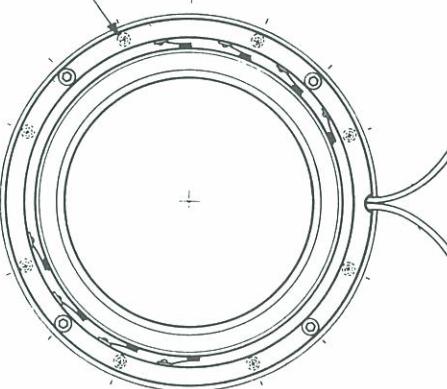
## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	26.2	13.2	52.6	105	21.7		
Peak Current - $I_p$	AMPERES	Rated	15	30.1	7.52	3.76	18.9		
Torque Sensitivity - $K_t$	LB.FT./AMP.	± 10%	1.33	0.665	2.66	5.32	1.06		
Back EMF Constant - $K_b$	V per RAD/S	± 10%	1.8	0.902	3.61	7.21	1.44		
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	± 12.5%	1.75	0.440	7.00	28.0	1.15		
Inductance - $L_m$	mH	± 30%	7	1.8	28	110	4.5		



#20 (.161) DIA. THRU C'SINK 82° × .284  
DIA. MIN. (8) HOLES EQ. SPACED AS  
SHOWN ON 11.000 DIA. B.C.



NOTES:

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH RING ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY WITH KEEPER. CAUTION: DO NOT REMOVE KEEPER UNTIL ROTOR IS FULLY IN PLACE.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN IN .003(.006T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

LEADS:

#16 AWG TYPE "E" TEFLON COATED  
12" MIN. LG.

### SIZE CONSTANTS

Value      Units

Peak Torque Rating - $T_p$	40	LB.FT.	
Power Input, Stalled at $T_p$ (25°C) - $P_p$	512	WATTS	
Motor Constant - $K_m$	1.77	LB.FT./√WATT	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	9.5	RAD/S	
Electrical Time Constant - $\tau_e$	6.3	MS	
Static Friction (Max.) - $T_f$	0.65	LB.FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	4.2	LB.FT. PER RAD/S
	Infinite Impedance - $F_i$	0.03	LB.FT. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	0.40	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	4	PERCENT	
Ripple Frequency - (Fundamental)	143	CYCLES/REV.	
Number of Poles	16		
Rotor Inertia - $J_m$	0.05	LB.FT.S <sup>2</sup>	
Motor Weight	32.3	LB.	

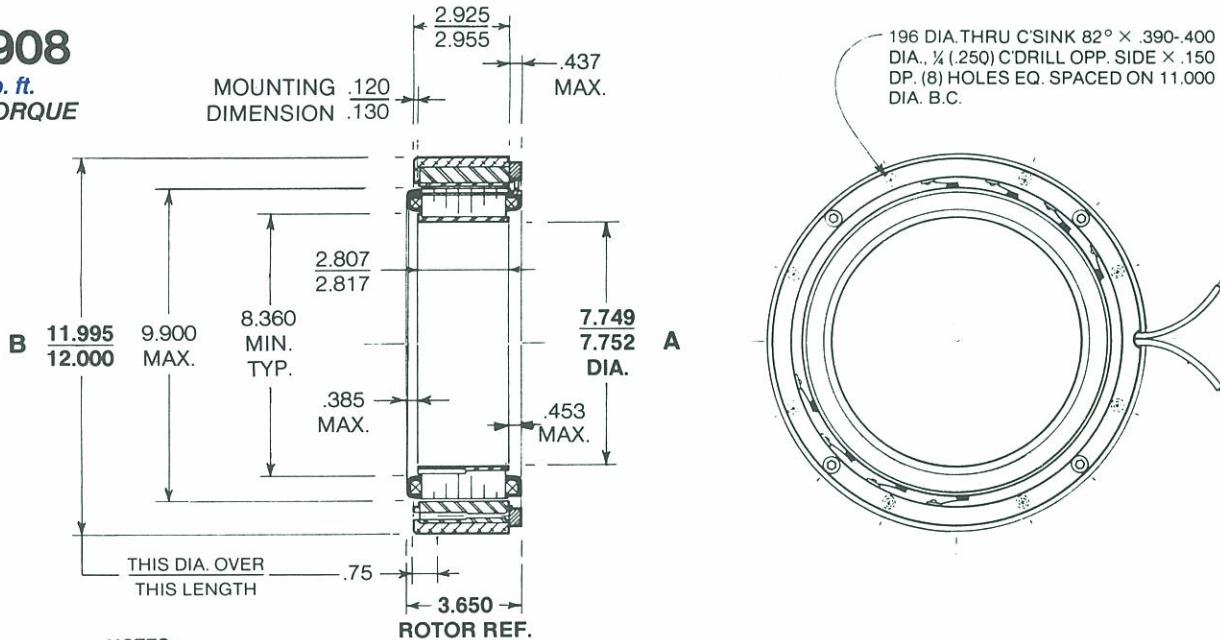
### WINDING CONSTANTS

Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	53.9	27.0	21.5	135.7	34.2		
Peak Current - $I_p$	AMPERES	Rated	9.5	19.0	25.3	3.80	15.2		
Torque Sensitivity - $K_t$	LB.FT./AMP	±10%	4.20	2.10	1.58	10.5	2.63		
Back EMF Constant - $K_b$	V per RAD/S	±10%	5.70	2.85	2.14	14.2	3.57		
DC Resistance (25°C) - $R_m$	OHMS	±12.5%	5.67	1.42	0.85	35.7	2.25		
Inductance - $L_m$	mH	±30%	36	9.0	5.1	225	14		

# T-9908

**70 lb. ft.**  
**PEAK TORQUE**



**NOTES:**

- MOTOR TO BE SHIPPED AS (2) SEPARATE COMPONENTS: STATOR WITH ROTOR SECURED IN PLACE BY SHIPPING CLAMP AND MYLAR IN AIR GAP AND BRUSH RING ASSEMBLY. REMOVE MYLAR AFTER ROTOR AND STATOR ARE SECURELY MOUNTED.  
**CAUTION:** ROTOR MUST REMAIN INSIDE STATOR AT ALL TIMES.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO CONCENTRIC WITHIN .003 (.006 T.I.R.) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**LEADS**  
#16 AWG TYPE "E" TEFLOX COATED  
12" MIN. LG.

## SIZE CONSTANTS

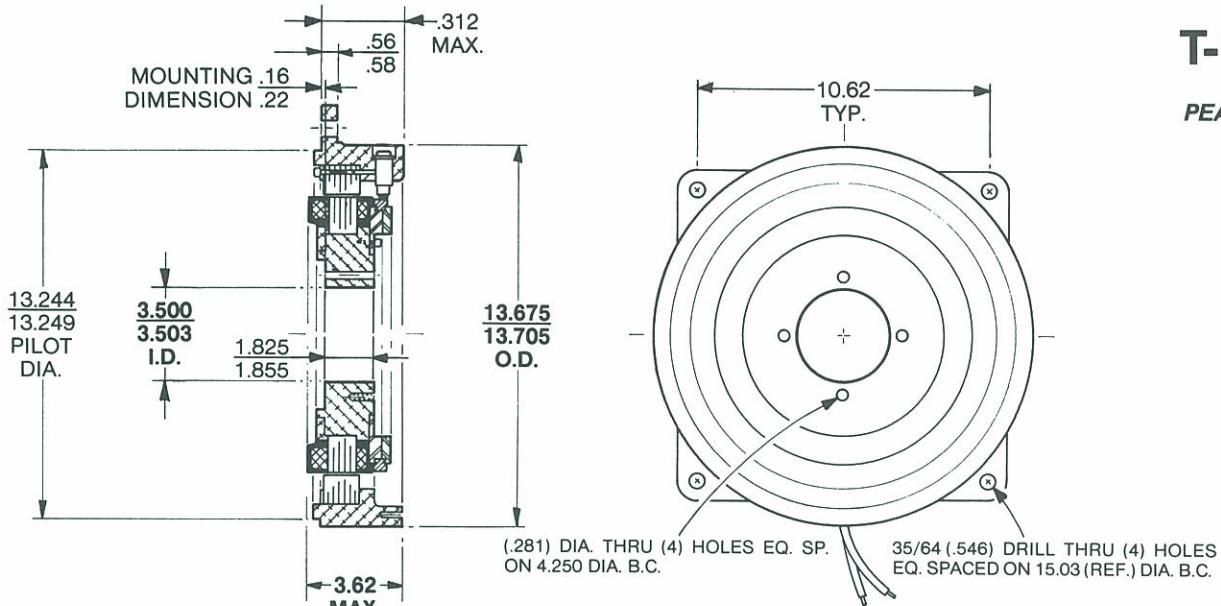
**Value      Units**

Peak Torque Rating - $T_p$	70	LB. FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	720	WATTS	
Motor Constant - $K_M$	2.61	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	7.8	RAD/S	
Electrical Time Constant - $\tau_E$	6.4	MS	
Static Friction (Max.) - $T_f$	0.6	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	9.1	LB. FT. PER RAD/S
	Infinite Impedance - $F_i$	0.3	LB. FT. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	0.4	°C/WATT	
Ripple Torque (Average to Peak) - $T_R$	4	PERCENT	
Ripple Frequency - (Fundamental)	143	CYCLES/REV.	
Number of Poles	16		
Rotor Inertia - $J_M$	0.11	LB.FT.S <sup>2</sup>	
Motor Weight	50	LB.	

## WINDING CONSTANTS

**Winding Designation**

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	142.5	44.8	36.0	72.0			
Peak Current - $I_p$	AMPERES	Rated	5.0	16.0	20.0	10.0			
Torque Sensitivity - $K_T$	LB.FT./AMP.	$\pm 10\%$	14.1	4.40	3.52	7.04			
Back EMF Constant - $K_B$	V per RAD/S	$\pm 10\%$	19.1	5.97	4.77	9.54			
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	28.5	2.80	1.80	7.20			
Inductance - $L_m$	mH	$\pm 30\%$	180	18	11	44			



**NOTES:**

- MOTOR TO BE SHIPPED AS COMPLETE ASSEMBLY WITH ROTOR SECURED IN PLACE BY SHIPPING CLAMP. **CAUTION:** DO NOT REMOVE ROTOR FROM STATOR.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .010 T.I.R. WHEN MOUNTED.
- WITH A POSITIVE CURRENT APPLIED TO GREEN LEAD WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W WHEN VIEWED FROM END OPPOSITE FLANGE MOUNTING.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
- SPECIAL BRUSH MATERIAL FOR IMPROVED COMMUTATION AT HIGH POWER INPUT LEVELS.

**LEADS:**

#18 AWG TYPE "EE" TEFLO COATED  
18" MIN. LENGTH.

## SIZE CONSTANTS

## Value      Units

Peak Torque Rating - $T_p$	35	LB. FT.	
Power Input, Stalled at $T_p$ (25°C) - $P_p$	740	WATTS	
Motor Constant - $K_M$	1.28	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	16	RAD/S	
Electrical Time Constant - $\tau_E$	3.5	MS	
Static Friction (Max.) - $T_f$	0.5	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_\infty$	2.3      0.025	LB. FT. PER RAD/S      LB. FT. PER RAD/S
Maximum Winding Temperature	105	°C	
Temperature Rise per Watt - TPR	0.42	°C/WATT	
Ripple Torque (Average to Peak) - $T_R$	4	PERCENT	
Ripple Frequency - (Fundamental)	190	CYCLES/REV.	
Number of Poles	14		
Rotor Inertia - $J_M$	0.060	LB.FT.S <sup>2</sup>	
Motor Weight	52.5	LB.	

## WINDING CONSTANTS

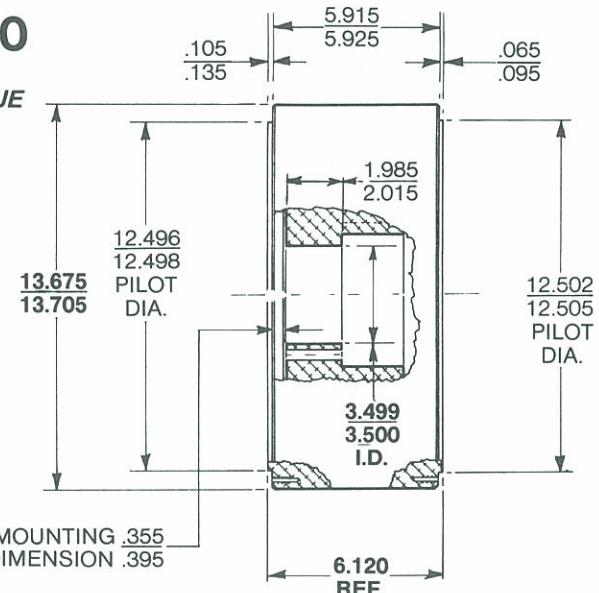
## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ (25°C) - $V_p$	VOLTS	Nom.		38.2	59	90	154	240	
Peak Current - $I_p$	AMPERES	Rated		19.1	12.8	7.65	4.8	3.0	
Torque Sensitivity - $K_T$	LB.FT./AMP	$\pm 10\%$		1.83	2.75	4.58	7.33	11.6	
Back EMF Constant - $K_B$	V per RAD/S	$\pm 10\%$		2.48	3.73	6.20	9.90	15.7	
DC Resistance (25°C) - $R_M$	OHMS	$\pm 12.5\%$		2.0	4.6	11.7	32	80	
Inductance - $L_M$	mH	$\pm 30\%$		7.0	15.7	44	112	281	

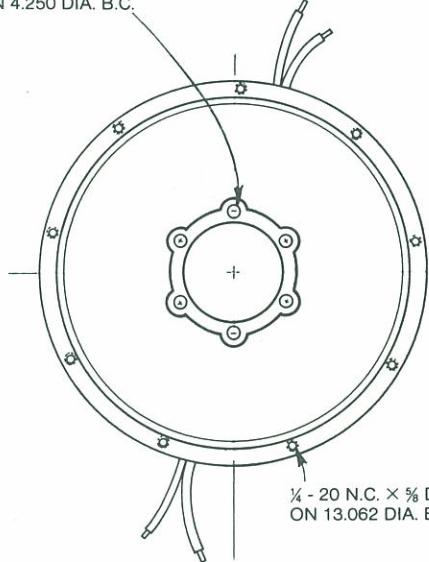
# T-10020

100 lb. ft.

PEAK TORQUE



13/32 (.406) THRU (6) HOLES EQ. SP.  
ON 4.250 DIA. B.C.



1/4 - 20 N.C. X 5/8 DP. (9) HOLES EQ. SP.  
ON 13.062 DIA. B.C. (BOTH ENDS).

NOTES:

1. — MOTOR TO BE SUPPLIED AS COMPLETE ASSEMBLY, WITH ROTOR SECURED INSIDE STATOR. CAUTION: DO NOT REMOVE ROTOR FROM STATOR AT ANY TIME.
2. — MOUNTING REQUIREMENTS: ROTOR AND STATOR TO BE CONCENTRIC WITHIN .007 (.014 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO BLACK LEADS, WITH RESPECT TO WHITE LEADS, ROTATION SHALL BE C.C.W. FACING BRUSH END. CONNECT (2)BLACK LEADS TOGETHER AND (2) WHITE LEADS TOGETHER FOR PROPER OPERATION.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
5. — SPECIAL BRUSH MATERIAL FOR IMPROVED COMMUTATION AT HIGH POWER INPUT LEVELS.

LEADS:  
#18 TEFLON TYPE "E" WIRE, 3' LG.

## SIZE CONSTANTS

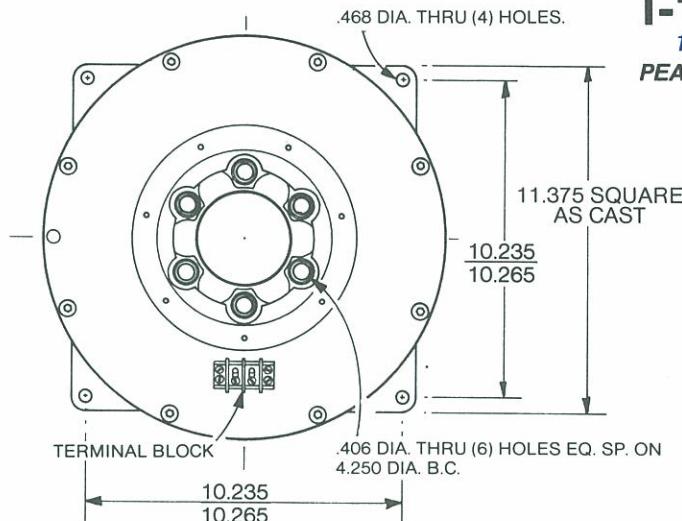
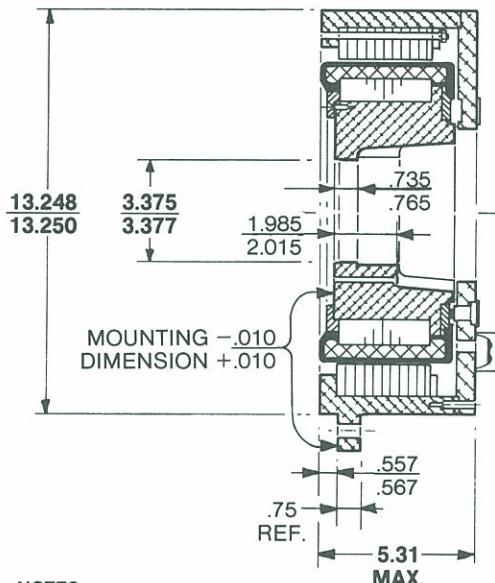
**Value      Units**

Peak Torque Rating - $T_p$	100	LB. FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	930	WATTS	
Motor Constant - $K_m$	3.3	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	7	RAD/S	
Electrical Time Constant - $\tau_e$	7.5	MS	
Static Friction (Max.) - $T_f$	2	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	14.5	LB. FT. PER RAD/S
	Infinite Impedance - $F_i$	0.05	LB. FT. PER RAD/S
Maximum Winding Temperature	105	°C	
Temperature Rise per Watt - TPR	0.3	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	4	PERCENT	
Ripple Frequency - (Fundamental)	190	CYCLES/REV.	
Number of Poles	14		
Rotor Inertia - $J_m$	0.18	LB.FT.S <sup>2</sup>	
Motor Weight	110	LB.	

## WINDING CONSTANTS

## Winding Designations

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	134.9	53.3	84.7	70.2	67.0	33.0	
Peak Current - $I_p$	AMPERES	Rated	7.1	17.2	11.0	18.0	13.4	30.0	
Torque Sensitivity - $K_t$	LB.FT/AMP.	± 10%	14.2	5.8	9.1	5.7	7.46	3.33	
Back EMF Constant - $K_b$	V per RAD/S	± 10%	19.2	7.9	12.3	7.7	10.1	4.50	
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	± 12.5%	19.0	3.1	7.7	3.9	5.00	1.10	
Inductance - $L_m$	mH	± 30%	143	24	60	20	40	7.0	



NOTES:

- MOTOR TO BE SHIPPED AS COMPLETE ASSEMBLY WITH ROTOR SECURED IN PLACE BY SHIPPING CLAMP. **CAUTION:** DO NOT REMOVE ROTOR FROM STATOR.
- MOUNTING REQUIREMENTS: ROTOR AND STATOR ARE TO BE CONCENTRIC WITHIN 0.009" (0.018 T.I.R.) WHEN MOUNTED.
- WITH A POSITIVE CURRENT APPLIED TO TERMINAL "A" WITH RESPECT TO TERMINAL "B", ROTATION SHALL BE C.C.W. FACING BRUSH PLATE SIDE.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
- FULL COMPLEMENT OF SPECIAL BRUSHES FOR IMPROVED COMMUTATION AT HIGH POWER INPUT LEVELS.

### SIZE CONSTANTS

**Value      Units**

Peak Torque Rating - $T_p$	100	LB. FT.	
Power Input, Stalled at $T_p$ (25°C) - $P_p$	1040	WATTS	
Motor Constant - $K_m$	3.10	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	7.67	RAD/S	
Electrical Time Constant - $\tau_e$	5.77	MS	
Static Friction (Max.) - $T_f$	1.0	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	13.0	LB. FT. PER RAD/S
	Infinite Impedance - $F_1$	0.05	LB. FT. PER RAD/S
Maximum Winding Temperature	105	°C	
Temperature Rise per Watt - TPR	0.3	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	4	PERCENT	
Ripple Frequency - (Fundamental)	190	CYCLES/REV.	
Number of Poles	14		
Rotor Inertia - $J_m$	0.178	LB.FT.S <sup>2</sup>	
Motor Weight	95.5	LB.	

### WINDING CONSTANTS

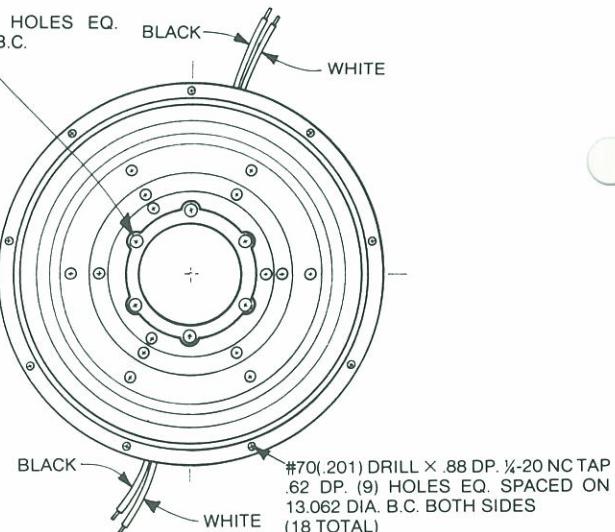
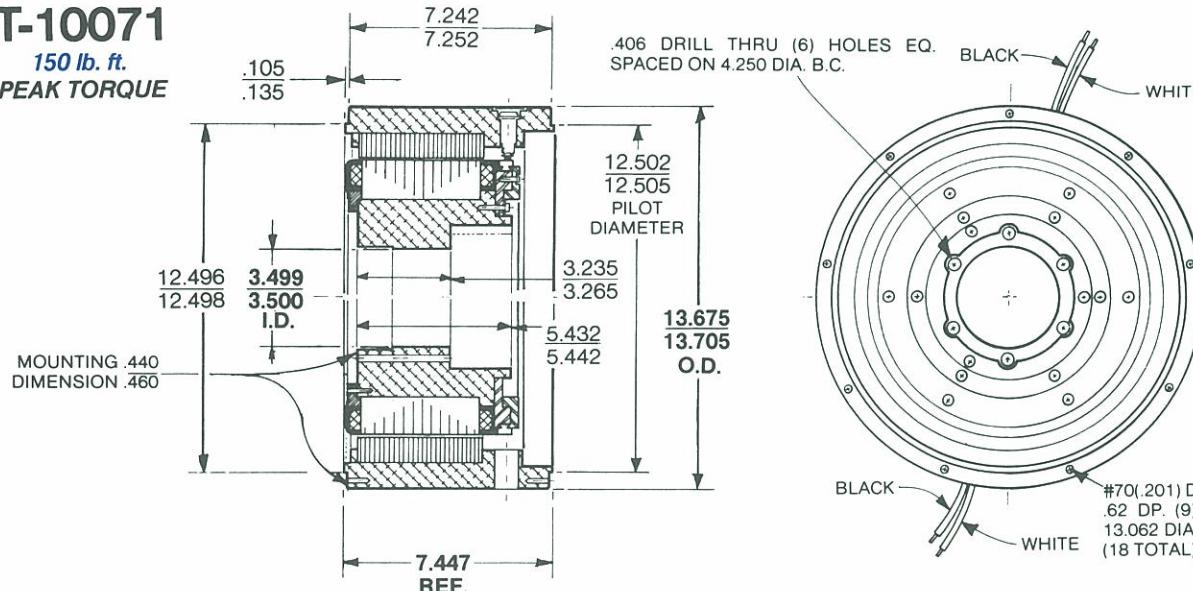
**Winding Designation**

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ (25°C) - $V_p$	VOLTS	Nom.	52.0	208	26.2	33.0	66.5	103	165
Peak Current - $I_p$	AMPERES	Rated	20.0	5.00	40.0	30.0	17.1	10.0	6.33
Torque Sensitivity - $K_t$	LB.FT./AMP	±10%	5.00	20.0	2.50	3.33	5.80	10.0	15.8
Back EMF Constant - $K_b$	V per RAD/S	±10%	6.78	27.1	3.40	4.50	7.90	13.6	21.4
DC Resistance (25°C) - $R_m$	OHMS	±12.5%	2.60	41.6	0.660	1.10	3.90	10.3	26.0
Inductance - $L_m$	mH	±30%	15	260	4.0	7.0	20	60	150

# T-10071

150 lb. ft.

PEAK TORQUE



NOTES:

- MOTOR TO BE SUPPLIED AS COMPLETE ASSEMBLY WITH ROTOR SECURED INSIDE STATOR. **CAUTION:** DO NOT REMOVE ROTOR FROM STATOR AT ANY TIME.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .005(.010 T.I.R) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO BLACK LEADS, ROTATION SHALL BE C.C.W. FACING COMMUTATOR.
- CONNECT (2) BLACK LEADS TOGETHER AND (2) WHITE LEADS TOGETHER FOR PROPER OPERATION.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
- SPECIAL BRUSH MATERIAL FOR HIGH VOLTAGE OPERATION.

BRUSH LEADS:  
#18 AWG TYPE "E" TEFLON COATED,  
3' LG.

## SIZE CONSTANTS

### Value      Units

Peak Torque Rating - $T_p$	150	LB. FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	1470	WATTS	
Motor Constant - $K_m$	3.9	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	7.2	RAD/S	
Electrical Time Constant - $\tau_e$	6.6	MS	
Static Friction (Max.) - $T_f$	1.8	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	20.8	LB. FT. PER RAD/S
	Infinite Impedance - $F_\infty$	0.06	LB. FT. PER RAD/S
Maximum Winding Temperature	105	°C	
Temperature Rise per Watt - TPR	0.27	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	4	PERCENT	
Ripple Frequency - (Fundamental)	190	CYCLES/REV.	
Number of Poles	14		
Rotor Inertia - $J_m$	0.22	LB.FT.S <sup>2</sup>	
Motor Weight	145	LB.	

## WINDING CONSTANTS

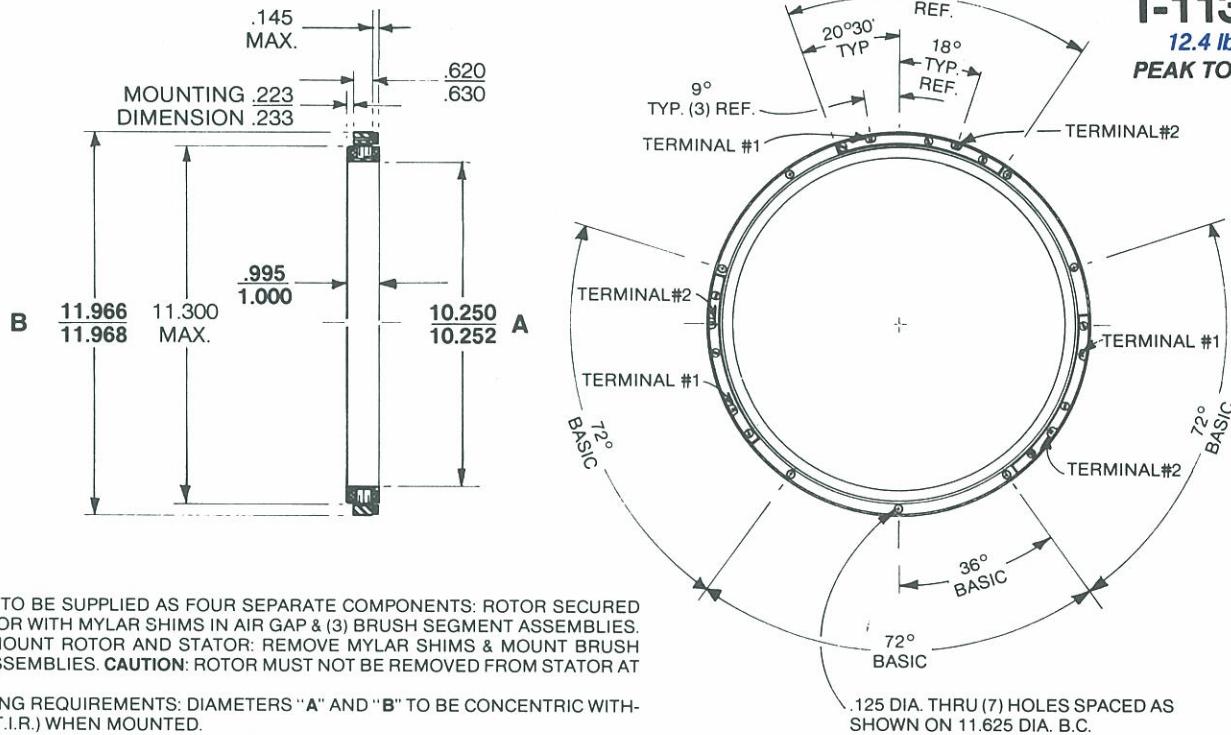
### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	68.8	56.8	109	218	173	34.4	
Peak Current - $I_p$	AMPERES	Rated	21.5	25.8	14.3	6.76	8.60	43.0	
Torque Sensitivity - $K_t$	LB.FT./AMP.	± 10%	7.0	5.8	10.5	22.2	17.5	3.5	
Back EMF Constant - $K_b$	V per RAD/S	± 10%	9.5	7.9	14.2	30.1	23.8	4.75	
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	± 12.5%	3.2	2.2	7.63	32.2	20.2	0.80	
Inductance - $L_m$	mH	± 30%	21.0	14.6	47	210	131	5.2	

**T-11306**

12.4 lb. ft.

PEAK TORQUE

**NOTES:**

1. — MOTOR TO BE SUPPLIED AS FOUR SEPARATE COMPONENTS: ROTOR SECURED INSIDE STATOR WITH MYLAR SHIMS IN AIR GAP & (3) BRUSH SEGMENT ASSEMBLIES. SECURELY MOUNT ROTOR AND STATOR: REMOVE MYLAR SHIMS & MOUNT BRUSH SEGMENT ASSEMBLIES. **CAUTION:** ROTOR MUST NOT BE REMOVED FROM STATOR AT ANY TIME.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO TERMINALS #2, WITH RESPECT TO TERMINALS #1, ROTATION SHALL BE C.W. FACING BRUSH END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**SIZE CONSTANTS****Value****Units**

Peak Torque Rating - $T_p$	12.4	LB.FT.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	260	WATTS
Motor Constant - $K_m$	0.77	LB.FT./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	16	RAD/S
Electrical Time Constant - $\tau_e$	1.0	MS
Static Friction (Max.) - $F_f$	0.37	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_\infty$	0.8      0.006
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	0.30	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	4	PERCENT
Ripple Frequency - (Fundamental)	241	CYCLES/REV.
Number of Poles	40	
Rotor Inertia - $J_m$	0.02	LB.FT.S <sup>2</sup>
Motor Weight	7.2	LB.

**WINDING CONSTANTS****Winding Designation**

	UNITS	TOLERANCES	A	B	C	D*	E*	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	16.0	26.9	63.6	127	160	19.5	40.5
Peak Current - $I_p$	AMPERES	Rated	16.3	8.16	4.08	2.04	1.63	13.0	6.53
Torque Sensitivity - $K_t$	LB.FT/AMP.	± 10%	0.76	1.52	3.04	6.08	7.6	0.95	1.9
Back EMF Constant - $K_b$	V per RAD/S	± 10%	1.03	2.06	4.12	8.24	10.3	1.29	2.57
DC Resistance (25°C) - $R_m$	OHMS	± 12.5%	0.98	3.30	14.0	62.4	98.3	1.5	6.2
Inductance - $L_m$	mH	± 30%	1.0	2.4	16	64	100	1.6	6.3

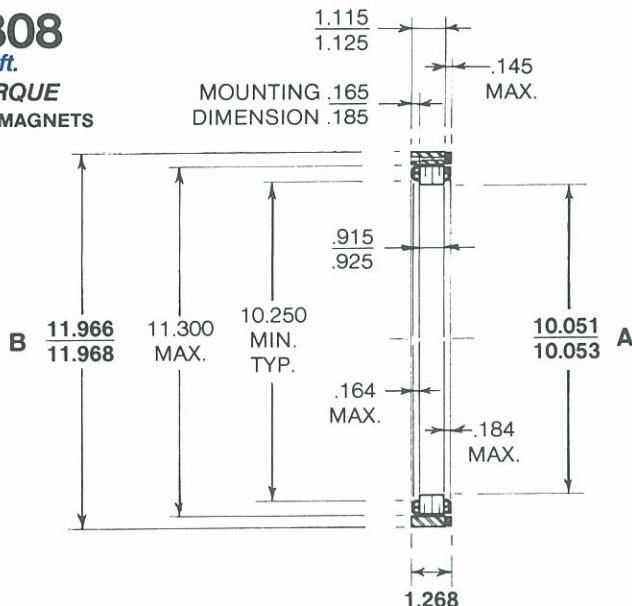
\*SPECIAL WINDING

# T-11308

20 lb. ft.

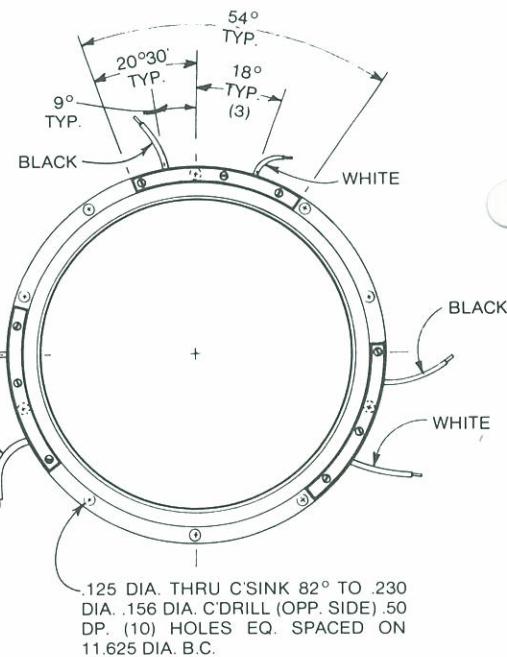
PEAK TORQUE

HIGH ENERGY MAGNETS



### ROTOR REF.

- NOTES:**
- MOTOR TO BE SUPPLIED AS **FOUR** SEPARATE COMPONENTS: ROTOR-STATOR (WITH MYLAR STRIPS IN AIR GAP) AND (3) BRUSH RING SEGMENT ASSEMBLIES. **CAUTION:** DO NOT REMOVE MYLAR UNTIL ROTOR IS FULLY IN PLACE.
  - MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
  - WITH A POSITIVE CURRENT APPLIED TO WHITE LEADS, WITH RESPECT TO BLACK LEADS, ROTATION SHALL BE C.W. FACING BRUSH RING END.
  - CONNECT (3) BLACK LEADS TOGETHER AND (3) WHITE LEADS TOGETHER FOR PROPER OPERATION.
  - TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.



### LEADS:

#22 AWG TYPE "E" TEFLON COATED PER MIL W-16878 36" MIN. LG.

## SIZE CONSTANTS

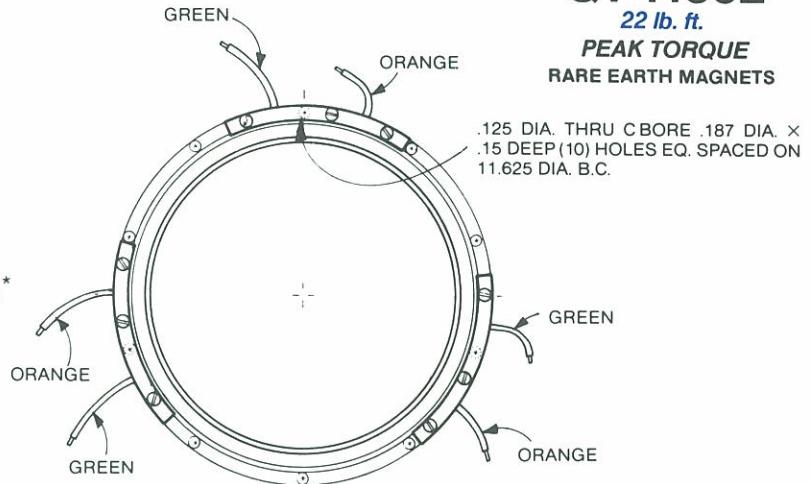
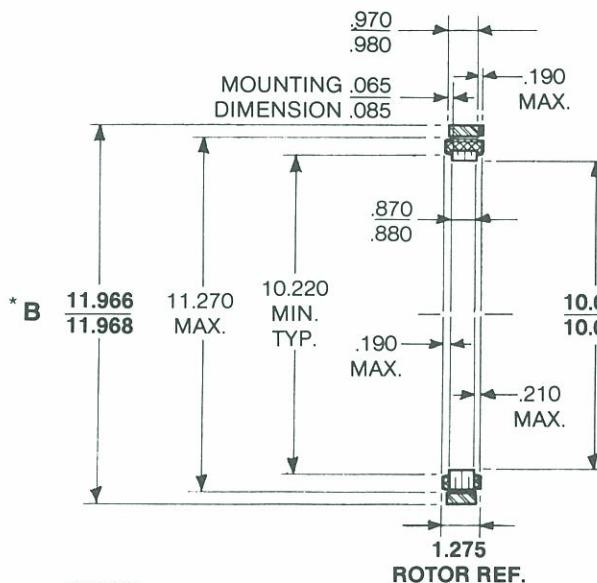
### Value      Units

Peak Torque Rating - $T_p$	20	LB. FT.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	218	WATTS
Motor Constant - $K_m$	1.35	LB.FT./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	8	RAD/S
Electrical Time Constant - $\tau_e$	1.4	MS
Static Friction (Max.) - $T_f$	0.71	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_\infty$	2.5      LB. FT. PER RAD/S 0.02      LB. FT. PER RAD/S
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	0.30	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	4	PERCENT
Ripple Frequency - (Fundamental)	181	CYCLES/REV.
Number of Poles	40	
Rotor Inertia - $J_m$	0.03	LB.FT.S <sup>2</sup>
Motor Weight	9	LB.

## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	64.1	32.1	40.4	80.6			
Peak Current - $I_p$	AMPERES	Rated	3.39	6.78	5.51	2.75			
Torque Sensitivity - $K_t$	LB.FT./AMP.	$\pm 10\%$	5.90	2.95	3.63	7.26			
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	8.00	4.00	4.92	9.84			
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	18.9	4.73	7.33	29.3			
Inductance - $L_m$	mH	$\pm 30\%$	26	6.5	9.8	39			

**NOTES:**

1. — MOTOR TO BE SHIPPED AS FIVE (5) SEPARATE COMPONENTS: STATOR ASSEM-BLY, ROTOR ASSEMBLY, AND (3) THREE BRUSH SEGMENT ASSEMBLIES.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITH-IN .004 (.008 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEADS, WITH RESPECT TO ORANGE LEADS, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — CONNECT (3) GREEN LEADS TOGETHER AND (3) ORANGE LEADS TOGETHER FOR PROPER OPERATION.
5. — DIAMETERS MARKED "\*" ARE AVERAGE OF FREE STATE.
6. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**LEADS:**

#22 AWG TEFLON COATED PER MIL W-16878, 36" MIN. LENGTH.

**SIZE CONSTANTS****Value      Units**

Peak Torque Rating - $T_p$	22	LB. FT.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	232	WATTS
Motor Constant - $K_m$	1.44	LB.FT./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	7.8	RAD/S
Electrical Time Constant - $\tau_e$	0.93	MS
Static Friction (Max.) - $T_f$	1.0	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_\infty$	2.83      0.02
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	0.5	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	4	PERCENT
Ripple Frequency (Fundamental)	181	CYCLES/REV.
Number of Poles	40	
Rotor Inertia - $J_m$	0.03	LB.FT.S <sup>2</sup>
Motor Weight	8.7	LB.

**WINDING CONSTANTS****Winding Designation**

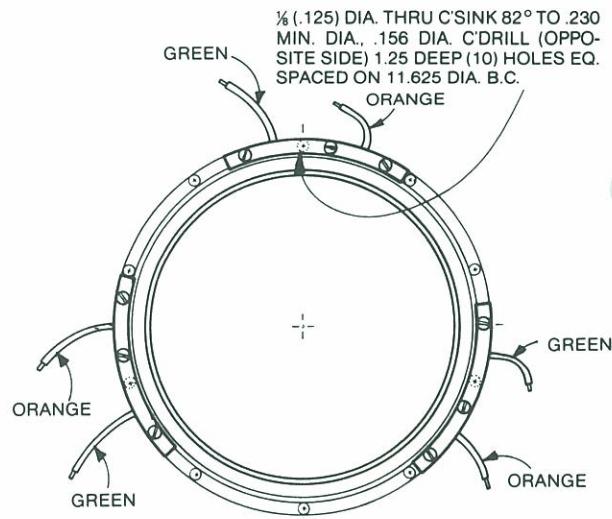
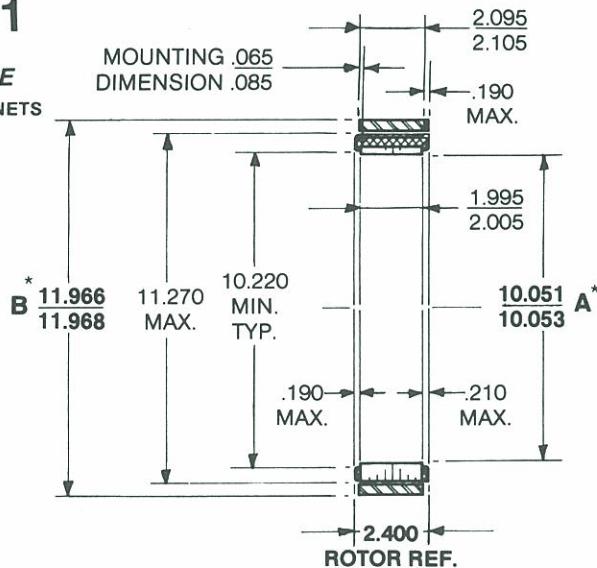
	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	26.4	41.9					
Peak Current - $I_p$	AMPERES	Rated	8.80	5.38					
Torque Sensitivity - $K_t$	LB.FT./AMPS	$\pm 10\%$	2.50	4.09					
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	3.39	5.55					
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	3.00	7.79					
Inductance - $L_m$	mH	$\pm 30\%$	2.8	7.5					

# QT-11301

50 lb. ft.

PEAK TORQUE

RARE EARTH MAGNETS



NOTES:

- MOTOR TO BE SUPPLIED AS FIVE SEPARATE COMPONENTS: ROTOR ASSEMBLY, STATOR ASSEMBLY, AND (3) BRUSH SEGMENT ASSEMBLIES.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .004 (.008 T.I.R.) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO GREEN LEADS, WITH RESPECT TO ORANGE LEADS, ROTATION SHALL BE C.C.W FACING BRUSH RING END.
- CONNECT (3) GREEN LEADS TOGETHER AND (3) ORANGE LEADS TOGETHER FOR PROPER OPERATION.
- DIAMETERS MARKED "\*" ARE AVERAGE OF FREE STATE.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

LEADS:  
#22 AWG TEFLON COATED PER MIL  
W-16878, 36" MIN. LENGTH.

## SIZE CONSTANTS

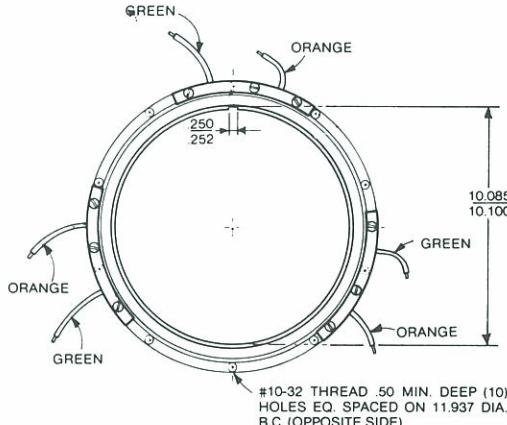
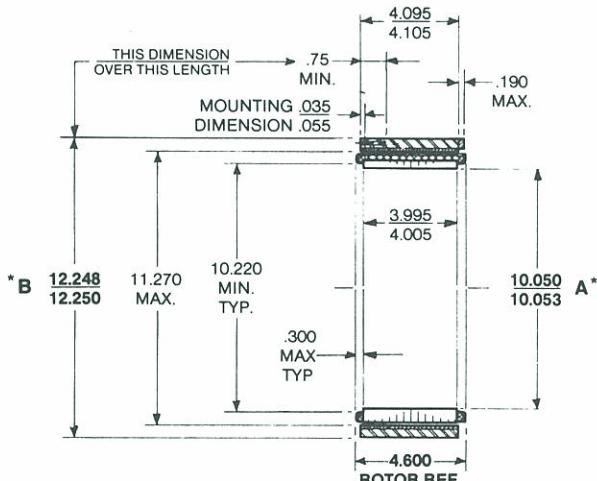
**Value      Units**

Peak Torque Rating - $T_p$	50	LB. FT.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	331	WATTS
Motor Constant - $K_M$	2.75	LB.FT./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	4.87	RAD/S
Electrical Time Constant - $\tau_E$	1.20	MS
Static Friction (Max.) - $T_f$	1.6	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_\infty$	10.3      0.30
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - TPR	0.30	°C/WATT
Ripple Torque (Average to Peak) - $T_R$	4	PERCENT
Ripple Frequency (Fundamental)	181	CYCLES/REV.
Number of Poles	40	
Rotor Inertia - $J_M$	0.060	LB.FT.S <sup>2</sup>
Motor Weight	17.5	LB.

## WINDING CONSTANTS

*Winding Designation*

	UNITS	TOLERANCES	A	B	C	D	E	F	G
	VOLTS	Nom.	57.5	28.7	36.2	45.6			
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	AMPERES	Rated	5.75	12.2	9.78	7.52			
Peak Current - $I_p$	LB.FT./AMP	$\pm 10\%$	8.70	4.10	5.12	6.65			
Torque Sensitivity - $K_T$	V per RAD/S	$\pm 10\%$	11.8	5.56	6.94	9.02			
Back EMF Constant - $K_B$	OHMS	$\pm 12.5\%$	10.0	2.35	3.70	6.07			
DC Resistance ( $25^\circ\text{C}$ ) - $R_M$	mH	$\pm 30\%$	12	2.7	4.2	7.0			
Inductance - $L_M$									



## NOTES:

- MOTOR TO BE SHIPPED AS FOUR (4) SEPARATE COMPONENTS: (3) BRUSH RING SEGMENTS, AND STATOR ASSEMBLY WITH ROTOR ASSEMBLY INSIDE SECURED WITH SHIPPING CLAMP AND MYLAR IN AIR GAP - REMOVE MYLAR AFTER ROTOR AND STATOR ARE SECURELY MOUNTED.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .004 (.008 T.I.R.) WHEN MOUNTED.
- WITH POSITIVE CURRENT APPLIED TO GREEN LEADS, WITH RESPECT TO ORANGE LEADS, ROTATION SHALL BE C.C.W. FACING BRUSH RING SIDE
- CONNECT (3) GREEN LEADS TOGETHER AND (3) ORANGE LEADS TOGETHER FOR PROPER OPERATION.
- DIAMETERS MARKED \*\* ARE AVERAGE OF FREE STATE.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

## LEADS:

#22 AWG TYPE 'E' TEFLOX COATED PER MIL W-16878, .36" MIN. LENGTH.

**SIZE CONSTANTS****Value      Units**

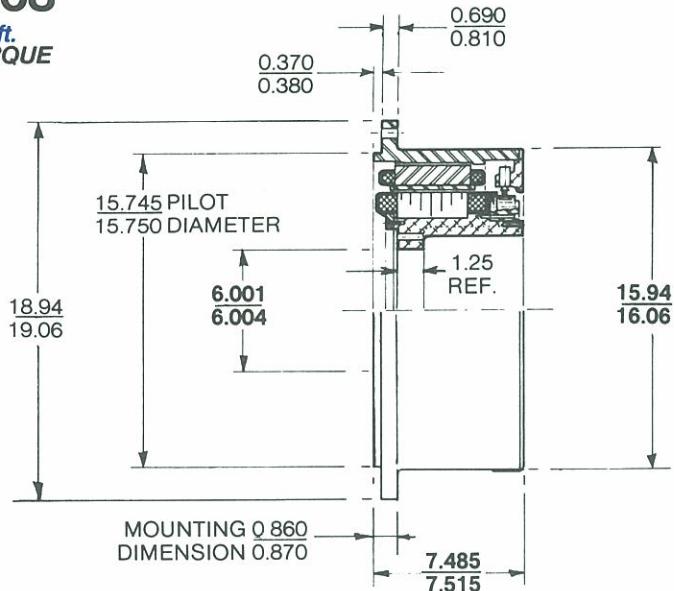
Peak Torque Rating - $T_p$	100	LB. FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	499	WATTS	
Motor Constant - $K_M$	4.5	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	3.6	RAD/S	
Electrical Time Constant - $\tau_E$	0.76	MS	
Static Friction (Max.) - $T_f$	2.5	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	27	LB. FT. PER RAD/S
	Infinite Impedance - $F_\infty$	0.50	LB. FT. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	0.21	°C/WATT	
Ripple Torque (Average to Peak) - $T_R$	4	PERCENT	
Ripple Frequency - (Fundamental)	181	CYCLES/REV.	
Number of Poles	40		
Rotor Inertia - $J_M$	0.11	LB.FT.S <sup>2</sup>	
Motor Weight	39	LB.	

**WINDING CONSTANTS****Winding Designation**

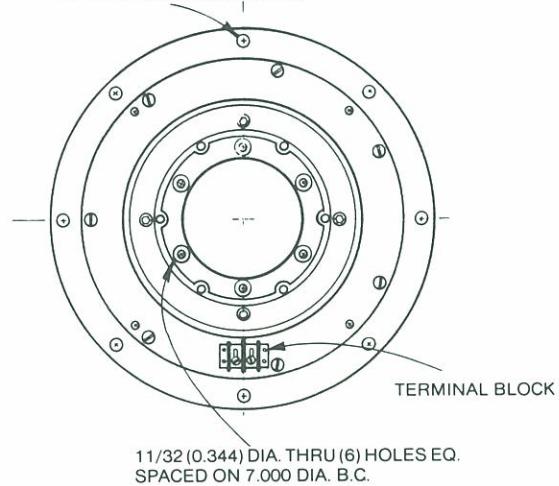
	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	45.8	37.8					
Peak Current - $I_p$	AMPERES	Rated	10.9	14.0					
Torque Sensitivity - $K_T$	LB.FT./AMP	$\pm 10\%$	9.20	7.15					
Back EMF Constant - $K_B$	V per RAD/S	$\pm 10\%$	12.5	9.70					
DC Resistance ( $25^\circ\text{C}$ ) - $R_M$	OHMS	$\pm 12.5\%$	4.20	2.70					
Inductance - $L_M$	mH	$\pm 30\%$	3.2	1.9					

# T-12008

**201 lb. ft.**  
**PEAK TORQUE**



17/32 (0.531) DIA. THRU (8) HOLES EQ.  
SPACED ON 17.750 DIA. B.C.



## NOTES:

1. — MOTOR SUPPLIED AS COMPLETE ASSEMBLY WITH ROTOR SECURED INSIDE STATOR. **CAUTION:** DO NOT REMOVE ROTOR FROM STATOR AT ANY TIME.
2. — MOUNTING REQUIREMENTS: STATOR AND ROTOR TO BE CONCENTRIC WITHIN .005 (.010 T.I.R.) WHEN MOUNTED.
3. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REVS.
4. — SPECIAL BRUSH MATERIAL FOR IMPROVED COMMUTATION AT HIGH POWER INPUT LEVELS.

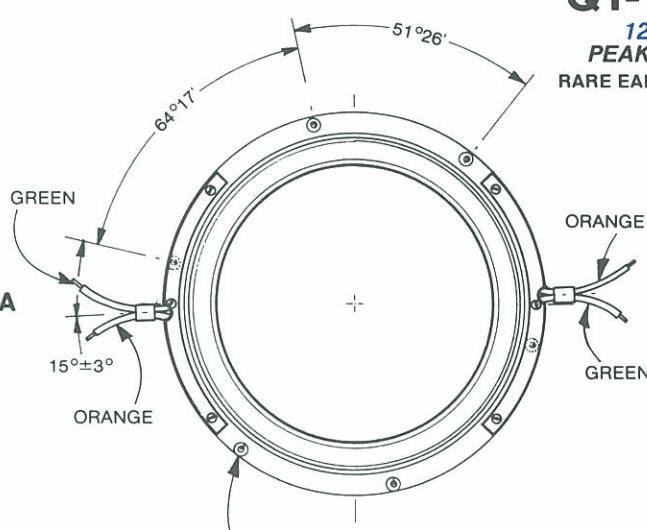
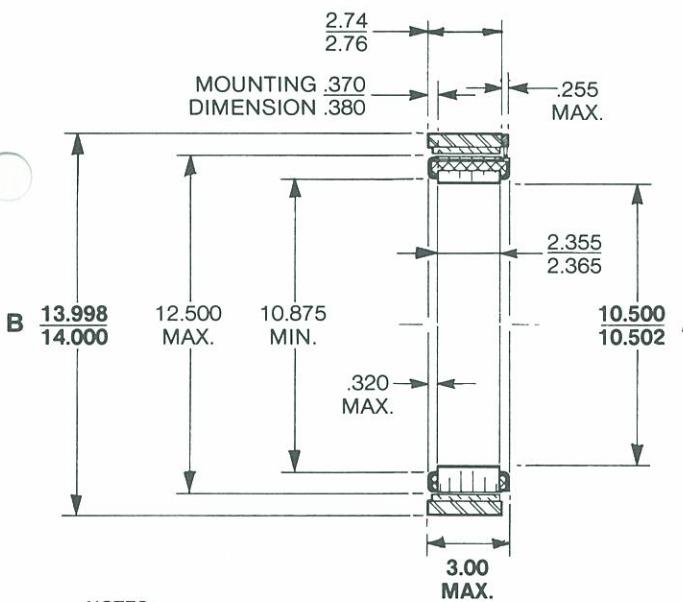
## SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>	
Peak Torque Rating - $T_p$	201	LB. FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	2628	WATTS	
Motor Constant - $K_m$	3.93	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p \cdot \omega_{NL}$	9.63	RAD/S	
Electrical Time Constant - $\tau_e$	8.33	MS	
Static Friction (Max.) - $T_f$	1.0	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	20.9	LB. FT. PER RAD/S
	Infinite Impedance - $F_\infty$	0.09	LB. FT. PER RAD/S
Maximum Winding Temperature	105	°C	
Temperature Rise per Watt - $TPR$	0.2	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	2	PERCENT	
Ripple Frequency - (Fundamental)	197	CYCLES/REV.	
Number of Poles	14		
Rotor Inertia - $J_m$	0.500	LB.FT.S <sup>2</sup>	
Motor Weight	194	LB.	

## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	112	50.0	59.5	69.0	87.5	138	28.5
Peak Current - $I_p$	AMPERES	Rated	23.4	51.5	42.5	36.5	28.2	18.4	85.9
Torque Sensitivity - $K_t$	LB.FT./AMP	±10%	8.60	3.90	4.70	5.50	7.10	10.9	2.32
Back EMF Constant - $K_b$	V per RAD/S	±10%	11.7	5.30	6.40	7.50	9.70	15.0	3.14
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	±12.5%	4.80	0.970	1.40	1.90	3.10	7.50	0.330
Inductance - $L_m$	mH	±30%	40	8.0	12	16	26	64	3.0

**NOTES:**

1. — MOTOR SUPPLIED AS FOUR SEPARATE COMPONENTS: ROTOR ASSEMBLY, STATOR ASSEMBLY, AND (2) BRUSH SEGMENTS.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH A POSITIVE VOLTAGE APPLIED TO ORANGE LEADS WITH RESPECT TO GREEN LEADS ROTATION SHALL BE C.W. FACING BRUSH END.
4. — FOR PROPER OPERATION CONNECT (2) GREEN LEADS TOGETHER AND (2) ORANGE LEADS TOGETHER.
5. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

.196 DIA. THRU C'SINK 82° TO .400 ± .02 DIA. (6) HOLES AS SHOWN ON 13.420 DIA. B.C.

**LEADS:**

#16 AWG TYPE "E" TEFLON COATED PER MIL W-16878 12" MIN. LENGTH.

**SIZE CONSTANTS****Value      Units**

Peak Torque Rating - $T_p$	123	LB. FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	794	WATTS	
Motor Constant - $K_m$	4.36	LB.FT./√WATT	
No Load Speed, Theoretical @ $V_p \cdot \omega_{NL}$	4.76	RAD/S	
Electrical Time Constant - $\tau_e$	3.24	MS	
Static Friction (Max.) - $T_f$	1.2	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	25.8      0.2	LB. FT. PER RAD/S      LB. FT. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	0.1	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	2	PERCENT	
Ripple Frequency - (Fundamental)	139	CYCLES/REV.	
Number of Poles	28		
Rotor Inertia - $J_m$	0.170	LB.FT.S <sup>2</sup>	
Motor Weight	42	LB.	

**WINDING CONSTANTS****Winding Designation**

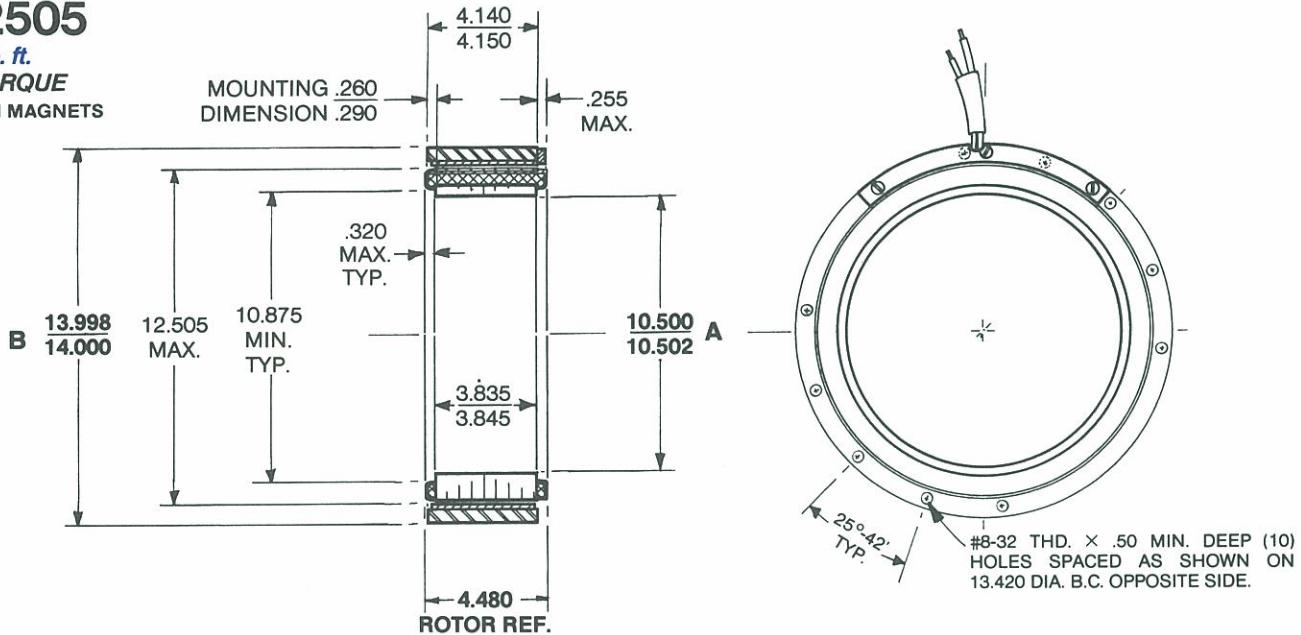
	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	64.6	32.2	41.0				
Peak Current - $I_p$	AMPERES	Rated	12.3	23.4	19.5				
Torque Sensitivity - $K_t$	LB.FT./AMP	± 10%	10.0	5.26	6.32				
Back EMF Constant - $K_b$	V per RAD/S	± 10%	13.6	7.13	8.57				
DC Resistance (25°C) - $R_m$	OHMS	± 12.5%	5.25	1.38	2.10				
Inductance - $L_m$	mH	± 30%	17	4.7	6.8				

# QT-12505

200 lb. ft.

PEAK TORQUE

RARE EARTH MAGNETS



**NOTES:**

1. — MOTOR TO BE SHIPPED AS THREE SEPARATE COMPONENTS: BRUSH SEGMENT ASSEMBLY, ROTOR ASSEMBLY, AND STATOR ASSEMBLY.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .003 (.006 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**LEADS:**

#16 AWG TYPE "E" TEFLON COATED PER MIL W-16878, 12" MIN. LENGTH.

## SIZE CONSTANTS

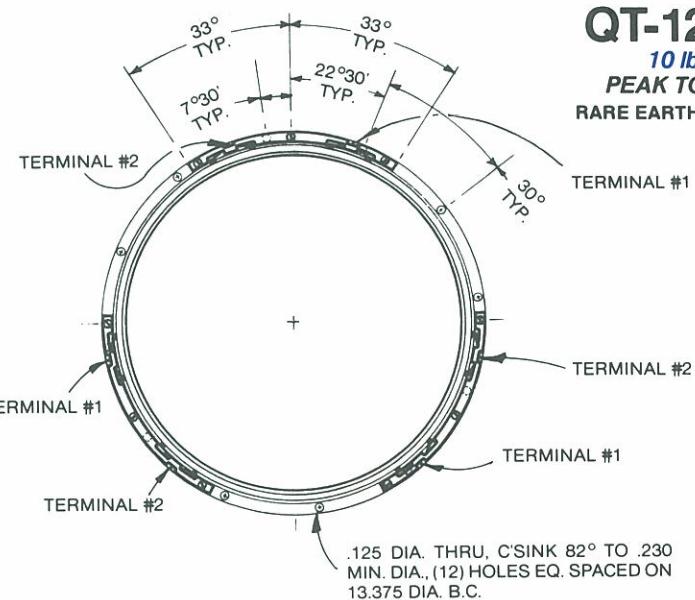
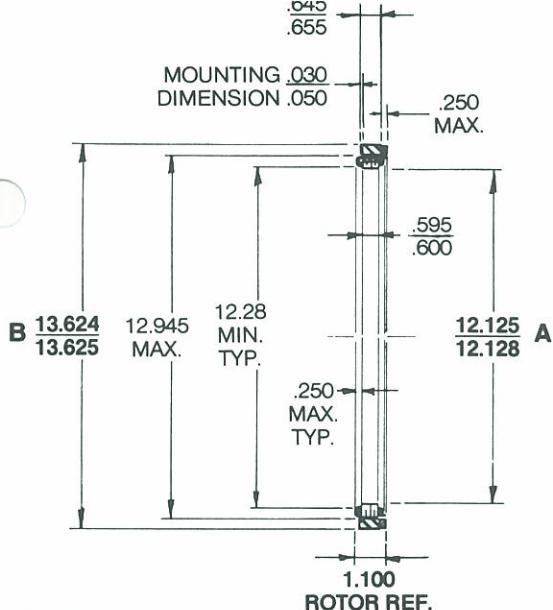
Value      Units

Peak Torque Rating - $T_p$	200	LB. FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	1095	WATTS	
Motor Constant - $K_m$	6.04	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p - \omega_{NL}$	4	RAD/S	
Electrical Time Constant - $\tau_e$	3.78	MS	
Static Friction (Max.) - $T_f$	1.6	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	49.5      0.30	LB. FT. PER RAD/S      LB. FT. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - TPR	0.1	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	2	PERCENT	
Ripple Frequency (Fundamental)	139	CYCLES/REV.	
Number of Poles	28		
Rotor Inertia - $J_m$	0.27	LB.FT.S <sup>2</sup>	
Motor Weight	67	LB.	

## WINDING CONSTANTS

Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	70.2						
Peak Current - $I_p$	AMPERES	Rated	15.6						
Torque Sensitivity - $K_t$	LB.FT./AMP	$\pm 10\%$	12.8						
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	17.4						
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	4.50						
Inductance - $L_m$	mH	$\pm 30\%$	17						



## NOTES:

1. — MOTOR TO BE SHIPPED AS FOUR (4) SEPARATE COMPONENTS: (3) BRUSH RING SEGMENTS, AND STATOR ASSEMBLY WITH ROTOR ASSEMBLY INSIDE, SECURED BY SHIPPING CLAMP WITH MYLAR IN AIR GAP. REMOVE MYLAR AFTER ROTOR AND STATOR ARE SECURELY MOUNTED. **CAUTION:** STATOR TO BE MOUNTED WITH MAGNETIC STEEL SCREWS.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH A POSITIVE CURRENT APPLIED TO TERMINALS MARKED #1, ROTATION OF ROTOR SHALL BE C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

## SIZE CONSTANTS

## Value      Units

Peak Torque Rating - $T_p$	10	LB. FT.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	135	WATTS
Motor Constant - $K_m$	0.86	LB.FT./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ , $\omega_{NL}$	10	RAD/S
Electrical Time Constant - $\tau_e$	0.37	MS
Static Friction (Max.) - $T_f$	0.4	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_\infty$	1.0      0.03
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	0.30	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	4	PERCENT
Ripple Frequency - (Fundamental)	287	CYCLES/REV.
Number of Poles	48	
Rotor Inertia - $J_m$	0.024	LB.FT.S <sup>2</sup>
Motor Weight	5	LB.

## WINDING CONSTANTS

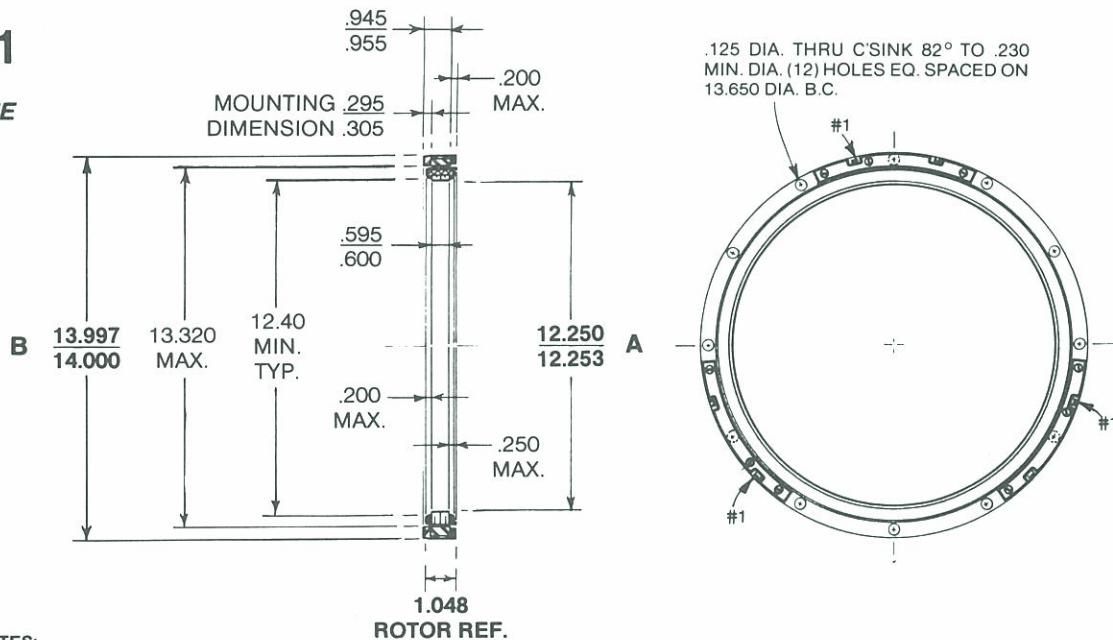
## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	27.0	15.2					
Peak Current - $I_p$	AMPERES	Rated	5.00	9.01					
Torque Sensitivity - $K_t$	LB. FT./AMP	$\pm 10\%$	2.00	1.11					
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	2.71	1.51					
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	5.40	1.68					
Inductance - $L_m$	mH	$\pm 30\%$	2.0	0.62					

**T-13301**

14.4 lb. ft.

PEAK TORQUE

**NOTES:**

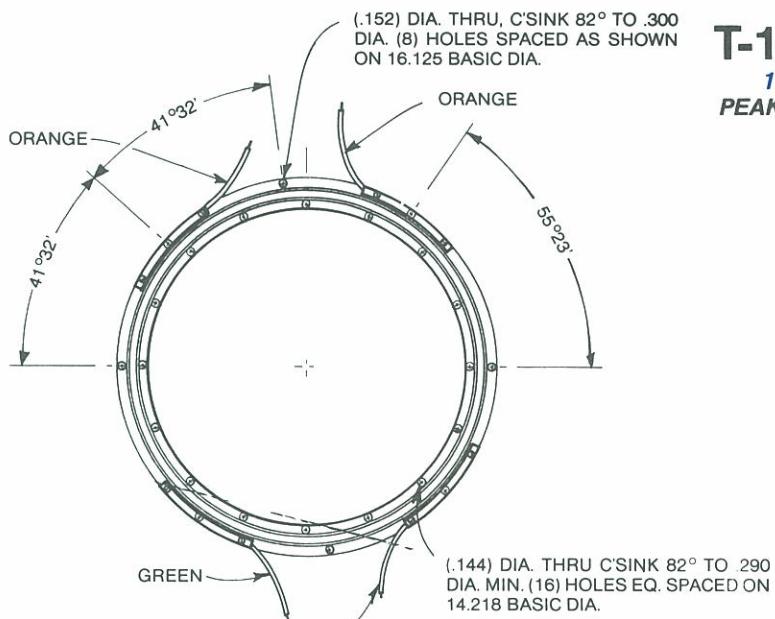
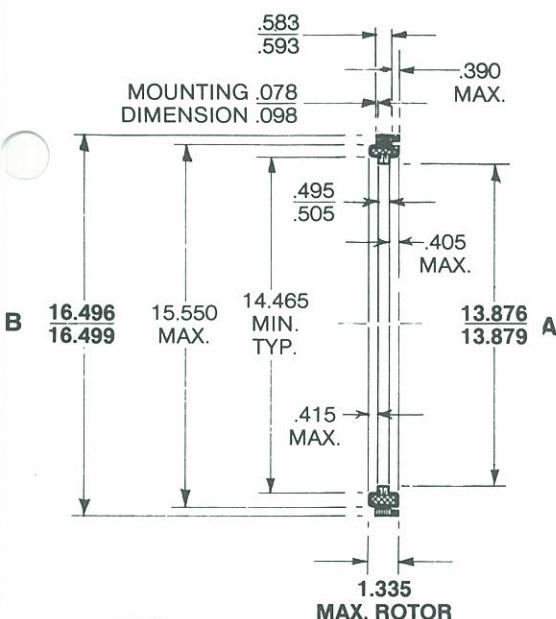
1. — MOTOR TO BE SUPPLIED AS FIVE SEPARATE COMPONENTS: ROTOR, (3) BRUSH RING SEGMENT ASSEMBLIES, AND STATOR WITH (4) KEEPERS. **CAUTION:** DO NOT REMOVE KEEPERS UNTIL ROTOR IS FULLY IN PLACE.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002/.004 T.I.R. WHEN MOUNTED.
3. — WITH A POSITIVE CURRENT APPLIED TO TERMINALS #1, ROTATION SHALL BE C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**SIZE CONSTANTS****Value      Units**

Peak Torque Rating - $T_p$	14.4	LB. FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	256	WATTS	
Motor Constant - $K_M$	0.9	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p - \omega_{NL}$	13	RAD/S	
Electrical Time Constant - $\tau_E$	1.0	MS	
Static Friction (Max.) - $T_f$	0.4	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	1.1	LB. FT. PER RAD/S
	Infinite Impedance - $F_i$	0.03	LB. FT. PER RAD/S
Maximum Winding Temperature		155	°C
Temperature Rise per Watt - $TPR$	0.30	°C/WATT	
Ripple Torque (Average to Peak) - $T_R$	5	PERCENT	
Ripple Frequency - (Fundamental)	215	CYCLES/REV.	
Number of Poles	48		
Rotor Inertia - $J_M$	0.032	LB.FT.S <sup>2</sup>	
Motor Weight	8.5	LB.	

**WINDING CONSTANTS****Winding Designation**

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	32.4	16.2	64.9	131			
Peak Current - $I_p$	AMPERES	Rated	7.91	17.4	3.96	1.98			
Torque Sensitivity - $K_T$	LB.FT./AMP.	±10%	1.82	0.827	3.64	7.28			
Back EMF Constant - $K_B$	V per RAD/S	±10%	2.47	1.12	4.94	9.87			
DC Resistance ( $25^\circ\text{C}$ ) - $R_M$	OHMS	±12.5%	4.1	0.930	16.4	65.6			
Inductance - $L_M$	mH	±30%	4.0	0.82	16	64			



**NOTE:**

1. — MOTOR SUPPLIED AS FIVE SEPARATE COMPONENTS: STATOR WITH ROTOR IN PLACE WITH MYLAR IN AIR GAP & (4) BRUSH SEGMENT ASSEMBLIES.
  2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITH-.  
IN. .004 (.008 T.I.R.) WHEN MOUNTED.
  3. — WITH A POSITIVE CURRENT APPLIED TO GREEN LEADS WITH RESPECT TO ORANGE LEADS, ROTATION SHALL BE C.C.W. FACING BRUSH RING SIDE.
  4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV'S

LEADS:

#20 AWG TYPE "EE" TEFLON COATED  
PER MIL W-16878 48" MIN. LG.

<b>SIZE CONSTANTS</b>	<b>Value</b>	<b>Units</b>	
Peak Torque Rating - $T_p$	11	LB.FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	198	WATTS	
Motor Constant - $K_m$	0.78	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	13.3	RAD/S	
Electrical Time Constant - $\tau_e$	2.2	MS	
Static Friction (Max.) - $T_f$	0.25	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.83	LB. FT. PER RAD/S
	Infinite Impedance - $F_1$	0.01	LB. FT. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - TPR	0.25	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	4	PERCENT	
Ripple Frequency - (Fundamental)	235	CYCLES/REV.	
Number of Poles	26		
Rotor Inertia - $J_m$	0.08	LB.FT.S <sup>2</sup>	
Motor Weight	13	LB.	

## **WINDING CONSTANTS**

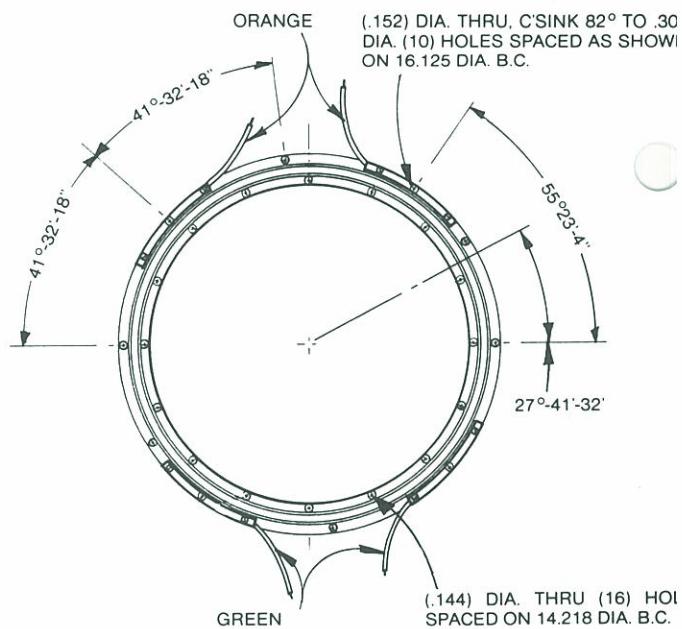
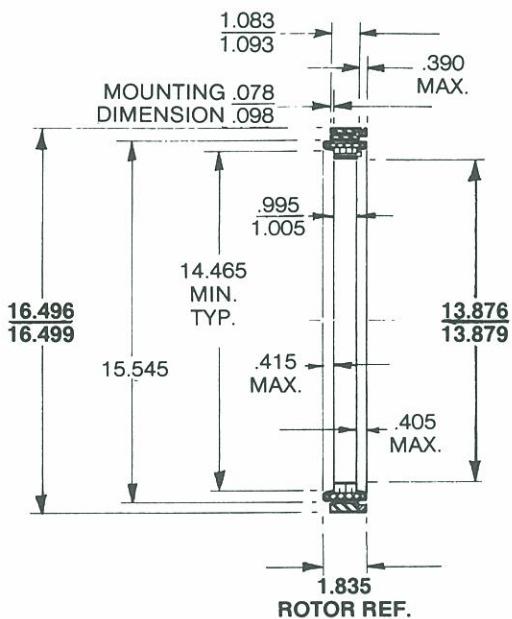
## ***Winding Designation***

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	18.9	37.7	75.5	151			
Peak Current - $I_p$	AMPERES	Rated	10.5	5.24	2.62	1.31			
Torque Sensitivity - $K_t$	LB.FT./AMP	$\pm 10\%$	1.05	2.10	4.20	8.40			
Back EMF Constant - $K_B$	V per RAD/S	$\pm 10\%$	1.42	2.85	5.69	11.4			
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	1.80	7.20	28.8	115			
Inductance - $L_m$	mH	$\pm 30\%$	4.0	16	64	260			

# T-15603

**30 lb. ft.**

**PEAK TORQUE**



**NOTE:**

1. — MOTOR SUPPLIED AS FIVE SEPARATE COMPONENTS: STATOR WITH ROTOR IN PLACE WITH MYLAR IN AIR GAP & (4) BRUSH SEGMENT ASSEMBLIES.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .004 (.008 T.I.R.) WHEN MOUNTED.
3. — WITH A POSITIVE CURRENT APPLIED TO GREEN LEADS WITH RESPECT TO ORANGE LEADS, ROTATION SHALL BE C.C.W. FACING BRUSH RING SIDE.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**LEADS:**  
#20 AWG TYPE "EE" TEFLON COATED  
PER MIL W-16878, 48" MIN. LG.

## SIZE CONSTANTS

### Value

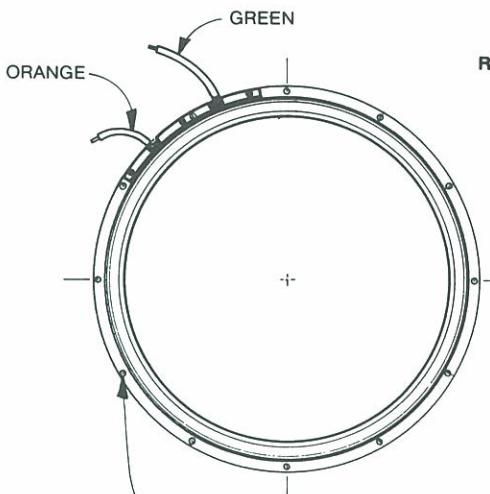
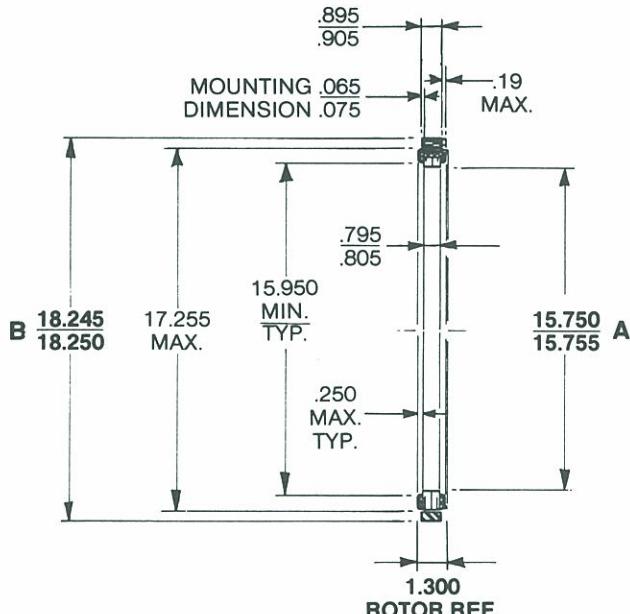
### Units

Peak Torque Rating - $T_p$	30	LB FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	450	WATTS	
Motor Constant - $K_M$	1.41	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	11	RAD/S	
Electrical Time Constant - $\tau_E$	3.6	MS	
Static Friction (Max.) - $T_f$	0.35	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	2.72	LB. FT. PER RAD/S
	Infinite Impedance - $F_\infty$	0.02	LB. FT. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - TPR	0.22	°C/WATT	
Ripple Torque (Average to Peak) - $T_R$	4	PERCENT	
Ripple Frequency - (Fundamental)	235	CYCLES/REV.	
Number of Poles	26		
Rotor Inertia - $J_M$	0.14	LB.FT.S <sup>2</sup>	
Motor Weight	22	LB.	

## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	31.5	62.8	126	158	39.5		
Peak Current - $I_p$	AMPERES	Rated	14.3	7.14	3.57	2.86	11.1		
Torque Sensitivity - $K_T$	LB.FT./AMP	$\pm 10\%$	2.1	4.20	8.40	10.5	2.70		
Back EMF Constant - $K_B$	V per RAD/S	$\pm 10\%$	2.85	5.69	11.4	14.2	3.66		
DC Resistance ( $25^\circ\text{C}$ ) - $R_M$	OHMS	$\pm 12.5\%$	2.2	8.80	35.2	55.4	3.56		
Inductance - $L_M$	mH	$\pm 30\%$	8.0	32	130	200	13		



.135/.141 DIA. THRU 82° C SINK TO  
.230 MIN. DIA. .156 C DRILL (OPPO-  
SITE SIDE) .50 DP. (12) HOLES EQ.  
SPACED ON 17.915 DIA. B.C.

#### NOTES:

- MOTOR SUPPLIED AS THREE SEPARATE COMPONENTS: ROTOR ASSEMBLY, BRUSH SEGMENT ASSEMBLY, AND STATOR ASSEMBLY.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITH-.004 (.008 T.I.R.) WHEN MOUNTED.
- WITH A POSITIVE CURRENT APPLIED TO GREEN LEAD WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING SIDE.
- TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

#### LEADS:

#22 AWG TYPE "E" TEFLON COATED  
PER MIL W-16878 36" MIN. LENGTH.

## SIZE CONSTANTS

**Value      Units**

Peak Torque Rating - $T_p$	54.0	LB. FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	386	WATTS	
Motor Constant - $K_m$	2.75	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	5.27	RAD/S	
Electrical Time Constant - $\tau_e$	1.56	MS	
Static Friction (Max.) - $T_f$	1.2	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	10.2      0.040	LB. FT. PER RAD/S      LB. FT. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	0.20	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT	
Ripple Frequency - (Fundamental)	241	CYCLES/REV.	
Number of Poles	48		
Rotor Inertia - $J_m$	0.130	LB.FT.S <sup>2</sup>	
Motor Weight	18	LB.	

## WINDING CONSTANTS

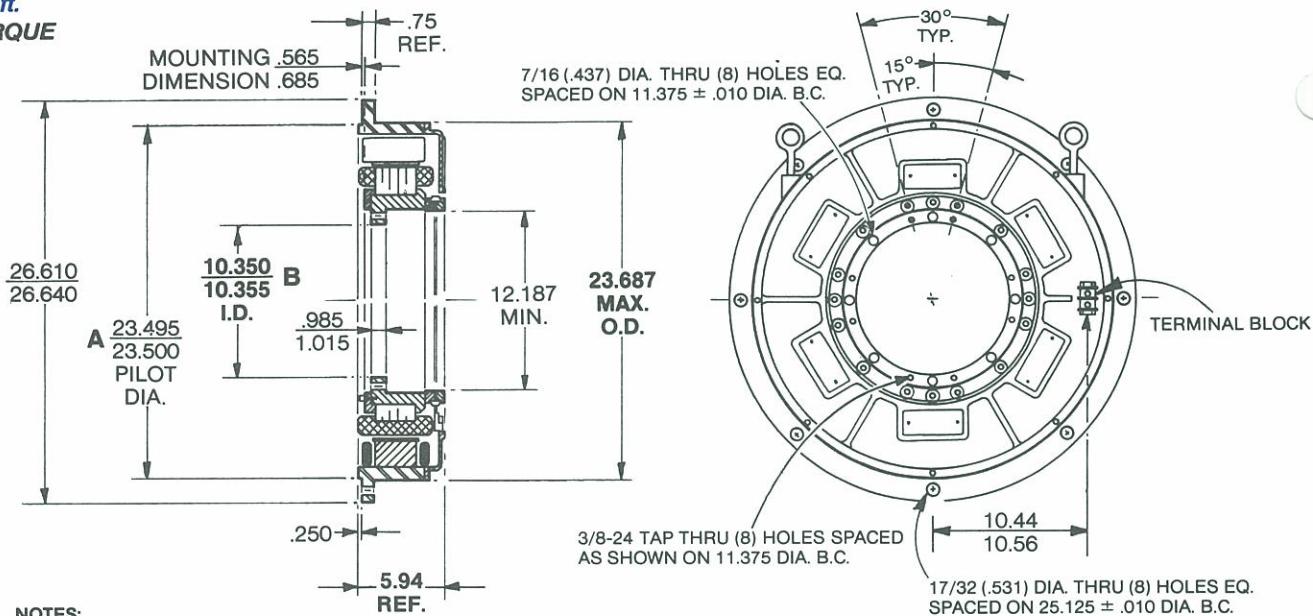
*Winding Designation*

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	78.6	24.6					
Peak Current - $I_p$	AMPERES	Rated	4.91	15.4					
Torque Sensitivity - $K_t$	LB.FT./AMP	$\pm 10\%$	11.0	3.52					
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	14.9	4.77					
DC Resistance (25°C) - $R_m$	OHMS	$\pm 12.5\%$	16.0	1.60					
Inductance - $L_m$	mH	$\pm 30\%$	25	2.6					

# T-18002

300 lb. ft.

PEAK TORQUE



NOTES:

1. — MOTOR TO BE SUPPLIED AS COMPLETE ASSEMBLY. CAUTION: DO NOT REMOVE ROTOR FROM STATOR AT ANY TIME.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .010 (.020 T.I.R.) WHEN MOUNTED.
3. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

## SIZE CONSTANTS

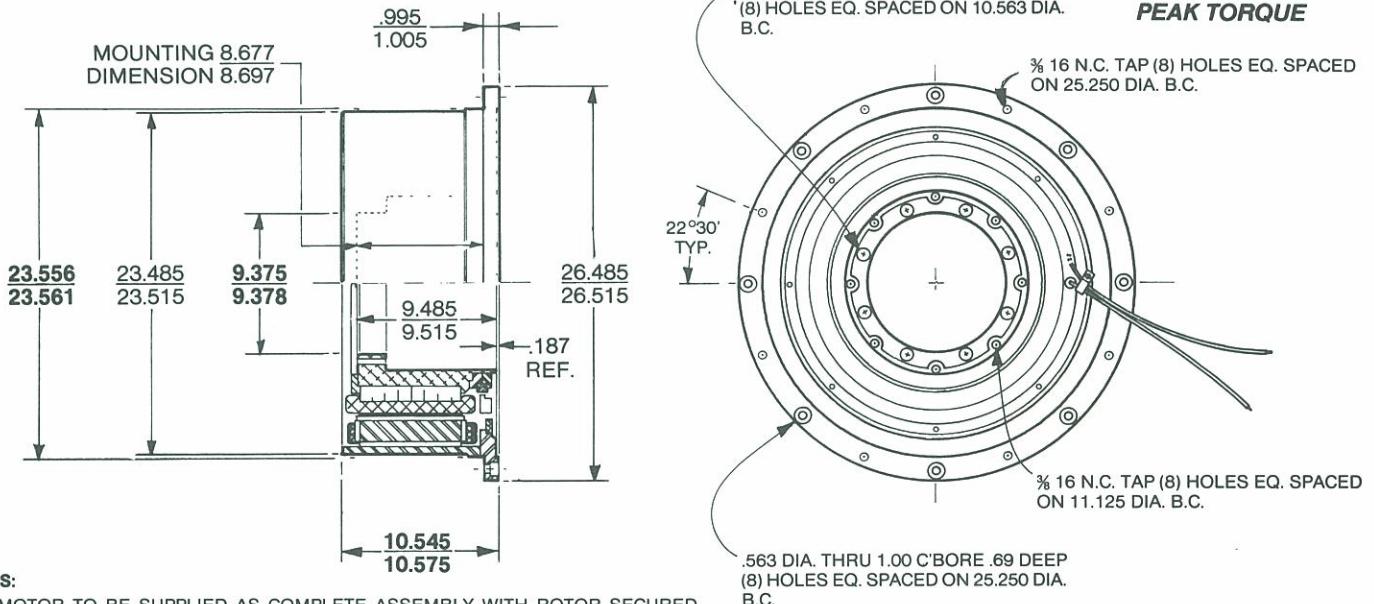
### Value      Units

Peak Torque Rating - $T_P$	300	LB. FT.	
Power Input, Stalled at $T_P$ (25°C) - $P_P$	1452	WATTS	
Motor Constant - $K_M$	7.85	LB.FT./√ WATT	
No Load Speed, Theoretical @ $V_P$ - $\omega_{NL}$	3.6	RAD/S	
Electrical Time Constant - $\tau_E$	20.0	MS	
Static Friction (Max.) - $T_F$	3.0	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	83.6	LB. FT. PER RAD/S
	Infinite Impedance - $F_\infty$	0.5	LB. FT. PER RAD/S
Maximum Winding Temperature	105	°C	
Temperature Rise per Watt - $TPR$	0.13	°C/WATT	
Ripple Torque (Average to Peak) - $T_R$	2	PERCENT	
Ripple Frequency - (Fundamental)	235	CYCLES/REV.	
Number of Poles	18		
Rotor Inertia - $J_M$	1.40	LB.FT.S <sup>2</sup>	
Motor Weight	300	LB.	

## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_P$ (25°C) - $V_P$	VOLTS	Nom.	66.0		33.0	41.4	84.5	132	168
Peak Current - $I_P$	AMPERES	Rated	22.0		44.2	36.6	18.4	11.0	8.80
Torque Sensitivity - $K_T$	LB.FT./AMP	± 10%	13.6		6.80	8.20	16.3	27.2	34.0
Back EMF Constant - $K_B$	V per RAD/S	± 10%	18.4		9.20	11.0	22.1	36.9	46.1
DC Resistance (25°C) - $R_M$	OHMS	± 12.5%	3.00		0.750	1.13	4.60	12.0	19.0
Inductance - $L_M$	mH	± 30%	60		15	22	88	240	380

**NOTES:**

1. — MOTOR TO BE SUPPLIED AS COMPLETE ASSEMBLY WITH ROTOR SECURED INSIDE STATOR. **CAUTION:** DO NOT REMOVE ROTOR FROM STATOR AT ANY TIME.
2. — MOUNTING REQUIREMENT: ROTOR AND STATOR TO BE CONCENTRIC WITHIN .005 (.010 T.I.R.) WHEN MOUNTED.
3. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REVS.
4. — SPECIAL BRUSH MATERIAL FOR HIGH CURRENT OPERATION.

**SIZE CONSTANTS****Value      Units**

Peak Torque Rating - $T_p$	900	LB.FT.	
Power Input, Stalled at $T_p$ (25°C) - $P_p$	3435	WATTS	
Motor Constant - $K_m$	15.3	LB.FT./√WATT	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	2.8	RAD/S	
Electrical Time Constant - $\tau_e$	25.0	MS	
Static Friction (Max.) - $T_f$	4.0	LB.FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	319	LB.FT. PER RAD/S
	Infinite Impedance - $F_\infty$	0.20	LB.FT. PER RAD/S
Maximum Winding Temperature	105	°C	
Temperature Rise per Watt - TPR	0.12	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	2	PERCENT	
Ripple Frequency - (Fundamental)	235	CYCLES/REV.	
Number of Poles	18		
Rotor Inertia - $J_m$	3.10	LB.FT.S <sup>2</sup>	
Motor Weight	650	LB.	

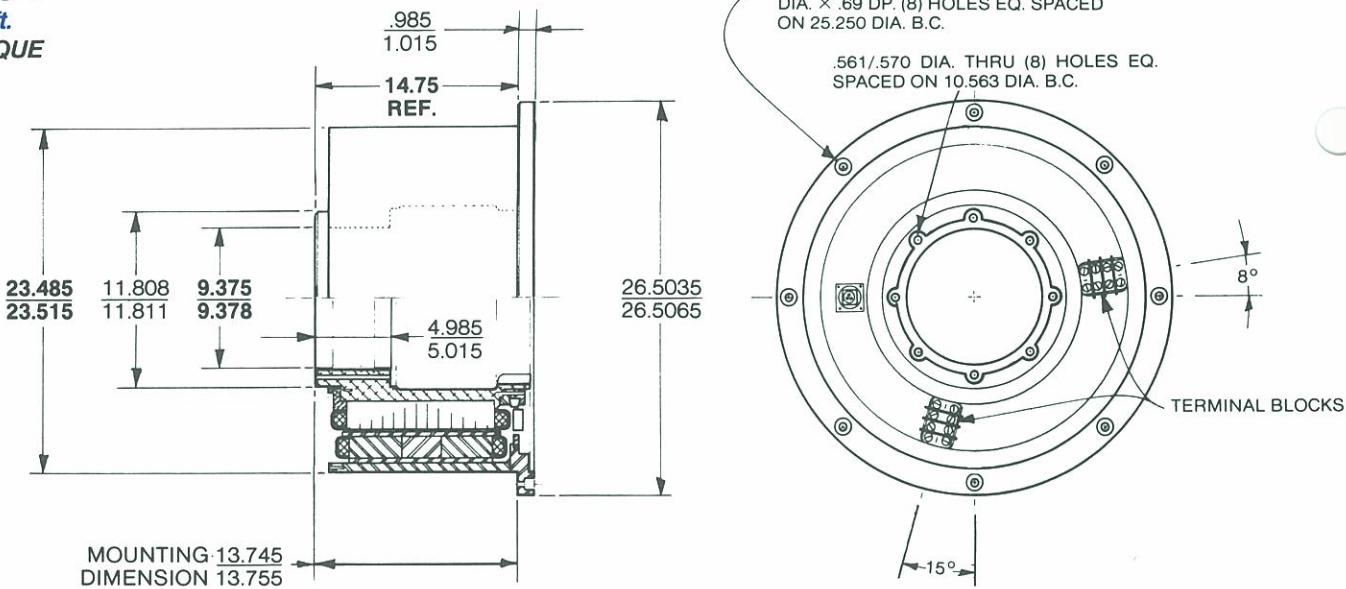
**WINDING CONSTANTS****Winding Designation**

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	133	212	110	168	268	333	69.0
Peak Current - $I_p$	AMPERES	Rated	25.7	16.0	33.4	21.4	12.9	10.3	53.0
Torque Sensitivity - $K_t$	LB.FT./AMP	±10%	35.0	56.0	27.0	42.0	70.0	87.5	17.0
Back EMF Constant - $K_b$	V per RAD/S	±10%	47.5	76.1	36.7	57.1	95.1	119	23.0
DC Resistance (25°C) - $R_m$	OHMS	±12.5%	5.20	13.2	3.30	7.85	20.6	32.8	1.3
Inductance - $L_m$	mH	±30%	130	330	83	190	520	810	33

# T-18031

1600 lb. ft.

PEAK TORQUE



**NOTES:**

1. — MOTOR TO BE SUPPLIED AS COMPLETE ASSEMBLY WITH ROTOR SECURED INSIDE STATOR. **CAUTION:** DO NOT REMOVE ROTOR FROM STATOR AT ANY TIME.
2. — MOUNTING REQUIREMENT: ROTOR AND STATOR TO BE CONCENTRIC WITHIN .005 (.010 T.I.R.) WHEN MOUNTED.
3. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REVS.
4. — SPECIAL BRUSH MATERIAL FOR IMPROVED COMMUTATION AT HIGH POWER INPUT LEVELS.

## SIZE CONSTANTS

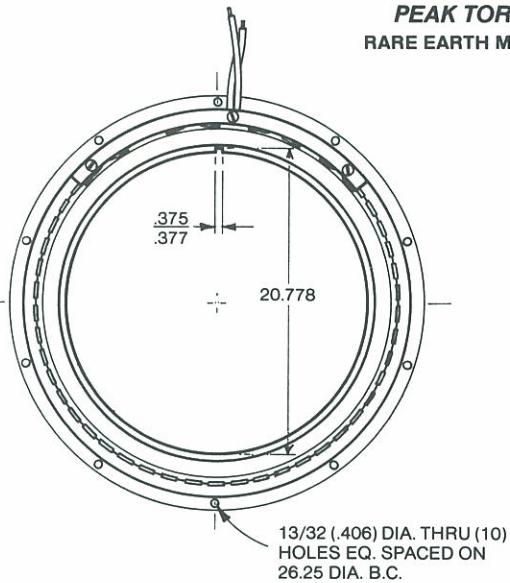
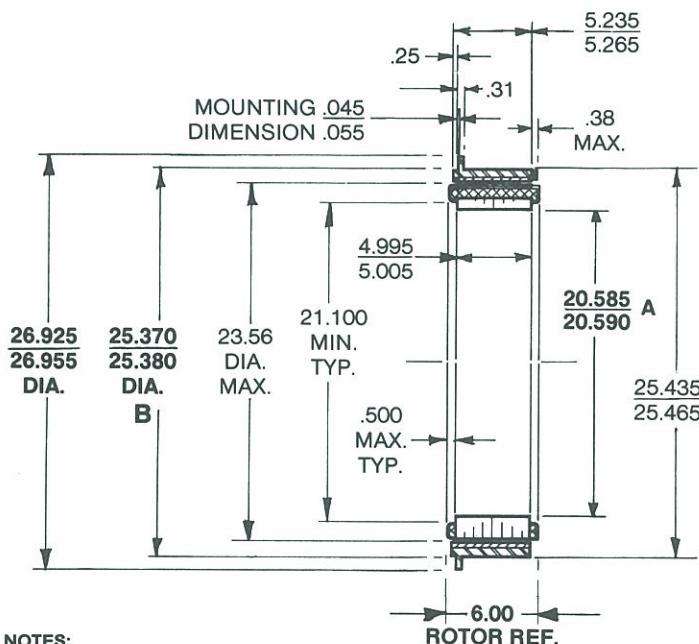
**Value      Units**

Peak Torque Rating - $T_p$	1600	LB FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	5600	WATTS	
Motor Constant - $K_M$	21.4	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p - \omega_{NL}$	2.55	RAD/S	
Electrical Time Constant - $\tau_E$	23	MS	
Static Friction (Max.) - $T_f$	6	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	630	LB. FT. PER RAD/S
	Infinite Impedance - $F_i$	1.00	LB. FT. PER RAD/S
Maximum Winding Temperature	130	°C	
Temperature Rise per Watt - TPR	0.08	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	2	PERCENT	
Ripple Frequency - (Fundamental)	235	CYCLES/REV.	
Number of Poles	18		
Rotor Inertia - $J_M$	4.2	LB.FT.S <sup>2</sup>	
Motor Weight	850	LB.	

## WINDING CONSTANTS

*Winding Designation*

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	85	89.3	166	179			
Peak Current - $I_p$	AMPERES	Rated	65	81.2	40.6	36.1			
Torque Sensitivity - $K_t$	LB.FT./AMP	±10%	24.6	19.7	39.4	44.3			
Back EMF Constant - $K_B$	V per RAD/S	±10%	33.4	26.7	53.4	60.1			
DC Resistance ( $25^\circ\text{C}$ ) - $R_M$	OHMS	±12.5%	1.3	1.10	4.10	4.95			
Inductance - $L_M$	mH	±30%	30	19	76	97			



**NOTES:**

1. — MOTOR SHIPPED AS (2) SEPARATE COMPONENTS: ROTOR-STATOR ASSEMBLY WITH SHIPPING CLAMP, MYLAR IN AIR GAP AND BRUSH SEGMENT ASSEMBLY.
2. — MOUNTING REQUIREMENT: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITH-.005,.010 T.I.R. WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REVS.

**LEADS:**

#18 AWG TYPE "E" TEFLON COATED PER MIL W-16878, 12" MIN. LG.

### SIZE CONSTANTS

**Value      Units**

Peak Torque Rating - $T_p$	700	LB. FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	1310	WATTS	
Motor Constant - $K_M$	19	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p - \omega_{NL}$	1.4	RAD/S	
Electrical Time Constant - $\tau_E$	4.8	MS	
Static Friction (Max.) - $T_f$	7.0	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	510	LB. FT. PER RAD/S
	Infinite Impedance - $F_i$	2.0	LB. FT. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	.13	°C/WATT	
Ripple Torque (Average to Peak) - $T_R$	4.0	PERCENT	
Ripple Frequency - (Fundamental)	326	CYCLES/REV.	
Number of Poles	50		
Rotor Inertia - $J_M$	2.9	LB.FT.S <sup>2</sup>	
Motor Weight	230	LB.	

### WINDING CONSTANTS

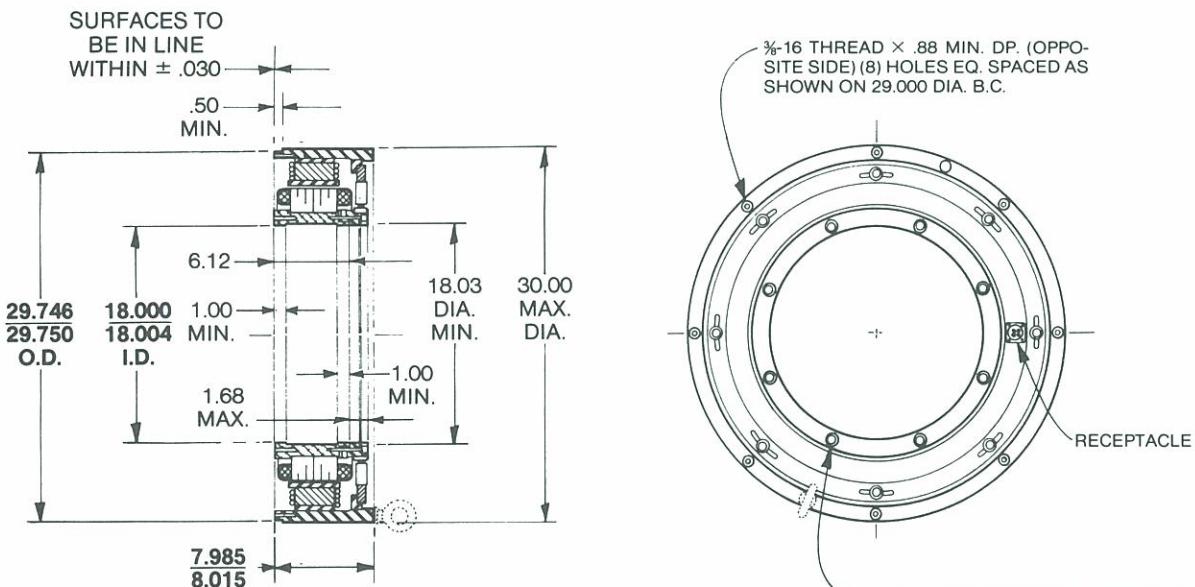
### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	52.5						
Peak Current - $I_p$	AMPERES	Rated	25.0						
Torque Sensitivity - $K_T$	LB.FT./AMP.	$\pm 10\%$	28.0						
Back EMF Constant - $K_B$	V per RAD/S	$\pm 10\%$	38.0						
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	2.10						
Inductance - $L_m$	mH	$\pm 30\%$	10						

# T-24005

1000 lb. ft.

PEAK TORQUE



**NOTES:**

- MOTOR SUPPLIED AS COMPLETE ASSEMBLY WITH ROTOR SECURED INSIDE STATOR BY SHIPPING CLAMPS. **CAUTION:** DO NOT REMOVE ROTOR FROM STATOR AT ANY TIME.
- MOUNTING REQUIREMENTS: ROTOR AND STATOR TO BE CONCENTRIC WITHIN .020 (.040 T.I.R.) WHEN MOUNTED.
- TYPICAL BRUSH LIFE >  $10^7$  REVS.
- SPECIAL BRUSH MATERIAL FOR IMPROVED COMMUTATION.

## SIZE CONSTANTS

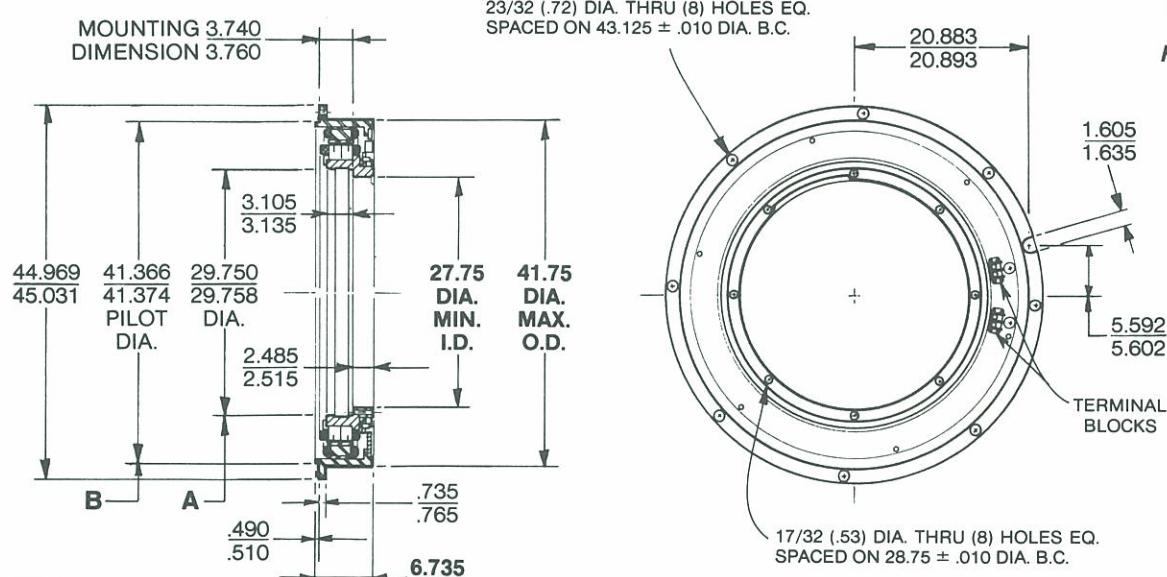
## Value      Units

Peak Torque Rating - $T_p$	1000	LB FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	7000	WATTS	
Motor Constant - $K_m$	12	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p - \omega_{NL}$	5	RAD/S	
Electrical Time Constant - $\tau_e$	12.5	MS	
Static Friction (Max.) - $T_f$	5	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	194	LB. FT. PER RAD/S
	Infinite Impedance - $F_\infty$	0.5	LB. FT. PER RAD/S
Maximum Winding Temperature	105	°C	
Temperature Rise per Watt - TPR	0.08	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	2	PERCENT	
Ripple Frequency - (Fundamental)	320	CYCLES/REV.	
Number of Poles	22		
Rotor Inertia - $J_m$	8	LB.FT.S <sup>2</sup>	
Motor Weight	730	LB.	

## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
	VOLTS	Nom.	158	123	200	224			
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	AMPERES	Rated	44	58.7	35.2	32.0			
Peak Current - $I_p$	LB.FT./AMP.	$\pm 10\%$	22.7	17.0	28.4	31.2			
Torque Sensitivity - $K_t$	V per RAD/S	$\pm 10\%$	30.8	23.0	38.5	42.3			
Back EMF Constant - $K_b$	OHMS	$\pm 12.5\%$	3.60	2.10	5.70	7.00			
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	mH	$\pm 30\%$	45	25	70	85			
Inductance - $L_m$									



NOTES:

1. — MOTOR SUPPLIED AS COMPLETE ASSEMBLY WITH ROTOR SECURED INSIDE STATOR BY SHIPPING STRAPS. **CAUTION:** DO NOT REMOVE ROTOR FROM STATOR AT ANY TIME.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITH-.005 (.010 T.I.R.) WHEN MOUNTED.
3. — WITH A POSITIVE CURRENT APPLIED TO (2) TERMINALS "A" WITH RESPECT TO (2) TERMINALS "B", ROTATION SHALL BE C.C.W. FACING BRUSH RING END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REVS.
5. — SPECIAL BRUSH MATERIAL TO ALLOW FOR HIGH VOLTAGE OPERATION.

### SIZE CONSTANTS

**Value      Units**

Peak Torque Rating - $T_p$	1500	LB FT.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	4900	WATTS
Motor Constant - $K_m$	21	LB.FT./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	2.4	RAD/S
Electrical Time Constant - $\tau_e$	14	MS
Static Friction (Max.) - $T_f$	10	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	617      5
Maximum Winding Temperature	105	°C
Temperature Rise per Watt - $TPR$	0.07	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	2	PERCENT
Ripple Frequency - (Fundamental)	469	CYCLES/REV.
Number of Poles	36	
Rotor Inertia - $J_m$	15	LB.FT.S <sup>2</sup>
Motor Weight	820	LB.

### WINDING CONSTANTS

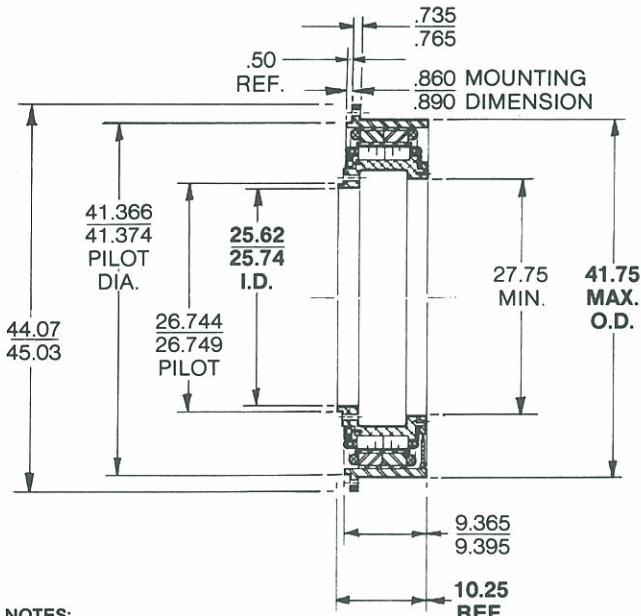
### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	56.7						
Peak Current - $I_p$	AMPERES	Rated	87.2						
Torque Sensitivity - $K_t$	LB.FT./AMP.	± 10%	17.2						
Back EMF Constant - $K_b$	V per RAD/S	± 10%	23.3						
DC Resistance (25°C) - $R_m$	OHMS	± 12.5%	0.65						
Inductance - $L_m$	mH	± 30%	9.0						

# T-36001

3000 lb. ft.

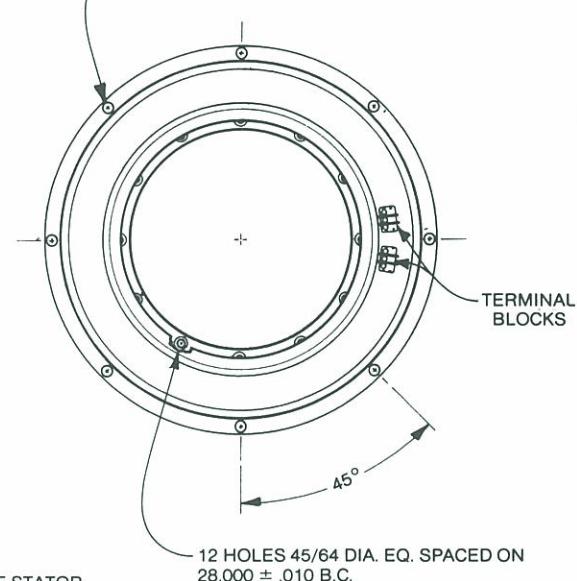
PEAK TORQUE



NOTES:

1. — UNIT SHIPPED AS COMPLETE ASSEMBLY WITH ROTOR SECURED INSIDE STATOR BY SHIPPING CLAMP. **CAUTION:** DO NOT REMOVE ROTOR FROM STATOR AT ANY TIME.
2. — MOUNTING REQUIREMENT: ROTOR AND STATOR TO BE CONCENTRIC WITHIN .025(.050 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE VOLTAGE APPLIED TO TERMINAL "A" WITH RESPECT TO TERMINAL "B" THE ROTATION OF THE ARMATURE SHALL BE C.C.W. FACING THE BRUSH END.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.
5. — SPECIAL BRUSH MATERIAL FOR HIGH VOLTAGE OPERATION.

8 HOLES 23/32 DIA. EQ. SPACED ON  
43.125 ± .010 B.C.



## SIZE CONSTANTS

Value      Units

Peak Torque Rating - $T_p$	3000	LB.FT.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	6300	WATTS	
Motor Constant - $K_M$	37.8	LB.FT./√WATT	
No Load Speed, Theoretical @ $V_p - \omega_{NL}$	1.6	RAD/S	
Electrical Time Constant - $\tau_E$	22	MS	
Static Friction (Max.) - $T_f$	12	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	1932      10	LB. FT. PER RAD/S      LB. FT. PER RAD/S
Maximum Winding Temperature	105	°C	
Temperature Rise per Watt - $TPR$	0.04	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	2	PERCENT	
Ripple Frequency - (Fundamental)	469	CYCLES/REV.	
Number of Poles	36		
Rotor Inertia - $J_m$	26	LB.FT.S <sup>2</sup>	
Motor Weight	1360	LB.	

## WINDING CONSTANTS

Winding Designation

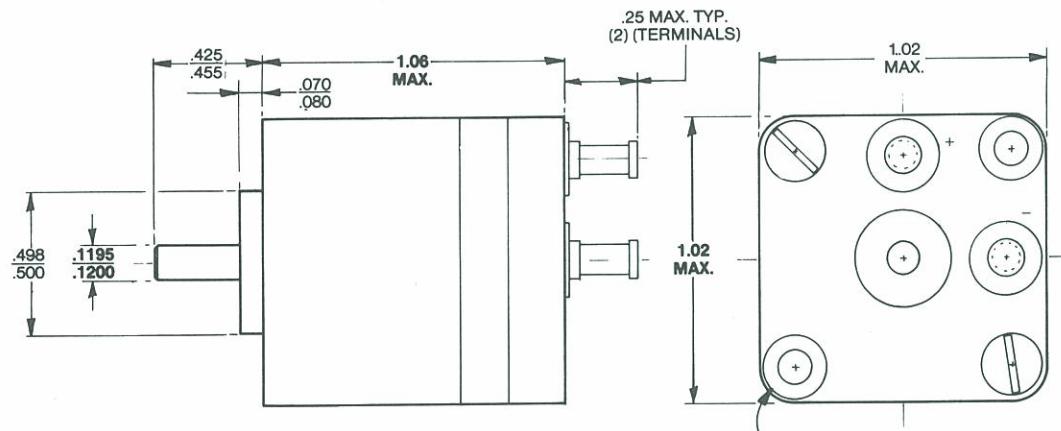
	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	229.6	144.4	183.2	288.6	120.1	123.9	78.3
Peak Current - $I_p$	AMPERES	Rated	27.5	43.5	34.9	21.7	52.2	65.2	87.0
Torque Sensitivity - $K_t$	LB.FT./AMP.	±10%	109	69.0	86.0	138	57.5	46.0	34.5
Back EMF Constant - $K_b$	V per RAD/S	±10%	148	93.6	116.6	187	78.0	62.4	46.8
DC Resistance (25°C) - $R_m$	OHMS	±12.5%	8.35	3.32	5.25	13.3	2.3	1.9	0.90
Inductance - $L_m$	mH	±30%	180	72	110	290	50	32	18

## Housed Torquer Selection Guide (oz. in. & lb. ft.)

MODEL NUMBER	Peak Torque @ Stall		Motor Constant	No Load Speed	Electrical Time Constant	Friction	Rotor Inertia	Physical Dimensions		Weight
	T <sub>P</sub> oz. in.	P <sub>P</sub> watts	K <sub>M</sub> oz. in./watt	ω <sub>NL</sub> rad/sec	τ <sub>e</sub> msec.	T <sub>f</sub> oz. in.	J <sub>M</sub> oz. in. sec. <sup>2</sup>	OD in.	Length in.	oz.
T-0716	7	40	1.1	814	0.36	0.35	1.3 × 10 <sup>-4</sup>	1.02	1.06	2.9
QT-0701	11	60	1.4	770	0.28	0.35	1.3 × 10 <sup>-4</sup>	1.02	1.06	2.9
QT-0714	20	132	1.74	933	0.31	0.35	1.6 × 10 <sup>-4</sup>	1.02	1.19	3.1
T-1397	20	60	2.58	400	0.34	1.0	9.5 × 10 <sup>-4</sup>	2.10	1.09	8.8
NT-2116	35	41	5.45	160	0.60	1.1	6.4 × 10 <sup>-3</sup>	3.02	1.32	19
T-1341	40	98	4.05	340	0.34	1.0	1.6 × 10 <sup>-3</sup>	2.22	1.22	7.6
NT-2117	60	34	10.3	80	1.0	2.3	1.2 × 10 <sup>-2</sup>	3.02	1.48	25
NT-1387	90	256	5.65	400	0.41	4.0	3.5 × 10 <sup>-3</sup>	2.09	2.50	16.1
NT-2158	120	50	17.0	57	1.5	3.5	1.95 × 10 <sup>-2</sup>	3.02	1.98	32
QT-1413	157	346	8.45	312	0.28	4.42	4.4 × 10 <sup>-3</sup>	2.22	2.48	32
T-2998	163	77	18.6	67	1.6	3.26	4.6 × 10 <sup>-2</sup>	3.95	1.75	40
	lb. ft.	watts	lb. ft./watt	rad/sec	msec.	lb. ft.	lb. ft. sec <sup>2</sup>	in.	in.	lbs.
QT-2606	1.5	25	0.30	12.2	2.2	0.12	5.0 × 10 <sup>-4</sup>	3.25	3.50	5
NT-2171	1.77	440	0.08	183	2.0	0.05	1.3 × 10 <sup>-4</sup>	4.02	4.50	10
T-4055	1.8	91	0.19	37	1.9	0.04	8.7 × 10 <sup>-4</sup>	5.39	1.97	4
T-4054	2.7	147	0.22	40	2.0	0.05	1.1 × 10 <sup>-3</sup>	5.52	2.70	4
T-5144	2.7	85	0.29	22	2.6	0.05	2.0 × 10 <sup>-3</sup>	6.44	1.84	7
T-5721	7	260	0.4	27	3.0	0.1	5.4 × 10 <sup>-3</sup>	8.31	2.78	10.5
T-7208	11	335	0.60	22.5	3.2	0.15	1.0 × 10 <sup>-2</sup>	9.65	3.00	10.3
T-7215	22	530	0.96	15	5.7	0.25	1.9 × 10 <sup>-2</sup>	9.65	3.75	35
T-8005	64	720	2.38	8	13.3	0.65	6.2 × 10 <sup>-2</sup>	10.75	7.00	100
T-10081	100	1070	3.06	7.5	6.7	1.2	0.29	13.00	7.97	130

# T-0716

**7.0 oz. in.**  
**PEAK TORQUE**



**NOTES:**

1. — WITH POSITIVE CURRENT APPLIED TO POSITIVE (+) TERMINAL, ROTATION SHALL BE C.W. WHEN VIEWED FROM SHAFT END.
2. — MAXIMUM SOLDERING TEMPERATURE FOR ATTACHING LEADS TO TERMINALS 400°F.
3. — GOLD PLATED COMMUTATOR.
4. — UNIT HAS METAL END BELLS.

1/125 DRILL THRU C'SINK 82° TO  
.235 MIN. DIA (2) HOLES EQ. SP. AS  
SHOWN ON 1.062 DIA. B.C.

## SIZE CONSTANTS

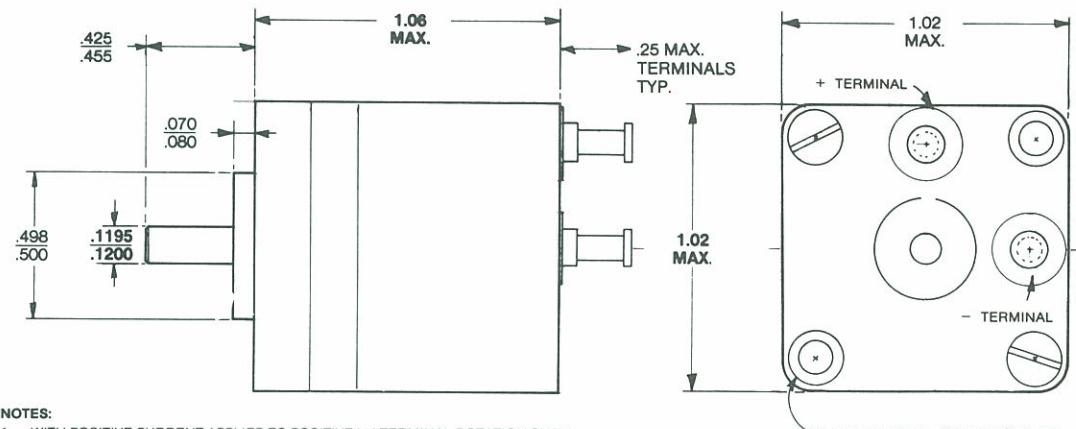
### Value      Units

Peak Torque Rating - $T_p$	7.0	OZ. IN.						
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	40.1	WATTS						
Motor Constant - $K_m$	1.10	OZ.IN./ $\sqrt{\text{WATT}}$						
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	814	RAD/S						
Electrical Time Constant $\tau_e$	0.359	MS						
Static Friction (Max.) - $T_f$	0.35	OZ. IN.						
Viscous Damping Coefficients	<table border="0"> <tr> <td>Zero Impedance - <math>F_0</math></td> <td><math>8.56 \times 10^{-3}</math></td> <td>OZ. IN. PER RAD/S</td> </tr> <tr> <td>Infinite Impedance - <math>F_i</math></td> <td><math>3.90 \times 10^{-4}</math></td> <td>OZ. IN. PER RAD/S</td> </tr> </table>	Zero Impedance - $F_0$	$8.56 \times 10^{-3}$	OZ. IN. PER RAD/S	Infinite Impedance - $F_i$	$3.90 \times 10^{-4}$	OZ. IN. PER RAD/S	
Zero Impedance - $F_0$	$8.56 \times 10^{-3}$	OZ. IN. PER RAD/S						
Infinite Impedance - $F_i$	$3.90 \times 10^{-4}$	OZ. IN. PER RAD/S						
Maximum Winding Temperature	155	°C						
Temperature Rise per Watt - $TPR$	12	°C/WATT						
Ripple Torque (Average to Peak) - $T_r$	10	PERCENT						
Ripple Frequency - (Fundamental)	13	CYCLES/REV.						
Number of Poles	4							
Rotor Inertia - $J_m$	$1.30 \times 10^{-4}$	OZ.IN.S <sup>2</sup>						
Motor Weight	2.93	OZ.						

## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	25.9	20.5	13.0	38.9	30.0		
Peak Current - $I_p$	AMPERES	Rated	1.55	1.95	3.12	1.06	1.25		
Torque Sensitivity - $K_t$	OZ. IN./AMP.	± 10%	4.50	3.57	2.24	6.60	5.60		
Back EMF Constant - $K_b$	V per RAD/S	± 10%	0.031	0.025	0.016	0.047	0.040		
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	± 12.5%	16.7	10.5	4.18	36.7	24.0		
Inductance - $L_m$	mH	± 30%	6.0	4.0	1.6	13	9.5		



**NOTES:**

1. — WITH POSITIVE CURRENT APPLIED TO POSITIVE (+) TERMINAL ROTATION SHALL BE C.W. WHEN VIEWED FROM THE SHAFT END.
2. — MAXIMUM SOLDERING TEMPERATURE FOR ATTACHING LEADS TO TERMINALS = 400°F.
3. — GOLD PLATED COMMUTATOR.

## SIZE CONSTANTS

**Value      Units**

Peak Torque Rating - $T_p$	11	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	60	WATTS	
Motor Constant - $K_m$	1.4	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ , $\omega_{NL}$	770	RAD/S	
Electrical Time Constant - $\tau_e$	0.28	MS	
Static Friction (Max.) - $T_f$	0.35	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.014	OZ. IN. PER RAD/S
	Infinite Impedance - $F_\infty$	$4.6 \times 10^{-4}$	OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	12	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	10	PERCENT	
Ripple Frequency - (Fundamental)	13	CYCLES/REV.	
Number of Poles	4		
Rotor Inertia - $J_m$	$1.3 \times 10^{-4}$	OZ.IN.S <sup>2</sup>	
Motor Weight	2.9	OZ.	

## WINDING CONSTANTS

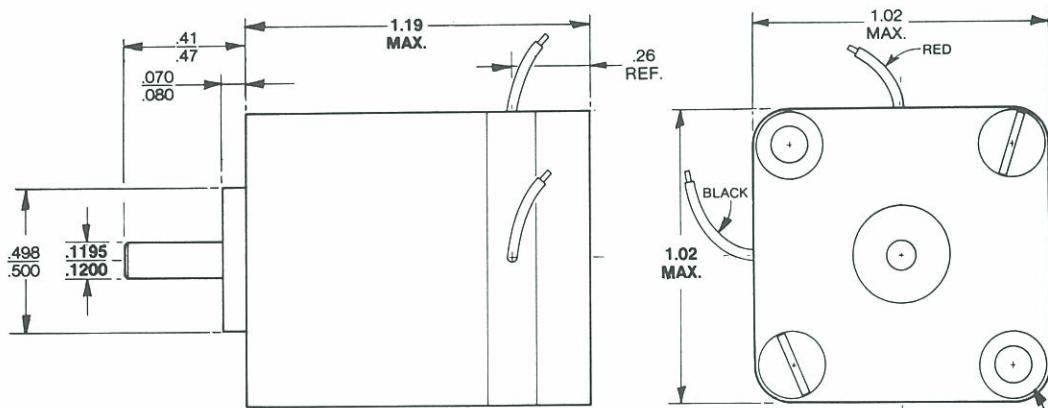
*Winding Designation*

	UNITS	TOLERANCES	A	B	C	D	E	F	G
	VOLTS	Nom.	41.2	32.6	25.9	20.5	16.2	51.6	12.9
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	AMPERES	Rated	1.45	1.82	2.31	2.89	3.67	1.15	4.68
Peak Current - $I_p$	OZ.IN./AMP.	± 10%	7.60	6.06	4.77	3.80	3.00	9.54	2.35
Torque Sensitivity - $K_t$	V per RAD/S	± 10%	.054	.043	.034	.027	.021	.067	.017
Back EMF Constant - $K_b$	OHMS	± 12.5%	28.4	17.9	11.2	7.10	4.42	44.9	2.75
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	mH	± 30%	8.0	5.1	3.2	2.0	1.2	13	0.74
Inductance - $L_m$									

# QT-0714

**20.0 oz. in.  
PEAK TORQUE**

RARE EARTH MAGNETS



1/8 (.125) DIA. THRU C'SINK 82° TO .235  
MIN. DIA. (2) HOLES EQ. SPACED ON  
1.062 DIA. B.C.

**NOTE:**  
WITH POSITIVE CURRENT APPLIED TO BLACK LEAD ROTATION SHALL BE C.W. WHEN  
VIEWED FROM SHAFT END.

**LEADS:**  
#26 AWG TYPE "E" TEFLON COATED  
LEAD WIRE 12" MIN LENGTH.

## SIZE CONSTANTS

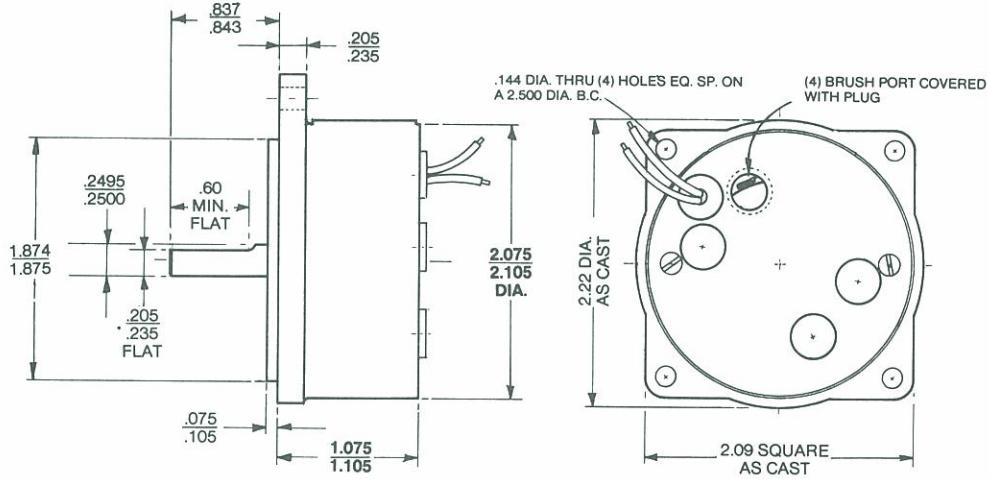
## Value      Units

Peak Torque Rating - $T_p$	20.0	OZ. IN.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	132	WATTS
Motor Constant - $K_m$	1.74	OZ.IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p - \omega_{NL}$	933	RAD/S
Electrical Time Constant - $\tau_e$	0.312	MS
Static Friction (Max.) - $T_f$	0.35	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_\infty$	0.021 $6.0 \times 10^{-4}$
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - TPR	12	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	10	PERCENT
Ripple Frequency - (Fundamental)	13	CYCLES/REV.
Number of Poles	4	
Rotor Inertia - $J_m$	$1.6 \times 10^{-4}$	OZ.IN.S <sup>2</sup>
Motor Weight	3.1	OZ.

## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	20.8	26.2	65.8	41.6	52.4		
Peak Current - $I_p$	AMPERES	Rated	6.35	4.98	2.00	3.17	2.52		
Torque Sensitivity - $K_t$	OZ.IN./AMP	$\pm 10\%$	3.15	4.02	10.0	6.30	7.93		
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.022	0.028	0.071	0.045	0.056		
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	3.27	5.26	32.9	13.1	20.8		
Inductance - $L_m$	mH	$\pm 30\%$	1.02	1.66	10	4.1	6.5		



**NOTE:**  
1. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, ROTATION SHALL BE C.C.W.  
FACING BRUSH END.

**LEADS:**  
(2) LEADS #28 AWG TYPE "E" TEFLO  
COATED 12' MIN. LG.

## SIZE CONSTANTS

**Value      Units**

Peak Torque Rating - $T_p$	20	OZ. IN.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	60	WATTS
Motor Constant - $K_M$	2.58	OZ IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	400	RAD/S
Electrical Time Constant - $\tau_e$	0.34	MS
Static Friction (Max.) - $T_f$	1.0	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.049 OZ. IN. PER RAD/S
	Infinite Impedance - $F_1$	$4.6 \times 10^{-3}$ OZ. IN. PER RAD/S
Maximum Winding Temperature	105	°C
Temperature Rise per Watt - TPR	15	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	7	PERCENT
Ripple Frequency - (Fundamental)	31	CYCLES/REV.
Number of Poles	6	
Rotor Inertia - $J_m$	$9.5 \times 10^{-4}$	OZ.IN.S <sup>2</sup>
Motor Weight	8.8	OZ.

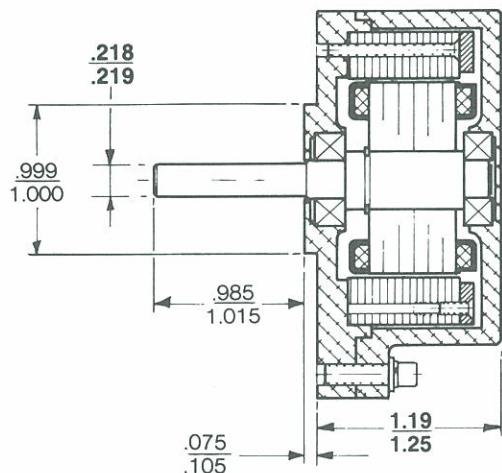
## WINDING CONSTANTS

*Winding Designation*

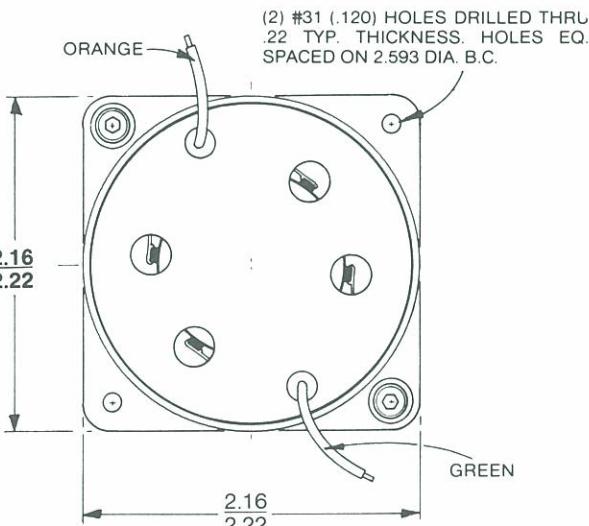
	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	31.0	49.4	26.0	40.6	13.0		
Peak Current - $I_p$	AMPERES	Rated	1.8	1.2	2.3	1.5	4.8		
Torque Sensitivity - $K_t$	OZ.IN./AMP	$\pm 10\%$	11.0	16.5	8.7	13.7	4.2		
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.078	0.116	0.061	0.097	0.0296		
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	17.2	41.2	11.3	27.1	2.7		
Inductance - $L_m$	mH	$\pm 30\%$	6.0	13.0	4.0	10.0	0.90		

**T-1341**

40 oz. in.

**PEAK TORQUE****NOTES:**

1. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, ROTATION SHALL BE C.C.W. FACING LEAD END.



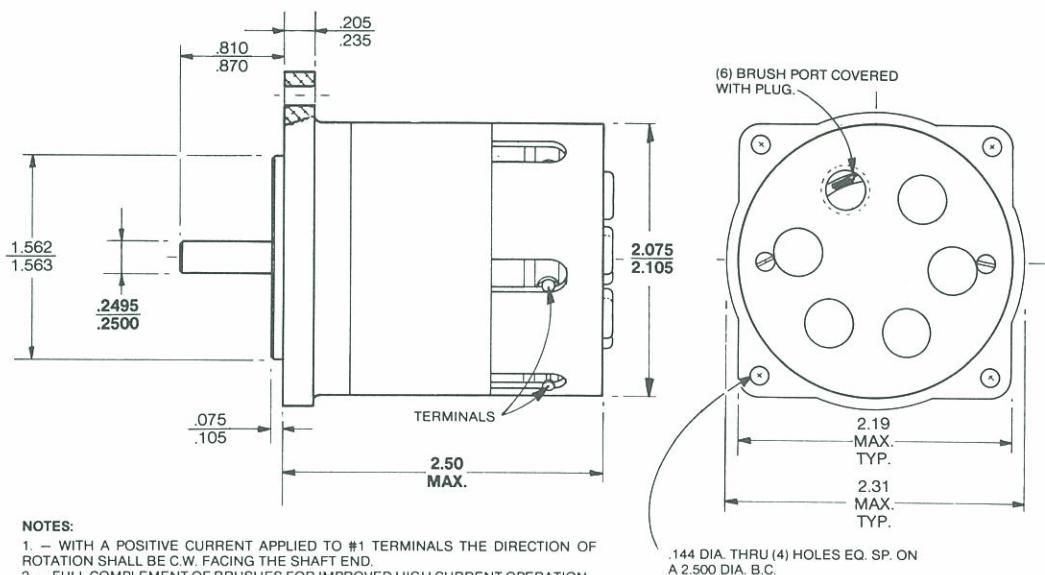
**LEADS:**  
#28 FLEXIBLE WIRE TYPE "E" TEFLON COATED. (2) REQ'D, 10" MIN. LG.

**SIZE CONSTANTS****Value****Units**

Peak Torque Rating - $T_p$	40	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	98	WATTS	
Motor Constant - $K_m$	4.05	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p - \omega_{NL}$	340	RAD/S	
Electrical Time Constant - $\tau_e$	0.34	MS	
Static Friction (Max.) - $T_f$	1.0	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.12	OZ. IN. PER RAD/S
	Infinite Impedance - $F_i$	0.007	OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	13.4	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	7	PERCENT	
Ripple Frequency - (Fundamental)	31	CYCLES/REV.	
Number of Poles	6		
Rotor Inertia - $J_m$	$1.6 \times 10^{-3}$	OZ.IN.S <sup>2</sup>	
Motor Weight	7.6	OZ.	

**WINDING CONSTANTS****Winding Designation**

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	12.8	28.5	23.4				
Peak Current - $I_p$	AMPERES	Rated	7.6	3.31	4.04				
Torque Sensitivity - $K_t$	OZ. IN. / AMP	$\pm 10\%$	5.24	12.1	9.9				
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.037	0.086	0.07				
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	1.67	8.9	5.8				
Inductance - $L_m$	mH	$\pm 30\%$	0.5	3.0	2.0				



## SIZE CONSTANTS

**Value      Units**

Peak Torque Rating - $T_p$	90	OZ. IN.	
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	256	WATTS	
Motor Constant - $K_m$	5.65	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p - \omega_{NL}$	400	RAD/S	
Electrical Time Constant - $\tau_e$	0.411	MS	
Static Friction (Max.) - $T_f$	4.0	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.226	OZ. IN. PER RAD/S
	Infinite Impedance - $F_\infty$	0.019	OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	9	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	7	PERCENT	
Ripple Frequency - (Fundamental)	31	CYCLES/REV.	
Number of Poles	6		
Rotor Inertia - $J_m$	$3.50 \times 10^{-3}$	OZ.IN.S <sup>2</sup>	
Motor Weight	16.1	OZ.	

## WINDING CONSTANTS

**Winding Designation**

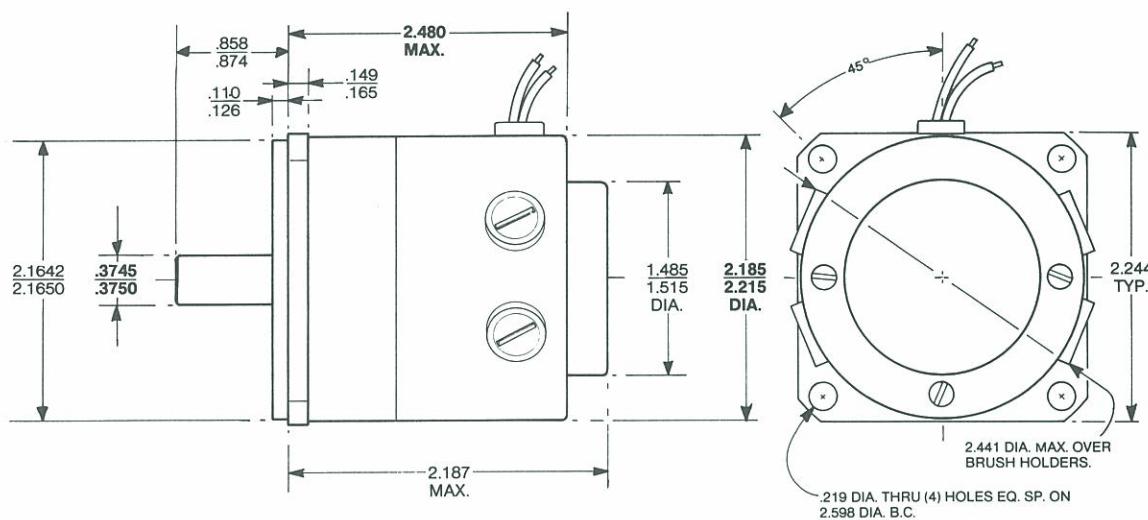
	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	22.0						
Peak Current - $I_p$	AMPERES	Rated	11.6						
Torque Sensitivity - $K_t$	OZ.IN./AMP	± 10%	7.80						
Back EMF Constant - $K_b$	V PER RAD/S	± 10%	0.0551						
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	± 12.5%	1.90						
Inductance - $L_m$	mH	± 30%	0.78						

# QT-1413

0.817 lb. ft.

PEAK TORQUE

RARE EARTH MAGNETS



**NOTE:**  
WITH A POSITIVE CURRENT APPLIED TO RED LEAD WITH RESPECT TO BLUE LEAD, A  
C.W. ROTATION SHALL BE VIEWED FROM SHAFT END.

**LEADS:**  
#26 AWG TYPE "E" TEFLON COATED,  
12" MIN. LENGTH.

## SIZE CONSTANTS

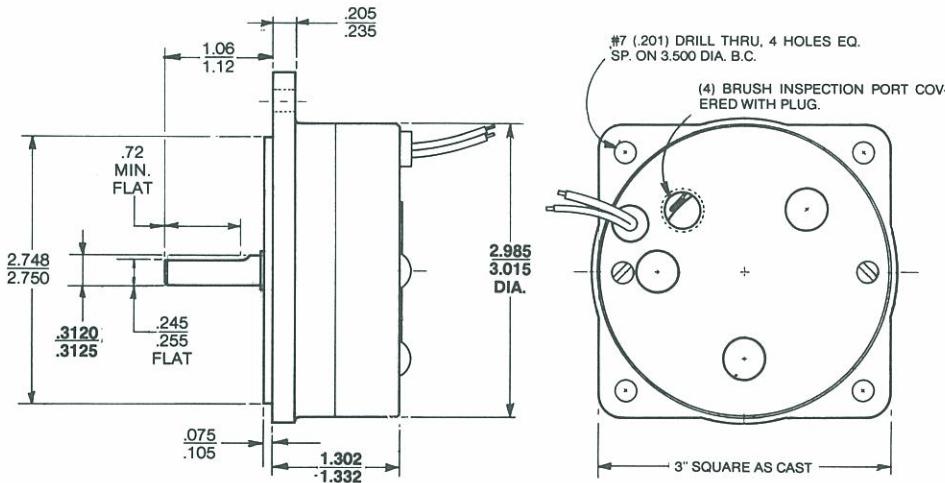
## Value      Units

Peak Torque Rating - $T_p$	0.817	LB. FT.				
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	346	WATTS				
Motor Constant - $K_m$	0.044	LB.FT./ $\sqrt{\text{WATT}}$				
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	312	RAD/S				
Electrical Time Constant - $\tau_e$	0.278	MS				
Static Friction (Max.) - $T_f$	0.023	LB. FT.				
Viscous Damping Coefficients	<table border="0"> <tr> <td>Zero Impedance - <math>F_0</math></td> <td><math>2.62 \times 10^{-3}</math></td> </tr> <tr> <td>Infinite Impedance - <math>F_\infty</math></td> <td><math>1.00 \times 10^{-4}</math></td> </tr> </table>	Zero Impedance - $F_0$	$2.62 \times 10^{-3}$	Infinite Impedance - $F_\infty$	$1.00 \times 10^{-4}$	LB. FT. PER RAD/S
Zero Impedance - $F_0$	$2.62 \times 10^{-3}$					
Infinite Impedance - $F_\infty$	$1.00 \times 10^{-4}$					
Maximum Winding Temperature	155	°C				
Temperature Rise per Watt - TPR	8	°C/WATT				
Ripple Torque (Average to Peak) - $T_r$	7	PERCENT				
Ripple Frequency - (Fundamental)	31	CYCLES/REV.				
Number of Poles	8					
Rotor Inertia - $J_m$	$2.30 \times 10^{-5}$	LB.FT.S <sup>2</sup>				
Motor Weight	2	LB.				

## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	70.6						
Peak Current - $I_p$	AMPERES	Rated	4.90						
Torque Sensitivity - $K_t$	LB.FT./AMP	$\pm 10\%$	0.167						
Back EMF Constant - $K_b$	V PER RAD/S	$\pm 10\%$	0.226						
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	14.4						
Inductance - $L_m$	mH	$\pm 30\%$	4.0						

**NOTE:**

1. - WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, ROTATION SHALL BE C.C.W. FACING THE BRUSH END.

**LEADS:**

#22 AWG TYPE "E" TEFLO COATED  
12" MIN. LG.

**SIZE CONSTANTS****Value      Units**

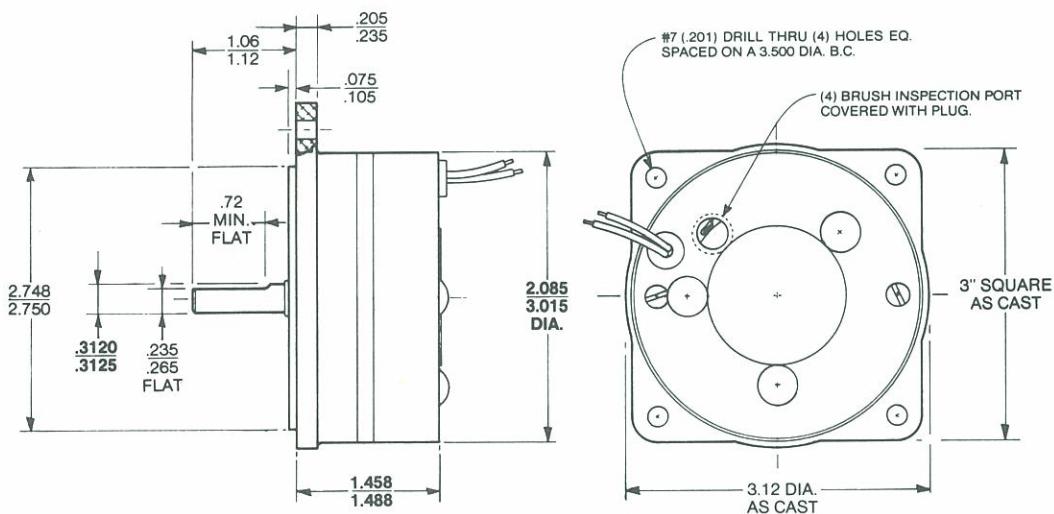
Peak Torque Rating - $T_p$	35	OZ. IN.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	41	WATTS
Motor Constant - $K_m$	5.45	OZ.IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p \cdot \omega_{NL}$	160	RAD/S
Electrical Time Constant - $\tau_e$	0.60	MS
Static Friction (Max.) - $T_f$	1.1	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.22 OZ. IN. PER RAD/S
	Infinite Impedance - $F_i$	$3.6 \times 10^{-4}$ OZ. IN. PER RAD/S
Maximum Winding Temperature	105	°C
Temperature Rise per Watt - $TPR$	7.0	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	6	PERCENT
Ripple Frequency - (Fundamental)	33	CYCLES/REV.
Number of Poles	8	
Rotor Inertia - $J_m$	$6.4 \times 10^{-3}$	OZ.IN.S <sup>2</sup>
Motor Weight	19	OZ.

**WINDING CONSTANTS****Winding Designation**

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	18.9						
Peak Current - $I_p$	AMPERES	Rated	2.0						
Torque Sensitivity - $K_t$	OZ.IN./AMP.	$\pm 10\%$	17.5						
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.12						
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	9.5						
Inductance - $L_m$	mH	$\pm 30\%$	6.0						

# NT-2117

**60 oz. in.**  
**PEAK TORQUE**



**NOTES:**

1. WITH A POSITIVE CURRENT APPLIED TO GREEN LEAD WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING THE BRUSH END.
2. TYPICAL BRUSH LIFE > 10' REV.

**LEADS:**  
#22 AWG TYPE "E" TEFLON COATED,  
12" MIN. LENGTH.

## SIZE CONSTANTS

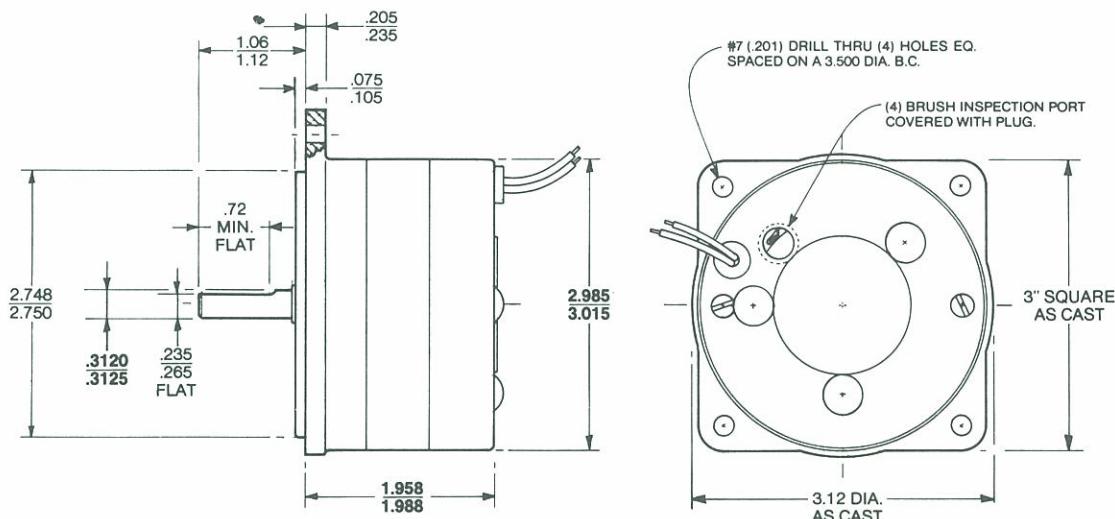
**Value      Units**

Peak Torque Rating - $T_p$	60	OZ. IN.	
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	34	WATTS	
Motor Constant - $K_m$	10.3	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	80	RAD/S	
Electrical Time Constant - $\tau_e$	1.0	MS	
Static Friction (Max.) - $T_f$	2.3	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.75	OZ. IN. PER RAD/S
	Infinite Impedance - $F_i$	0.04	OZ.IN. PER RAD/S
Maximum Winding Temperature	105	°C	
Temperature Rise per Watt - $TPR$	7.8	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	6	PERCENT	
Ripple Frequency - (Fundamental)	33	CYCLES/REV.	
Number of Poles	8		
Rotor Inertia - $J_m$	0.012	OZ.IN.S <sup>2</sup>	
Motor Weight	25	OZ.	

## WINDING CONSTANTS

*Winding Designation*

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	10.6	25.0	49.9	16.8			
Peak Current - $I_p$	AMPERES	Rated	3.2	1.25	0.61	2.0			
Torque Sensitivity - $K_t$	OZ.IN./AMP	$\pm 10\%$	18.7	46.8	98	30.5			
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.13	0.33	0.69	0.22			
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	3.3	20.0	81.5	8.4			
Inductance - $L_m$	mH	$\pm 30\%$	3.2	20	85	8.0			

**NOTES:**

1. - WITH A POSITIVE CURRENT APPLIED TO GREEN LEAD WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING THE BRUSH END.
2. - TYPICAL BRUSH LIFE > 10' REV.

**LEADS:**  
#22 AWG TYPE "E" TEFLOX COATED,  
12" MIN. LENGTH.

**SIZE CONSTANTS****Value      Units**

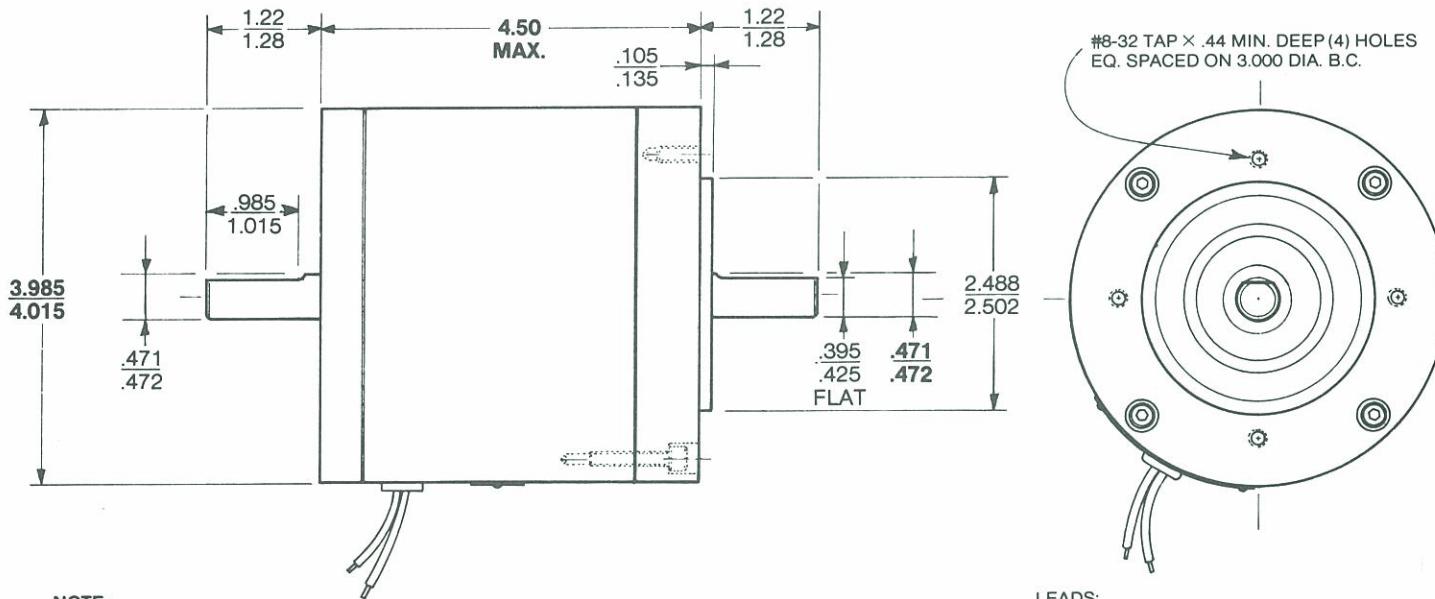
Peak Torque Rating - $T_p$	120	OZ. IN.
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	50	WATTS
Motor Constant - $K_m$	17.0	OZ.IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	57	RAD/S
Electrical Time Constant - $\tau_e$	1.5	MS
Static Friction (Max.) - $T_f$	3.5	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$	2.2 OZ. IN. PER RAD/S
	Infinite Impedance - $F_i$	0.08 OZ. IN. PER RAD/S
Maximum Winding Temperature	105	$^\circ\text{C}$
Temperature Rise per Watt - $TPR$	5.4	$^\circ\text{C}/\text{WATT}$
Ripple Torque (Average to Peak) - $T_r$	6	PERCENT
Ripple Frequency - (Fundamental)	33	CYCLES/REV.
Number of Poles	8	
Rotor Inertia - $J_m$	0.0195	OZ.IN. $^2$
Motor Weight	32	OZ.

**WINDING CONSTANTS****Winding Designation**

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	22.9	28.9	18.2				
Peak Current - $I_p$	AMPERES	Rated	2.1	1.7	2.67				
Torque Sensitivity - $K_t$	OZ.IN./AMP	$\pm 10\%$	57.2	70.8	44.9				
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.404	0.50	0.317				
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	10.9	17.0	6.80				
Inductance - $L_m$	mH	$\pm 30\%$	17.0	26.0	10				

**NT-2171**  
340 oz. in.  
**PEAK TORQUE**

SPECIAL MAGNET FOR RESISTANCE  
TO TORQUE SENSITIVITY DEGRADA-  
TION AT HIGH POWER INPUT LEVELS.



**NOTE:**

WITH A POSITIVE CURRENT APPLIED TO GREEN LEAD WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH END.

**LEADS:**

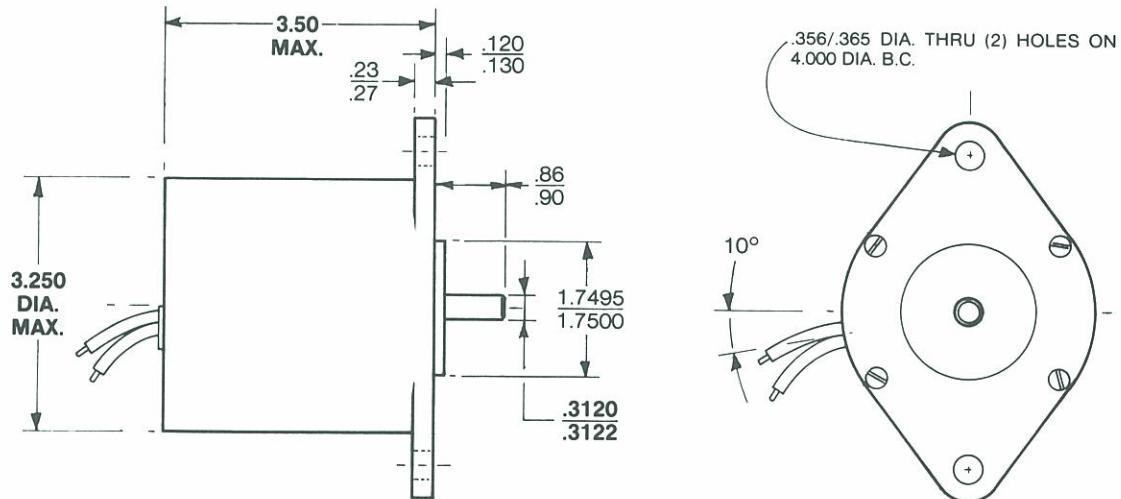
#20 AWG TYPE "EE"TEFLON COATED  
12" MIN. LENGTH.

Peak Torque Rating - $T_p$	340	OZ. IN.
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	440	WATTS
Motor Constant - $K_m$	16.2	OZ.IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	183	RAD/S
Electrical Time Constant - $\tau_e$	2.0	MS
Static Friction (Max.) - $T_f$	9.0	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$	1.85 OZ. IN. PER RAD/S
	Infinite Impedance - $F_i$	0.033 OZ. IN. PER RAD/S
Maximum Winding Temperature	155	$^\circ\text{C}$
Temperature Rise per Watt - $TPR$	2.3	$^\circ\text{C}/\text{WATT}$
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT
Ripple Frequency - (Fundamental)	31	CYCLES/REV.
Number of Poles	4	
Rotor Inertia - $J_m$	0.025	OZ.IN.S <sup>2</sup>
Motor Weight	160	oz.

**WINDING CONSTANTS**

*Winding Designation*

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	22.0						
Peak Current - $I_p$	AMPERES	Rated	20.0						
Torque Sensitivity - $K_t$	OZ.IN./AMP	$\pm 10\%$	17.0						
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.12						
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	1.1						
Inductance - $L_m$	mH	$\pm 30\%$	2.25						



**NOTE:**

1. —WITH A POSITIVE CURRENT APPLIED TO RED LEAD, ROTATION SHALL BE C.C.W. FACING SHAFT END.
2. —GOLD PLATED COMMUTATOR.

**LEADS:**  
**#24 AWG 19-STAND TYPE "E" TEF-  
 LON COATED PER MIL W-16878 12"  
 MIN. LG.**

### SIZE CONSTANTS

**Value      Units**

Peak Torque Rating - $T_p$	1.50	LB. FT.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	25	WATTS
Motor Constant - $K_m$	0.301	LB.FT./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	12.2	RAD/S
Electrical Time Constant - $\tau_e$	2.25	MS
Static Friction (Max.) - $T_f$	0.12	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_\infty$	0.123 $1.4 \times 10^{-3}$
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	4.3	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT
Ripple Frequency - (Fundamental)	39	CYCLES/REV.
Number of Poles	10	
Rotor Inertia - $J_m$	$5.00 \times 10^{-4}$	LB.FT.S <sup>2</sup>
Motor Weight	5.0	LB.

### WINDING CONSTANTS

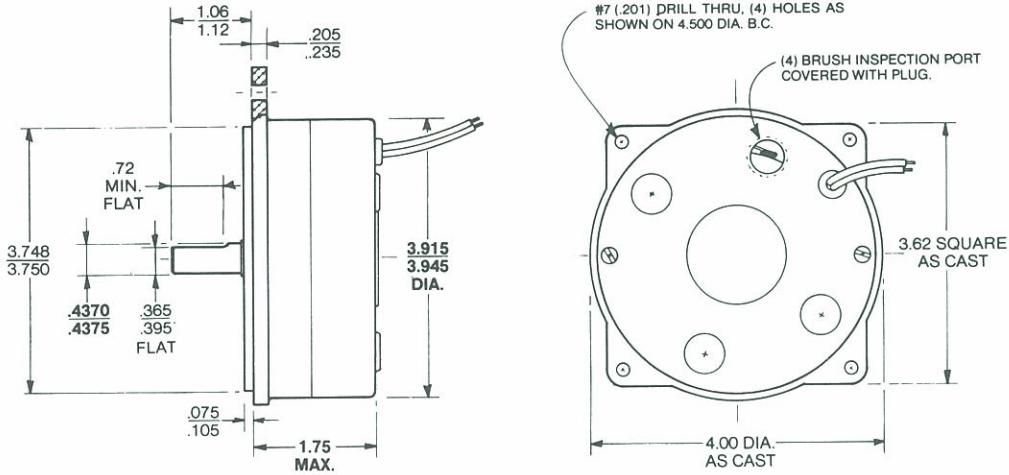
**Winding Designation**

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	5.46	17.3					
Peak Current - $I_p$	AMPERES	Rated	4.55	1.44					
Torque Sensitivity - $K_t$	LB.FT./AMP	$\pm 10\%$	0.330	1.04					
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.447	1.41					
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	1.20	12.0					
Inductance - $L_m$	mH	$\pm 30\%$	2.7	27					

# T-2998

0.85 lb. ft.

PEAK TORQUE



NOTES:

1. WITH A POSITIVE CURRENT APPLIED TO GREEN LEAD WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W.FACING THE BRUSH END.
2. TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

LEADS:  
#22 AWG TYPE "E" TEFLON COATED  
12" MIN. LENGTH.

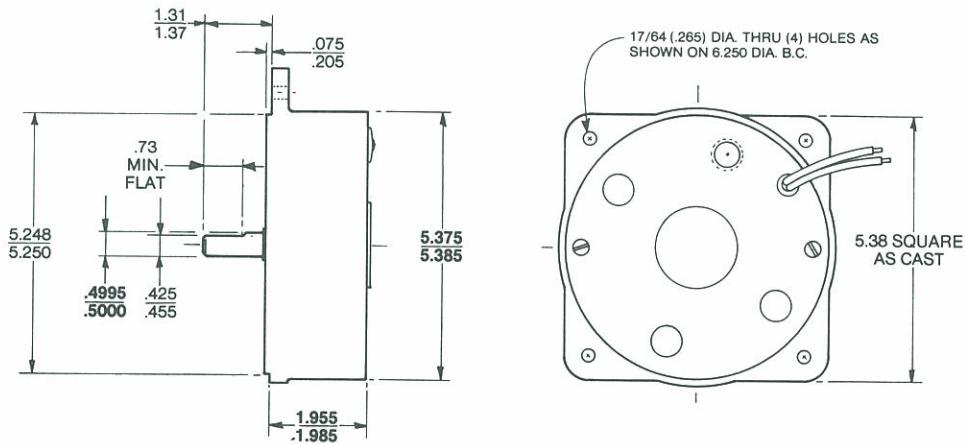
## SIZE CONSTANTS

Peak Torque Rating - $T_p$	0.85	LB. FT.						
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	77	WATTS						
Motor Constant - $K_m$	0.097	LB.FT./ $\sqrt{\text{WATT}}$						
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	67	RAD/S						
Electrical Time Constant - $\tau_e$	1.6	MS						
Static Friction (Max.) - $T_f$	0.017	LB. FT.						
Viscous Damping Coefficients	<table border="0"> <tr> <td>Zero Impedance - <math>F_0</math></td> <td>0.013</td> <td>LB. FT. PER RAD/S</td> </tr> <tr> <td>Infinite Impedance - <math>F_\infty</math></td> <td><math>0.5 \times 10^{-3}</math></td> <td>LB. FT. PER RAD/S</td> </tr> </table>	Zero Impedance - $F_0$	0.013	LB. FT. PER RAD/S	Infinite Impedance - $F_\infty$	$0.5 \times 10^{-3}$	LB. FT. PER RAD/S	
Zero Impedance - $F_0$	0.013	LB. FT. PER RAD/S						
Infinite Impedance - $F_\infty$	$0.5 \times 10^{-3}$	LB. FT. PER RAD/S						
Maximum Winding Temperature	105	$^\circ\text{C}$						
Temperature Rise per Watt - $TPR$	3.5	$^\circ\text{C}/\text{WATT}$						
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT						
Ripple Frequency - (Fundamental)	41	CYCLES/REV.						
Number of Poles	10							
Rotor Inertia - $J_m$	$2.4 \times 10^{-4}$	LB.FT.S <sup>2</sup>						
Motor Weight	2.5	LB.						

## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	28.2	14.9	22.8	89.2	34.5	56.7	12.2
Peak Current - $I_p$	AMPERES	Rated	2.74	5.5	3.4	0.85	2.13	1.36	6.8
Torque Sensitivity - $K_t$	LB.FT./AMP	$\pm 10\%$	0.31	0.155	0.25	1.0	0.40	0.63	0.125
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.42	0.21	0.34	1.36	0.54	0.85	0.17
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	10.3	2.7	6.7	105	16.2	41.7	1.8
Inductance - $L_m$	mH	$\pm 30\%$	17	4.1	11	175	27	68	2.7



**NOTE:**

WITH A POSITIVE CURRENT APPLIED TO GREEN LEAD WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.W. FACING THE SHAFT END.

**LEADS:**

#24 AWG TYPE "E" TEFLON COATED,  
12" MIN. LENGTH.

### SIZE CONSTANTS

**Value      Units**

Peak Torque Rating - $T_p$	1.8	LB. FT.	
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	91	WATTS	
Motor Constant - $K_m$	0.19	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	37	RAD/S	
Electrical Time Constant - $\tau_e$	1.9	MS	
Static Friction (Max.) - $T_f$	0.04	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.048	LB. FT. PER RAD/S
	Infinite Impedance - $F_i$	0.001	LB. FT. PER RAD/S
Maximum Winding Temperature	105	°C	
Temperature Rise per Watt - $TPR$	3.3	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT	
Ripple Frequency - (Fundamental)	56	CYCLES/REV.	
Number of Poles	10		
Rotor Inertia - $J_m$	$8.72 \times 10^{-4}$	LB.FT.S <sup>2</sup>	
Motor Weight	4	LB.	

### WINDING CONSTANTS

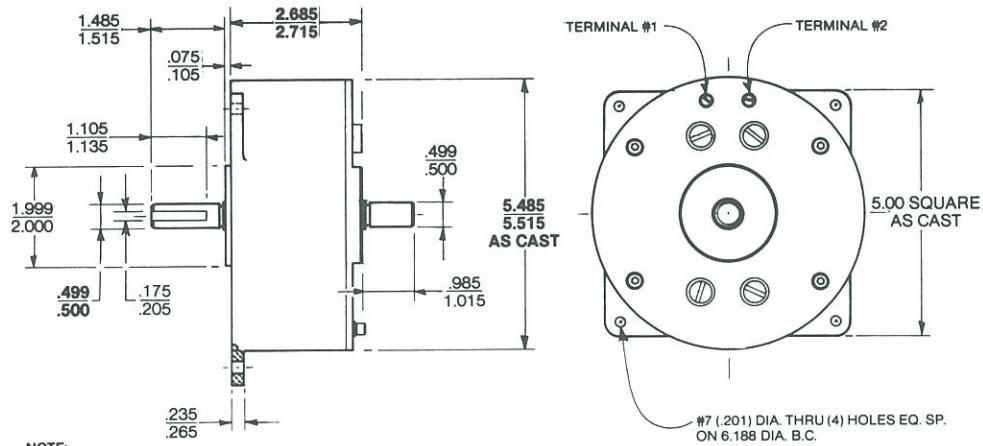
*Winding Designation*

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	15.7	19.8	25.5	39.8			
Peak Current - $I_p$	AMPERES	Rated	5.60	4.60	3.70	2.30			
Torque Sensitivity - $K_t$	LB.FT./AMP	$\pm 10\%$	0.32	0.39	0.49	0.79			
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.43	0.53	0.66	1.07			
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	2.80	4.30	6.90	17.3			
Inductance - $L_m$	mH	$\pm 30\%$	5.0	8.0	13	33			

# T-4054

**2.7 lb. ft.**

**PEAK TORQUE**



**NOTE:**  
WITH A POSITIVE CURRENT APPLIED TO TERMINAL #1 WITH RESPECT TO TERMINAL  
#2. ROTATION SHALL BE C.C.W. FACING BRUSH END.

## SIZE CONSTANTS

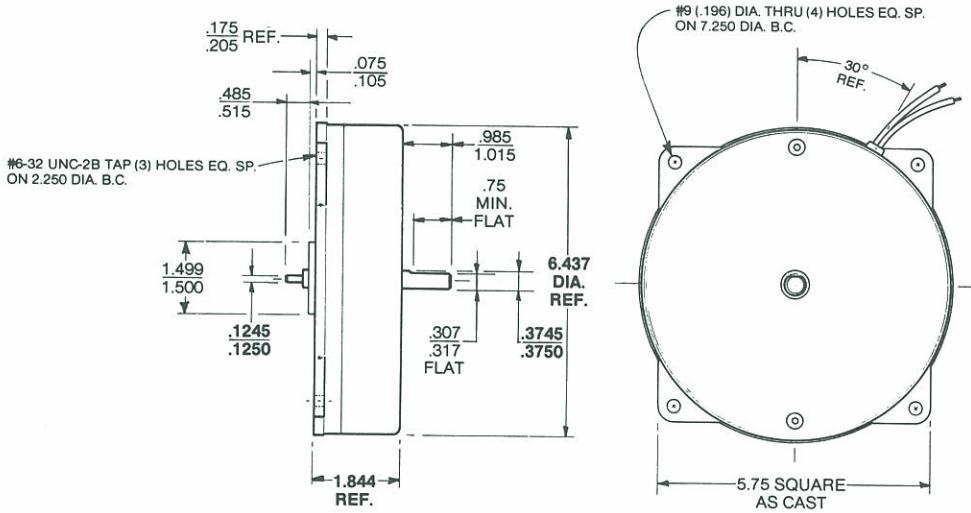
**Value      Units**

Peak Torque Rating - $T_p$	2.7	LB. FT.	
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	147	WATTS	
Motor Constant - $K_M$	0.22	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	40	RAD/S	
Electrical Time Constant - $\tau_E$	2.0	MS	
Static Friction (Max.) - $T_f$	0.052	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.067	LB. FT. PER RAD/S
	Infinite Impedance - $F_i$	0.0015	LB. FT. PER RAD/S
Maximum Winding Temperature	105	$^\circ\text{C}$	
Temperature Rise per Watt - $TPR$	1.3	$^\circ\text{C}/\text{WATT}$	
Ripple Torque (Average to Peak) - $T_R$	5	PERCENT	
Ripple Frequency - (Fundamental)	56	CYCLES/REV.	
Number of Poles	10		
Rotor Inertia - $J_m$	0.0011	LB.FT. $\text{S}^2$	
Motor Weight	4	LB.	

## WINDING CONSTANTS

**Winding Designation**

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	30.0	14.6					
Peak Current - $I_p$	AMPERES	Rated	4.92	10.0					
Torque Sensitivity - $K_T$	LB.FT./AMP	$\pm 10\%$	0.55	0.27					
Back EMF Constant - $K_B$	V per RAD/S	$\pm 10\%$	0.75	0.37					
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	6.1	1.46					
Inductance - $L_m$	mH	$\pm 30\%$	12.0	2.8					



NOTE:

WITH A POSITIVE CURRENT APPLIED TO GREEN LEAD WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.W. WHEN VIEWED FROM MOUNTING FLANGE END.

LEADS:  
#20 AWG TYPE "EE" TEFLON COATED  
18" MIN LG.

## SIZE CONSTANTS

### Value      Units

Peak Torque Rating - $T_p$	2.7	LB. FT.
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	85	WATTS
Motor Constant - $K_M$	0.29	LB.FT./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	22	RAD/S
Electrical Time Constant - $\tau_E$	2.6	MS
Static Friction (Max.) - $T_f$	0.05	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	0.12      0.0015
Maximum Winding Temperature	105	°C
Temperature Rise per Watt - $TPR$	1.1	°C/WATT
Ripple Torque (Average to Peak) - $T_R$	5	PERCENT
Ripple Frequency - (Fundamental)	71	CYCLES/REV.
Number of Poles	12	
Rotor Inertia - $J_m$	0.002	LB.FT.S <sup>2</sup>
Motor Weight	7	LB.

## WINDING CONSTANTS

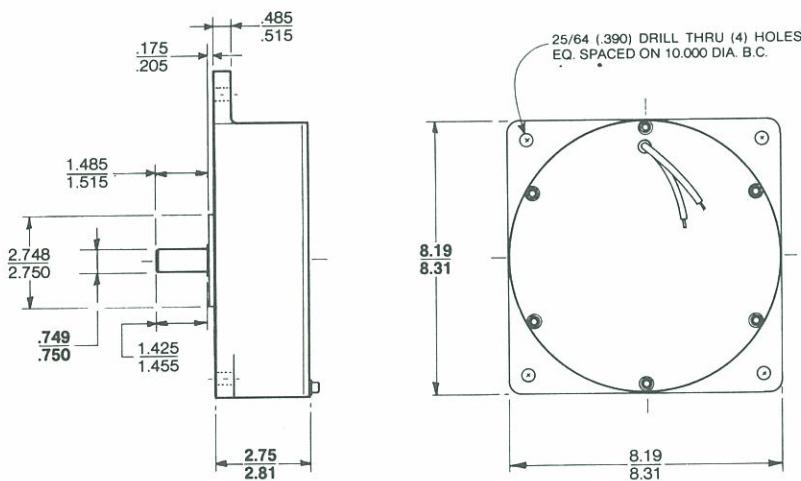
### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	28.7	22.9	18.1	45.0			
Peak Current - $I_p$	AMPERES	Rated	2.84	3.75	4.53	1.80			
Torque Sensitivity - $K_T$	LB.FT./AMP	$\pm 10\%$	0.95	0.72	0.595	1.50			
Back EMF Constant - $K_B$	V per RAD/S	$\pm 10\%$	1.29	0.98	0.81	2.03			
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	10.1	6.10	4.00	25.0			
Inductance - $L_m$	mH	$\pm 30\%$	26	16	10	64			

# T-5721

7.0 lb. ft.

PEAK TORQUE



**NOTES:**

1. - WITH A POSITIVE CURRENT APPLIED TO GREEN LEAD WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. WHEN VIEWED FROM SHAFT END.
2. - TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**LEADS:**

#18 AWG TYPE "E" TEFLON COATED  
24" MIN. LENGTH.

## SIZE CONSTANTS

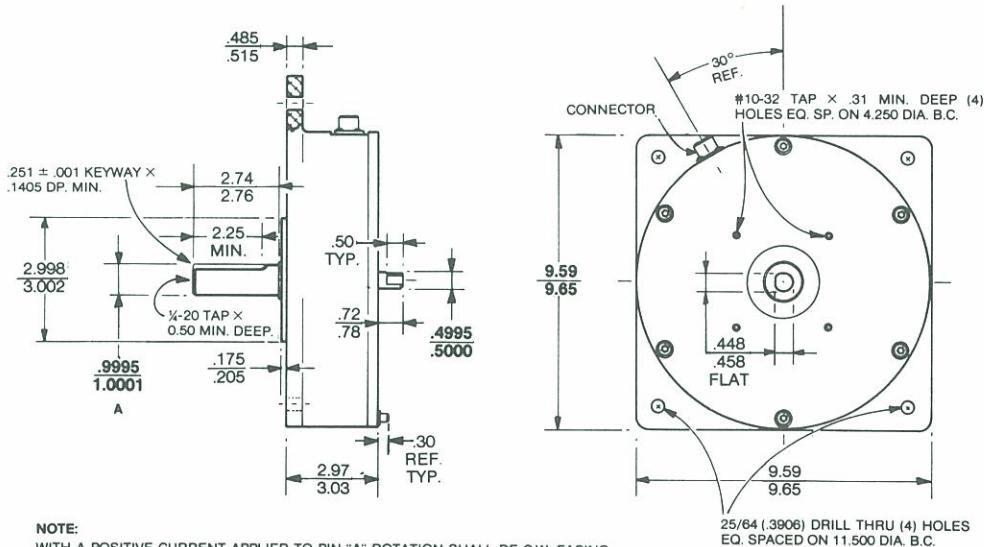
**Value      Units**

Peak Torque Rating - $T_P$	7.0	LB. FT.
Power Input, Stalled at $T_P$ (25°C) - $P_P$	260	WATTS
Motor Constant - $K_M$	0.43	LB.FT./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_P$ - $\omega_{NL}$	27	RAD/S
Electrical Time Constant - $\tau_E$	3.0	MS
Static Friction (Max.) - $T_F$	0.1	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_I$	0.26      0.003
Maximum Winding Temperature	105	°C
Temperature Rise per Watt - $TPR$	1.0	°C/WATT
Ripple Torque (Average to Peak) - $T_R$	4	PERCENT
Ripple Frequency - (Fundamental)	79	CYCLES/REV.
Number of Poles	10	
Rotor Inertia - $J_M$	$5.4 \times 10^{-3}$	LB.FT.S <sup>2</sup>
Motor Weight	10.5	LB.

## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_P$ (25°C) - $V_P$	VOLTS	Nom.	37.8	19.8	57.4	113.4	45.7		
Peak Current - $I_P$	AMPERES	Rated	7.00	13.2	4.38	2.12	5.38		
Torque Sensitivity - $K_T$	LB.FT./AMP	±10%	1.00	0.53	1.60	3.30	1.30		
Back EMF Constant - $K_B$	V per RAD/S	±10%	1.36	0.72	2.17	4.47	1.76		
DC Resistance (25°C) - $R_M$	OHMS	±12.5%	5.40	1.50	13.1	53.5	8.50		
Inductance - $L_M$	mH	±30%	17	5.0	40	174	27		



**NOTE:**  
 WITH A POSITIVE CURRENT APPLIED TO PIN "A" ROTATION SHALL BE C.W. FACING  
 PILOT END.

## SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>	
Peak Torque Rating - $T_p$	11	LB. FT.	
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	335	WATTS	
Motor Constant - $K_m$	0.601	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	22.5	RAD/S	
Electrical Time Constant - $\tau_e$	3.18	MS	
Static Friction (Max.) - $F_f$	0.15	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.489	LB. FT. PER RAD/S
	Infinite Impedance - $F_\infty$	0.005	LB. FT. PER RAD/S
Maximum Winding Temperature	105	°C	
Temperature Rise per Watt - $TPR$	1.2	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	4	PERCENT	
Ripple Frequency - (Fundamental)	97	CYCLES/REV.	
Number of Poles	12		
Rotor Inertia - $J_m$	0.010	LB.FT.S <sup>2</sup>	
Motor Weight	10.3	LB.	

## WINDING CONSTANTS

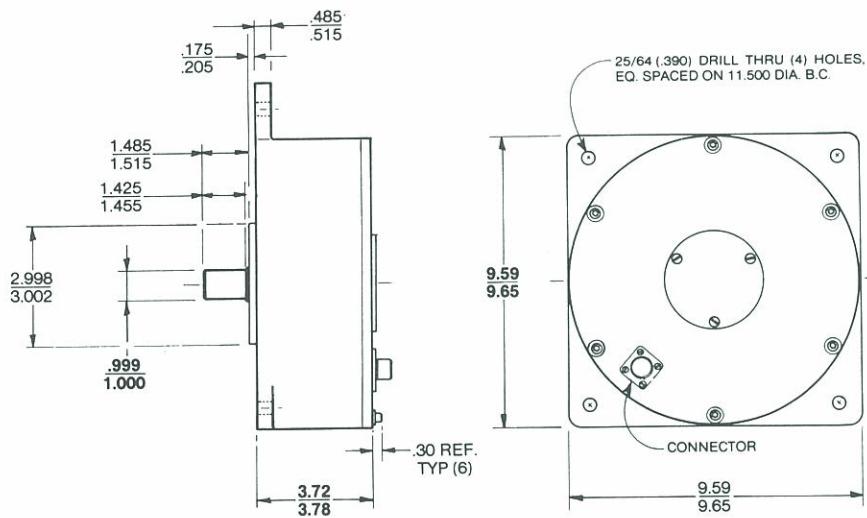
## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	Volts	Nom.	38.4	30.5					
Peak Current - $I_p$	AMPERES	Rated	8.73	11					
Torque Sensitivity - $K_t$	LB. FT./AMP	± 10%	1.26	1					
Back EMF Constant - $K_b$	V PER RAD/S	± 10%	1.71	1.36					
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	± 12.5%	4.40	2.77					
Inductance - $L_m$	mH	± 30%	14	8.81					

# T-7215

22 lb. ft.

PEAK TORQUE



## SIZE CONSTANTS

**Value**

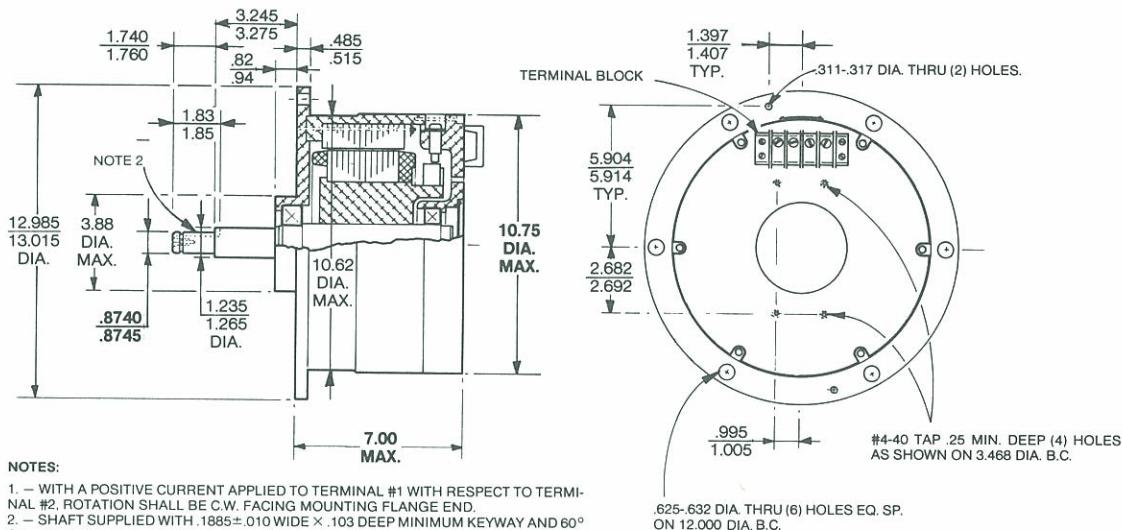
**Units**

Peak Torque Rating - $T_p$	22	LB. FT.
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	530	WATTS
Motor Constant - $K_m$	0.96	LB.FT./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p - \omega_{NL}$	15	RAD/S
Electrical Time Constant - $\tau_e$	5.7	MS
Static Friction (Max.) - $T_f$	0.25	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	1.25      0.013
Maximum Winding Temperature	105	°C
Temperature Rise per Watt - TPR	1.1	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	4	PERCENT
Ripple Frequency - (Fundamental)	97	CYCLES/REV.
Number of Poles	12	
Rotor Inertia - $J_m$	0.019	LB.FT.S <sup>2</sup>
Motor Weight	35	LB.

## WINDING CONSTANTS

*Winding Designation*

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	66.7	50.1	23.8				
Peak Current - $I_p$	AMPERES	Rated	7.75	8.50	19.0				
Torque Sensitivity - $K_t$	LB.FT./AMP.	$\pm 10\%$	2.84	2.60	1.16				
Back EMF Constant - $K_B$	V per RAD/S	$\pm 10\%$	3.85	3.53	1.57				
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	8.60	5.90	1.25				
Inductance - $L_m$	mH	$\pm 30\%$	48.0	40.0	8.0				



## SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>	
Peak Torque Rating - $T_p$	64	LB. FT.	
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	720	WATTS	
Motor Constant - $K_m$	2.38	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	8	RAD/S	
Electrical Time Constant - $\tau_e$	13.3	MS	
Static Friction (Max.) - $T_f$	0.65	LB. FT.	
Viscous Damping Coefficients	Zero Impedance : $F_0$ Infinite Impedance : $F_i$	7.72      0.03	LB. FT. PER RAD/S      LB. FT. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	0.3	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT	
Ripple Frequency - (Fundamental)	77	CYCLES/REV.	
Number of Poles	12		
Rotor Inertia - $J_m$	0.062	LB.FT.S <sup>2</sup>	
Motor Weight	100	LB.	

## WINDING CONSTANTS

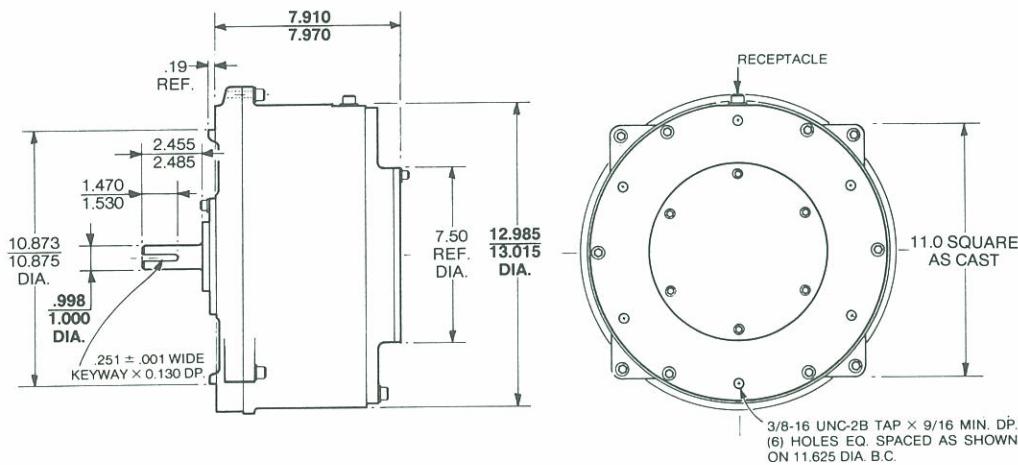
## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	18.0						
Peak Current - $I_p$	AMPERES	Rated	40.0						
Torque Sensitivity - $K_t$	LB.FT./AMP	$\pm 10\%$	1.60						
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	2.17						
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	0.45						
Inductance - $L_m$	mH	$\pm 30\%$	6.0						

# T-10081

100 lb. ft.

PEAK TORQUE



## SIZE CONSTANTS

		Value	Units
Peak Torque Rating - $T_P$	100	LB. FT.	
Power Input, Stalled at $T_P$ ( $25^\circ\text{C}$ ) - $P_P$	1070	WATTS	
Motor Constant - $K_M$	3.06	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_P$ - $\omega_{NL}$	7.5	RAD/S	
Electrical Time Constant - $\tau_E$	6.7	MS	
Static Friction (Max.) - $T_F$	1.2	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_I$	13      0.05	LB. FT. PER RAD/S      LB. FT. PER RAD/S
Maximum Winding Temperature	105	°C	
Temperature Rise per Watt - TPR	0.3	°C/WATT	
Ripple Torque (Average to Peak) - $T_R$	4	PERCENT	
Ripple Frequency - (Fundamental)	190	CYCLES/REV.	
Number of Poles	14		
Rotor Inertia - $J_M$	0.29	LB.FT.S <sup>2</sup>	
Motor Weight	130	LB.	

## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_P$ ( $25^\circ\text{C}$ ) - $V_P$	VOLTS	Nom.	44						
Peak Current - $I_P$	AMPERES	Rated	24.4						
Torque Sensitivity - $K_T$	LB.FT./AMP	$\pm 10\%$	4.1						
Back EMF Constant - $K_B$	V per RAD/S	$\pm 10\%$	5.55						
DC Resistance ( $25^\circ\text{C}$ ) - $R_M$	OHMS	$\pm 12.5\%$	1.8						
Inductance - $L_M$	mH	$\pm 30\%$	12						

## **SERVO MOTORS**

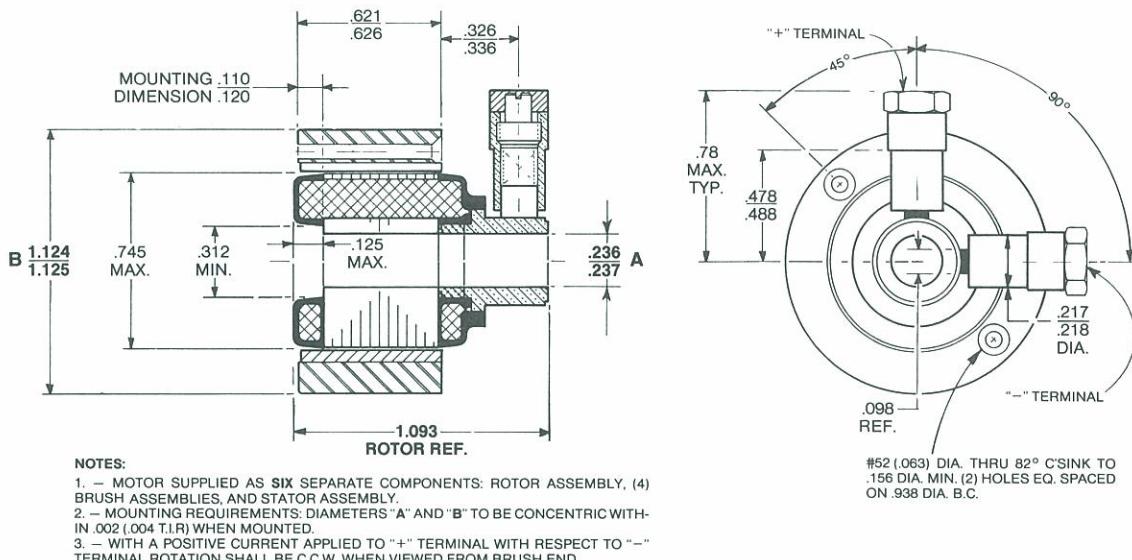
Servo motors are typically used in “running” applications where motor response time is critical. Because of the small diameter, long width configuration the torque is high, but the rotor inertia is minimized. Servo motors also typically have cartridge brushes for extended long life.

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*This section contains both frameless and housed versions of the basic servo motor.*

## Frameless Servo Selection Guide (oz. in. & lb. ft.)

MODEL NUMBER	Peak Torque @ Stall		Motor Constant	No Load Speed	Electrical Time Constant	Friction	Rotor Inertia	Physical Dimensions			Weight
	T <sub>P</sub> oz. in.	P <sub>P</sub> watts	K <sub>M</sub> oz. in./watt	ω <sub>NL</sub> rad/sec	τ <sub>e</sub> msec.	T <sub>f</sub> oz. in.	J <sub>M</sub> oz. in. sec. <sup>2</sup>	OD in.	ID in.	Length in.	oz.
QT-0718	12.3	63	1.5	725	0.32	0.8	1.6 × 10 <sup>-4</sup>	1.13	0.24	1.09	2.5
QT-0807	24	110	2.29	658	0.58	1.0	2.8 × 10 <sup>-4</sup>	1.25	shaft	1.55	7.3
T-1264	25	46	3.68	260	0.54	2.5	1.5 × 10 <sup>-3</sup>	2.25	shaft	1.53	22
T-1263	50	62	6.35	177	0.80	3.0	2.2 × 10 <sup>-3</sup>	2.25	shaft	1.97	16
QT-1809	54	140	4.56	368	0.60	5.5	8.0 × 10 <sup>-3</sup>	2.50	0.63	1.81	17
NT-2196	80	292	4.7	520	1.2	4.0	1.0 × 10 <sup>-2</sup>	3.07	0.79	1.93	24
NT-2191	90	56.5	11.9	89.3	1.64	7.5	1.9 × 10 <sup>-2</sup>	2.81	1.00	1.78	27
T-1265	100	102	9.9	143	1.06	6.0	3.2 × 10 <sup>-3</sup>	2.25	shaft	2.88	30
T-1806	100	95	10.3	130	1.3	3	1.0 × 10 <sup>-2</sup>	3.07	0.47	1.75	25
QT-2106	100	55	13.5	78	0.68	7	1.1 × 10 <sup>-2</sup>	2.81	shaft	1.75	25
T-1846	140	64	17.5	65	1.80	6	1.5 × 10 <sup>-2</sup>	3.07	0.47	2.37	45
QT-1403	157	347	8.42	313	0.28	3.5	3.73 × 10 <sup>-3</sup>	1.94	0.62	1.25	12
QT-1811	200	133	17.4	94.1	1.45	8.0	1.5 × 10 <sup>-2</sup>	2.90	0.43	2.31	48
T-1817	200	120	18.3	85	2.2	5	1.5 × 10 <sup>-2</sup>	3.07	0.47	2.37	45
	lb. ft.	watts	lb. ft./watt	rad/sec	msec.	lb. ft.	lb. ft. sec. <sup>2</sup>	in.	in.	in.	lbs.
NT-2952	1.2	79	0.13	48	2.1	0.05	3.9 × 10 <sup>-4</sup>	3.73	0.63	2.29	3.1
QT-2003	1.7	108	0.17	46.4	2.73	0.08	2.3 × 10 <sup>-4</sup>	2.90	0.50	4.00	3.1
T-1834	2.1	180	0.16	62	3.2	0.04	1.5 × 10 <sup>-4</sup>	3.07	shaft	3.81	5
T-7276	23	600	0.94	19.2	3.7	0.6	2.2 × 10 <sup>-2</sup>	9.00	4.25	3.57	22.5
QT-6404	26	560	1.1	15.9	3.9	0.5	1.3 × 10 <sup>-2</sup>	7.75	4.25	2.65	13.5
QT-6501	37	960	1.19	19	3.3	0.75	4.3 × 10 <sup>-2</sup>	8.50	1.00	6.33	42
QT-6405	40	819	1.4	15	4.3	0.75	1.85 × 10 <sup>-2</sup>	7.75	4.25	3.35	19
QT-7808	69	852	2.36	9.1	7.31	0.80	6.0 × 10 <sup>-2</sup>	9.00	2.15	5.00	47
T-9905	70	850	2.4	8.5	6.7	1.2	0.21	12.00	7.50	4.40	52



## SIZE CONSTANTS

	Value	Units	
Peak Torque Rating - $T_p$	12.3	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	63	WATTS	
Motor Constant - $K_m$	1.55	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	725	RAD/S	
Electrical Time Constant - $\tau_e$	0.315	MS	
Static Friction (Max.) - $T_f$	0.80	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	0.017 0.0002	OZ. IN. PER RAD/S OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	25	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	10	PERCENT	
Ripple Frequency - (Fundamental)	13	CYCLES/REV	
Number of Poles	4		
Rotor Inertia - $J_m$	$1.6 \times 10^{-4}$	OZ.IN.S <sup>2</sup>	
Motor Weight	2.5	OZ.	

## WINDING CONSTANTS

### Winding Designation

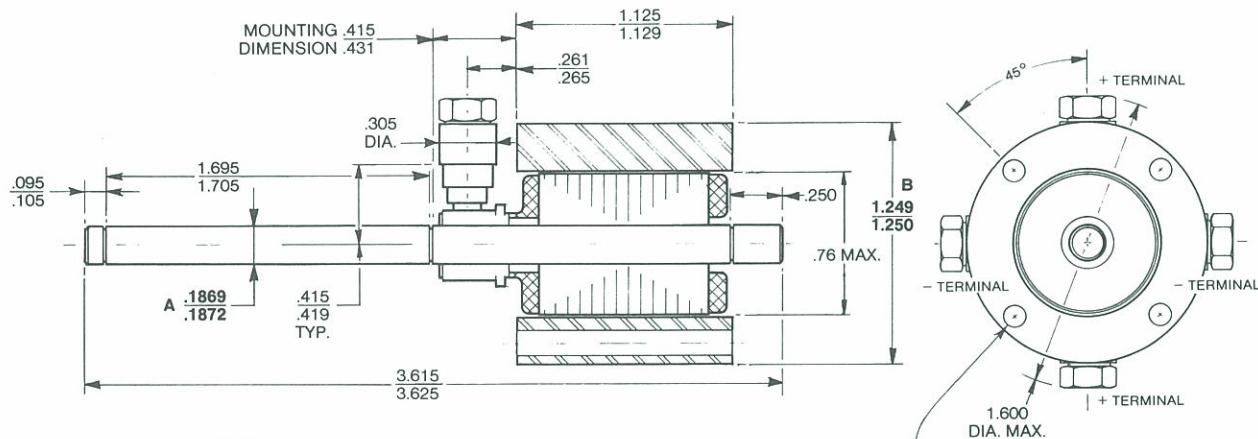
	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	21.0	16.7					
Peak Current - $I_p$	AMPERES	Rated	3.00	3.79					
Torque Sensitivity - $K_t$	OZ. IN./AMP	$\pm 10\%$	4.10	3.25					
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.029	0.023					
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	7.00	4.40					
Inductance - $L_m$	mH	$\pm 30\%$	2.2	1.4					

# QT-0807

24 oz. in.

PEAK TORQUE

RARE EARTH MAGNETS



**NOTES:**

1. — MOTOR TO BE SUPPLIED AS SIX SEPARATE COMPONENTS: ARMATURE, STATOR AND (4) BRUSH ASSEMBLIES.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .0035 (.007 T.I.R) WHEN MOUNTED.
3. — WITH A POSITIVE VOLTAGE APPLIED TO "+" TERMINALS WITH RESPECT TO "-" TERMINALS, ROTATION SHALL BE C.W. FACING BRUSH END.
4. — BRUSH HOLDERS TO BE MOUNTED BY CUSTOMER.

1/4 (.125) DIA. THRU (4) HOLES EQ. SP.  
ON 1.062 DIA. B.C.

## SIZE CONSTANTS

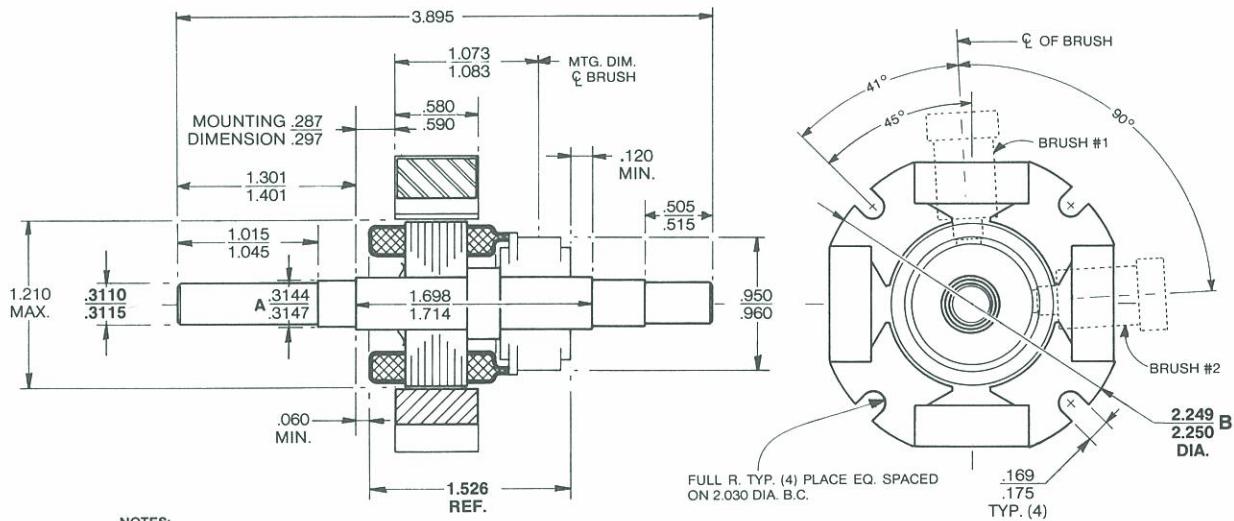
**Value      Units**

Peak Torque Rating - $T_p$	24	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	110	WATTS	
Motor Constant - $K_m$	2.29	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p \cdot \omega_{NL}$	658	RAD/S	
Electrical Time Constant - $\tau_e$	0.58	MS	
Static Friction (Max.) - $F_f$	1.0	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_\infty$	0.036      0.0011	OZ. IN. PER RAD/S      OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	9	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	10	PERCENT	
Ripple Frequency - (Fundamental)	13	CYCLES/REV.	
Number of Poles	4		
Rotor Inertia - $J_m$	$2.8 \times 10^{-4}$	OZ.IN.S <sup>2</sup>	
Motor Weight	7.3	OZ.	

## WINDING CONSTANTS

*Winding Designation*

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	21.7						
Peak Current - $I_p$	AMPERES	Rated	5.05						
Torque Sensitivity - $K_t$	OZ.IN./AMP	$\pm 10\%$	4.75						
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.033						
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	4.30						
Inductance - $L_m$	mH	$\pm 30\%$	2.5						



NOTES:

1. — MOTOR SUPPLIED AS TWO SEPARATE COMPONENTS: ROTOR, STATOR WITH KEEPER. CAUTION: DO NOT REMOVE KEEPER UNLESS ROTOR IS FULLY IN PLACE.
2. — BRUSHES AND HOLDERS ARE CUSTOMER SUPPLIED.
3. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .004 (.008 T.I.R.) WHEN MOUNTED.
4. — WITH POSITIVE CURRENT APPLIED TO BRUSH #1, WITH RESPECT TO BRUSH #2, ROTATION SHALL BE C.C.W. WHEN VIEWED FROM BRUSH SIDE.

### SIZE CONSTANTS

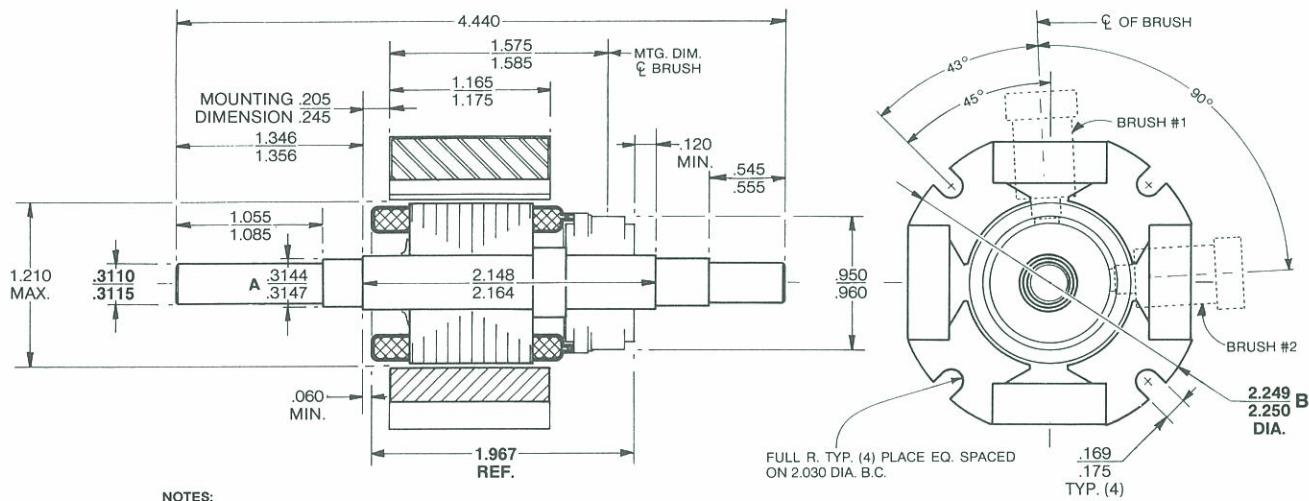
**Value      Units**

Peak Torque Rating - $T_p$	25	OZ. IN.	
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	46	WATTS	
Motor Constant - $K_m$	3.68	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	260	RAD/S	
Electrical Time Constant - $\tau_e$	0.542	MS	
Static Friction (Max.) - $T_f$	2.5	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_\infty$	0.096      0.0015	OZ. IN. PER RAD/S      OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	8.0	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	7	PERCENT	
Ripple Frequency - (Fundamental)	21	CYCLES/REV.	
Number of Poles	4		
Rotor Inertia - $J_m$	0.0015	OZ.IN.S <sup>2</sup>	
Motor Weight	22	OZ.	

### WINDING CONSTANTS

*Winding Designation*

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	10.5	21.0					
Peak Current - $I_p$	AMPERES	Rated	4.39	2.19					
Torque Sensitivity - $K_t$	OZ.IN./AMP	$\pm 10\%$	5.70	11.4					
Back EMF Constant - $K_b$	V PER RAD/S	$\pm 10\%$	0.040	0.080					
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	2.40	9.60					
Inductance - $L_m$	mH	$\pm 30\%$	1.3	5.2					



NOTES:

1. — MOTOR SHIPPED WITH ARMATURE INSIDE STATOR AND MYLAR IN AIR GAP.  
**CAUTION:** DO NOT REMOVE ARMATURE FROM STATOR. REMOVE MYLAR AFTER ARMATURE & STATOR ARE SECURELY IN PLACE.
2. — BRUSHES AND HOLDERS ARE CUSTOMER SUPPLIED.
3. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .004 (.008 I.R.) WHEN MOUNTED.
4. — WITH POSITIVE CURRENT APPLIED TO BRUSH #1, WITH RESPECT TO BRUSH #2, ROTATION SHALL BE C.C.W. WHEN VIEWED FROM BRUSH SIDE.

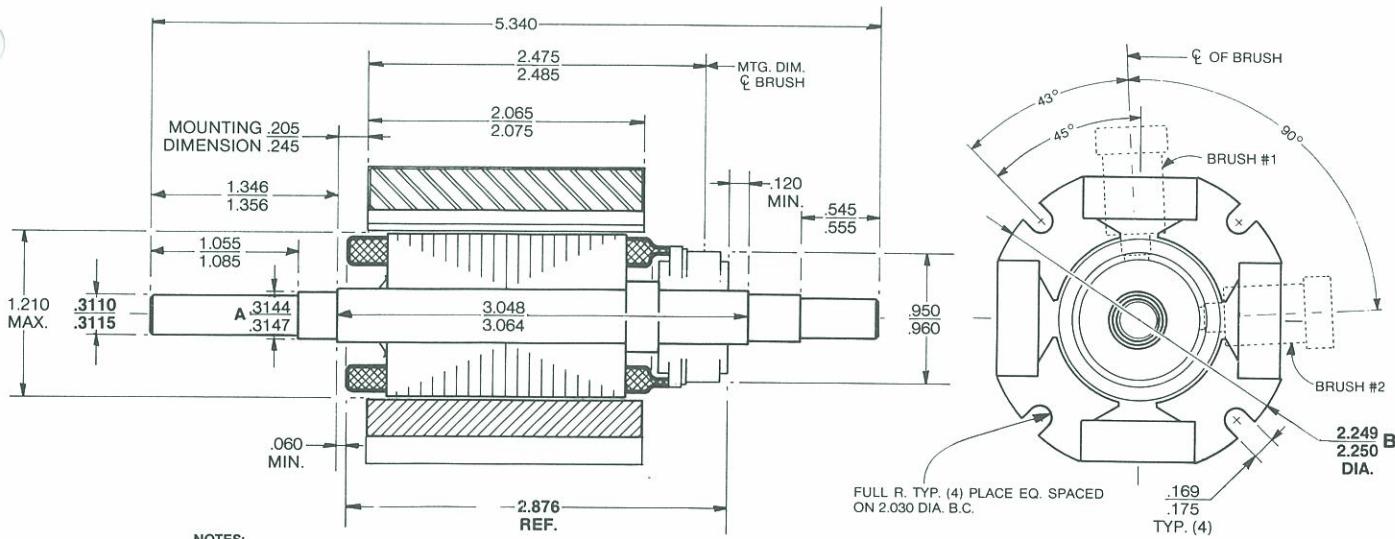
### SIZE CONSTANTS

	Value	Units	
Peak Torque Rating - $T_p$	50	OZ. IN.	
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	62	WATTS	
Motor Constant - $K_m$	6.35	$\text{OZ.IN./}\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	177	RAD/S	
Electrical Time Constant - $\tau_e$	0.80	MS	
Static Friction (Max.) - $T_f$	3.0	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_1$	0.28 0.003	OZ. IN. PER RAD/S OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	5.0	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	7	PERCENT	
Ripple Frequency - (Fundamental)	21	CYCLES/REV.	
Number of Poles	4		
Rotor Inertia - $J_m$	0.0022	OZ.IN.S <sup>2</sup>	
Motor Weight	16	OZ.	

### WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	14.2	23.0					
Peak Current - $I_p$	AMPERES	Rated	4.38	2.74					
Torque Sensitivity - $K_t$	OZ.IN./AMP	$\pm 10\%$	11.4	18.2					
Back EMF Constant - $K_b$	V PER RAD/S	$\pm 10\%$	0.080	0.129					
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	3.25	8.40					
Inductance - $L_m$	mH	$\pm 30\%$	2.6	6.8					



## SIZE CONSTANTS

	Value	Units	
Peak Torque Rating - $T_p$	100	OZ. IN.	
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	102	WATTS	
Motor Constant - $K_m$	9.9	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	143	RAD/S	
Electrical Time Constant - $\tau_e$	1.06	MS	
Static Friction (Max.) - $T_f$	6.0	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_\infty$	0.70 0.006	OZ. IN. PER RAD/S OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	3.5	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	7	PERCENT	
Ripple Frequency - (Fundamental)	21	CYCLES/REV.	
Number of Poles	4		
Rotor Inertia - $J_m$	0.0032	OZ.IN.S <sup>2</sup>	
Motor Weight	30	OZ.	

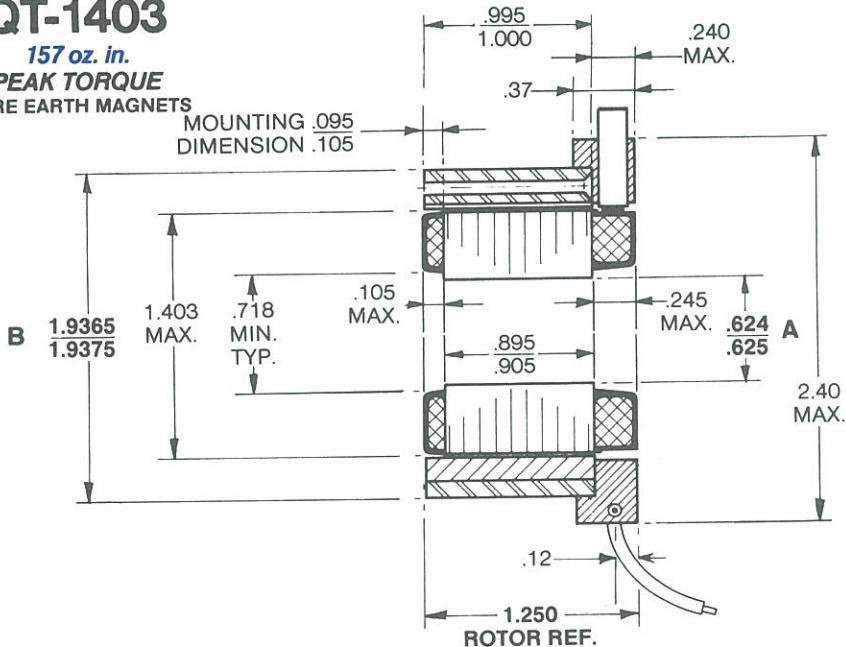
## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	22.3	14.0					
Peak Current - $I_p$	AMPERES	Rated	4.55	7.00					
Torque Sensitivity - $K_t$	OZ.IN./AMP	±10%	22.0	14.3					
Back EMF Constant - $K_B$	V PER RAD/S	±10%	0.155	0.101					
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	±12.5%	4.90	2.00					
Inductance - $L_m$	mH	±30%	5.2	2.2					

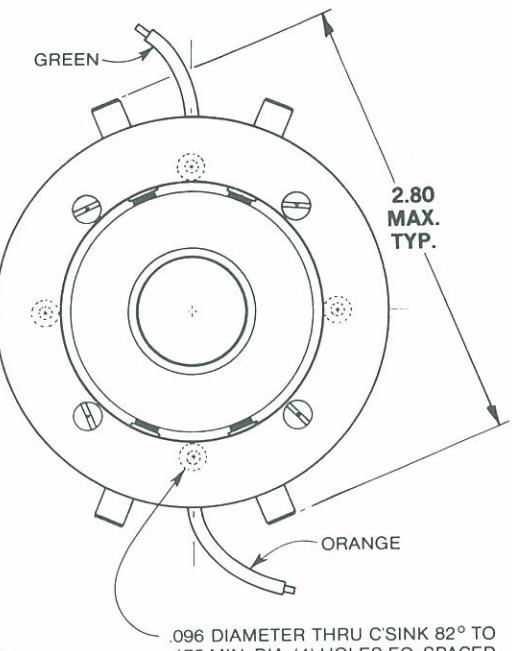
# QT-1403

**157 oz. in.**  
**PEAK TORQUE**  
RARE EARTH MAGNETS



NOTES:

1. — MOTOR SUPPLIED AS THREE SEPARATE COMPONENTS: ROTOR, STATOR, AND BRUSH RING.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.W. WHEN VIEWED FROM BRUSH RING SIDE.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.



.096 DIAMETER THRU C'SINK 82° TO .175 MIN. DIA. (4) HOLES EQ. SPACED AS SHOWN ON 1.727 DIA. B.C.

LEADS:

#24 AWG TYPE "E-E" TEFLON COATED PER-MIL-W-16878 12" MIN. LENGTH.

## SIZE CONSTANTS

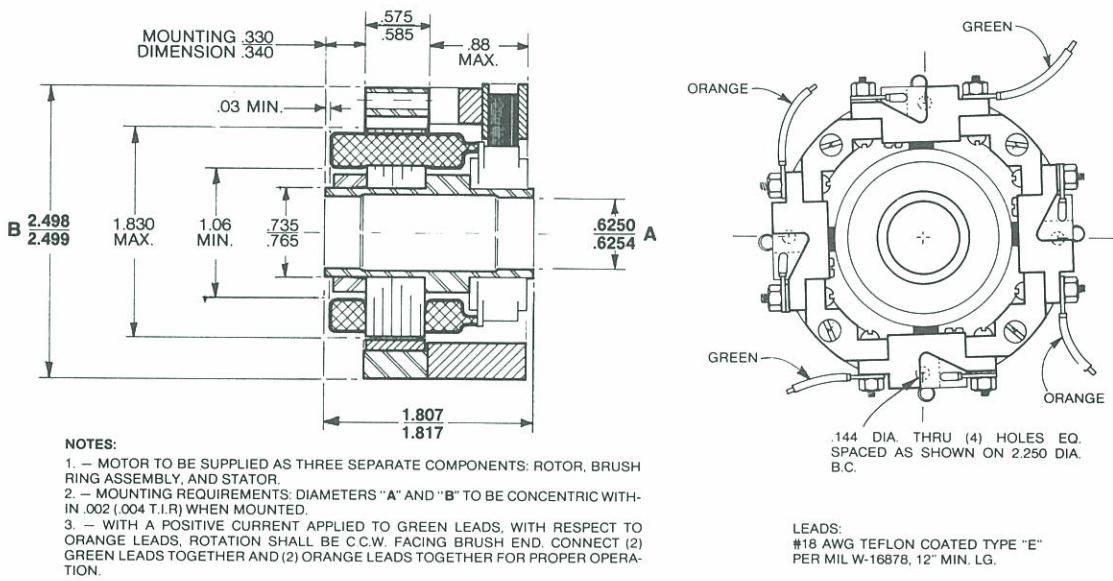
### Value      Units

Peak Torque Rating - $T_p$	157	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	347	WATTS	
Motor Constant - $K_m$	8.42	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	313	RAD/S	
Electrical Time Constant - $\tau_e$	0.277	MS	
Static Friction (Max.) - $T_f$	3.5	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.501	OZ. IN. PER RAD/S
	Infinite Impedance - $F_1$	0.020	OZ. IN. PER RAD/S
Maximum Winding Temperature		155	°C
Temperature Rise per Watt - $TPR$	10	°C/WATT	
Ripple Torque (Average to Peak) - $T_R$	7	PERCENT	
Ripple Frequency - (Fundamental)	31	CYCLES/REV.	
Number of Poles	8		
Rotor Inertia - $J_m$	$3.73 \times 10^{-3}$	OZ.IN.S <sup>2</sup>	
Motor Weight	12	OZ.	

## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	35.4	28.1					
Peak Current - $I_p$	AMPERES	Rated	9.80	12.3					
Torque Sensitivity - $K_t$	OZ.IN./AMP.	±10%	16.0	12.8					
Back EMF Constant - $K_b$	V per RAD/S	±10%	0.113	0.090					
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	±12.5%	3.61	2.29					
Inductance - $L_m$	mH	±30%	1.0	0.64					



## SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>	
Peak Torque Rating - $T_p$	54	OZ. IN.	
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	140	WATTS	
Motor Constant - $K_m$	4.56	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	368	RAD/S	
Electrical Time Constant - $\tau_e$	0.60	MS	
Static Friction (Max.) - $T_f$	5.5	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	0.147 0.003	OZ. IN. PER RAD/S OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	8	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT	
Ripple Frequency - (Fundamental)	25	CYCLES/REV.	
Number of Poles	4		
Rotor Inertia - $J_m$	0.008	OZ.IN.S <sup>2</sup>	
Motor Weight	17	OZ.	

## WINDING CONSTANTS

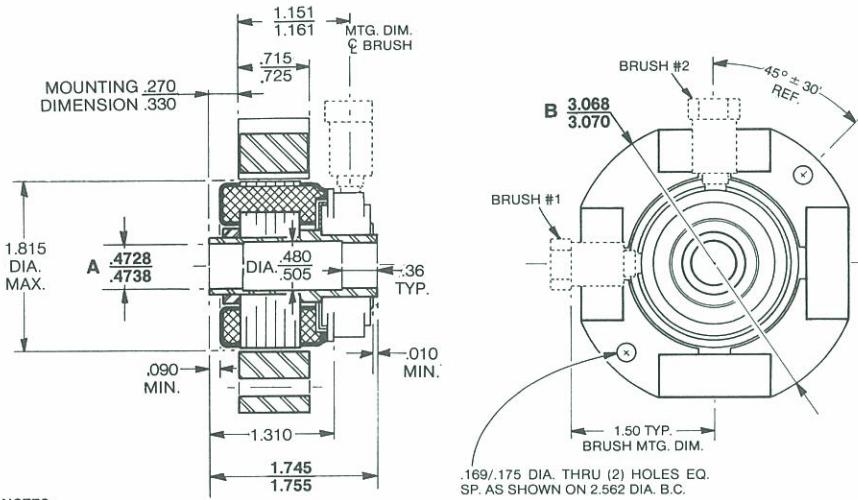
## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	14.0	28.0					
Peak Current - $I_p$	AMPERES	Rated	10.0	5.0					
Torque Sensitivity - $K_t$	OZ.IN./AMP	$\pm 10\%$	5.40	10.8					
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.038	0.076					
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	1.40	5.60					
Inductance - $L_m$	mH	$\pm 30\%$	0.84	3.4					

# T-1806

100 oz. in.

PEAK TORQUE



NOTES:

1. — MOTOR SUPPLIED AS TWO SEPARATE COMPONENTS: ROTOR, STATOR WITH KEEPER. CAUTION: DO NOT REMOVE KEEPER UNLESS ROTOR IS IN PLACE.
2. — BRUSHES AND HOLDERS ARE CUSTOMER SUPPLIED.
3. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .004 (.008 T.I.R.) WHEN MOUNTED.
4. — WITH POSITIVE CURRENT APPLIED TO BRUSH #1, WITH RESPECT TO BRUSH #2, ROTATION SHALL BE C.W. WHEN VIEWED FROM BRUSH SIDE.

## SIZE CONSTANTS

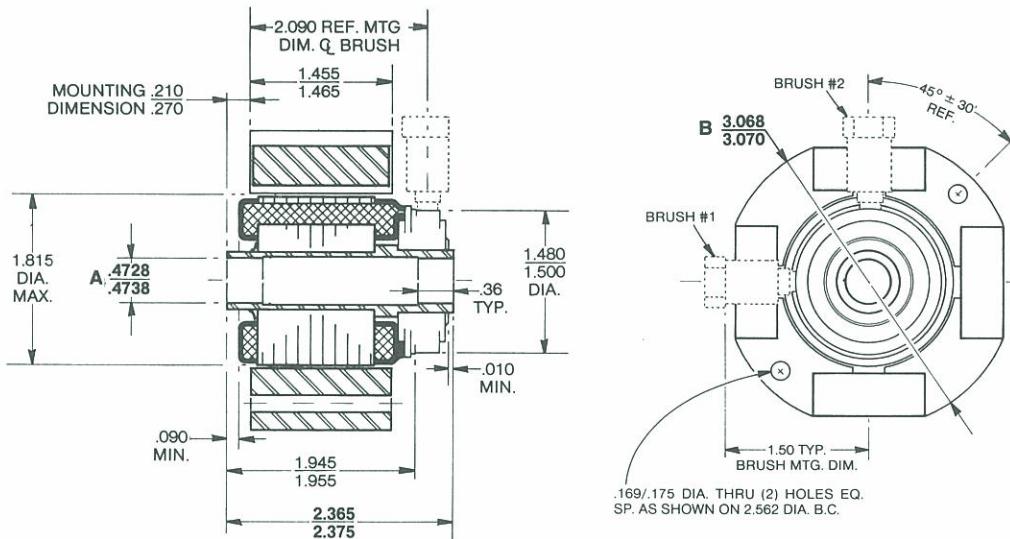
### Value      Units

Peak Torque Rating - $T_p$	100	OZ. IN.
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	95	WATTS
Motor Constant - $K_M$	10.3	OZ.IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	130	RAD/S
Electrical Time Constant - $\tau_E$	1.3	MS
Static Friction (Max.) - $T_F$	3	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	0.75      0.012
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	4.3	°C/WATT
Ripple Torque (Average to Peak) - $T_R$	5	PERCENT
Ripple Frequency - (Fundamental)	25	CYCLES/REV.
Number of Poles	4	
Rotor Inertia - $J_M$	0.010	OZ.IN.S <sup>2</sup>
Motor Weight	25	OZ.

## WINDING CONSTANTS

### Winding Designation

UNITS	TOLERANCES	A	B	C	D	E	F	G
VOLTS	Nom.	9.6	100.0	14.7	46.6	16.8	24.3	37.0
AMPERES	Rated	10.7	0.85	6.7	2.1	6.0	3.37	2.66
OZ.IN./AMP	± 10%	9.3	118.0	14.9	47.2	16.7	29.7	37.2
V PER RAD/S	± 10%	0.066	0.83	0.105	0.333	0.127	0.210	0.263
OHMS	± 12.5%	0.90	118.0	2.2	22.2	3.0	7.2	13.9
mH	± 30%	1.1	176.0	2.8	28.0	3.6	11.2	17.5



NOTES:

1. — MOTOR SUPPLIED AS TWO SEPARATE COMPONENTS; ROTOR, STATOR WITH (2) KEEPERS. **CAUTION:** DO NOT REMOVE KEEPERS UNLESS ROTOR IS IN PLACE.
2. — BRUSHES AND HOLDERS ARE CUSTOMER SUPPLIED.
3. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .004 (.008 T.I.R.) WHEN MOUNTED.
4. — WITH A POSITIVE CURRENT APPLIED TO BRUSH #1, ROTATION SHALL BE C.W. WHEN VIEWED FROM BRUSH SIDE.

### SIZE CONSTANTS

	Value	Units	
Peak Torque Rating - $T_p$	140	OZ. IN.	
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	64	WATTS	
Motor Constant - $K_m$	17.5	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	65	RAD/S	
Electrical Time Constant - $\tau_e$	1.80	MS	
Static Friction (Max.) - $T_f$	6	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	2.16      0.022	OZ. IN. PER RAD/S      OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	4	°C/WATT	
Ripple Torque (Average to Peak) - $T_R$	5	PERCENT	
Ripple Frequency - (Fundamental)	25	CYCLES/REV.	
Number of Poles	4		
Rotor Inertia - $J_m$	0.015	OZ.IN.S <sup>2</sup>	
Motor Weight	45	OZ.	

### WINDING CONSTANTS

### Winding Designation

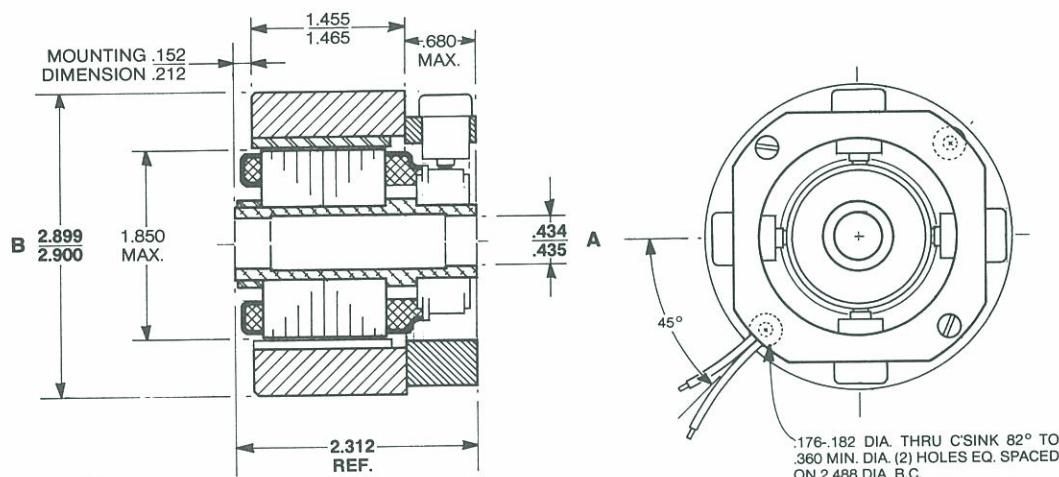
	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	8.00	12.7	25.4				
Peak Current - $I_p$	AMPERES	Rated	8.00	5.09	2.55				
Torque Sensitivity - $K_t$	OZ.IN./AMP	±10%	17.5	27.5	55.0				
Back EMF Constant - $K_b$	V PER RAD/S	±10%	0.123	0.193	0.387				
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	±12.5%	1.00	2.49	9.98				
Inductance - $L_m$	mH	±30%	1.8	4.4	18				

# QT-1811

200 oz. in.

PEAK TORQUE

RARE EARTH MAGNETS



**NOTES:**

1. — MOTOR SUPPLIED AS THREE SEPARATE COMPONENTS: ROTOR, STATOR, & BRUSH RING.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. WHEN VIEWED FROM BRUSH RING SIDE.

**LEADS:**  
#22 AWG TYPE "E" TEFILON COATED  
PER MIL W-16878, 8" MIN. LENGTH.

## SIZE CONSTANTS

### Value

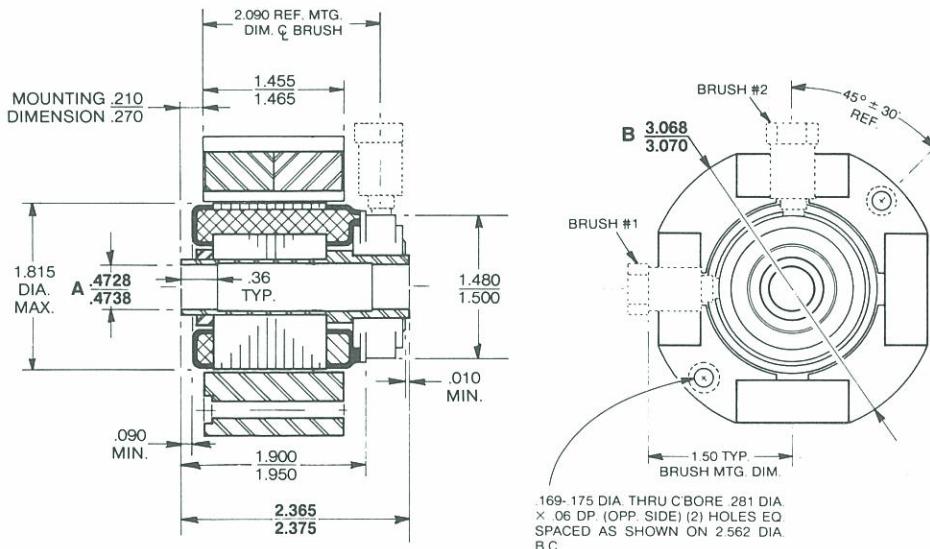
### Units

Peak Torque Rating - $T_p$	200	OZ. IN.
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	133	WATTS
Motor Constant - $K_m$	17.4	OZ.IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	94.1	RAD/S
Electrical Time Constant - $\tau_e$	1.45	MS
Static Friction (Max.) - $T_f$	8.0	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_\infty$	2.13      0.020
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	4	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT
Ripple Frequency - (Fundamental)	25	CYCLES/REV.
Number of Poles	4	
Rotor Inertia - $J_m$	0.015	OZ.IN. $\text{s}^2$
Motor Weight	48	OZ.

## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	12.1						
Peak Current - $I_p$	AMPERES	Rated	11.0						
Torque Sensitivity - $K_t$	OZ.IN./AMP	$\pm 10\%$	18.2						
Back EMF Constant - $K_b$	V PER RAD/S	$\pm 10\%$	0.129						
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	1.10						
Inductance - $L_m$	mH	$\pm 30\%$	1.6						



NOTES:

- 1 - MOTOR SUPPLIED AS TWO SEPARATE COMPONENTS: ROTOR AND STATOR WITH (2) KEEPERS. CAUTION: DO NOT REMOVE KEEPERS UNLESS ROTOR IS IN PLACE.
- 2 - BRUSHES AND HOLDERS ARE CUSTOMER SUPPLIED
- 3 - MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .004 (.008 T.I.R.) WHEN MOUNTED.
- 4 - WITH A POSITIVE CURRENT APPLIED TO BRUSH #1, ROTATION SHALL BE C.W. WHEN VIEWED FROM BRUSH SIDE.

## SIZE CONSTANTS

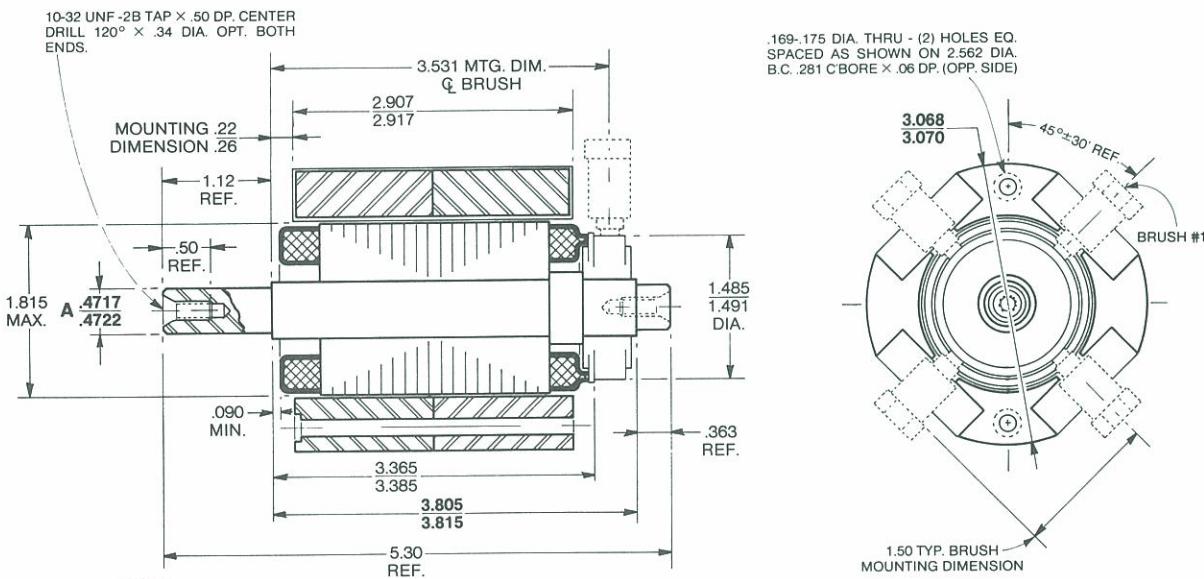
	Value	Units	
Peak Torque Rating - $T_p$	200	OZ. IN.	
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	120	WATTS	
Motor Constant - $K_m$	18.3	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	85	RAD/S	
Electrical Time Constant - $\tau_e$	2.2	MS	
Static Friction (Max.) - $F_f$	5	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_\infty$	2.3      0.024	OZ. IN. PER RAD/S      OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	4	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT	
Ripple Frequency - (Fundamental)	25	CYCLES/REV.	
Number of Poles	4		
Rotor Inertia - $J_m$	0.015	OZ.INS <sup>2</sup>	
Motor Weight	45	OZ.	

## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	12.3	81.7	14.5	32.1	22.0	7.88	
Peak Current - $I_p$	AMPERES	Rated	10.7	1.34	8.5	3.38	5.40	17.9	
Torque Sensitivity - $K_t$	OZ.IN./AMP	±10%	18.6	149.0	23.5	59.4	36.8	11.2	
Back EMF Constant - $K_b$	V PER RAD/S	±10%	0.131	1.05	0.166	0.42	0.262	0.079	
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	±12.5%	1.15	61.0	1.70	9.5	4.08	0.44	
Inductance - $L_m$	mH	±30%	2.2	141.0	3.6	22.4	8.8	0.79	

**T-1834**  
400 oz. in.  
**PEAK TORQUE**



**NOTES:**

1. — MOTOR SHIPPED WITH ARMATURE INSIDE STATOR AND MYLAR IN AIR GAP. CAUTION: DO NOT REMOVE ARMATURE FROM STATOR. REMOVE MYLAR AFTER ARMATURE AND STATOR ARE SECURELY IN PLACE.
2. — BRUSHES AND HOLDERS ARE CUSTOMER SUPPLIED.
3. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .004 (.008 T.I.R.) WHEN MOUNTED.
4. — WITH A POSITIVE CURRENT APPLIED TO BRUSH #1, ROTATION SHALL BE C.W. WHEN VIEWED FROM BRUSH SIDE.

### SIZE CONSTANTS

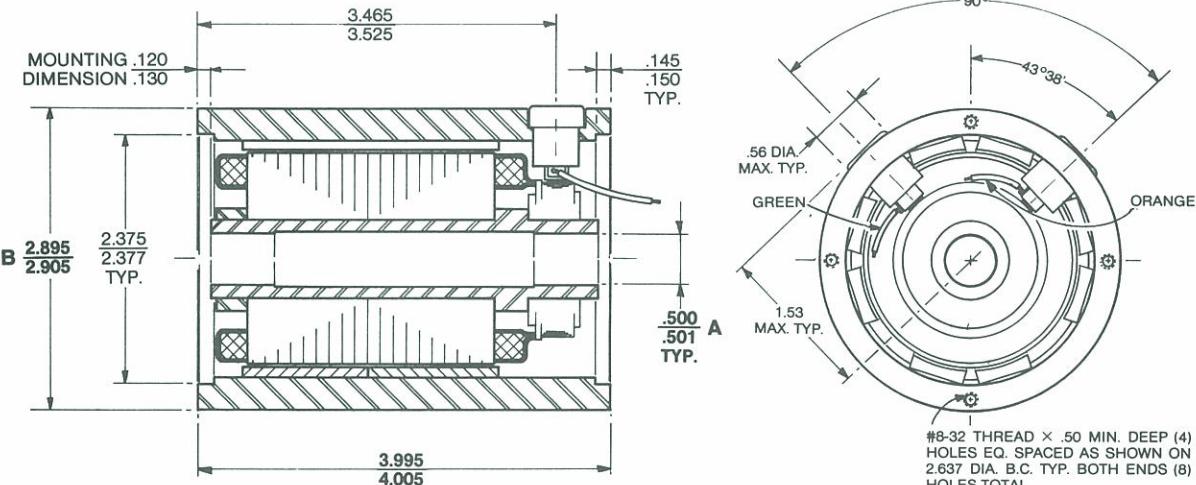
**Value      Units**

Peak Torque Rating - $T_p$	400	OZ. IN.				
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	180	WATTS				
Motor Constant - $K_m$	29.7	OZ.IN./√WATT				
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	62	RAD/S				
Electrical Time Constant - $\tau_e$	3.2	MS				
Static Friction (Max.) - $T_f$	8	OZ. IN.				
Viscous Damping Coefficients	<table border="0"> <tr> <td>Zero Impedance - <math>F_0</math></td> <td>6.4</td> </tr> <tr> <td>Infinite Impedance - <math>F_i</math></td> <td>0.048</td> </tr> </table>	Zero Impedance - $F_0$	6.4	Infinite Impedance - $F_i$	0.048	OZ. IN. PER RAD/S OZ. IN. PER RAD/S
Zero Impedance - $F_0$	6.4					
Infinite Impedance - $F_i$	0.048					
Maximum Winding Temperature	155	°C				
Temperature Rise per Watt - TPR	2.5	°C/WATT				
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT				
Ripple Frequency - (Fundamental)	25	CYCLES/REV.				
Number of Poles	4					
Rotor Inertia - $J_m$	0.028	OZ.IN.S <sup>2</sup>				
Motor Weight	80	OZ.				

### WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	21	16.7					
Peak Current - $I_p$	AMPERES	Rated	8.4	11.2					
Torque Sensitivity - $K_t$	OZ.IN./AMP	±10%	47.6	35.7					
Back EMF Constant - $K_b$	V PER RAD/S	±10%	0.336	0.252					
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	±12.5%	2.5	1.49					
Inductance - $L_m$	mH	±30%	8.0	4.5					



**NOTES:**

- MOTOR TO BE SUPPLIED AS TWO SEPARATE COMPONENTS: ROTOR AND STATOR.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
- WITH A POSITIVE CURRENT APPLIED TO GREEN LEAD ROTATION SHALL BE C.C.W. WHEN VIEWED FROM LEAD SIDE.

**LEADS:**  
#26 AWG TYPE "E" TEFLON COATED  
PER MIL-W-16878 12" MIN. LENGTH.

## SIZE CONSTANTS

**Value      Units**

Peak Torque Rating - $T_p$	329	oz. in.
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	108	WATTS
Motor Constant - $K_M$	31.7	oz.in./√ WATT
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	46.4	RAD/S
Electrical Time Constant - $\tau_E$	2.73	MS
Static Friction (Max.) - $T_f$	15	oz. in.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_\infty$	7.09      0.030
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	2.5	°C/WATT
Ripple Torque (Average to Peak) - $T_R$	6	PERCENT
Ripple Frequency - (Fundamental)	33	CYCLES/REV.
Number of Poles	4	
Rotor Inertia - $J_M$	0.045	oz.in.s <sup>2</sup>
Motor Weight	50	oz.

## WINDING CONSTANTS

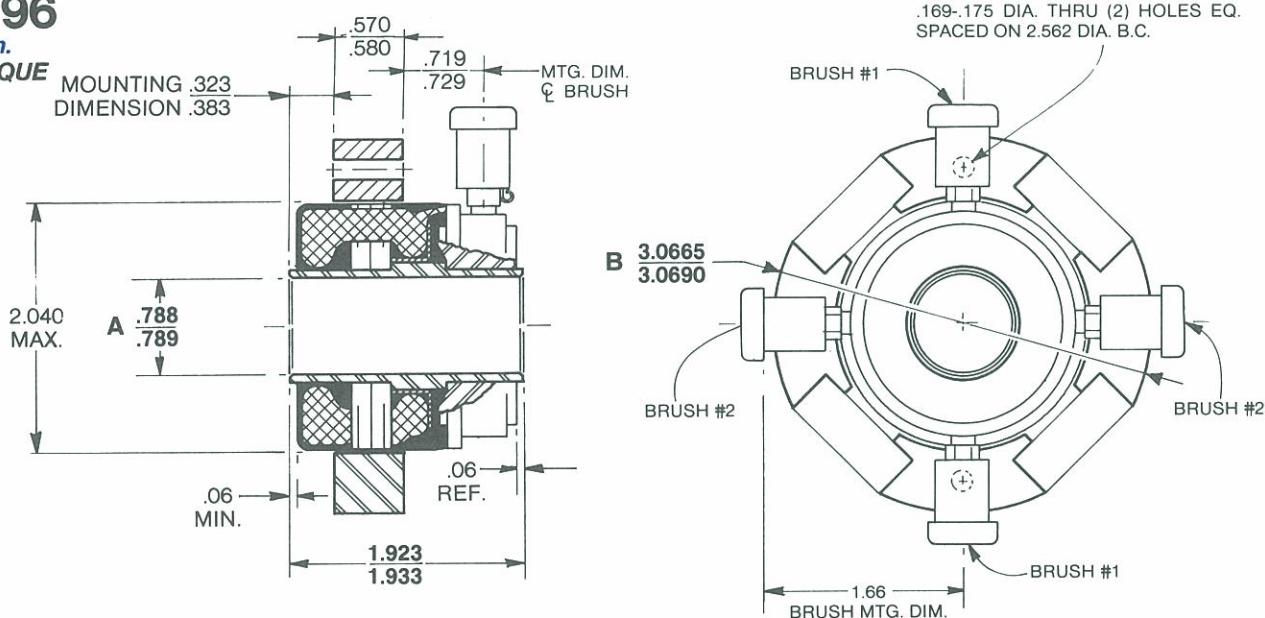
**Winding Designation**

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	30.8						
Peak Current - $I_p$	AMPERES	Rated	3.50						
Torque Sensitivity - $K_T$	OZ.IN./AMP	± 10%	94.0						
Back EMF Constant - $K_B$	V PER RAD/S	± 10%	0.664						
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	± 12.5%	8.80						
Inductance - $L_m$	mH	± 30%	24						

# NT-2196

80 oz. in.

PEAK TORQUE



**NOTES:**

1. — MOTOR SUPPLIED AS SIX SEPARATE COMPONENTS: ROTOR, STATOR WITH KEEPER AND (4) BRUSH HOLDER ASSEMBLIES. **CAUTION:** DO NOT REMOVE KEEPER UNLESS ROTOR IS FULLY IN PLACE.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .004(.008 T.I.R.) WHEN MOUNTED.
3. — WITH A POSITIVE CURRENT APPLIED TO BRUSH #1, ROTATION SHALL BE C.C.W. WHEN VIEWED FROM BRUSH SIDE.

SPECIAL MAGNET MATERIAL  
FOR RESISTANCE TO TORQUE  
SENSITIVITY DEGRADATION AT  
HIGH POWER INPUT  
LEVELS

## SIZE CONSTANTS

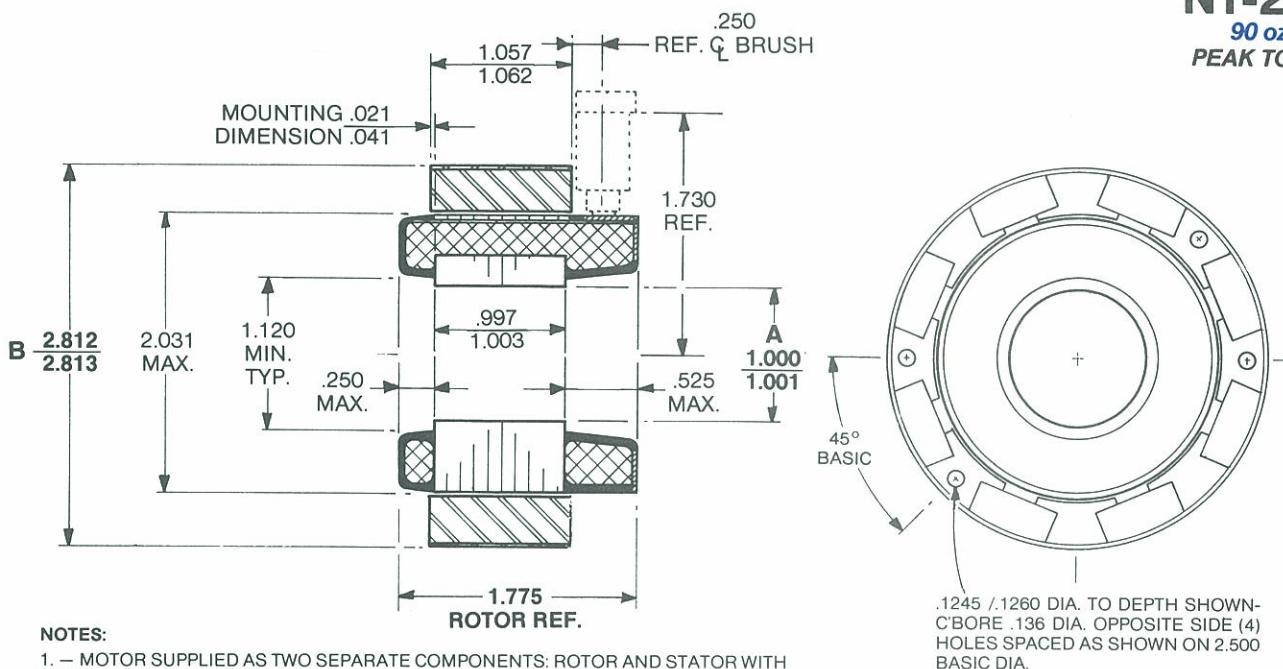
**Value      Units**

Peak Torque Rating - $T_p$	80	OZ. IN.						
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	292	WATTS						
Motor Constant - $K_m$	4.7	OZ.IN./ $\sqrt{\text{WATT}}$						
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	520	RAD/S						
Electrical Time Constant - $\tau_e$	1.2	MS						
Static Friction (Max.) - $T_f$	4.0	OZ. IN.						
Viscous Damping Coefficients	<table border="0"> <tr> <td>Zero Impedance - <math>F_0</math></td> <td>0.15</td> <td>OZ. IN. PER RAD/S</td> </tr> <tr> <td>Infinite Impedance - <math>F_i</math></td> <td>0.0024</td> <td>OZ. IN. PER RAD/S</td> </tr> </table>	Zero Impedance - $F_0$	0.15	OZ. IN. PER RAD/S	Infinite Impedance - $F_i$	0.0024	OZ. IN. PER RAD/S	
Zero Impedance - $F_0$	0.15	OZ. IN. PER RAD/S						
Infinite Impedance - $F_i$	0.0024	OZ. IN. PER RAD/S						
Maximum Winding Temperature	155	°C						
Temperature Rise per Watt - TPR	3.5	°C/WATT						
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT						
Ripple Frequency - (Fundamental)	31	CYCLES/REV.						
Number of Poles	4							
Rotor Inertia - $J_m$	0.01	OZ.IN.S <sup>2</sup>						
Motor Weight	24	OZ.						

## WINDING CONSTANTS

*Winding Designation*

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	14.6						
Peak Current - $I_p$	AMPERES	Rated	20.0						
Torque Sensitivity - $K_t$	OZ.IN./AMP	$\pm 10\%$	4.0						
Back EMF Constant - $K_b$	V PER RAD/S	$\pm 10\%$	0.028						
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	0.73						
Inductance - $L_m$	mH	$\pm 30\%$	0.9						



## SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>	
Peak Torque Rating - $T_p$	90	OZ. IN.	
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	56.5	WATTS	
Motor Constant - $K_m$	11.9	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	89.3	RAD/S	
Electrical Time Constant - $\tau_E$	1.64	MS	
Static Friction (Max.) - $T_f$	7.5	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	1.00	OZ. IN. PER RAD/S
	Infinite Impedance - $F_\infty$	0.040	OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	5.4	°C/WATT	
Ripple Torque (Average to Peak) - $T_R$	5	PERCENT	
Ripple Frequency - (Fundamental)	33	CYCLES/REV.	
Number of Poles	8		
Rotor Inertia - $J_M$	0.019	OZ.IN.S <sup>2</sup>	
Motor Weight	27	OZ.	

## WINDING CONSTANTS

### Winding Designation

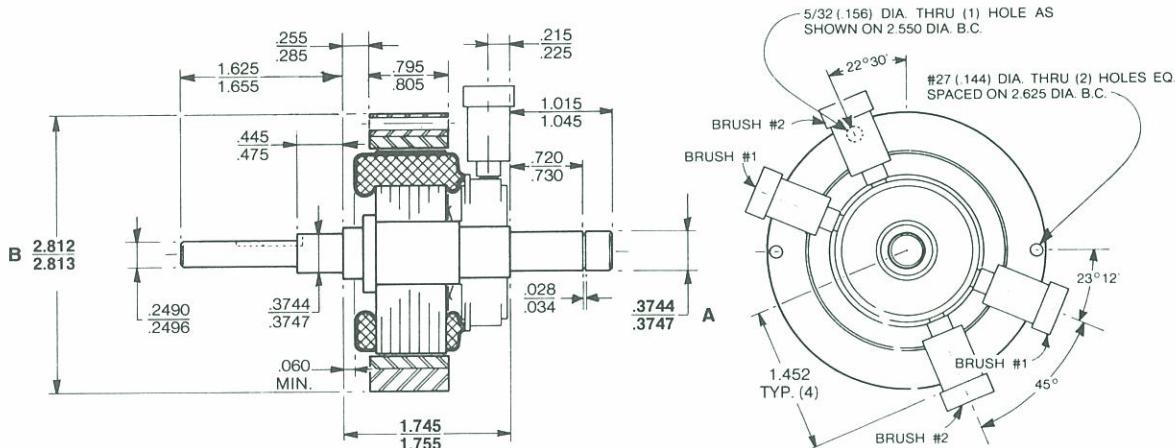
	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	30.5						
Peak Current - $I_p$	AMPERES	Rated	1.85						
Torque Sensitivity - $K_t$	OZ.IN./AMP	± 10%	48.4						
Back EMF Constant - $K_b$	V PER RAD/S	± 10%	0.342						
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	± 12.5%	16.5						
Inductance - $L_m$	mH	± 30%	27						

# QT-2106

100 oz. in.

PEAK TORQUE

RARE EARTH MAGNETS



**NOTES:**

1. - MOTOR SUPPLIED AS SIX SEPARATE COMPONENTS: ROTOR, STATOR, & (4) BRUSH HOLDER ASSEMBLIES.
2. - MOUNTING REQUIREMENTS: DIAMETERS 'A' AND 'B' TO BE CONCENTRIC WITHIN .003 (.006 T.I.R.) WHEN MOUNTED.
3. - WITH POSITIVE CURRENT APPLIED TO #1 BRUSHES WITH RESPECT TO #2 BRUSHES, ROTATION SHALL BE C.C.W. WHEN VIEWED FROM BRUSH SIDE.

## SIZE CONSTANTS

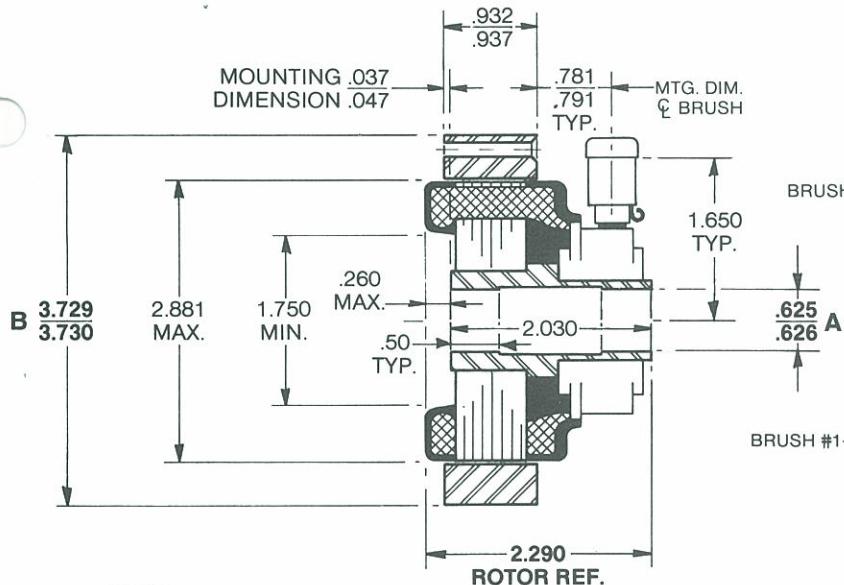
### Value      Units

Peak Torque Rating - $T_p$	100	OZ. IN.	
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	55	WATTS	
Motor Constant - $K_M$	13.5	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	78	RAD/S	
Electrical Time Constant - $\tau_e$	0.68	MS	
Static Friction (Max.) - $F_f$	7	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	1.28	OZ. IN. PER RAD/S
	Infinite Impedance - $F_\infty$	0.058	OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	5	°C/WATT	
Ripple Torque (Average to Peak) - $T_R$	5	PERCENT	
Ripple Frequency - (Fundamental)	33	CYCLES/REV.	
Number of Poles	8		
Rotor Inertia - $J_M$	0.011	OZ.IN.S <sup>2</sup>	
Motor Weight	25	OZ.	

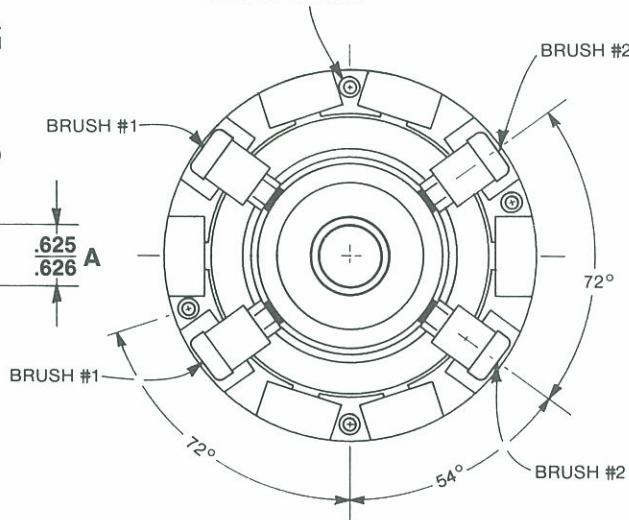
## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	19.7	9.84					
Peak Current - $I_p$	AMPERES	Rated	2.81	5.62					
Torque Sensitivity - $K_T$	OZ.IN./AMP	$\pm 10\%$	35.6	17.8					
Back EMF Constant - $K_B$	V PER RAD/S	$\pm 10\%$	0.251	0.126					
DC Resistance ( $25^\circ\text{C}$ ) - $R_M$	OHMS	$\pm 12.5\%$	7.00	1.75					
Inductance - $L_M$	mH	$\pm 30\%$	4.8	1.2					



.125 DIA. THRU C'SINK 82° TO .230  
MIN. DIA. (4) HOLES SPACED AS  
SHOWN ON 3.468 DIA. B.C.



## NOTES:

1. — MOTOR TO BE SUPPLIED AS SIX SEPARATE COMPONENTS: STATOR WITH KEEPER, ROTOR ASSEMBLY, AND (4) BRUSH HOLDER ASSEMBLIES WITH BRUSHES. CAUTION: DO NOT REMOVE KEEPER UNLESS ROTOR IS FULLY IN PLACE.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002(.004 T.I.R.) WHEN MOUNTED.
3. — WITH A POSITIVE CURRENT APPLIED TO #1 BRUSHES, ROTATION SHALL BE C.C.W. WHEN FACING BRUSH END.

## SIZE CONSTANTS

## Value      Units

Peak Torque Rating - $T_p$	1.2	LB. FT.	
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	79	WATTS	
Motor Constant - $K_m$	0.135	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	48	RAD/S	
Electrical Time Constant - $\tau_e$	2.1	MS	
Static Friction (Max.) - $T_f$	0.052	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.025	LB. FT. PER RAD/S
	Infinite Impedance - $F_i$	$1.0 \times 10^{-3}$	LB. FT. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	4.3	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT	
Ripple Frequency - (Fundamental)	41	CYCLES/REV.	
Number of Poles	10		
Rotor Inertia - $J_m$	$3.9 \times 10^{-4}$	LB.FT.S <sup>2</sup>	
Motor Weight	3.1	LB.	

## WINDING CONSTANTS

## Winding Designation

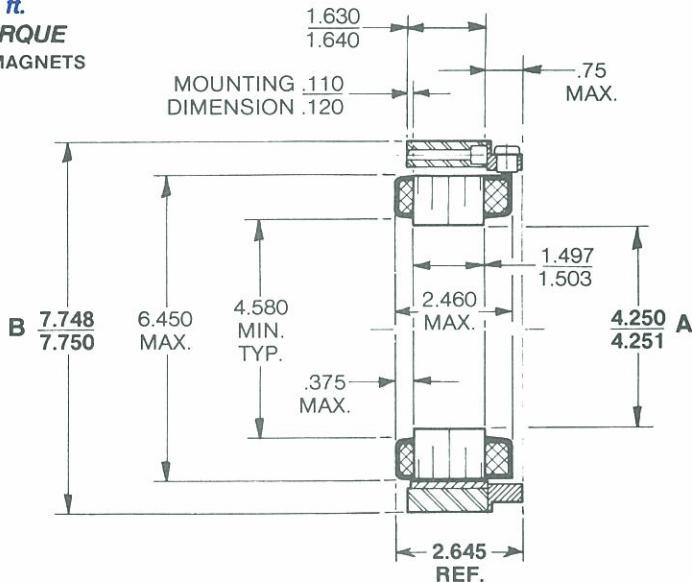
	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	12.0	20					
Peak Current - $I_p$	AMPERES	Rated	6.3	4.0					
Torque Sensitivity - $K_t$	LB.FT./AMP	$\pm 10\%$	0.19	0.30					
Back EMF Constant - $K_b$	V PER RAD/S	$\pm 10\%$	0.26	0.41					
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	1.9	5.0					
Inductance - $L_m$	mH	$\pm 30\%$	4.1	10.4					

# QT-6404

26 lb. ft.

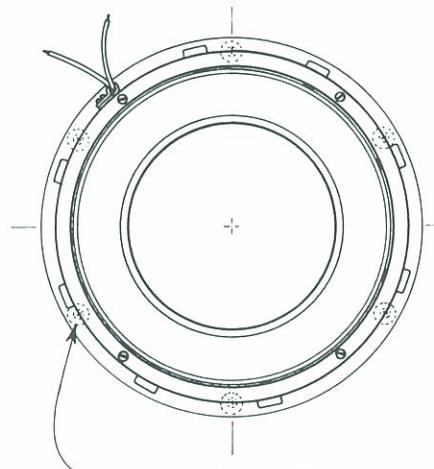
PEAK TORQUE

RARE EARTH MAGNETS



NOTES:

1. — MOTOR SUPPLIED AS THREE SEPARATE COMPONENTS: ROTOR ASSEMBLY, BRUSH RING ASSEMBLY, AND STATOR ASSEMBLY.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH A POSITIVE CURRENT APPLIED TO GREEN LEAD WITH RESPECT TO ORANGE LEAD ROTATION WILL BE C.C.W. WHEN VIEWED FROM THE BRUSH RING SIDE.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.



.251 DIA. THRU C'BORE .443 DIA. X  
.315 DEEP (6) HOLES EQ. SPACED ON  
7.250 DIA. B.C.

LEADS:

#16 AWG TEFLON COATED TYPE "E"  
PER MIL W-16878 12" MIN. LENGTH.

## SIZE CONSTANTS

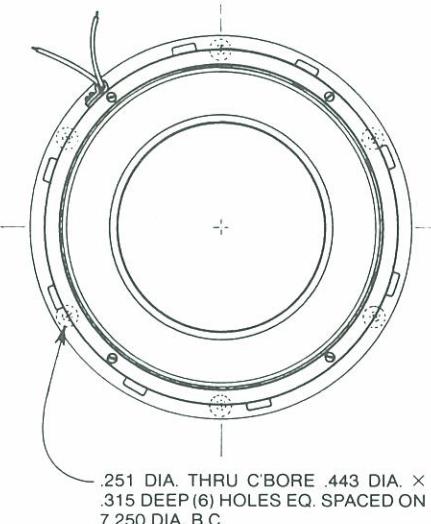
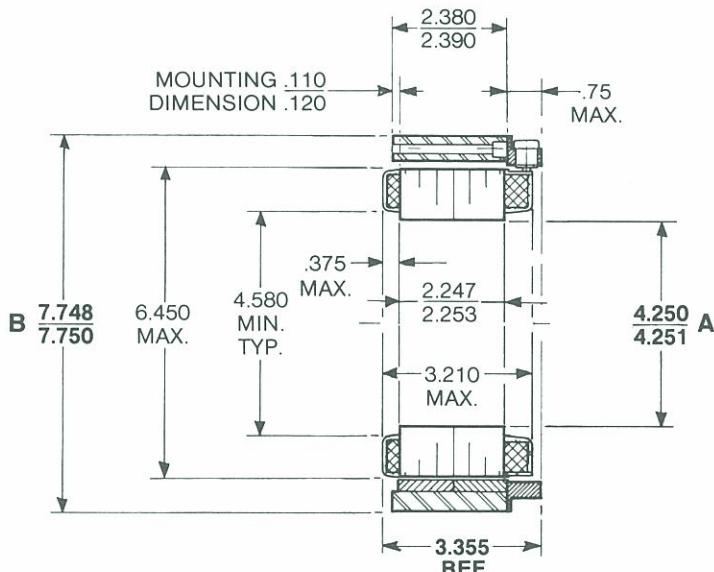
### Value      Units

Peak Torque Rating - $T_p$	26	LB. FT.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	560	WATTS
Motor Constant - $K_m$	1.1	LB.FT./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	15.9	RAD/S
Electrical Time Constant - $\tau_E$	3.9	MS
Static Friction (Max.) - $T_f$	0.50	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$	1.63 LB. FT. PER RAD/S
	Infinite Impedance - $F_i$	0.006 LB. FT. PER RAD/S
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	1.4	°C/WATT
Ripple Torque (Average to Peak) - $T_R$	4	PERCENT
Ripple Frequency - (Fundamental)	91	CYCLES/REV.
Number of Poles	18	
Rotor Inertia - $J_M$	0.013	LB.FT.S <sup>2</sup>
Motor Weight	13.5	LB.

## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	28.0						
Peak Current - $I_p$	AMPERES	Rated	20.0						
Torque Sensitivity - $K_t$	LB.FT./AMP	$\pm 10\%$	1.30						
Back EMF Constant - $K_B$	V per RAD/S	$\pm 10\%$	1.76						
DC Resistance ( $25^\circ\text{C}$ ) - $R_M$	OHMS	$\pm 12.5\%$	1.40						
Inductance - $L_M$	mH	$\pm 30\%$	5.4						



**NOTES:**

1. — MOTOR SUPPLIED AS THREE SEPARATE COMPONENTS: ROTOR ASSEMBLY, BRUSH RING ASSEMBLY, AND STATOR ASSEMBLY.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH A POSITIVE CURRENT APPLIED TO GREEN LEAD WITH RESPECT TO ORANGE LEAD ROTATION WILL BE C.W. WHEN VIEWED FROM THE BRUSH RING SIDE.
4. — TYPICAL BRUSH LIFE > 10<sup>7</sup> REV.

**LEADS:**  
#16 AWG TEFLON COATED TYPE "E"  
PER MIL W-16878 12" MIN. LENGTH.

### SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>
Peak Torque Rating - $T_p$	40	LB. FT.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	819	WATTS
Motor Constant - $K_M$	1.4	LB.FT./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	15	RAD/S
Electrical Time Constant - $\tau_E$	4.3	MS
Static Friction (Max.) - $T_f$	0.75	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	2.66 0.009
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	1.1	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	4	PERCENT
Ripple Frequency - (Fundamental)	91	CYCLES/REV.
Number of Poles	18	
Rotor Inertia - $J_M$	0.0185	LB.FT.S <sup>2</sup>
Motor Weight	19	LB.

### WINDING CONSTANTS

### Winding Designation

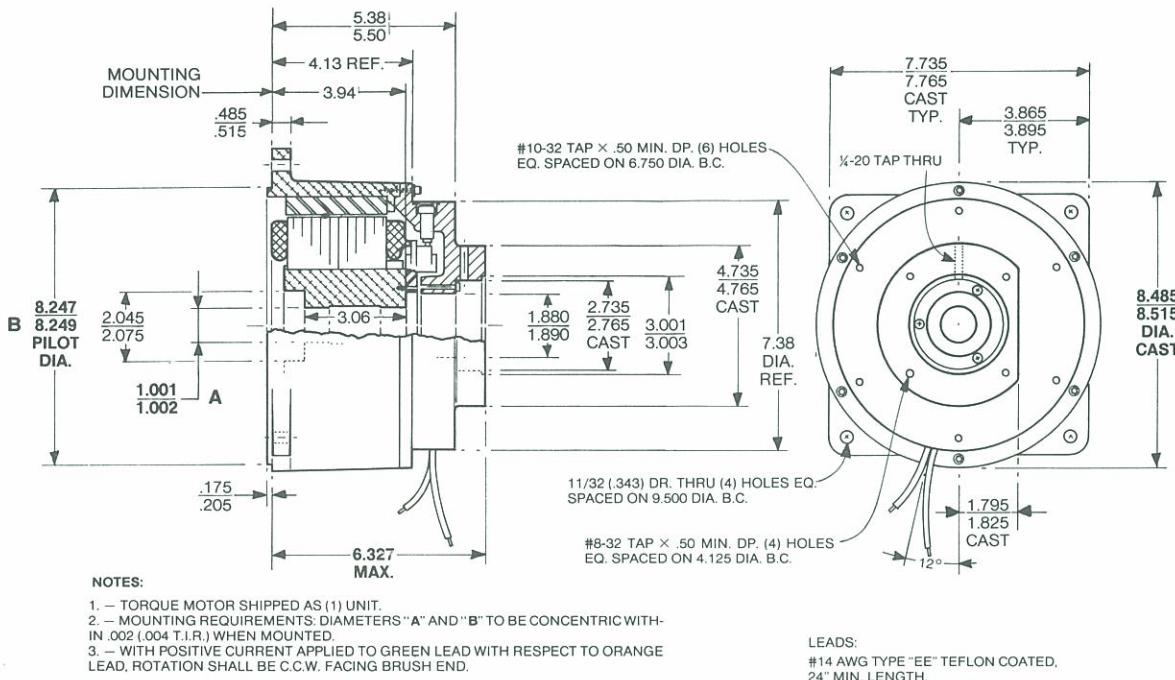
	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	25.6	39.1					
Peak Current - $I_p$	AMPERES	Rated	32.0	20.6					
Torque Sensitivity - $K_T$	LB.FT./AMP.	± 10%	1.25	1.94					
Back EMF Constant - $K_B$	V per RAD/S	± 10%	1.70	2.63					
DC Resistance (25°C) - $R_M$	OHMS	± 12.5%	0.800	1.90					
Inductance - $L_M$	mH	± 30%	3.4	8.2					

# QT-6501

37 lb. ft.

PEAK TORQUE

RARE EARTH MAGNETS



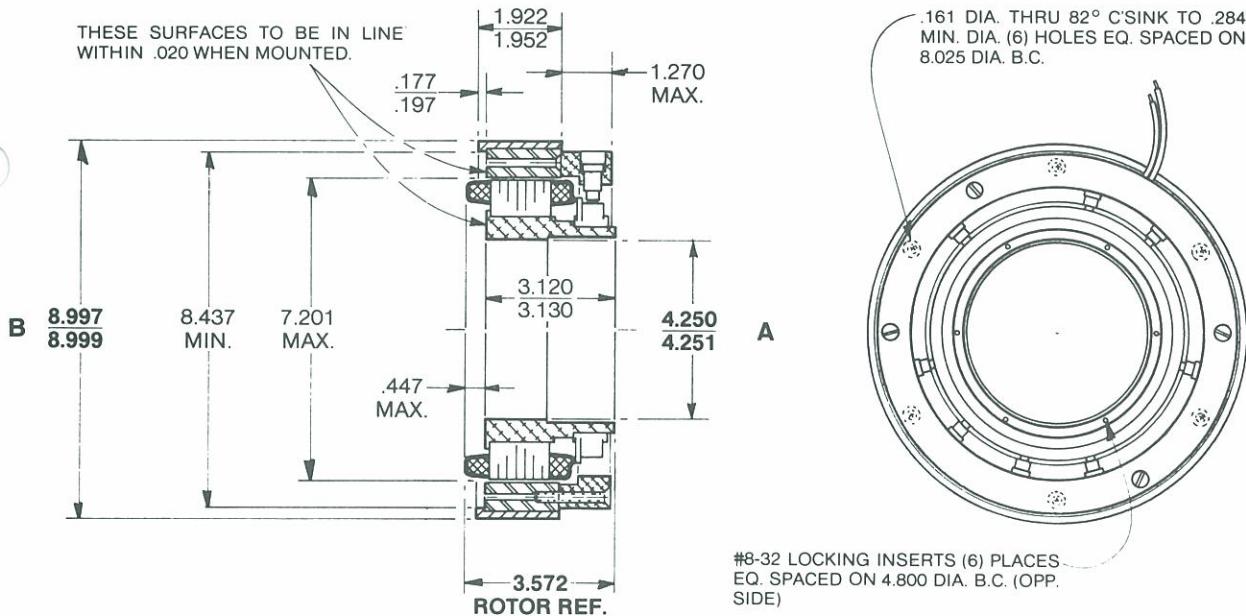
## SIZE CONSTANTS

	Value	Units
Peak Torque Rating - $T_p$	37	LB. FT.
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	960	WATTS
Motor Constant - $K_m$	1.19	$\text{LB.FT./}\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	19	RAD/S
Electrical Time Constant - $\tau_e$	3.3	MS
Static Friction (Max.) - $T_f$	0.75	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ , Infinite Impedance - $F_i$	LB. FT. PER RAD/S
Maximum Winding Temperature	155	$^\circ\text{C}$
Temperature Rise per Watt - $TPR$	1.4	$^\circ\text{C/WATT}$
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT
Ripple Frequency - (Fundamental)	79	CYCLES/REV.
Number of Poles	10	
Rotor Inertia - $J_m$	0.043	$\text{LB.FT.S}^2$
Motor Weight	42	LB.

## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	21.0						
Peak Current - $I_p$	AMPERES	Rated	45.7						
Torque Sensitivity - $K_t$	LB.FT./AMP	$\pm 10\%$	0.81						
Back EMF Constant - $K_b$	V PER RAD/S	$\pm 10\%$	1.10						
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	0.46						
Inductance - $L_m$	mH	$\pm 30\%$	1.5						



**NOTES:**

1. — MOTOR SUPPLIED AS THREE SEPARATE COMPONENTS: ROTOR, STATOR WITH (2) KEEPERS AND BRUSH RING ASSEMBLY. CAUTION: DO NOT REMOVE KEEPERS UNLESS ROTOR IS IN PLACE.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .003(.006 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD, ROTATION SHALL BE C.C.W. WHEN VIEWED FROM THE BRUSH SIDE.

**LEADS:**  
#16 AWG TEFLON INSULATED TYPE  
"EE" PER MIL-W 16878, 12" MIN. LG.

### SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>	
Peak Torque Rating - $T_p$	23.0	LB. FT.	
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	600	WATTS	
Motor Constant - $K_m$	0.94	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	19.2	RAD/S	
Electrical Time Constant - $\tau_e$	3.70	MS	
Static Friction (Max.) - $T_f$	0.6	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	1.20	LB. FT. PER RAD/S
	Infinite Impedance - $F_i$	0.013	LB. FT. PER RAD/S
Maximum Winding Temperature	155	$^\circ\text{C}$	
Temperature Rise per Watt - $TPR$	1.0	$^\circ\text{C}/\text{WATT}$	
Ripple Torque (Average to Peak) - $T_r$	4	PERCENT	
Ripple Frequency - (Fundamental)	97	CYCLES/REV.	
Number of Poles	12		
Rotor Inertia - $J_m$	0.022	LB.FT.S <sup>2</sup>	
Motor Weight	22.5	LB.	

### WINDING CONSTANTS

### Winding Designation

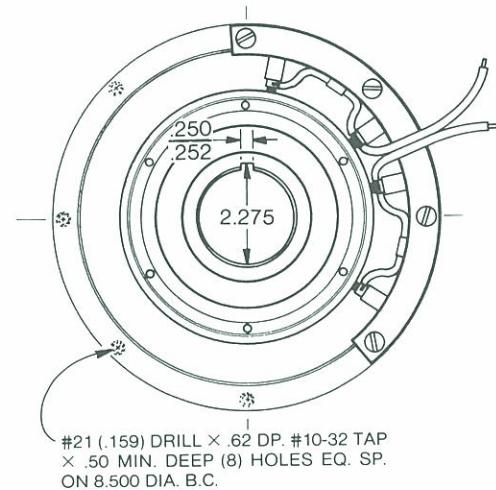
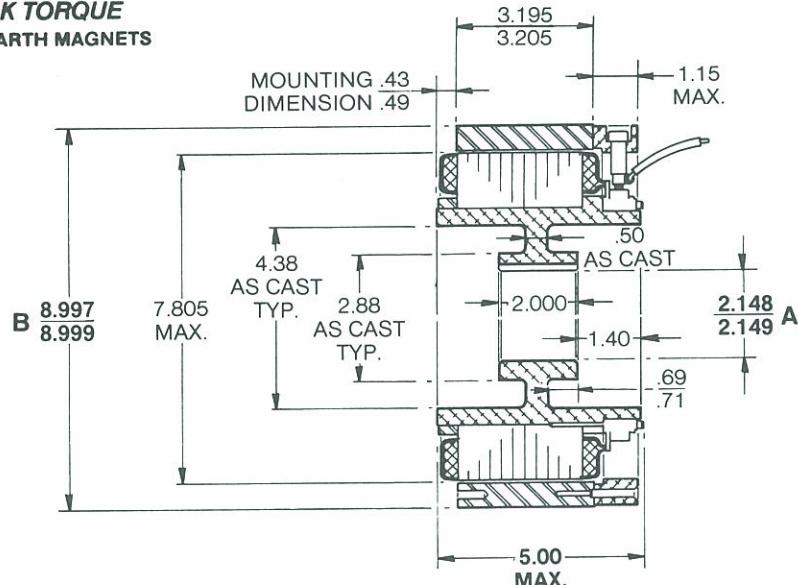
	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	24.5	12.3					
Peak Current - $I_p$	AMPERES	Rated	24.5	57.2					
Torque Sensitivity - $K_t$	LB.FT./AMP	$\pm 10\%$	0.94	0.40					
Back EMF Constant - $K_b$	V PER RAD/S	$\pm 10\%$	1.28	0.55					
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	1.00	0.214					
Inductance - $L_m$	mH	$\pm 30\%$	3.7	0.68					

# QT-7808

69 lb. ft.

PEAK TORQUE

RARE EARTH MAGNETS



**NOTES:**

1. — MOTOR SUPPLIED AS THREE SEPARATE COMPONENTS: ROTOR, STATOR, AND BRUSH RING SEGMENT.
2. — MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .002 (.004 T.I.R.) WHEN MOUNTED.
3. — WITH POSITIVE CURRENT APPLIED TO GREEN LEAD WITH RESPECT TO ORANGE LEAD, ROTATION SHALL BE C.C.W. FACING BRUSH SIDE.

**LEADS:**

#16 AWG TYPE "EE" TEFLON INSULATED PER MIL W-16878, 12" MIN. LG.

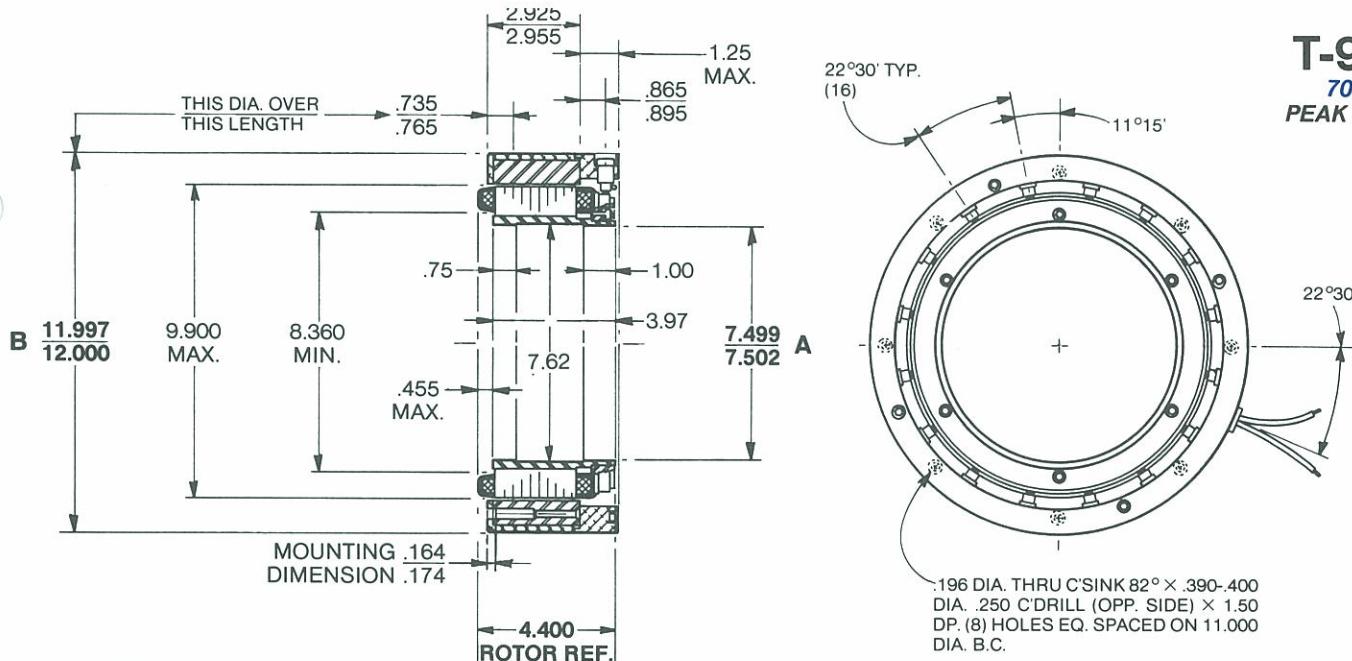
## SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>
Peak Torque Rating - $T_p$	69	LB.FT.
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	852	WATTS
Motor Constant - $K_m$	2.36	LB.FT./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	9.12	RAD/S
Electrical Time Constant - $\tau_e$	7.31	MS
Static Friction (Max.) - $T_f$	0.80	LB.FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	7.55      0.033
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	0.5	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	4	PERCENT
Ripple Frequency - (Fundamental)	97	CYCLES/REV.
Number of Poles	16	
Rotor Inertia - $J_m$	0.06	LB.FT.S <sup>2</sup>
Motor Weight	47	LB.

## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	33.3						
Peak Current - $I_p$	AMPERES	Rated	25.6						
Torque Sensitivity - $K_t$	LB.FT./AMP	$\pm 10\%$	2.69						
Back EMF Constant - $K_b$	V PER RAD/S	$\pm 10\%$	3.65						
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	1.30						
Inductance - $L_m$	mH	$\pm 30\%$	9.5						



**NOTES:**

- MOTOR SUPPLIED AS (2) SEPARATE COMPONENTS: ROTOR AND STATOR MOUNTED ON SHIPPING CLAMP WITH MYLAR IN AIR GAP, AND BRUSH RING ASSEMBLY. CAUTION: ROTOR MUST REMAIN IN STATOR AT ALL TIMES.
- MOUNTING REQUIREMENTS: DIAMETERS "A" AND "B" TO BE CONCENTRIC WITHIN .003(.006 T.I.R.) WHEN MOUNTED.
- WITH A POSITIVE CURRENT APPLIED TO GREEN LEAD ROTATION SHALL BE C.C.W. FACING BRUSH RING SIDE.
- FULL COMPLEMENT OF BRUSHES FOR IMPROVED HIGH CURRENT OPERATION.

LEADS:  
# 14 AWG TEFLON COATED TYPE "EE"  
12" MIN. LG.

### SIZE CONSTANTS

**Value      Units**

Peak Torque Rating - $T_p$	70	LB. FT.	
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	850	WATTS	
Motor Constant - $K_m$	2.40	LB.FT./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	8.5	RAD/S	
Electrical Time Constant - $\tau_e$	6.7	MS	
Static Friction (Max.) - $T_f$	1.2	LB. FT.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	7.9	LB. FT. PER RAD/S
	Infinite Impedance - $F_i$	0.040	LB. FT. PER RAD/S
Maximum Winding Temperature	105	°C	
Temperature Rise per Watt - $TPR$	0.4	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	4	PERCENT	
Ripple Frequency - (Fundamental)	143	CYCLES/REV.	
Number of Poles	16		
Rotor Inertia - $J_m$	0.21	LB.FT.S <sup>2</sup>	
Motor Weight	52	LB.	

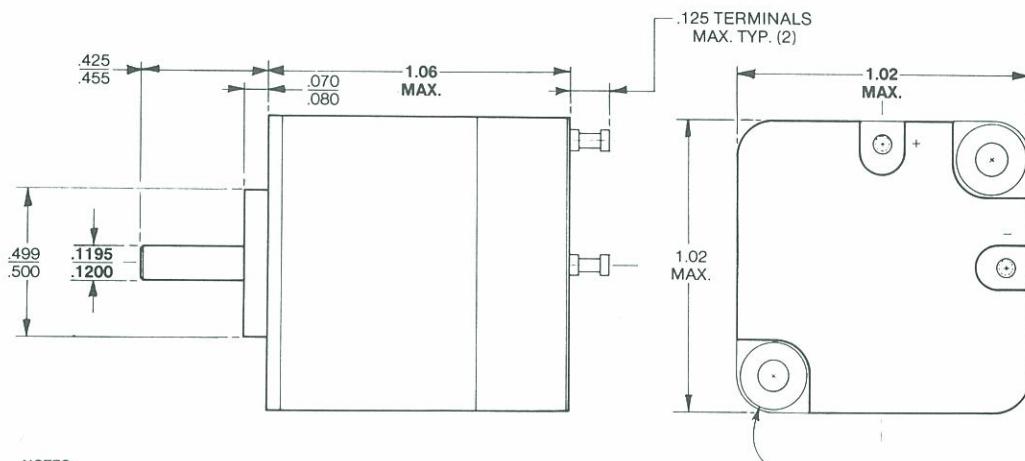
### WINDING CONSTANTS

*Winding Designation*

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	32	16					
Peak Current - $I_p$	AMPERES	Rated	26.5	53.0					
Torque Sensitivity - $K_t$	LB.FT./AMP	$\pm 10\%$	2.64	1.32					
Back EMF Constant - $K_b$	V PER RAD/S	$\pm 10\%$	3.6	1.79					
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	1.20	.300					
Inductance - $L_m$	mH	$\pm 30\%$	8	2.0					

## Housed Servo Selection Guide (oz. in. & lb. ft.)

MODEL NUMBER	Peak Torque @ Stall		Motor Constant	No Load Speed	Electrical Time Constant	Friction	Rotor Inertia	Physical Dimensions		Weight
	T <sub>P</sub> oz. in.	P <sub>P</sub> watts						J <sub>M</sub> oz. in. sec. <sup>2</sup>	OD in.	
NT-0716	7.0	40	1.10	800	0.36	0.35	1.3 × 10 <sup>-4</sup>	1.02	1.06	2.9
OT-0706	15	70	1.79	667	0.57	0.80	2.5 × 10 <sup>-4</sup>	1.02	2.00	5.5
QT-0805	24	110	2.29	658	0.58	1.0	2.8 × 10 <sup>-4</sup>	1.32	2.13	7.3
T-1262	25	46	3.68	260	0.54	2.5	1.5 × 10 <sup>-3</sup>	2.53	2.56	22
T-1258	50	62	6.35	177	0.80	3.5	2.2 × 10 <sup>-3</sup>	2.52	2.85	30
NT-2173	54	57	7.1	150	0.96	3	9.0 × 10 <sup>-3</sup>	3.54	2.50	45
QT-1209	100	287	5.90	360	0.68	3	2.2 × 10 <sup>-3</sup>	2.52	2.85	30
QT-1226	100	74	11.7	104	0.55	7	5.0 × 10 <sup>-3</sup>	2.03	4.41	42
T-1266	100	102	9.9	143	1.06	6.0	3.2 × 10 <sup>-3</sup>	2.52	3.75	48
T-1281	100	102	9.9	143	1.05	6	3.2 × 10 <sup>-3</sup>	2.51	3.75	48
T-1816	100	95	10.3	130	1.3	4	1.0 × 10 <sup>-2</sup>	3.54	2.58	60
T-1856	110	125	9.8	162	0.64	4	1.0 × 10 <sup>-2</sup>	3.38	3.00	50
T-1814	200	120	18.3	85	2.2	5	1.7 × 10 <sup>-2</sup>	3.54	3.15	80
	lb. ft.	watts	lb. ft./watt	rad/sec	msec.	lb. ft.	lb. ft. sec <sup>2</sup>	in.	in.	lbs.
NT-2960	1.2	77	0.14	47	1.5	0.05	3.9 × 10 <sup>-4</sup>	4.02	3.12	3.1
T-1809	1.56	183	0.11	87	3	0.06	1.5 × 10 <sup>-4</sup>	3.50	4.39	6.5



**NOTES:**

1. - WITH POSITIVE CURRENT APPLIED TO POSITIVE (+) TERMINAL ROTATION SHALL BE C.C.W. FACING TERMINAL END.
2. - MAXIMUM SOLDERING TEMPERATURE FOR ATTACHING LEADS TO TERMINALS 400°F.
3. - UNIT HAS TRANSFER MOLDED END BELLS.

125 DIA. THRU. CSINK 82° TO .235  
MIN. DIA. (2) HOLES EQ. SPACED ON  
1.062 DIA. B.C.

### SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>
Peak Torque Rating - $T_p$	7.0	OZ. IN.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	40.2	WATTS
Motor Constant - $K_m$	1.10	OZ.IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p \cdot \omega_{NL}$	800	RAD/S
Electrical Time Constant - $\tau_e$	0.36	MS
Static Friction (Max.) - $T_f$	0.35	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_1$	0.0086 $3.9 \times 10^{-4}$
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	12	°C/WATT
Ripple Torque (Average to Peak) - $T_R$	10	PERCENT
Ripple Frequency - (Fundamental)	13	CYCLES/REV.
Number of Poles	4	
Rotor Inertia - $J_M$	$1.3 \times 10^{-4}$	OZ.IN.S <sup>2</sup>
Motor Weight	2.93	OZ.

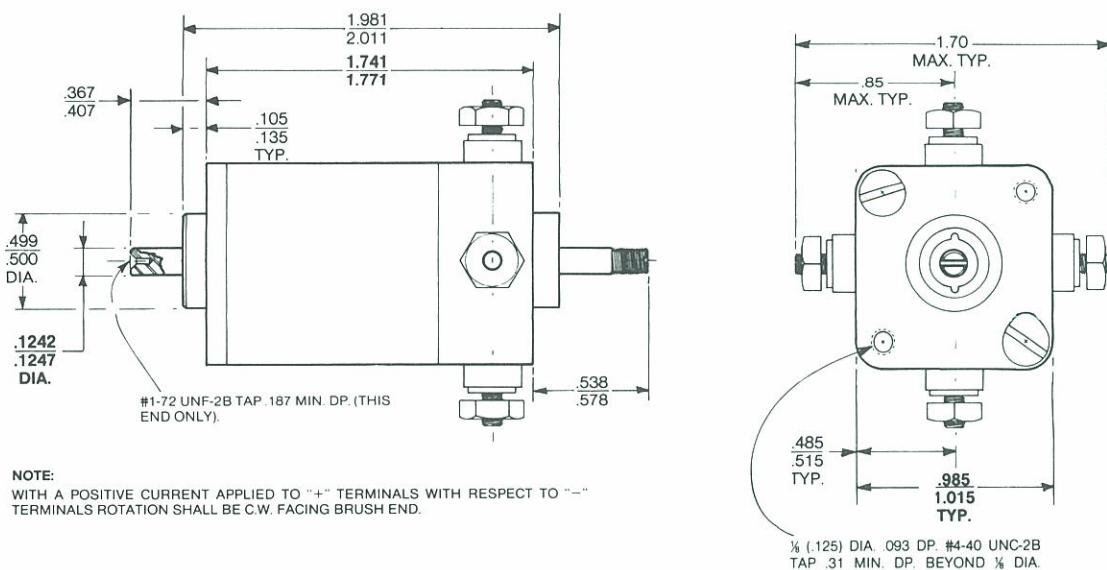
### WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p(25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	25.9	20.5	13.0	38.9	30.0		
Peak Current - $I_p$	AMPERES	Rated	1.55	1.95	3.12	1.06	1.25		
Torque Sensitivity - $K_t$	OZ.IN./AMP	$\pm 10\%$	4.5	3.57	2.24	6.6	5.6		
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	.0318	.0252	.0158	.0466	.0395		
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	16.7	10.5	4.18	36.7	24.0		
Inductance - $L_m$	mH	$\pm 30\%$	6.0	4.0	1.6	13.0	9.5		

# OT-0706

15 oz. in.  
PEAK TORQUE



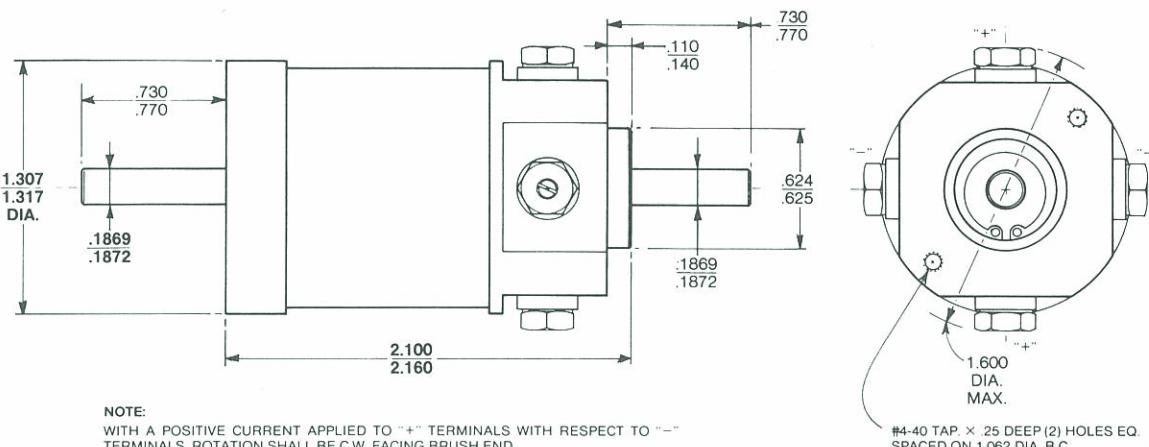
## SIZE CONSTANTS

		Value	Units
Peak Torque Rating - $T_p$		15	OZ. IN.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$		70	WATTS
Motor Constant - $K_m$		1.79	OZ.IN./√WATT
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$		667	RAD/S
Electrical Time Constant - $\tau_e$		0.57	MS
Static Friction (Max.) - $T_f$		0.80	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_\infty$	0.0225      0.0009	OZ. IN. PER RAD/S      OZ. IN. PER RAD/S
Maximum Winding Temperature		155	°C
Temperature Rise per Watt - $TPR$		10	°C/WATT
Ripple Torque (Average to Peak) - $T_r$		7	PERCENT
Ripple Frequency - (Fundamental)		13	CYCLES/REV.
Number of Poles		4	
Rotor Inertia - $J_m$		$2.5 \times 10^{-4}$	OZ.IN.S <sup>2</sup>
Motor Weight		5.5	OZ.

## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	17.2	28.0					
Peak Current - $I_p$	AMPERES	Rated	4.00	2.50					
Torque Sensitivity - $K_t$	OZ.IN./AMP	± 10%	3.75	6.00					
Back EMF Constant - $K_b$	V per RAD/S	± 10%	0.026	0.042					
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	± 12.5%	4.30	11.2					
Inductance - $L_m$	mH	± 30%	2.5	6.4					



## SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>
Peak Torque Rating - $T_p$	24	OZ. IN.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	110	WATTS
Motor Constant - $K_M$	2.29	OZ.IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	658	RAD/S
Electrical Time Constant - $\tau_E$	0.58	MS
Static Friction (Max.) - $T_f$	1.0	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	0.036      0.0011
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	9	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	10	PERCENT
Ripple Frequency - (Fundamental)	13	CYCLES/REV
Number of Poles	4	
Rotor Inertia - $J_m$	$2.8 \times 10^{-4}$	OZ.IN.S <sup>2</sup>
Motor Weight	7.3	OZ.

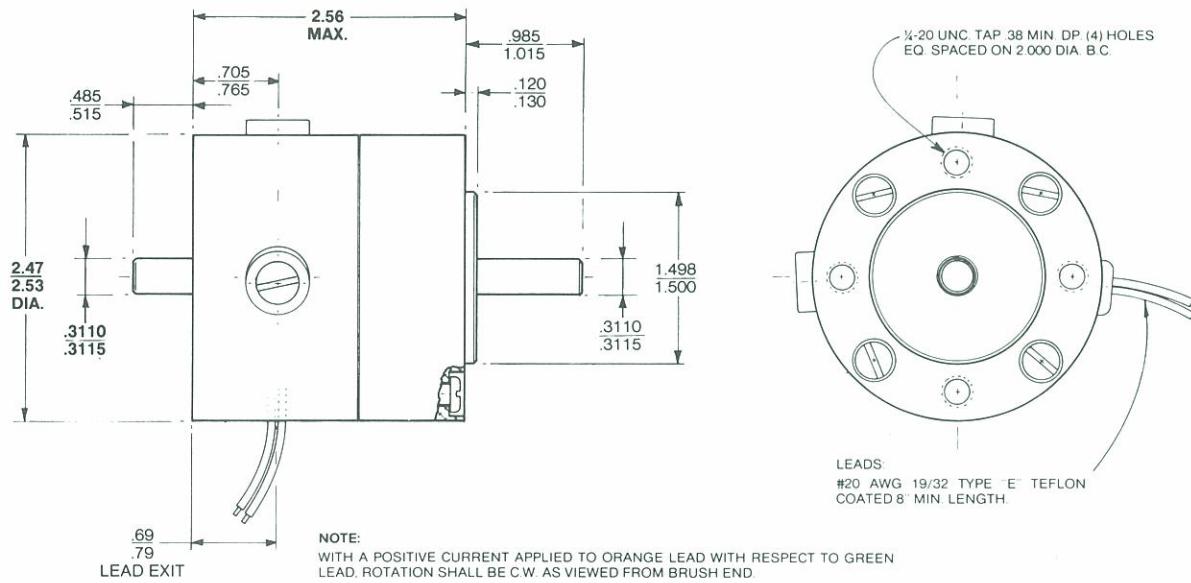
## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p (25^\circ\text{C})$ - $V_p$	VOLTS	Nom.	21.7						
Peak Current - $I_p$	AMPERES	Rated	5.05						
Torque Sensitivity - $K_t$	OZ.IN./AMP	$\pm 10\%$	4.75						
Back EMF Constant - $K_B$	V per RAD/S	$\pm 10\%$	0.033						
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	4.30						
Inductance - $L_m$	mH	$\pm 30\%$	2.5						

# T-1262

25 oz. in.  
PEAK TORQUE



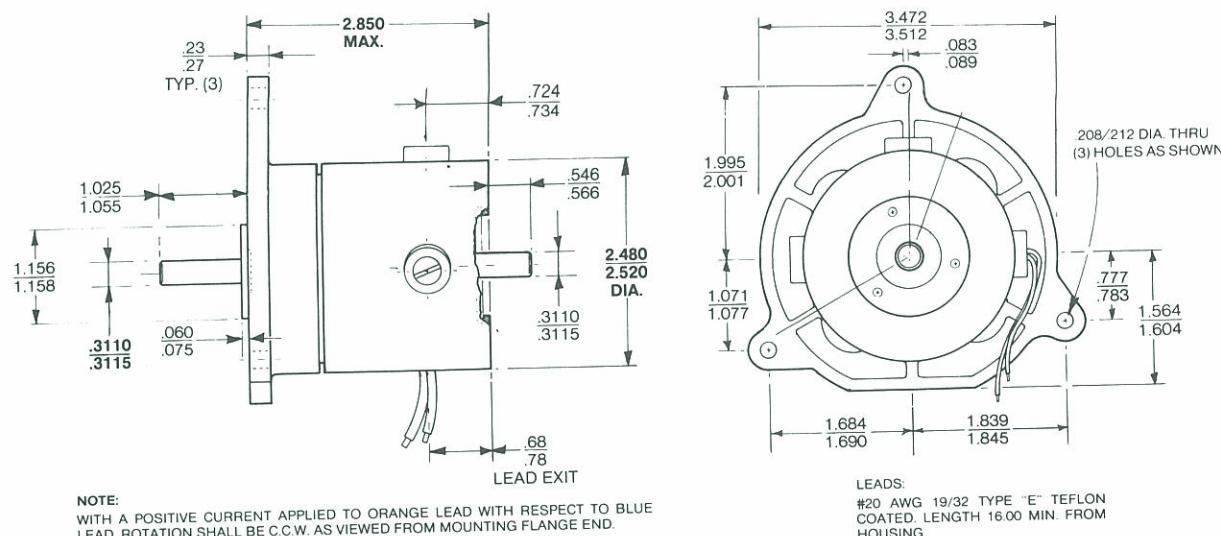
## SIZE CONSTANTS

	Value	Units	
Peak Torque Rating - $T_p$	25	OZ. IN.	
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	46	WATTS	
Motor Constant - $K_M$	3.68	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	260	RAD/S	
Electrical Time Constant - $\tau_E$	0.542	MS	
Static Friction (Max.) - $T_f$	2.5	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	0.096 0.0015	OZ. IN. PER RAD/S OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	8.0	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	7	PERCENT	
Ripple Frequency - (Fundamental)	21	CYCLES/REV	
Number of Poles	4		
Rotor Inertia - $J_M$	0.0015	OZ.IN.S <sup>2</sup>	
Motor Weight	22	OZ.	

## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	10.5	21.0					
Peak Current - $I_p$	AMPERES	Rated	4.39	2.19					
Torque Sensitivity - $K_t$	OZ.IN./AMP	$\pm 10\%$	5.70	11.4					
Back EMF Constant - $K_B$	V per RAD/S	$\pm 10\%$	0.040	0.080					
DC Resistance ( $25^\circ\text{C}$ ) - $R_M$	OHMS	$\pm 12.5\%$	2.40	9.60					
Inductance - $L_M$	mH	$\pm 30\%$	1.3	5.2					

**SIZE CONSTANTS**

	<b>Value</b>	<b>Units</b>
Peak Torque Rating - $T_p$	50	OZ. IN.
Power Input, Stalled at $T_p(25^\circ\text{C})$ - $P_p$	62	WATTS
Motor Constant - $K_m$	6.35	OZ.IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	177	RAD/S
Electrical Time Constant - $\tau_e$	0.80	MS
Static Friction (Max.) - $T_f$	3.5	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.28 OZ. IN. PER RAD/S
	Infinite Impedance - $F_\infty$	0.003 OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - TPR	5.0	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	7	PERCENT
Ripple Frequency - (Fundamental)	21	CYCLES/REV
Number of Poles	4	
Rotor Inertia - $J_m$	0.0022	OZ.IN. $^2$
Motor Weight	30	OZ.

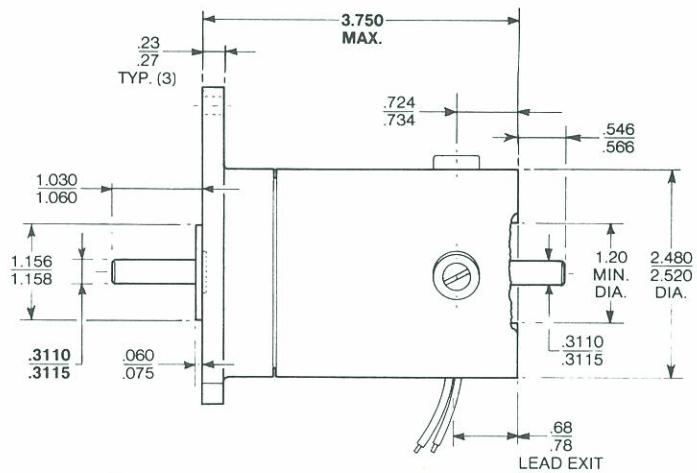
**WINDING CONSTANTS****Winding Designation**

Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	
Peak Current - $I_p$	
Torque Sensitivity - $K_t$	
Back EMF Constant - $K_b$	
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	
Inductance - $L_m$	

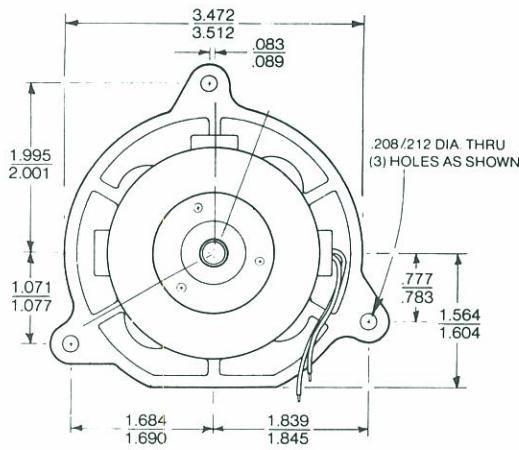
UNITS	TOLERANCES	A	B	C	D	E	F	G
VOLTS	Nom.	11.5	14.2	17.8	23.0	35.7		
AMPERES	Rated	5.48	4.38	3.50	2.74	1.75		
OZ.IN./AMP	$\pm 10\%$	9.12	11.4	14.2	18.2	28.4		
V per RAD/S	$\pm 10\%$	0.064	0.080	0.100	0.129	0.200		
OHMS	$\pm 12.5\%$	2.10	3.25	5.10	8.40	20.4		
mH	$\pm 30\%$	1.7	2.6	4.0	6.8	16		

# T-1266

100 oz. in.  
PEAK TORQUE



**NOTE:**  
WITH A POSITIVE CURRENT APPLIED TO ORANGE LEAD WITH RESPECT TO BLUE LEAD, ROTATION SHALL BE C.W. AS VIEWED FROM BRUSH END.



**LEADS:**  
#20 AWG 19/32 TYPE "E" TEFLON COATED, LENGTH 16.000 MIN FROM HOUSING

## SIZE CONSTANTS

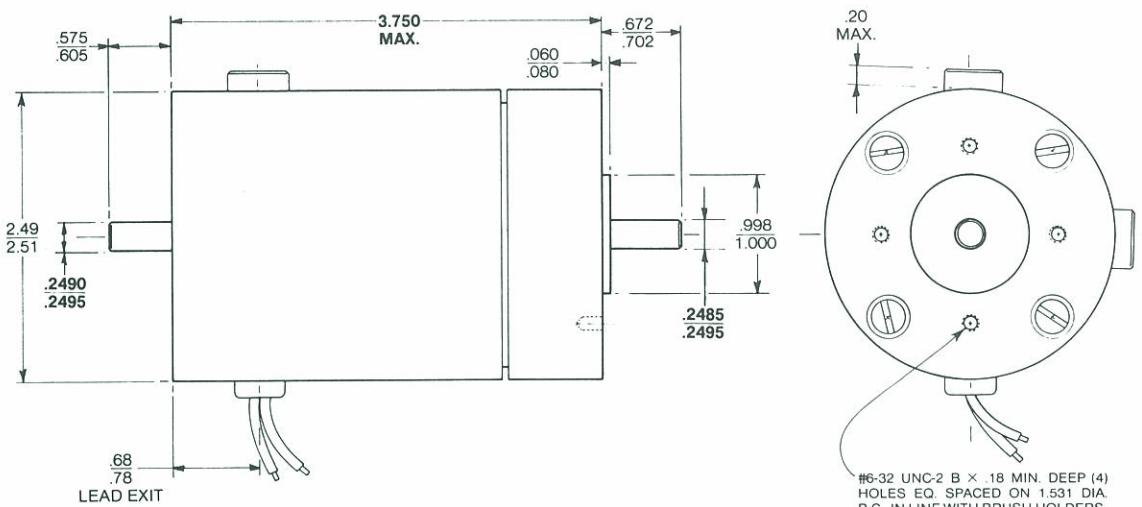
## Value      Units

Peak Torque Rating - $T_p$	100	OZ. IN.	
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	102	WATTS	
Motor Constant - $K_M$	9.9	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	143	RAD/S	
Electrical Time Constant - $\tau_E$	1.06	MS	
Static Friction (Max.) - $T_f$	6.0	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.70	OZ. IN. PER RAD/S
	Infinite Impedance - $F_I$	0.006	OZ. IN. PER RAD/S
Maximum Winding Temperature	155	$^\circ\text{C}$	
Temperature Rise per Watt - $TPR$	3.5	$^\circ\text{C}/\text{WATT}$	
Ripple Torque (Average to Peak) - $T_R$	7	PERCENT	
Ripple Frequency - (Fundamental)	21	CYCLES/REV	
Number of Poles	4		
Rotor Inertia - $J_M$	0.0032	OZ.IN. $\text{S}^2$	
Motor Weight	48	OZ.	

## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	22.3	17.7	28.1	35.2	14.0		
Peak Current - $I_p$	AMPERES	Rated	4.55	5.68	3.64	2.84	7.00		
Torque Sensitivity - $K_T$	OZ.IN./AMP	$\pm 10\%$	22.0	17.6	27.5	35.2	14.3		
Back EMF Constant - $K_B$	V per RAD/S	$\pm 10\%$	0.155	0.124	0.194	0.248	0.101		
DC Resistance ( $25^\circ\text{C}$ ) - $R_M$	OHMS	$\pm 12.5\%$	4.90	3.11	7.72	12.4	2.00		
Inductance - $L_M$	mH	$\pm 30\%$	5.2	3.3	8.1	13	2.2		



NOTES:

1. - WITH A POSITIVE CURRENT APPLIED TO ORANGE LEAD WITH RESPECT TO BLUE LEAD, ROTATION SHALL BE C.W. AS VIEWED FROM BRUSH END.
2. - UNIT SUPPLIED WITH ENCODER MOUNTING HOLES ON BRUSH END.

LEADS:  
#20 AWG 19/32 TYPE "E" TEFILON COATED 36" MIN. LG.

### SIZE CONSTANTS

	Value	Units	
Peak Torque Rating - $T_p$	100	OZ. IN.	
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	102	WATTS	
Motor Constant - $K_m$	9.9	$\text{OZ.IN./}\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	143	RAD/S	
Electrical Time Constant - $\tau_e$	1.05	MS	
Static Friction (Max.) - $T_f$	6	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	0.70 0.006	OZ. IN. PER RAD/S OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	3.5	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	7	PERCENT	
Ripple Frequency - (Fundamental)	21	CYCLES/REV.	
Number of Poles	4		
Rotor Inertia - $J_m$	0.0032	OZ.IN.S <sup>2</sup>	
Motor Weight	48	OZ.	

### WINDING CONSTANTS

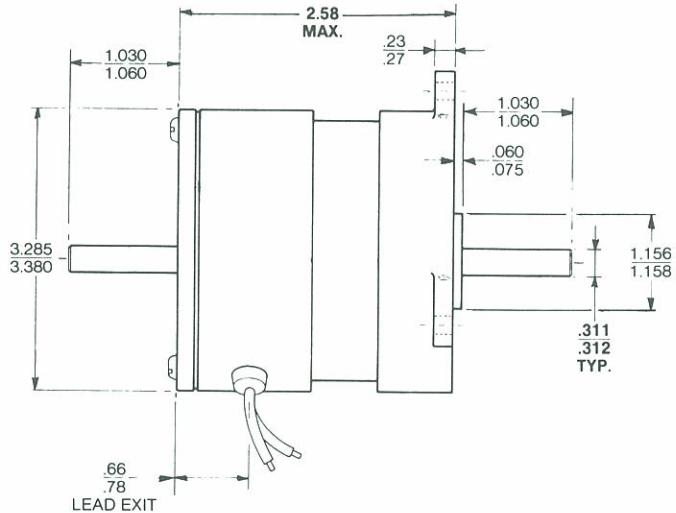
### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	28.0	17.7					
Peak Current - $I_p$	AMPERES	Rated	3.64	5.70					
Torque Sensitivity - $K_t$	OZ.IN./AMP	$\pm 10\%$	27.5	17.6					
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.194	0.124					
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	7.70	3.10					
Inductance - $L_m$	mH	$\pm 30\%$	8.1	3.3					

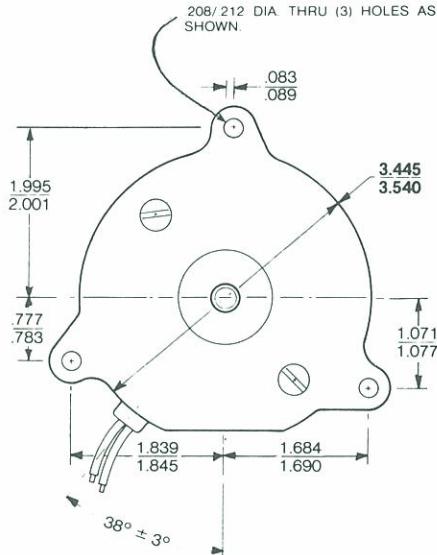
# T-1816

100 oz. in.

PEAK TORQUE



**NOTE:**  
WITH A POSITIVE CURRENT APPLIED TO ORANGE LEAD WITH RESPECT TO BLUE LEAD, ROTATION SHALL BE C.C.W FACING DRIVE END.



**LEADS:**  
#20 AWG TYPE 'E' TEFLON COATED  
12' MIN. LENGTH PER MIL-W-16878

## SIZE CONSTANTS

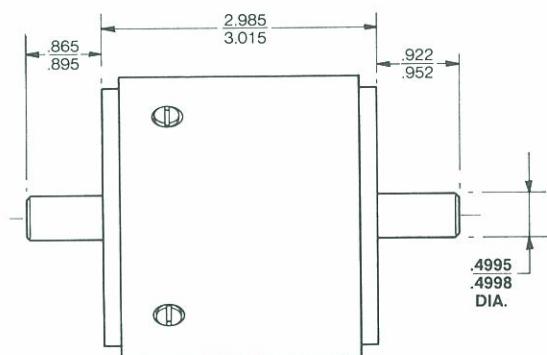
	<b>Value</b>	<b>Units</b>
Peak Torque Rating - $T_p$	* 100	OZ. IN.
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	95	WATTS
Motor Constant - $K_M$	10.3	OZ.IN./√ WATT
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	130	RAD/S
Electrical Time Constant - $\tau_E$	1.3	MS
Static Friction (Max.) - $T_f$	4	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_i$	0.75 0.012
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - TPR	4.3	°C/WATT
Ripple Torque (Average to Peak) - $T_R$	5	PERCENT
Ripple Frequency - (Fundamental)	25	CYCLES/REV.
Number of Poles	4	
Rotor Inertia - $J_m$	0.010	OZ.IN.S <sup>2</sup>
Motor Weight	60	OZ.

\*Cont. stall torque = 42 oz.in.;  $25^\circ\text{C}$  ambient

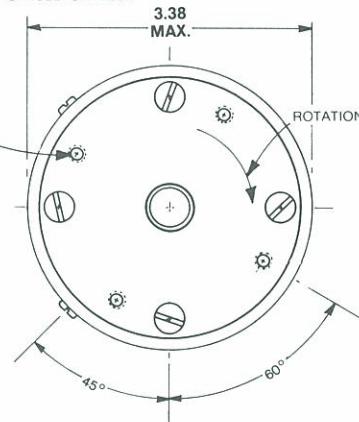
## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	9.6	100.0	12.2	14.9	24.3		
Peak Current - $I_p$	AMPERES	Rated	10.7	0.85	8.45	6.76	3.37		
Torque Sensitivity - $K_T$	OZ.IN./AMP.	± 10%	9.3	118.0	11.8	14.8	29.7		
Back EMF Constant - $K_B$	V per RAD/S	± 10%	0.066	0.83	0.083	0.105	0.210		
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	± 12.5%	0.90	118.0	1.44	2.2	7.20		
Inductance - $L_m$	mH	± 30%	1.1	176.0	1.76	2.8	11.2		



8-32 UNC-2B TAP X 5/16 DEEP 4  
HOLES EQUALLY SPACED ON 2.500  
DIA. B.C.



**NOTES:**

- 1 — WITH POSITIVE CURRENT APPLIED TO "+" TERMINAL, ROTATION SHALL BE C.C.W. FACING BRUSH END.
- 2 — EPOXY ENCAPSULATED STATOR ASSEMBLY.

### SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>
Peak Torque Rating - $T_p$	110	OZ.IN.
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	125	WATTS
Motor Constant - $K_m$	9.8	OZ.IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	162	RAD/S
Electrical Time Constant - $\tau_e$	.64	MS
Static Friction (Max.) - $T_f$	4	OZ.IN.
Viscous Damping Coefficients	.68	OZ.IN. PER RAD/S
Zero Impedance - $F_0$	.01	OZ.IN. PER RAD/S
Infinite Impedance - $F_\infty$		
Maximum Winding Temperature	155	$^\circ\text{C}$
Temperature Rise per Watt - $TPR$	4.0	$^\circ\text{C}/\text{WATT}$
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT
Ripple Frequency - (Fundamental)	25	CYCLES/REV.
Number of Poles	4	
Rotor Inertia - $J_m$	.01	OZ.IN.S <sup>2</sup>
Motor Weight	50	OZ.

### WINDING CONSTANTS

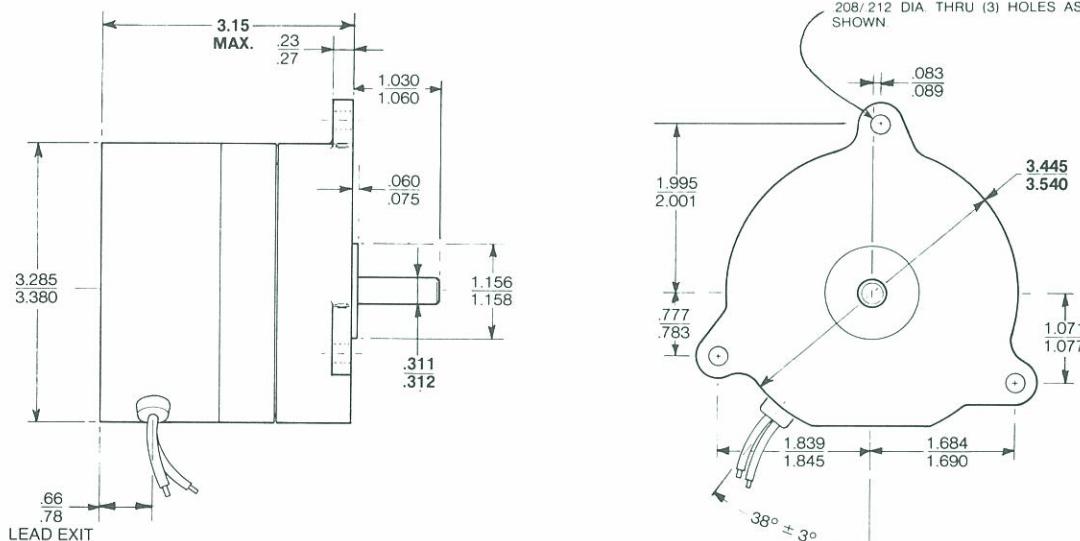
### Winding Designation

	UNITS	TOLERANCES
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom. 12.5
Peak Current - $I_p$	AMPERES	Rated 10
Torque Sensitivity - $K_t$	OZ.IN./AMP	$\pm 10\%$ 11
Back EMF Constant - $K_b$	V PER RAD/S	$\pm 10\%$ .077
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$ 1.25
Inductance - $L_m$	mH	$\pm 30\%$ .8

# T-1814

200 oz. in.

PEAK TORQUE



**NOTE:**  
WITH A POSITIVE CURRENT APPLIED TO ORANGE LEAD WITH RESPECT TO BLUE LEAD, ROTATION SHALL BE C.C.W. FACING DRIVE END.

**LEADS:**  
#20 AWG TYPE 'E' TEFILON COATED  
12' MIN LENGTH PER MIL-W-16878.

## SIZE CONSTANTS

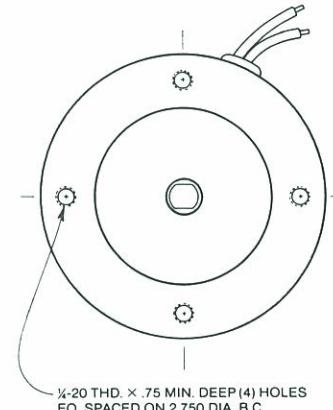
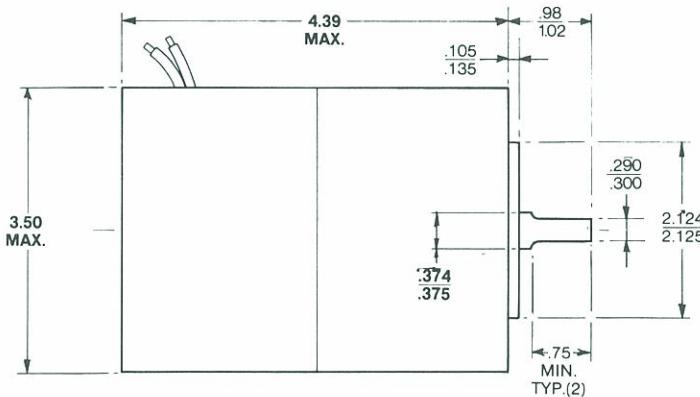
### Value      Units

Peak Torque Rating - $T_p$	200	OZ. IN.
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	120	WATTS
Motor Constant - $K_m$	18.3	OZ.IN./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	85	RAD/S
Electrical Time Constant - $\tau_e$	2.2	MS
Static Friction (Max.) - $T_f$	5	OZ. IN.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_1$	2.3      0.024
Maximum Winding Temperature	155	°C
Temperature Rise per Watt - $TPR$	3.5	°C/WATT
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT
Ripple Frequency - (Fundamental)	25	CYCLES/REV.
Number of Poles	4	
Rotor Inertia - $J_m$	0.017	OZ.IN.S <sup>2</sup>
Motor Weight	80	OZ.

## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	12.3	81.7	22.0				
Peak Current - $I_p$	AMPERES	Rated	10.7	1.34	5.40				
Torque Sensitivity - $K_t$	OZ.IN./AMP	± 10%	18.6	149.0	36.8				
Back EMF Constant - $K_b$	V per RAD/S	± 10%	0.131	1.052	0.262				
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	± 12.5%	1.15	61.0	4.08				
Inductance - $L_m$	mH	± 30%	2.2	141.0	8.8				



**NOTE:**  
WITH A POSITIVE CURRENT APPLIED TO GREEN LEAD WITH RESPECT TO ORANGE  
LEAD ROTATION SHALL BE C.W. FACING SHAFT END.

**LEADS:**  
#18 AWG TEFLON COATED TYPE "EE"  
6" MIN. LG.

## SIZE CONSTANTS

### Value      Units

Peak Torque Rating - $T_p$	300	OZ. IN.	
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	183	WATTS	
Motor Constant - $K_m$	22	OZ.IN./ $\sqrt{\text{WATT}}$	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	87	RAD/S	
Electrical Time Constant - $\tau_e$	3	MS	
Static Friction (Max.) - $T_f$	12	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	3.5	OZ. IN. PER RAD/S
	Infinite Impedance - $F_i$	0.040	OZ. IN. PER RAD/S
Maximum Winding Temperature	155	$^\circ\text{C}$	
Temperature Rise per Watt - $TPR$	2.6	$^\circ\text{C}/\text{WATT}$	
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT	
Ripple Frequency - (Fundamental)	25	CYCLES/REV.	
Number of Poles	4		
Rotor Inertia - $J_m$	0.028	OZ.IN.S <sup>2</sup>	
Motor Weight	6.5	OZ.	

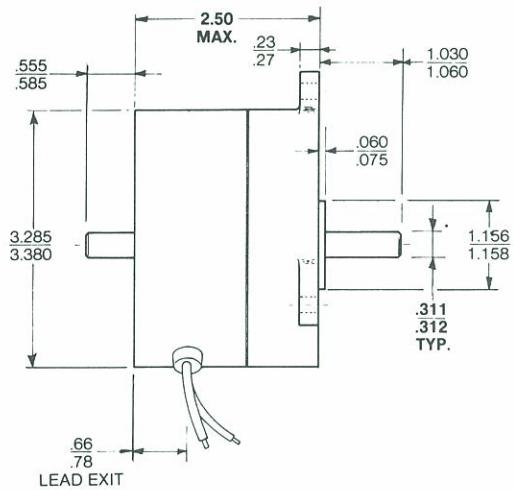
## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	30.6	9.9	85.6	16.2			
Peak Current - $I_p$	AMPERES	Rated	6	18.0	1.9	11.6			
Torque Sensitivity - $K_t$	OZ.IN./AMP	$\pm 10\%$	50	16.7	159.0	26.0			
Back EMF Constant - $K_b$	V per RAD/S	$\pm 10\%$	0.35	0.12	1.12	0.18			
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	5.1	0.55	45.0	1.4			
Inductance - $L_m$	mH	$\pm 30\%$	12	1.3	122	3.1			

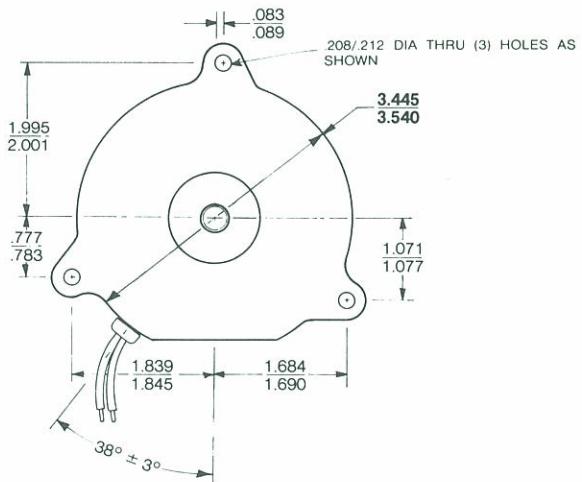
# NT-2173

54 oz. in.  
PEAK TORQUE



NOTE:

WITH A POSITIVE CURRENT APPLIED TO ORANGE LEAD WITH RESPECT TO BLUE LEAD, ROTATION SHALL BE C.C.W. FACING MOUNTING FLANGE END.



LEADS:

#20 AWG TYPE 'E' TEFILON COATED  
12" MIN. LENGTH PER MIL-W-16878.

## SIZE CONSTANTS

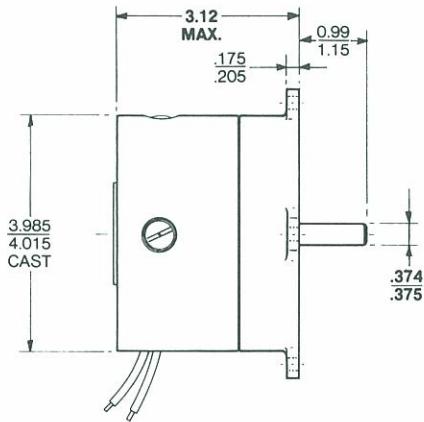
### Value      Units

Peak Torque Rating - $T_p$	54	OZ. IN.	
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	57	WATTS	
Motor Constant - $K_M$	7.1	OZ.IN./√ WATT	
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	150	RAD/S	
Electrical Time Constant - $\tau_e$	0.96	MS	
Static Friction (Max.) - $T_f$	3	OZ. IN.	
Viscous Damping Coefficients	Zero Impedance - $F_0$	0.36	OZ. IN. PER RAD/S
	Infinite Impedance - $F_i$	0.012	OZ. IN. PER RAD/S
Maximum Winding Temperature	155	°C	
Temperature Rise per Watt - $TPR$	5	°C/WATT	
Ripple Torque (Average to Peak) - $T_r$	6	PERCENT	
Ripple Frequency - (Fundamental)	33	CYCLES/REV.	
Number of Poles	4		
Rotor Inertia - $J_M$	0.009	OZ.IN.S <sup>2</sup>	
Motor Weight	45	OZ.	

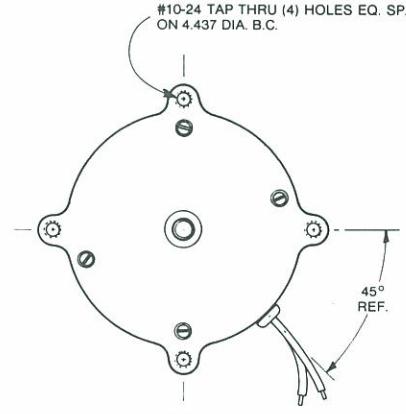
## WINDING CONSTANTS

### Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
	VOLTS	Nom.	12.0	27.9	22.4	5.6	106.4	9.4	19.2
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	AMPERES	Rated	4.8	1.51	1.90	10.2	0.38	6.25	3.00
Peak Current - $I_p$	OZ.IN./AMP	± 10%	11.3	36.0	28.6	5.3	144.0	8.65	18.0
Torque Sensitivity - $K_t$	V per RAD/S	± 10%	0.080	0.254	0.202	0.037	1.017	0.061	0.127
Back EMF Constant - $K_b$	OHMS	± 12.5%	2.5	18.5	11.8	0.55	280	1.50	6.40
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	mH	± 30%	2.4	24.2	15.4	0.53	387	1.4	6.0
Inductance - $L_m$									



**NOTE:**  
WITH A POSITIVE CURRENT APPLIED TO GREEN LEAD  
ROTATION SHALL BE C.W. FACING SHAFT END.



**LEADS:**  
#18 AWG TYPE "E" TEFLOX COATED  
8" MIN. LENGTH.

## SIZE CONSTANTS

	<b>Value</b>	<b>Units</b>
Peak Torque Rating - $T_p$	1.2	LB. FT.
Power Input, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $P_p$	77	WATTS
Motor Constant - $K_M$	0.137	LB.FT./ $\sqrt{\text{WATT}}$
No Load Speed, Theoretical @ $V_p$ - $\omega_{NL}$	47	RAD/S
Electrical Time Constant - $\tau_e$	1.5	MS
Static Friction (Max.) - $T_f$	0.052	LB. FT.
Viscous Damping Coefficients	Zero Impedance - $F_0$ Infinite Impedance - $F_1$	0.025 $1 \times 10^{-3}$ LB. FT. PER RAD/S
Maximum Winding Temperature	155	$^\circ\text{C}$
Temperature Rise per Watt - $TPR$	4.3	$^\circ\text{C}/\text{WATT}$
Ripple Torque (Average to Peak) - $T_r$	5	PERCENT
Ripple Frequency - (Fundamental)	41	CYCLES/REV.
Number of Poles	10	
Rotor Inertia - $J_M$	$3.9 \times 10^{-4}$	LB.FT.S <sup>2</sup>
Motor Weight	3.1	LB.

## WINDING CONSTANTS

## Winding Designation

	UNITS	TOLERANCES	A	B	C	D	E	F	G
Voltage, Stalled at $T_p$ ( $25^\circ\text{C}$ ) - $V_p$	VOLTS	Nom.	12.0	24.0					
Peak Current - $I_p$	AMPERES	Rated	6.3	3.15					
Torque Sensitivity - $K_T$	LB.FT./AMP	$\pm 10\%$	0.19	0.38					
Back EMF Constant - $K_B$	V per RAD/S	$\pm 10\%$	0.26	0.52					
DC Resistance ( $25^\circ\text{C}$ ) - $R_m$	OHMS	$\pm 12.5\%$	1.9	7.6					
Inductance - $L_m$	mH	$\pm 30\%$	3.1	12.3					







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