**Configuration of PLC Siemens S7-1500 ProfiNetTM and Kollmorgen AKD**®**2G-SPP**



***Application Note***

This is a guide to configure the PROFINET IRT communication in between the CPU S7-15xxTx-PN and the AKD2G-SPP PROFINET.

The result is to manage both axes by means of the Technology Objects that the PLC provides.

The axes will be configured in Velocity Mode and the PLC will handle the position loop control. For that the ProfiDrive Telegram 3 will be used inside the PROFINET I/O data.

# Record of Document Revisions

|  |  |
| --- | --- |
| Revision | Remarks |
| A 18/03/2021 | First Edition - Preliminary |
|  |  |

**DISCLAIMER**:

All programs in this release (application demos, Kollmorgen UDFBs, etc.) are provided "AS IS, WHERE IS", WITHOUT ANY WARRANTIES, EXPRESS OR IMPLIED.

There may be technical or editorial omissions in the programs and their specifications.

These programs are provided solely for Kollmorgen engineer and the user assumes all responsibility for their use. Programs and their content are subject to change without notice.

This guide doesn’t cover safety aspect of the application which remains a full responsibility of the machine builder.

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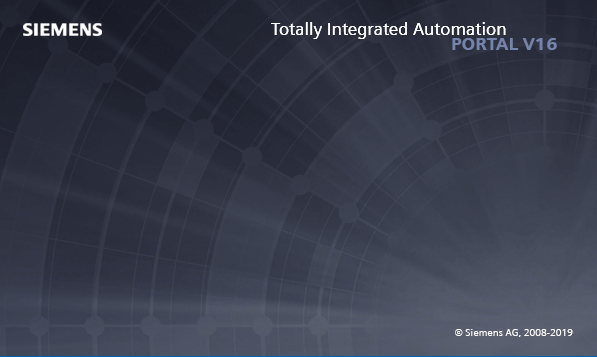
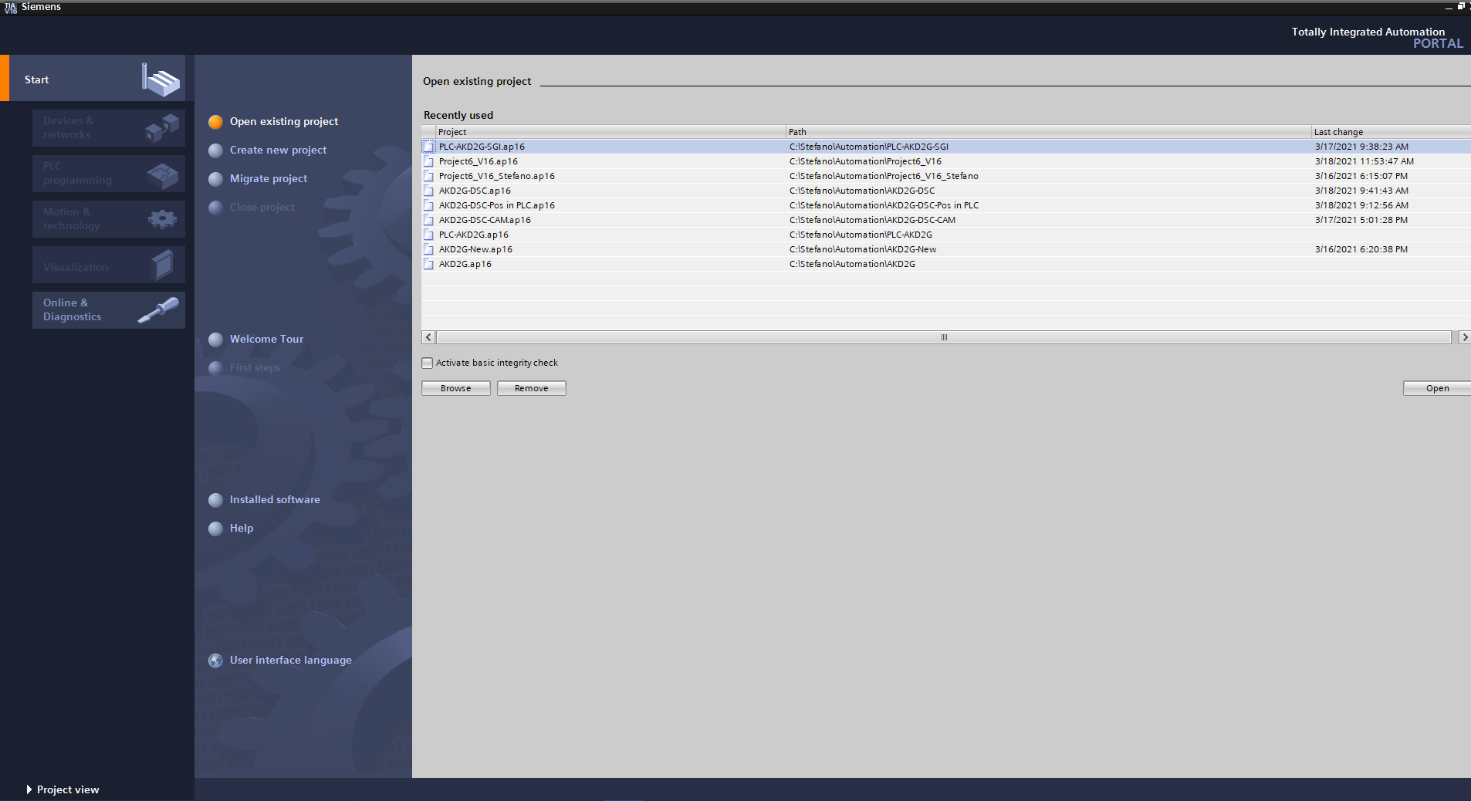
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**System used**

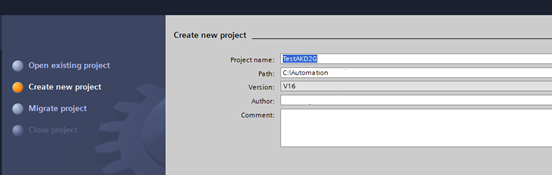
1. One drive Kollmorgen AKD2G-SPP-7V03D-A100-0000 (double axis drive), FW M\_02-06-00-001
2. One Siemens PLC S7-1500 CPU 1511T-1 PN 6ES7 511-1TK01-0AB0
3. Siemens TIA Version V16 (Options: TIA Portal Version Control Interface and TIA Portal Openness)
4. Siemens STEP7 Professional Version V16 (Options: STEP7 Safety)
5. Siemens WinCC Advanced Version V16
6. Kollmorgen Workbench Version 2.7.0.5821
7. Kollmorgen GSDML file Version GSDML-V2.35-KOLLMORGEN-AKD2G-20201208.xml
8. Profinet cable connected in between the PLC Port\_1 (X1.P1) and AKD2G Port 1 (X12).

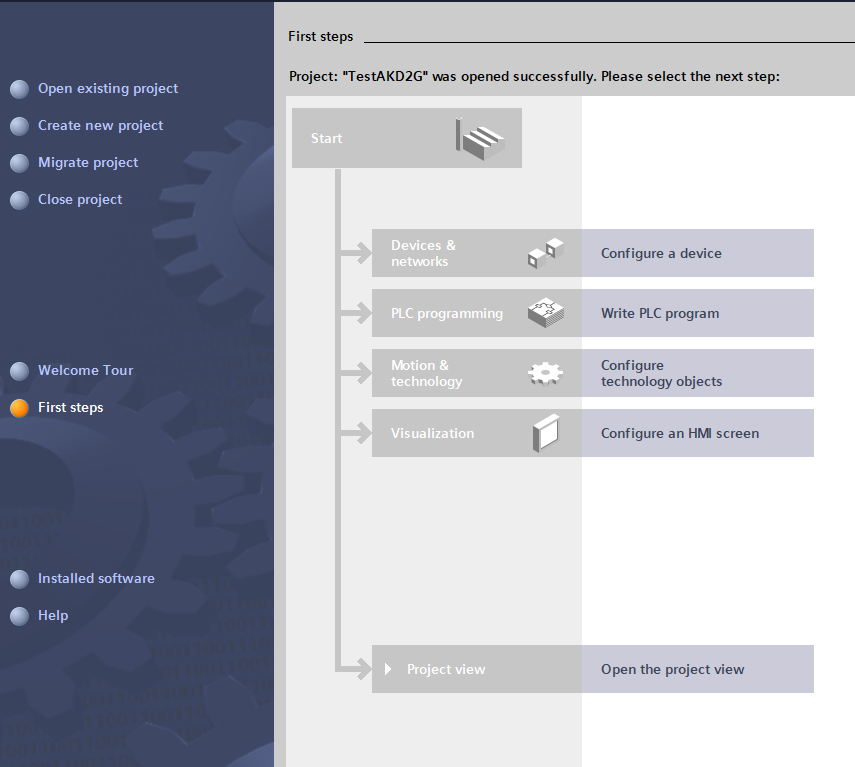
**Start a New Project**

Start TIA.



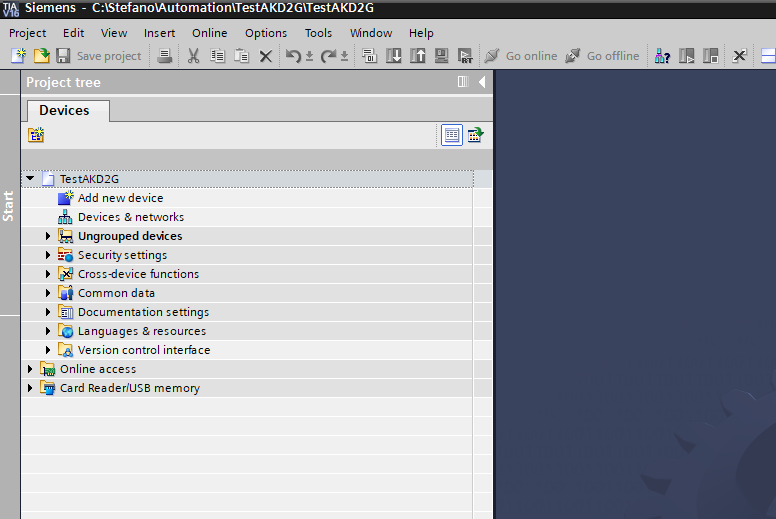
Click on *Create a New Project*, enter a *Project name*, *Path*, *Author* and click on *Create* (right bottom side)



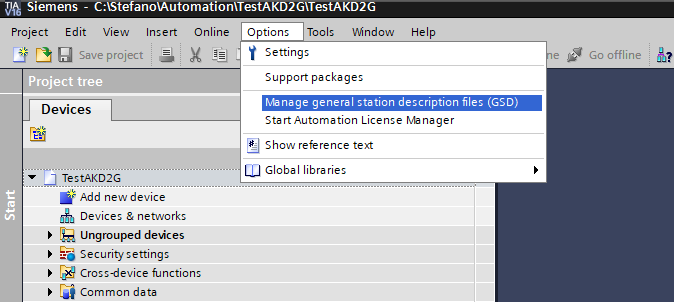


Go on clicking on *Open the project view*.

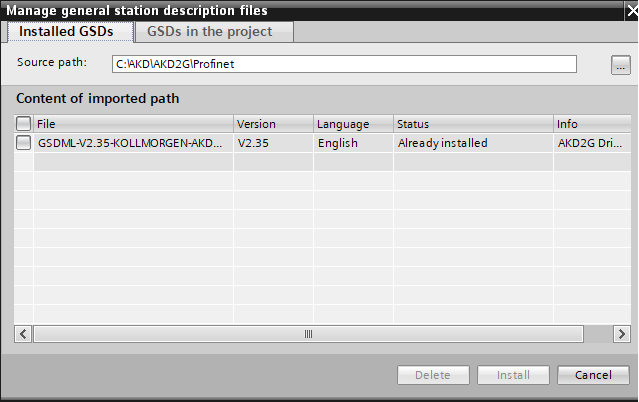
Next step is to import the AKD2G GSDML file.



From the menu *Options* click on *Manage general station description files (GSD)*

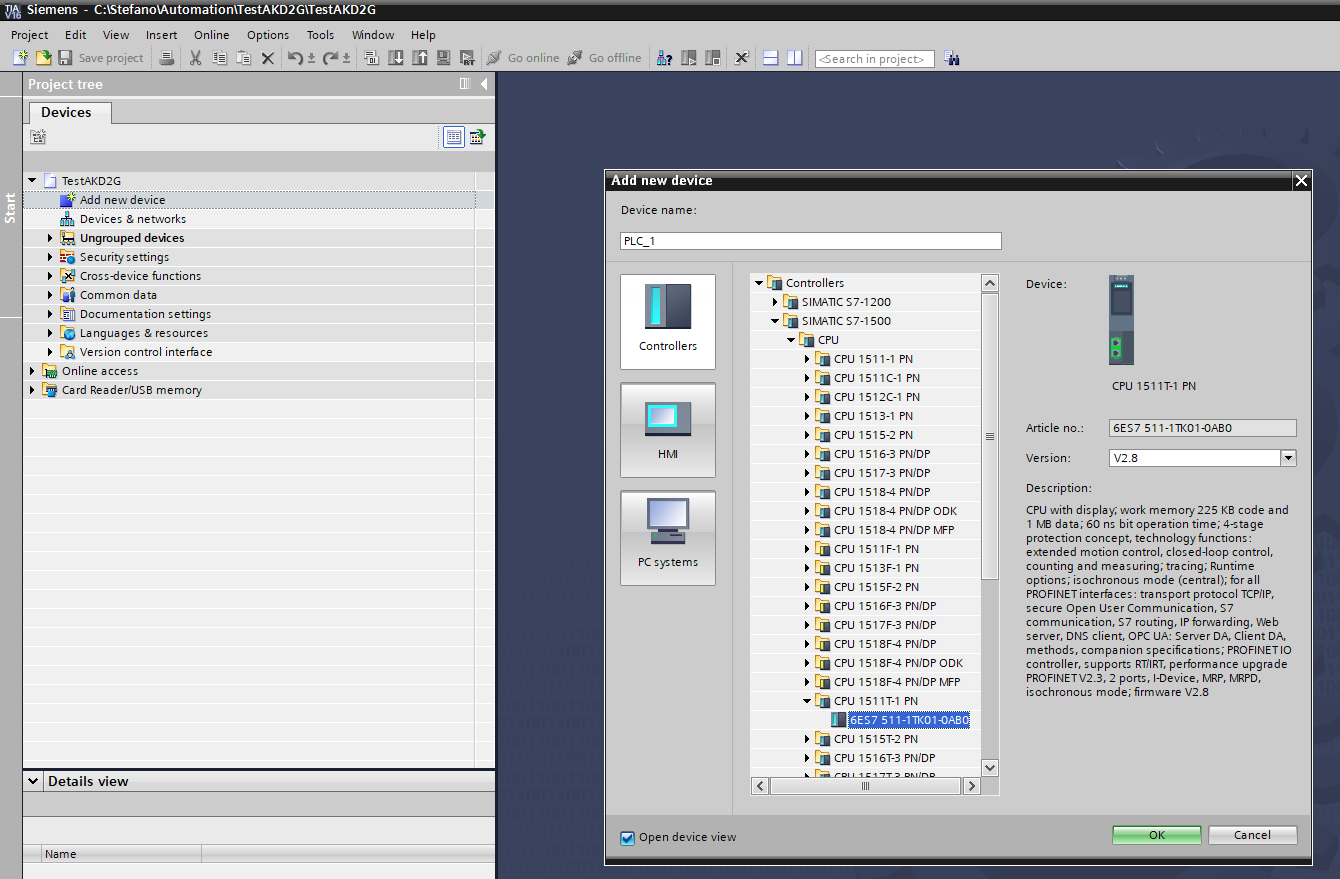


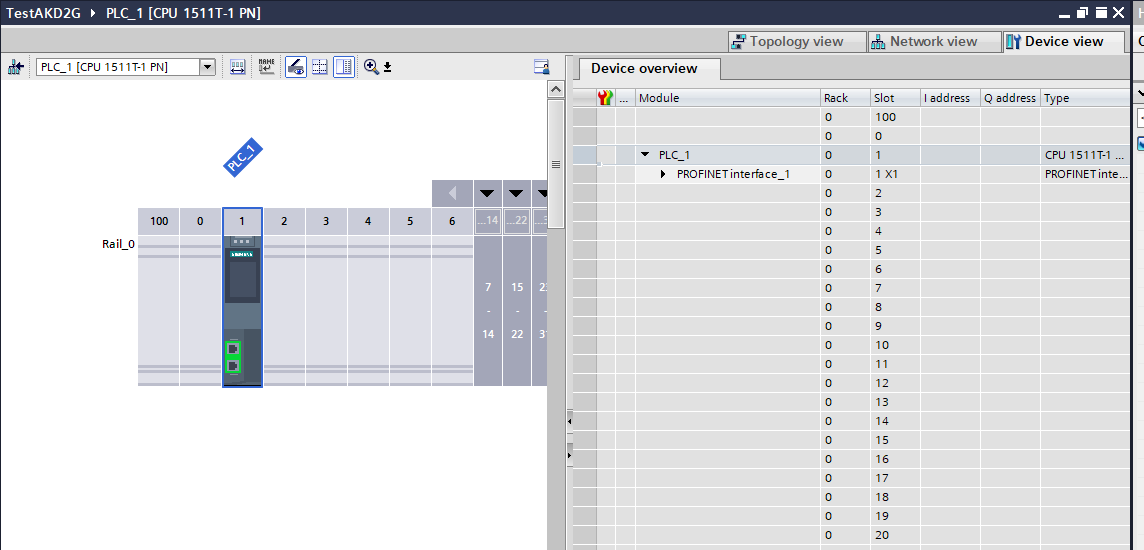
Install the SGDML file *GSDML-V2.35-KOLLMORGEN-AKD2G-20201208.xml*



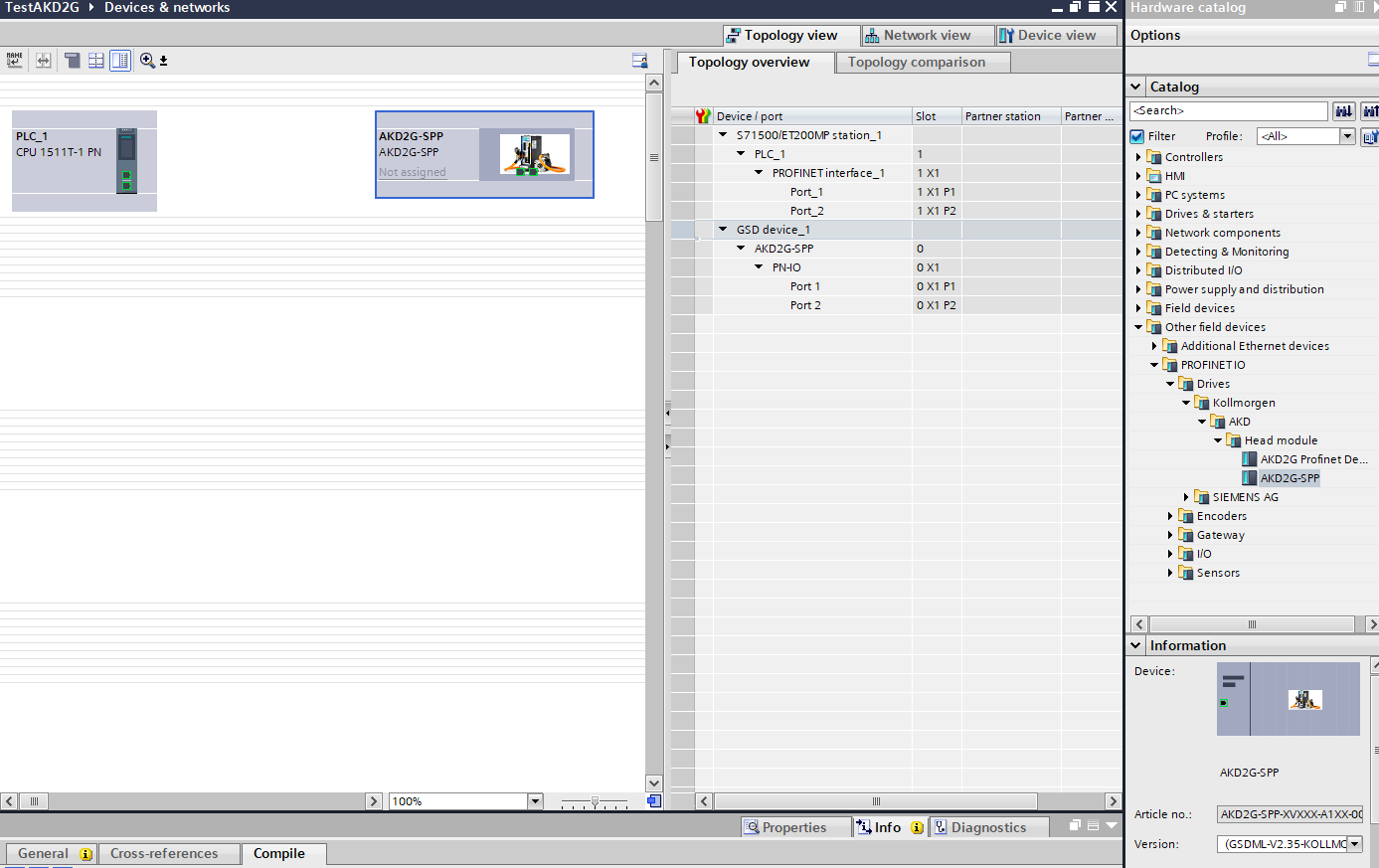
**Adding the devices**

Click on *Add new device* and select the CPU model you are using, in this case a S7-1511T-1 PN *6ES7 511-1TK01-0AB0*



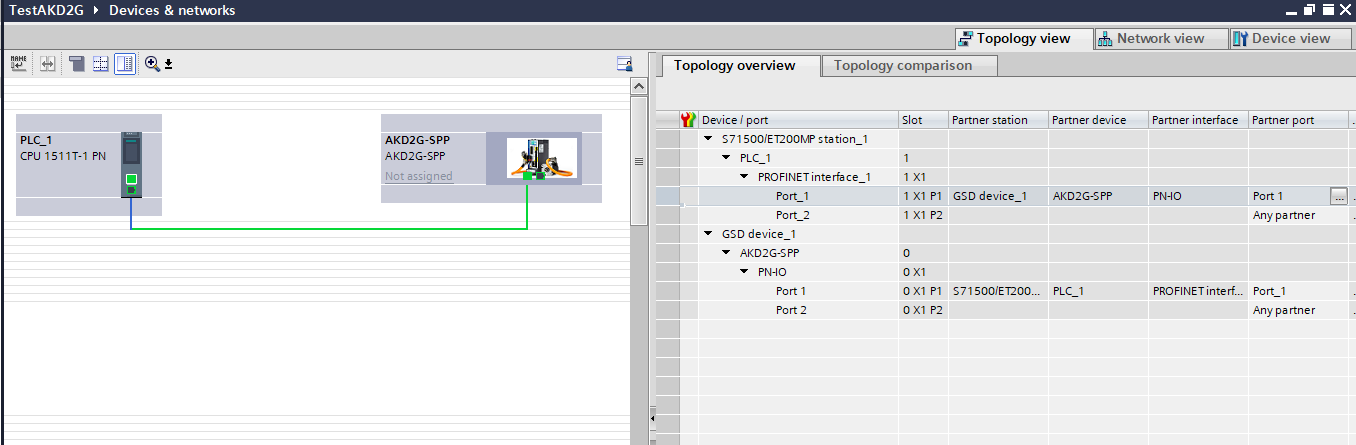


From the *Topology view* insert the *AKD2G-SPP* head module



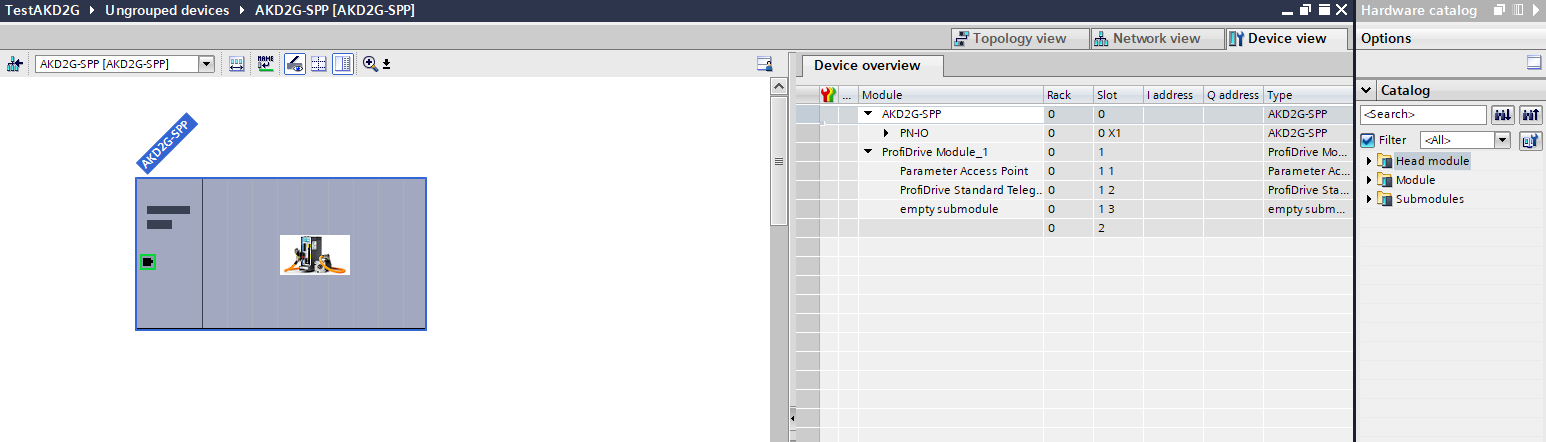
The Profinet cable is connected in between the PLC Port\_1 (X1.P1) and AKD2G Port 1 (X12).

Join the ports:

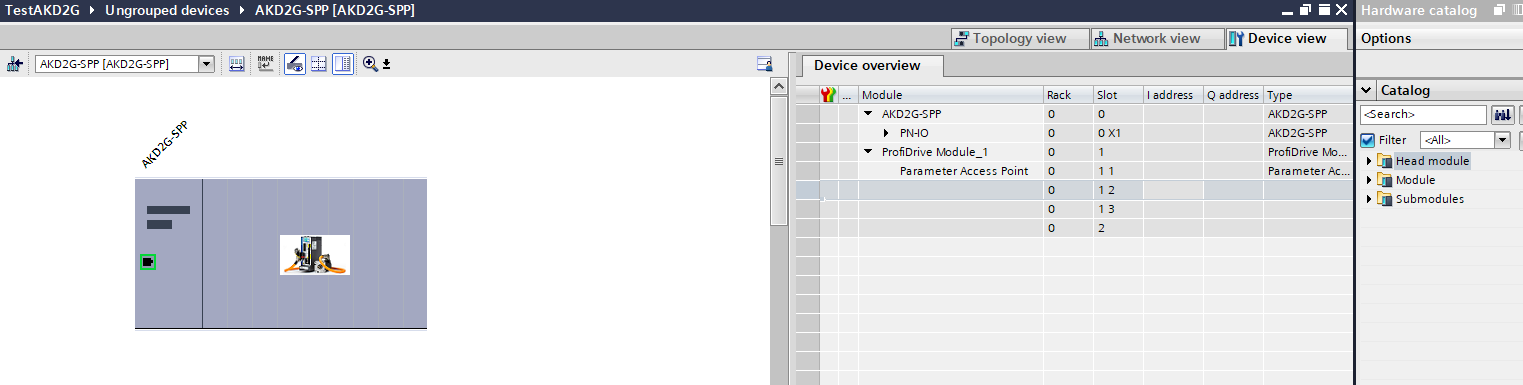


**Configuration of the AKD2G telegram 3**

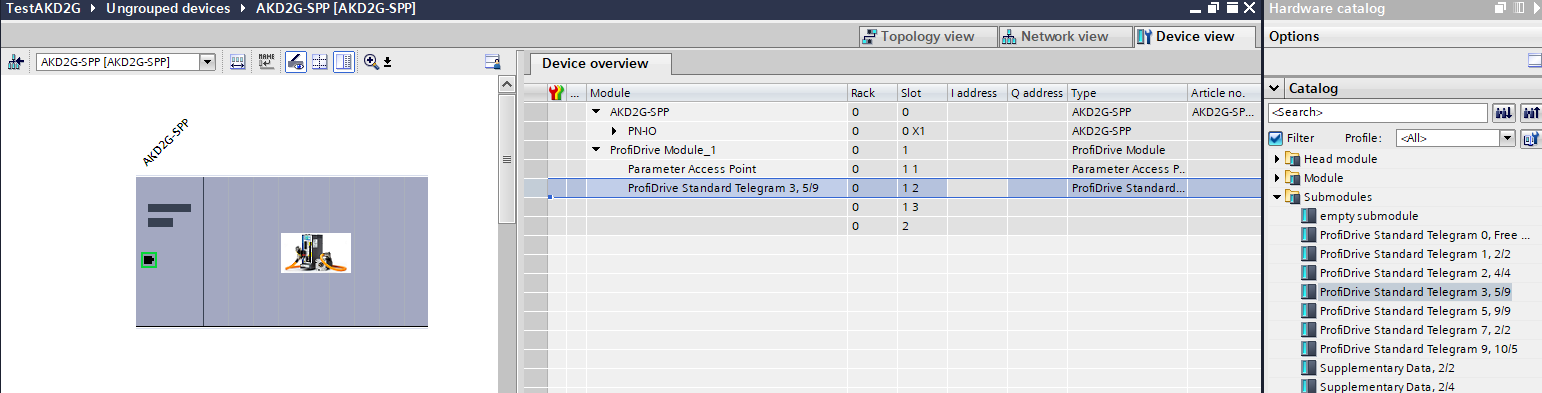
Double-click on AKD2G device:



Delete the *ProfiDrive Standard Telegram* and the *empty submodule* from *Device overview*:

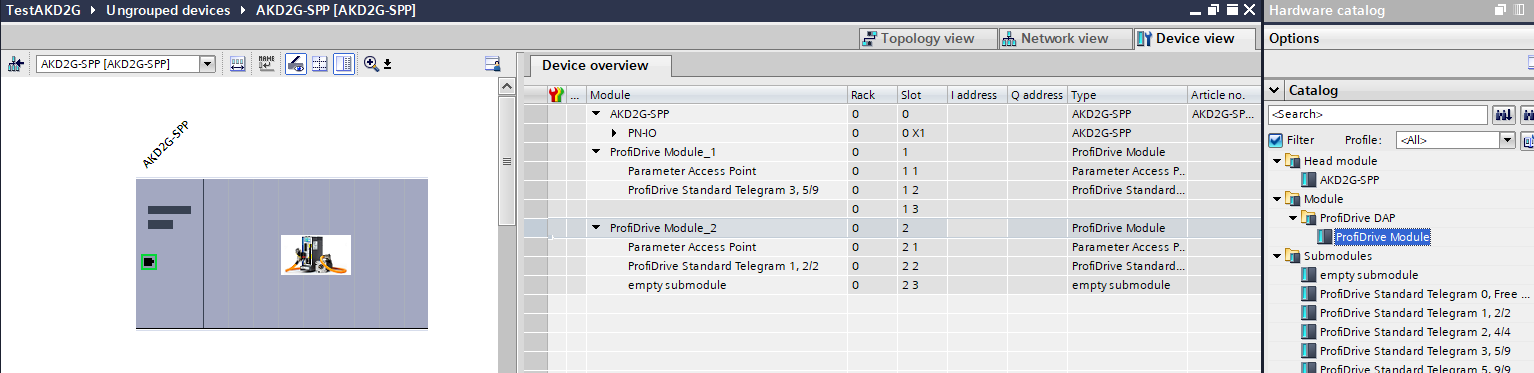


From the right side select *ProfiDrive Standard Telegram 3, 5/9* and drag and drop into *Device overview*:



If the drive is a double axis repeat the operation for the second one.

Select *ProfiDrive Module*, drag and drop:



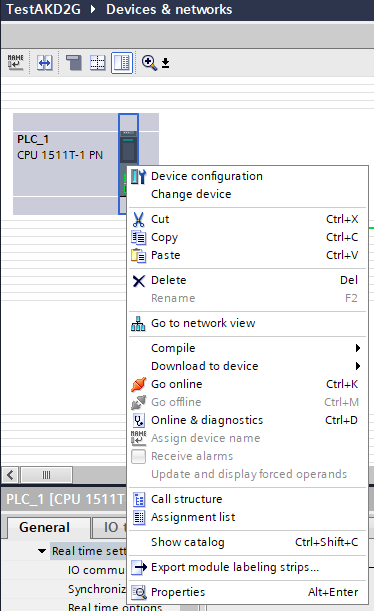
Delete the *ProfiDrive Standard Telegram 1, 2/2* and the *empty submodule*.

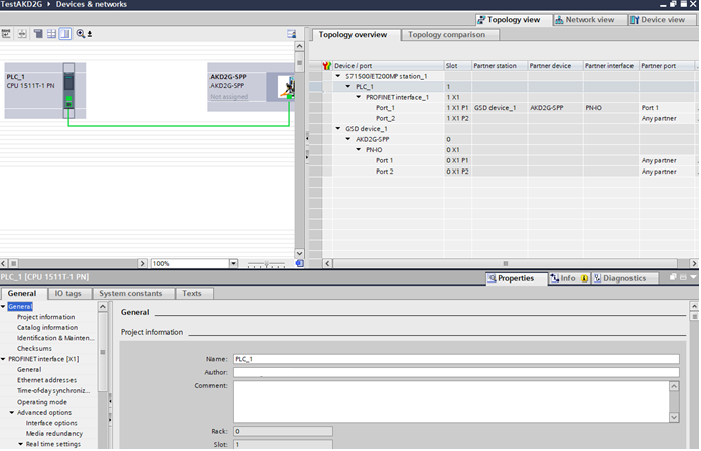
Then drag and drop the *ProfiDrive Standard Telegram 3, 5/9*:



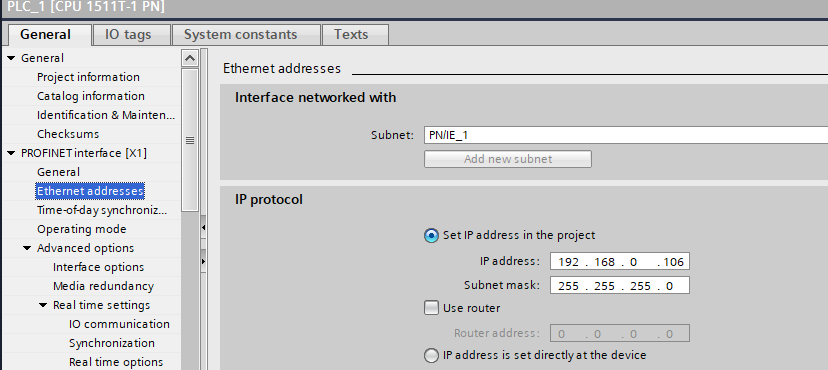
**PLC Configuration**

From the *Topology view* right-click on the PLC slot and select *Properties*:



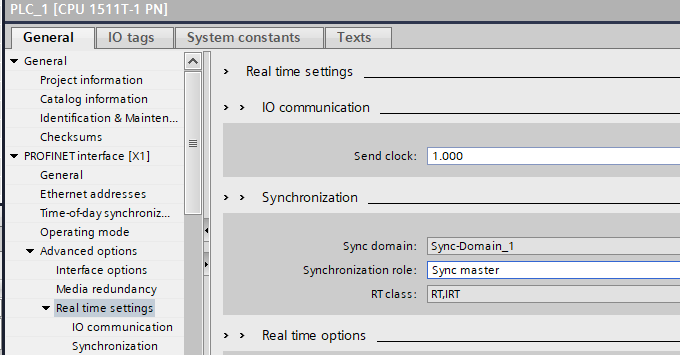


Set up the PLC *Ethernet Addresses*:



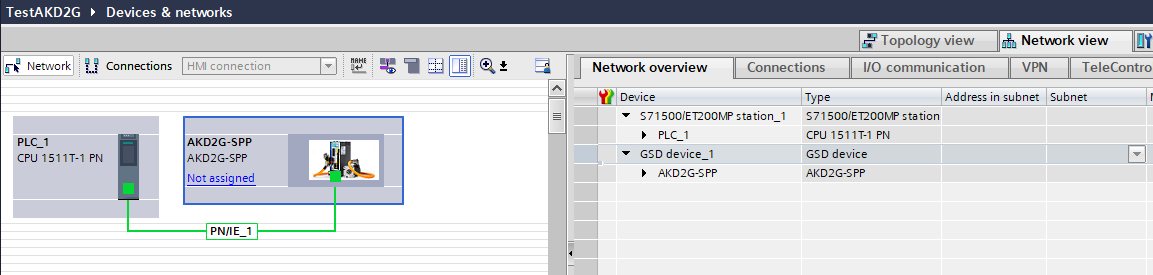
Set up the *Real time settings*:

* Send clock: 1ms
* Synchronization role: Sync master



**Profinet Domain Configuration**

Go to *Network view*:

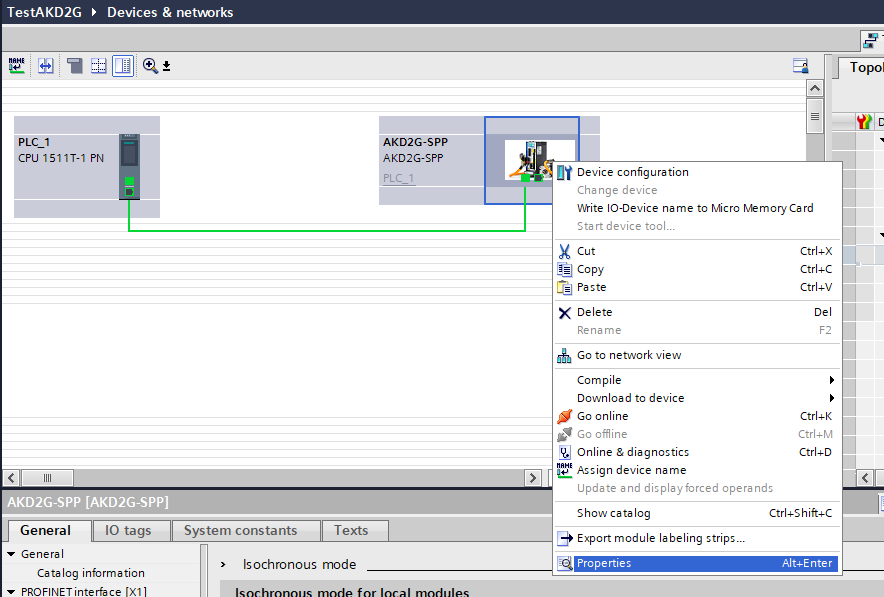


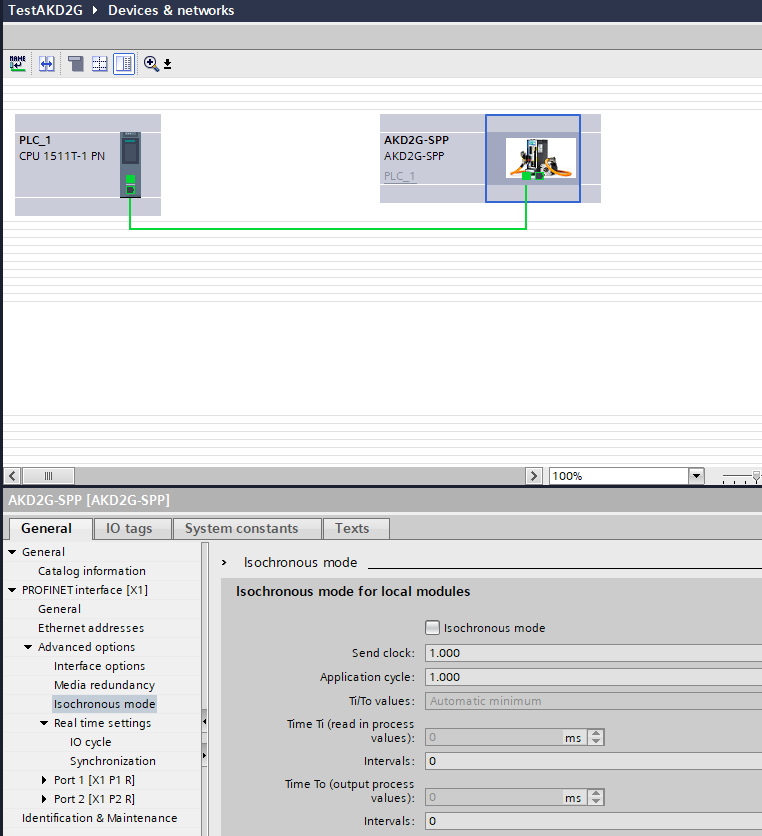
Click on Not assigned and select *PLC\_1.PROFINET interface\_1*:



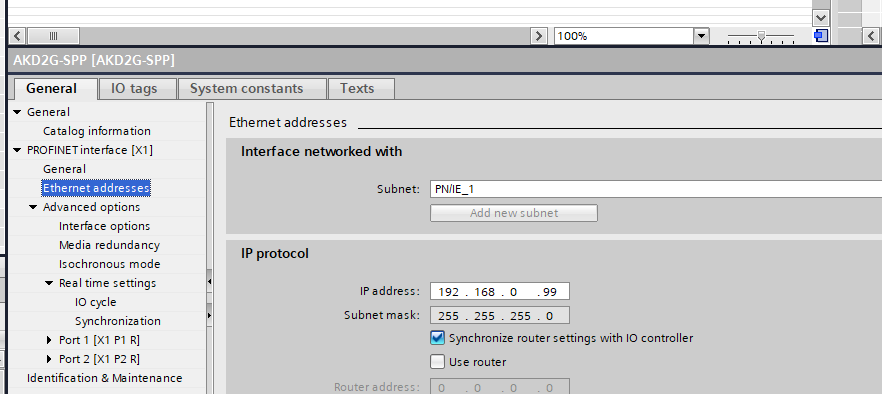
**AKD2G Configuration**

From the *Topology view* right-click on the AKD2G slot and select *Properties*:

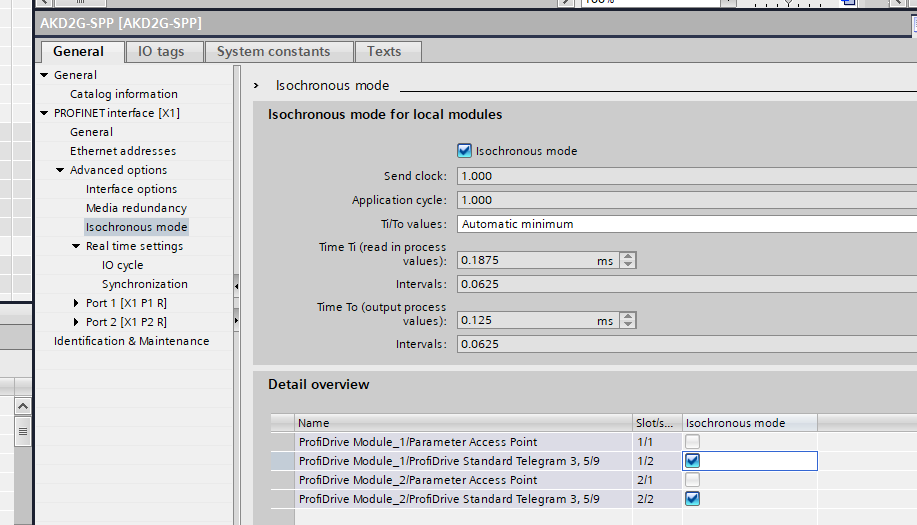




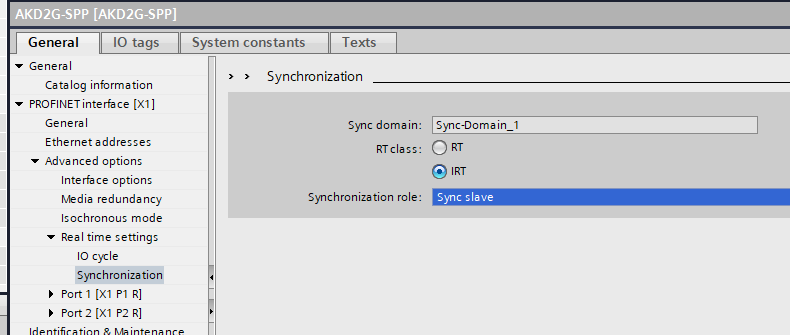
Set up the AKD2G *Ethernet Addresses* (this address must be different than IP address of the drive used by Workbench TCP/IP connection):



Activate the *Isochronous mode* for all the ProfiDrive Modules installed:



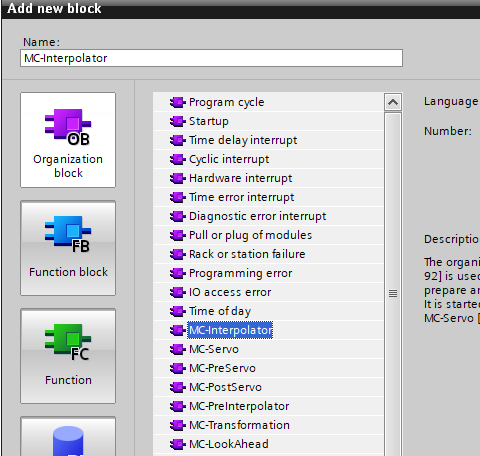
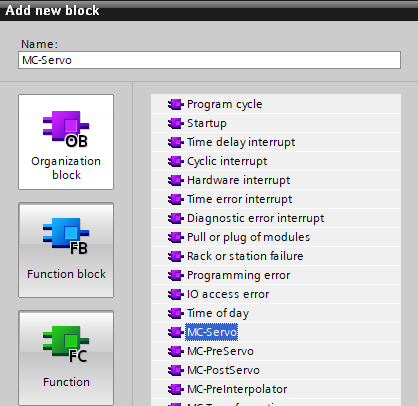
Set up the *Sync domain* to IRT:

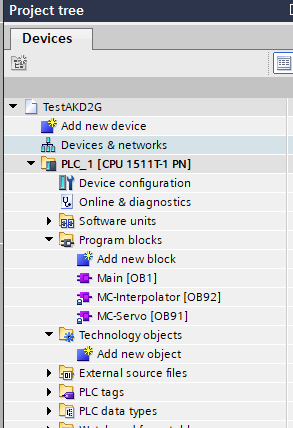


**Program blocks and Technology objects**

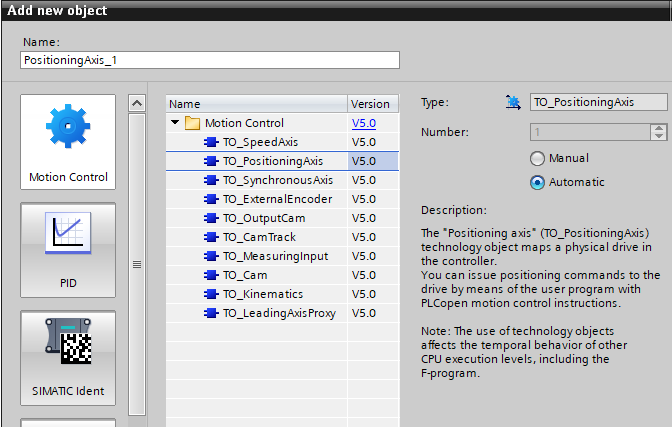
After the HW configuration the following step is to add the SW function blocks and tech objects for managing the axis.

From *Program blocks* click on *Add new block* and add *Organization block* **MC-Interpolator** and **MC-Servo**:

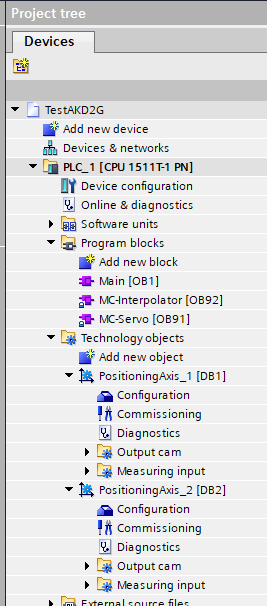
 



From *Technology objects* click on *Add new object* and add **TO\_PositioningAxis**:



If you have a second axis repeat this step. At the end we will have:

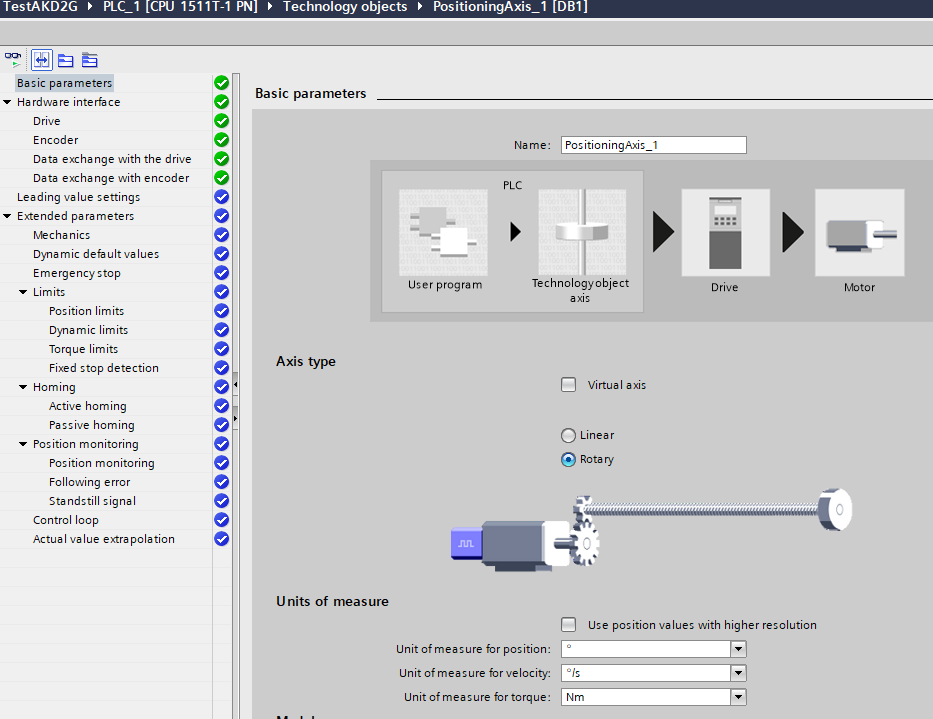


**Technology objects configuration**

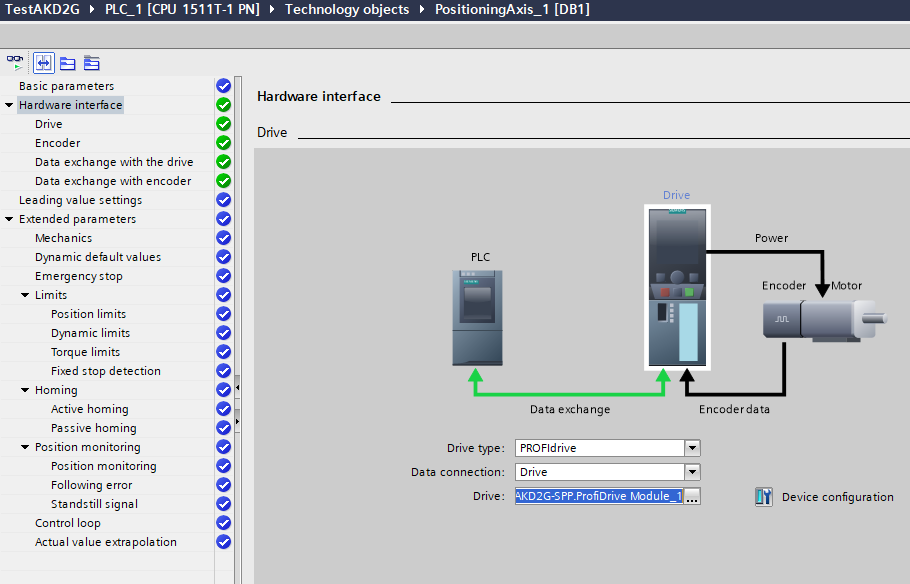
From the tree view, *PositioningAxis\_1* select *Configuration*.

Apply the following settings:

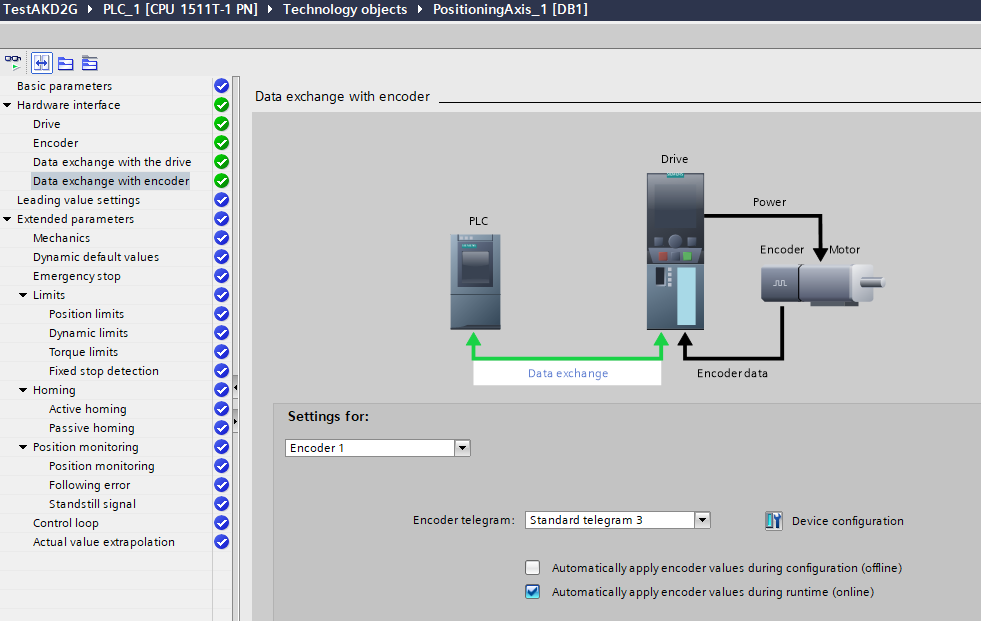
* Axis type: Rotary



* Drive: AKD2G-SPP.ProfiDrive Module\_1

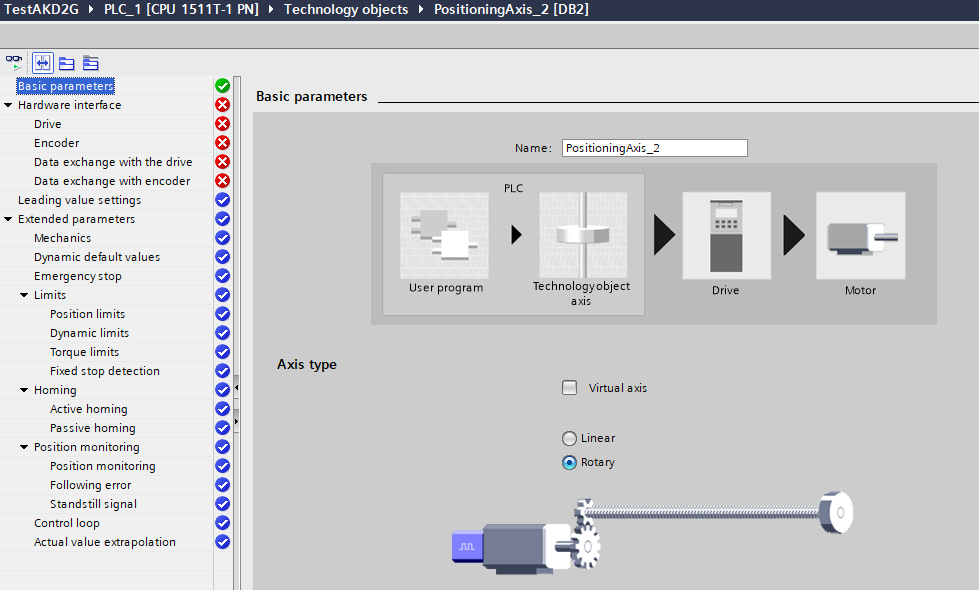


* Data exchange with encoder: Automatically apply encoder values during runtime (online)

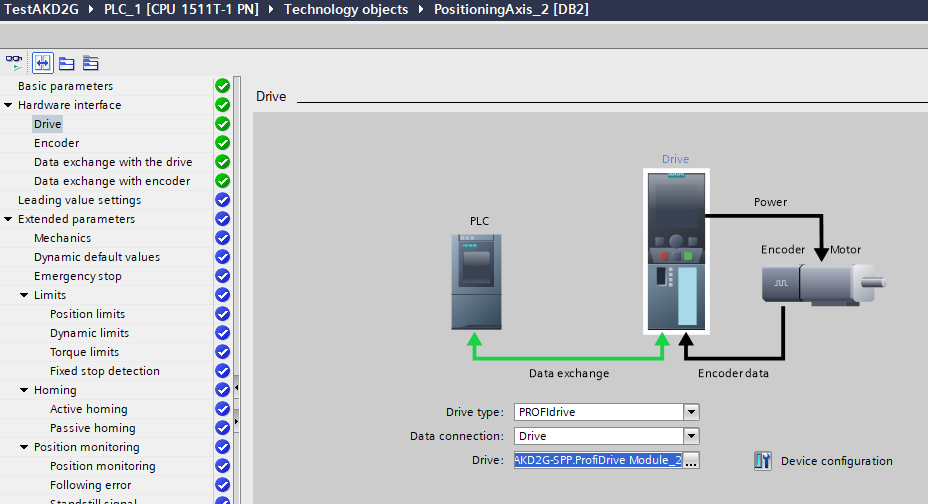


If you have a second axis repeat:

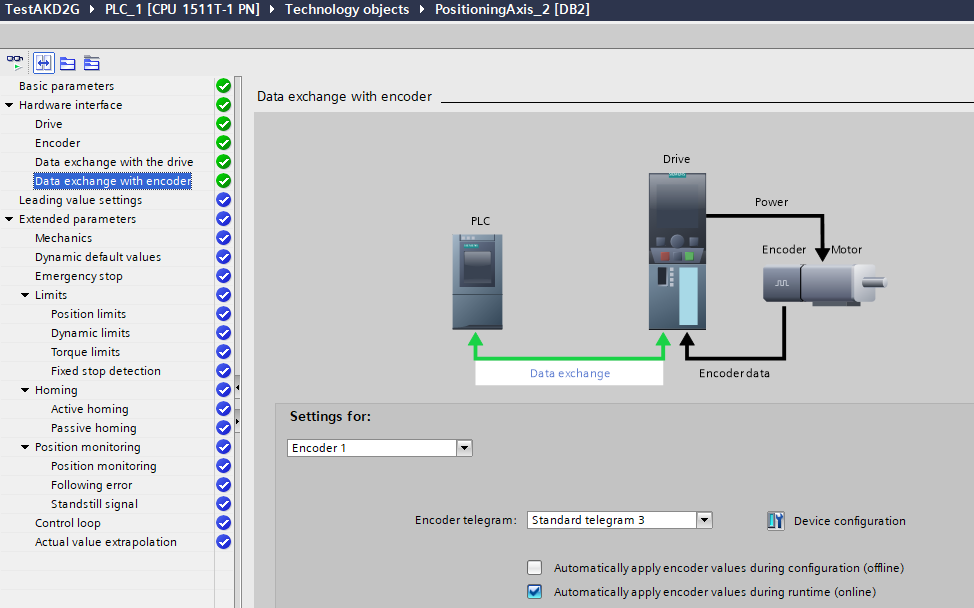
* Axis type: Rotary



* Drive: AKD2G-SPP.ProfiDrive Module\_2



* Data exchange with encoder: Automatically apply encoder values during runtime (online)



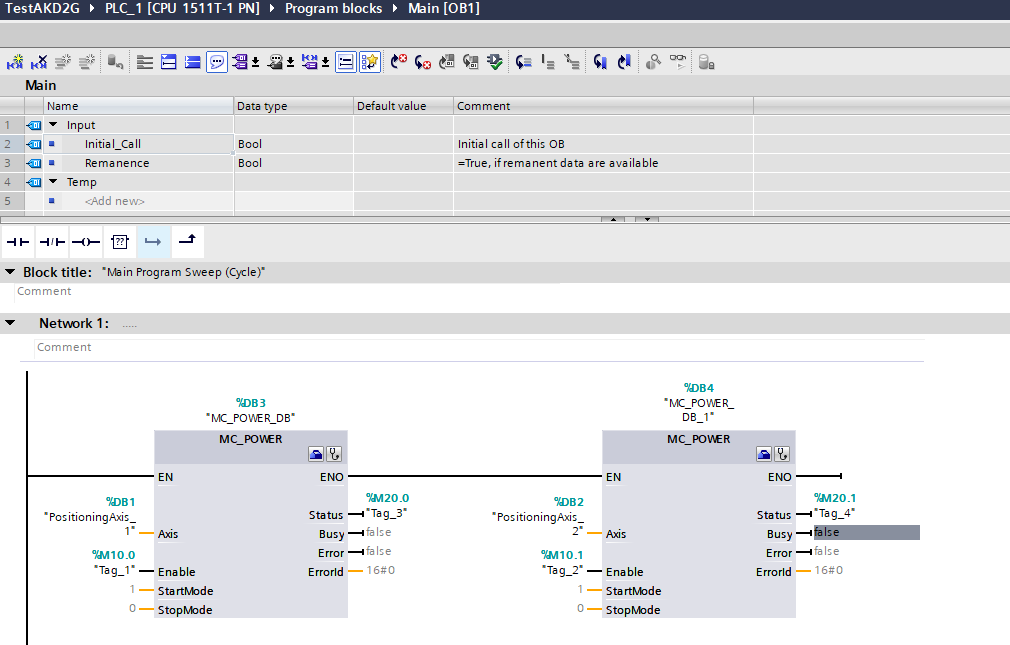
**Adding some Functions**

It’s time to add some Motion Functions inside the cyclic OB1.

Let’s start with:

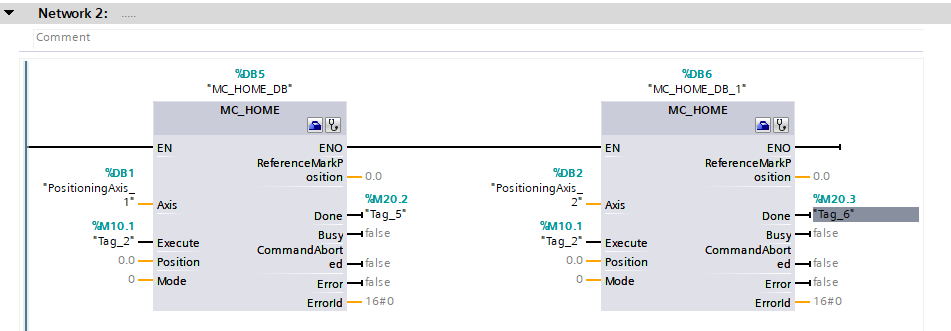
* MC\_Power
* MC\_Home
* MC\_MoveRelative
* SinaParaS (read/write AKD2G parameters)

Open OB1 and add the function *MC\_Power* for all the axes in the project:

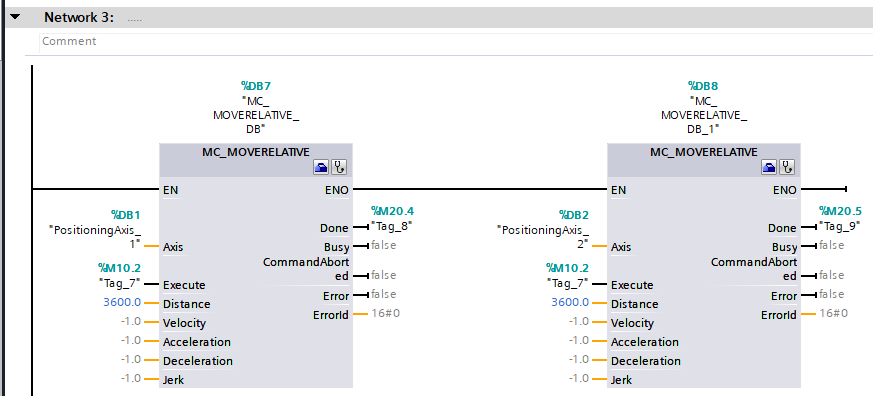


Pay attention to the inputs *Axis* of each function: *PositioningAxis\_1* and *PositioningAxis\_2* must be passed.

Add the function *MC\_Home*:

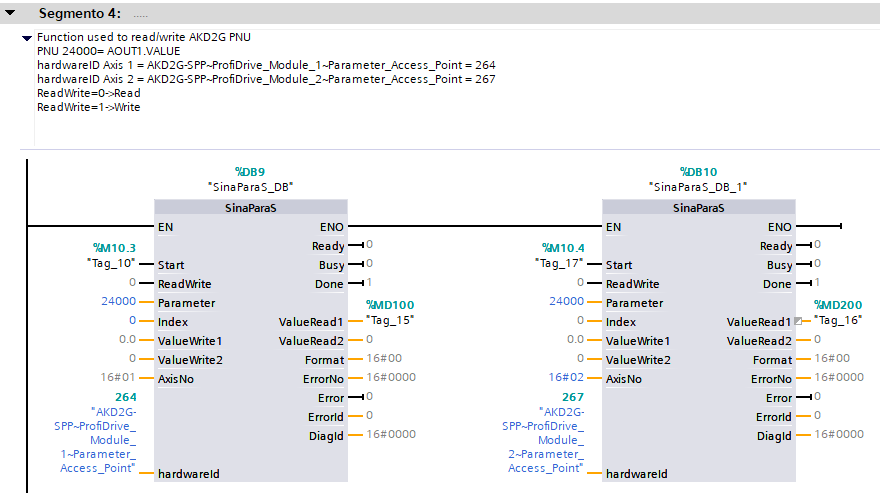


Add the function *MC\_MoveRelative*:



Because of the *PositioningAxis\_X* setting the *Distance* input of 3600.0 makes the motors move 10 turns.

Add the function *SinaParaS*:



This function is used to read/write a drive parameter.

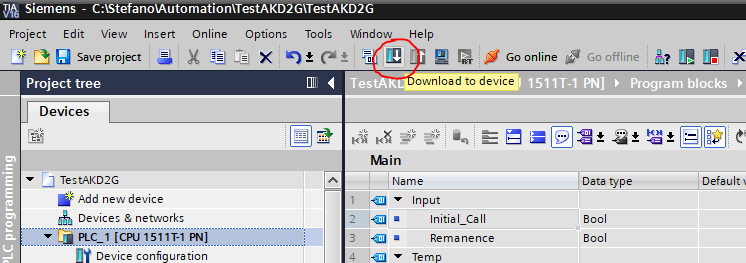
In the network above the PNU24000 is the parameter AOUT1.VALUE

**Compiling and Downloading into PLC**

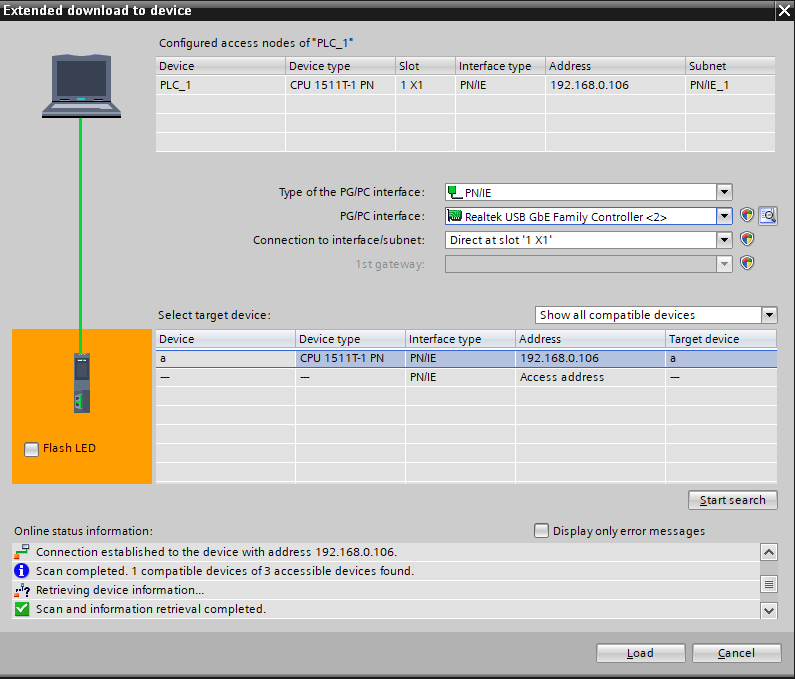
Right-click on *PLC\_1 [CPU 1511T-1 PN]*, select *Compile/Hardware (rebuild all)*.

Right-click on *PLC\_1 [CPU 1511T-1 PN]*, select *Compile/Software (rebuild all)*.

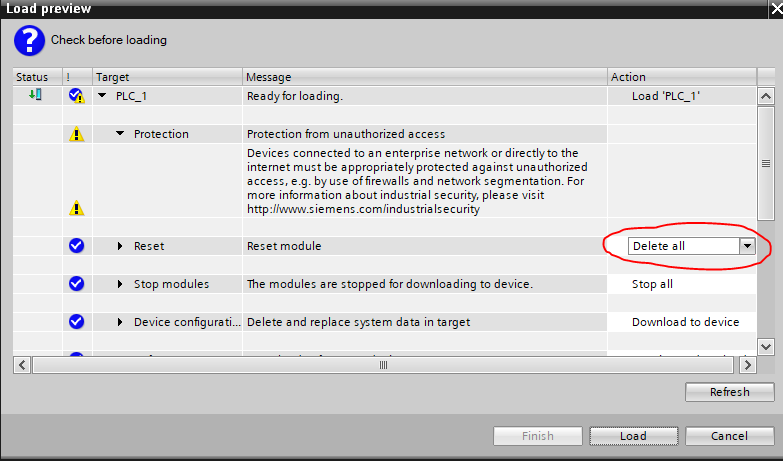
Click on *Download to device*:



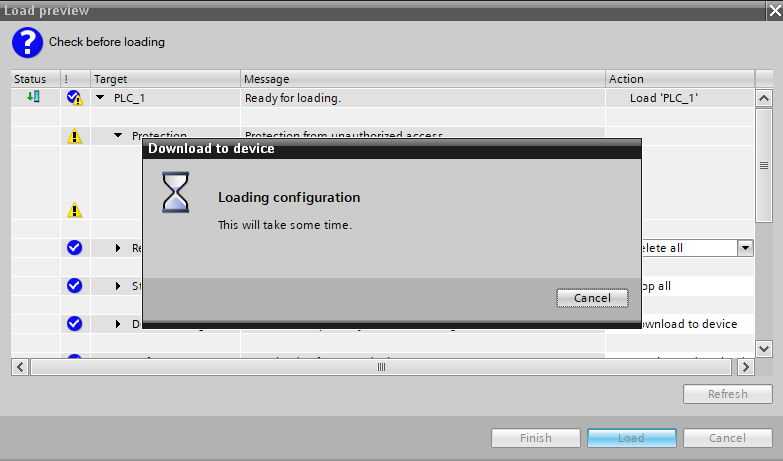
Select the right *PG/PC interface*, click on *Start search* and once found click on *Load*:



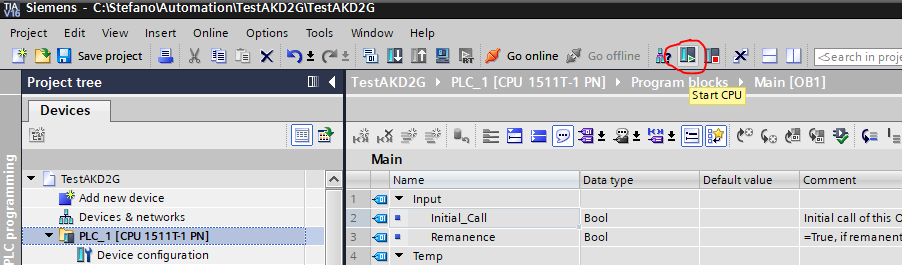
The first time requires to delete all the modules:



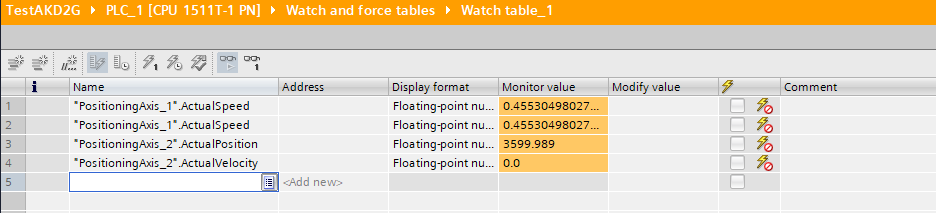
Go on clicking on Load:



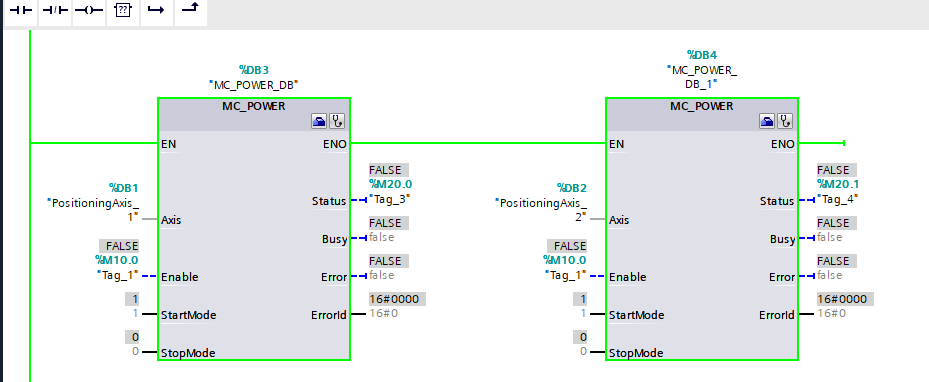
At the end click on *Start CPU*:



Add a new Watch table with some variables:



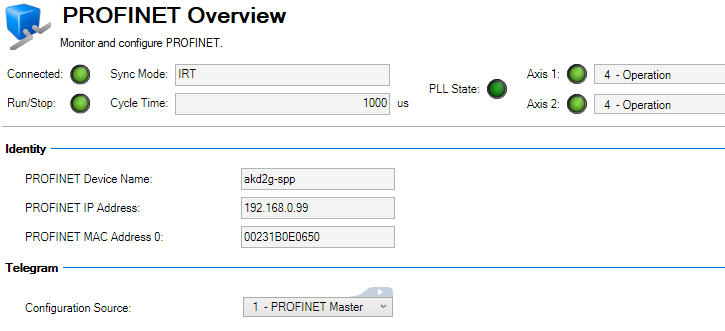
Going Online with OB1 and changing the merkers make it possible to power, home and move the axes:



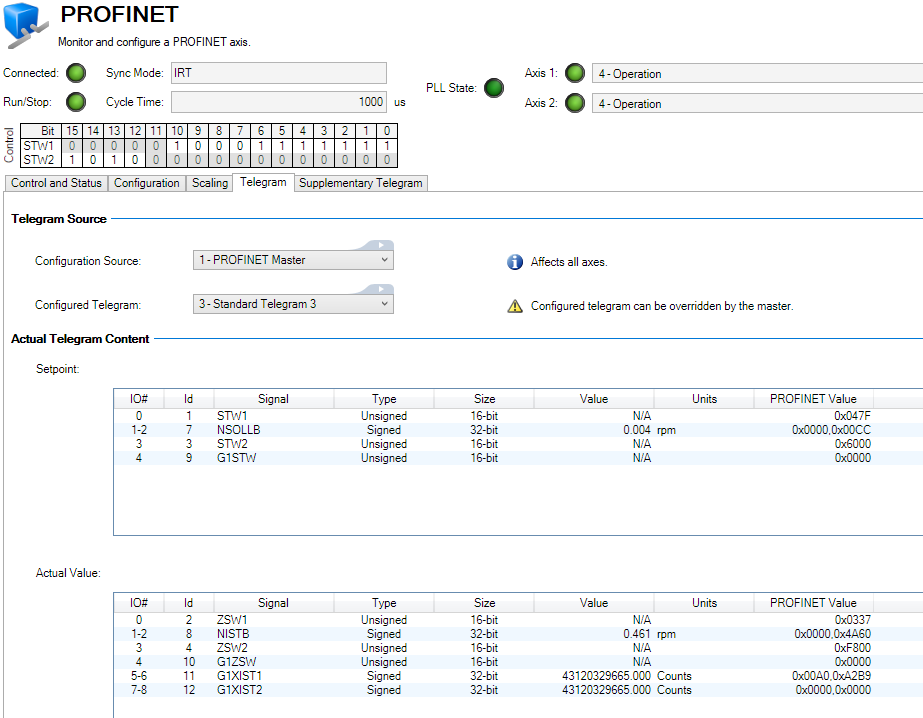
**AKD2G status view from Workbench**

Once the PLC is in run mode, then Workbench can monitor the status.

Profinet Status



AKD2G-AXIS 1 status



AKD2G-AXIS 2 status

