How to Upload the Kollmorgen S300 a Parameters to file

Connect

- Connect the interface cable to a serial interface on your PC and to the serial interface X6 of the servo amplifier. USB to serial converter can be used optionally.
- Switch on the 24 V power supply for the servo amplifier.
- Wait about 30 seconds, until the front display of the servo amplifier displays the current class (e.g. 48 8 for 48 A) If the power supply voltage is switched on, too, a leading P is displayed (e.g. 68 8 for Power, 48 A).

NOTE

8.3.2

If a fault code ($\mathbb{R} \oplus \mathbb{R}$) or a warning ($\mathbb{R} \oplus \mathbb{R}$) or a status message (./_ / E/S) appears in the display, you will find the description on page 114 / 115. If a fault message appears, fix the problem.



Double-Click the DRIVEGUI.EXE icon on your Windows desktop to start the software.

Drive	GUI 🛛 🕅
?	Would you like to connect to a drive? (Press "Yes" to connect or "No" to work offline)
	Ja S Nein

You can work offline or online with DRIVEGUI.EXE. Work ONLINE now.



If the communication is started for the first time, you have to setup the communication parameters. Choose the communication system and the interface, where the servo amplifier is connected to. Click OK.

The software tries to communicate with these parameters. If it's not successful, you receive this error message:

Drive	GUI 🛛 🔀
1	Communication Error: Communication timed out.

Frequent causes:

- wrong interface chosen
- wrong connector chosen at the servo amplifier
- interface is used by another software
- 24 V auxiliary voltage for the servo amplifier not working
- interface cable broken or wrong wiring

Quit the error message. The software starts in the offline mode now, that requires the manual selection of the amplifier's type. Quit this selection by closing the window. Fix the communication problem. Restart the software in Online mode.



When the GUI opens and connects to the S700 drive it will look similar to screen shown above. The Online LED will turn green if the drive is communicating with the GUI.



Select the Setup Wizzard in the Tree of the GUI

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Select the Save Disk at the top left of screen

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IP (\\RADVSVAP03\DATA\$) (J:)			under a la arrie
ENG (\\RADVSVFP02\DATA\$) (N:)			
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File name: Untitled.par			
Save as type: Parameter Files (*.par)			

Select where to save parameters on the computer and give the file a name

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SD-Card	DRIVE0 Setup Wizard Basic Setup Units / Mechanical CAN / Field Bus Settings Carrent Loop Velocity Loop Velocity Loop Position Loop Velocity Loop Position Registers Electronic Gearing Position Registers Electronic Gearing Digital I/O Digital I/O Monitor Status (Errors / Warnings) Monitor Sede Plot Preminal Auto-Tuning EtherCAT SD-Card	Basic Setup Power Supply Regen Resistor Internal Value Mains 1 Q Would you like to connect to a drive? OnveGUI Would you like to connect to a drive? OnveGUI Would you like to connect or "No" to work offline) Respon The Ves Ves No Ves No Software-Enable on Bootup The Ves No Software-Enable on Bootup The PwM = 8 kHz, current loop = 16 kHz, position loop = 4 kHz PwM = 8 kHz, current loop = 16 kHz, position loop = 4 kHz PwM = 8 kHz, current loop = 16 kHz, position loop = 8 kHz PwM = 4 kHz, current loop = 16 kHz, position loop = 4 kHz PwM = 4 kHz, current loop = 16 kHz, position loop = 4 kHz PwM = 4 kHz, current loop = 16 kHz, position loop = 4 kHz PwM = 4 kHz, current loop = 16 kHz, position loop = 4 kHz Next >