

AKMA Anodized Washdown Motor

Three-Phase AC Permanent Magnet Servo Motor

Catalog



KOLLMORGEN

A REGAL REXNORD BRAND

Kollmorgen: Your Partner, In Motion.

Every solution comes from a real understanding of the challenges facing machine designers and users.

Innovators consistently rate Kollmorgen as one of their best motion systems manufacturing partners. Whether you are looking for classic servo motors, direct-drive servo motors, stepper motors, drives & amplifiers, gearing, actuation, or multi-axis motion controllers, Kollmorgen is one of the few companies in the world that actually designs and manufactures all of these products.

Our customers are leaders in many industries such as Aerospace & Defense, Printing, Packaging & Converting, Food & Beverage Processing, Medical Imaging, In Vitro Diagnostics & Laboratory Automation, Pharmaceutical Manufacturing, Material Forming and Cutting, Oil & Gas, and Robotics. Kollmorgen is also a leader in Warehouse Automation, including complete AGV systems, software, awareness and autonomy.

Our Automation Solutions can be found on Mars and in space, ships and submarines, O&G drilling and metrology, surgical robots and laser eye surgery, even inside artificial hearts. These are just a few applications that demand high-performance and high-quality while satisfying their specific needs.

Because motion matters, it's our focus: Motion can distinctly differentiate a specific machine and deliver a marketplace advantage by increasing its performance and dramatically improving Overall Equipment Effectiveness (OEE).

High-performance motion can make your customer's machine more reliable and energy-efficient, enhance accuracy and improve operator safety. Motion also represents endless possibilities for innovation.

We've always understood this potential, and thus have kept motion at our core and in our Vision, Mission & Values, relentlessly developing products that offer precise control of torque, velocity and position accuracy in machines that rely on complex motion.

Removing the Barriers of Design, Sourcing, and Time

At Kollmorgen, we know that OEM engineers can achieve a lot more when obstacles aren't in the way. So, we clear obstacles in three important ways:

Integrating Standard and Custom Products

The optimal solution is often not clear-cut. Our application expertise allows us to modify standard products or develop totally custom solutions across our whole product portfolio so that designs can take flight.

Providing Motion Solutions, Not Just Components

As companies reduce their supplier base and focus their engineering manpower on the product design, they need a total system supplier with a wide range of integrated solutions. Kollmorgen offers complete solutions as well as motion subsystems that combine programming software, engineering services and best-in-class motion components.

Global Footprint

With direct sales, engineering support, manufacturing facilities, and distributors spanning the Americas, Europe, the Middle East, and Asia, we're close to OEMs worldwide. Our proximity helps speed delivery and lend support where and when they're needed.

Financial and Operational Stability

Kollmorgen is part of Regal Rexnord. A key driver in the growth of all Regal Rexnord segments is the Regal Rexnord Business System, which relies on the principle of "kaizen" – or continuous improvement. Using world-class tools, cross-disciplinary teams of exceptional people evaluate processes and develop plans that result in superior performance.

Kollmorgen: Your partner. In Motion.

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AKMA Anodized Washdown Motors

Designed for Fast Cleaning and Increased Uptime. The AKMA motor is designed to meet the standards for IP69K and is built with FDA approved, food-grade seals, cable connector, vent and shaft. The careful elimination of flat surfaces, cracks, and crevices prevents the build-up of foreign material and bacteria. The AKMA housing and cable can endure daily wash-downs with high pressure and high temperature. The robust design means that guards and covers are not required to protect the motor from harsh cleaning regimens. These AKMA features constitute quicker cleaning, more reliable machine performance and the increase of OEE for the entire manufacturing line.

Reduced Recall Risk. The Food Modernization Safety Act (FMSA) gives the US federal government the ability to shut down facilities, recall food products, and levy stiff fines to ensure public safety in regards to food manufacturing. The AKMA is designed to meet the toughest hygienic requirements in the industry in order to reduce the possibility of food borne illnesses and costly recalls.

Bottom Line. With 15 standard motor sizes, multiple standard windings, feedback options and vast Co-Engineering possibilities, the AKMA motor can be a great fit for diverse applications in industries such as food & beverage and pharmaceutical. Kollmorgen's AKMA environmental solutions help maintain the highest standard of machine cleanliness and increase OEE by reducing the risk of potentially devastating supplier/ government recalls.





The Benefits of AKMA Motors

- » Increase your machine's Overall Equipment Effectiveness (OEE) with water and chemical resistant designs that maximize motor **reliability**
 - » Reduce your machine's total cost of ownership with shortened cleaning times and improved **durability**
 - » Enhance the value of your machine by **lowering** your customer's **risk of recall** through the superior hygienic design of AKMA
 - » IP69K certification of motor and cable inside the washdown environment
 - » Unique design technique to eliminate condensation inside the motor
 - » FDA Approved, food-grade O-ring seals
 - » Motor shaft material is 316L or DIN 1.4404 Stainless Steel; superior to 303/304 for corrosion resistance
 - » Round design with no nooks or crannies
 - » Sloped rear cover and connector mounting surface to eliminate puddling, even in vertical mounting
 - » No external hardware (no bolts, washers, or screws) to trap soil or pathogens or fall into food
 - » Smooth surface meeting, promotes rapid cleaning and no harboring of pathogens
 - » FDA Approved, food-grade bearing lube
 - » FDA Approved, food-grade shaft seal
 - » Cable designed to eliminate the need for conduit
 - » Hygienic, IP69K shaft seal includes special shaft treatment for long life
 - » No protective covers needed for washdown; no secondary cleaning disassembly required
 - » Hygienic marking method eliminates harboring of pathogens
 - » IP69K vent that equalizes pressure when temperature drops; e.g., during wash-down
-
- » Innovative design features **reduce** associated **cost and time** of installation.
 - » Industry leading configurability for **optimized performance**
 - » 15 frame/stack length options
 - » Windings designed for optimized machine performance
 - » Cables designed for direct connection to AKD2G, AKD, and Kollmorgen Essentials servo drives (plug & play)
 - » Stainless steel connectors on motor and cables
 - » Flange mount for easy installation into application
 - » Holding brake option
 - » Single cable connection
 - » Multi-turn absolute feedback option; single-turn absolute feedback
 - » HIPERFACE DSL and EnDAT 2.2 functional safety capable feedback options
 - » Motor auto setup with AKD/AKD2G and Kollmorgen Essentials servo drives
 - » CE/RoHS/IP69K certifications

Specify only Kollmorgen AKMA systems to ensure:

- » Reduced risk of food recall
- » Reduced cleaning time, higher OEE
- » Highest reliability and durability

AKMA Design Features

The key benefits of AKMA hygienic design features:

- Reduces risk of food recall
- Increases reliability in wash-down applications
- Reduces cleaning time: higher OEE

● No protective covers required
● for washdown... no secondary cleaning disassembly required

● Smooth surface promotes rapid cleaning and no harboring of pathogens

“One-piece” housing structure eliminating the O-ring and enhancing water-ingress prevention capability

Hard anodized coating with strong chemical resistance with wide pH range for withstanding common cleaning agents and enhancing durability in washdown

● Aluminum material allows for higher torque density than stainless steel motors

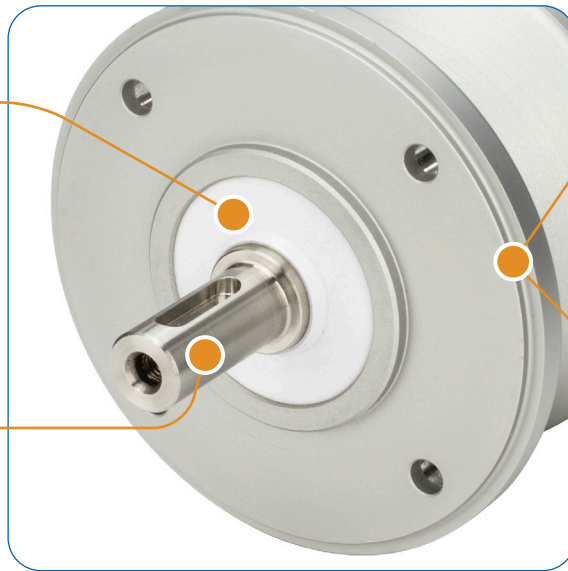
Standard single cable for cable cost savings, space savings, flexibility, and fewer places to harbor pathogens

● Water-tight cable exit

Chemical resistant cable for pH of 2-12, meeting IEC60364-5-52, UL, CSA, CE, RoHS

- Hygienic, IP69K shaft
- seal, special shaft
- treatment for long life

Flange Mount for easy mounting



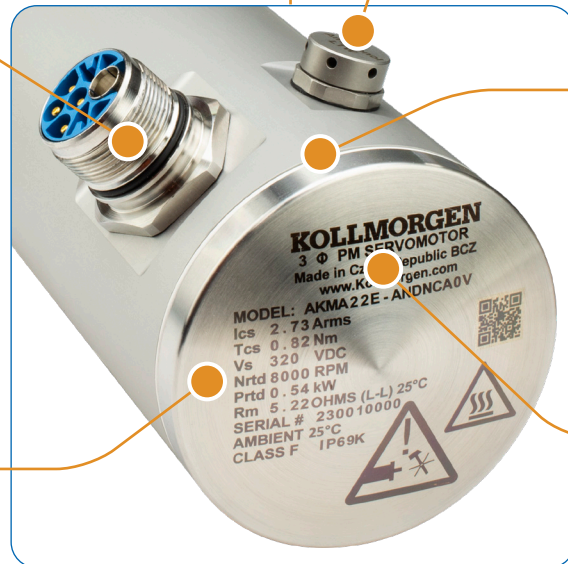
Flange compatible with common gearboxes

- Stainless steel shaft with high durability & capability to meet functional safety requirement

Unique vented connector design equalizes pressure in and outside the motor to prevent condensation inside the housing during changes of temperature

- Standard connector for easy mounting & maintenance

Viton or EPDM O-ring and gasket sealing with FDA approved materials



- Conical end cover to eliminate water puddling, even in vertical mounting

Hygienic marking method eliminates harboring of pathogens

AKMA Performance Overview

Parameters	Sym	Units	AKMA2x				AKMA3x		
			1	2	3	4	1	2	3
Continuous Torque	T_c	Nm	0.45	0.82	1.13	1.36	1.18	2.05	2.84
Rated Speed	N_{rt}	rpm	8000	8000	8000	8000	6000	6000	5500
Rotor Inertia	J_r	kg·cm ²	0.11	0.16	0.22	0.27	0.33	0.59	0.85

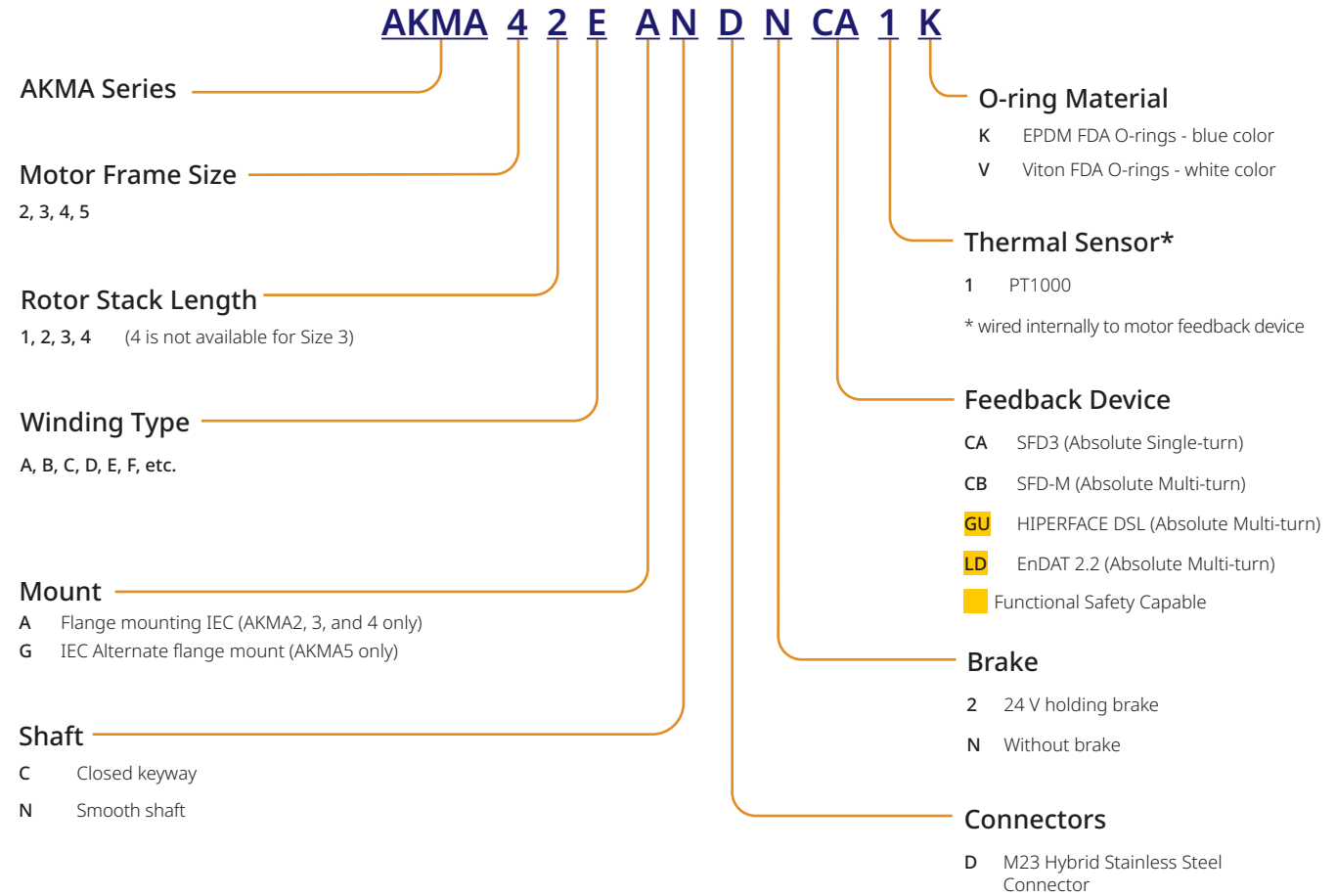
Parameters	Sym	Units	AKMA4x				AKMA5x			
			1	2	3	4	1	2	3	4
Continuous Torque	T_c	Nm	1.89	3.39	4.63	5.63	4.62	8.20	10.9	13.4
Rated Speed	N_{rt}	rpm	6000	6000	6000	6000	6000	6000	6000	6000
Rotor Inertia	J_r	kg·cm ²	0.81	1.5	2.1	2.7	3.4	6.2	9.1	12.0

Values shown are representative of each model. For exact information refer to the selection guide, installation manual, Motioneering and design tools.



AKMA Servo Motor Nomenclature

AKMA Brushless Servo Motor



AKMA2x Performance Data

AKMA2x Performance Data – Up to 640 Vdc

Parameters	Tol	Symbol	Units	AKMA21			AKMA22			AKMA23				AKMA24			
				C	E	G	C	E	G	C	D	E	F	C	D	E	F
Max Rated Voltage	Max	Vbus	Vac	240	120	-	480	240	120	480	480	240	240	480	480	240	240
			Vdc	320	160	75	640	320	160	640	640	320	320	640	640	320	320
Continuous Torque (Stall) for ΔT winding = 100 °C ①②④⑦	Nom	T _{CS}	Nm	0.43	0.44	0.45	0.79	0.81	0.82	1.08	1.10	1.11	1.13	1.32	1.35	1.35	1.36
			lb-in	3.8	3.9	4.0	7.0	7.2	7.3	9.6	9.7	9.9	10.0	11.7	11.9	12.0	12.0
Continuous Current (Stall) for ΔT winding = 100 °C ①②④⑦	Nom	I _{CS}	A _{RMS}	1.58	3.11	4.87	1.39	2.73	4.82	1.41	2.19	2.78	4.31	1.42	2.21	2.79	3.89
Continuous Torque (Stall) for ΔT winding = 60 °C ②④⑦	Nom	T _{CS}	Nm	0.33	0.34	0.35	0.61	0.63	0.64	0.84	0.85	0.86	0.87	1.03	1.04	1.05	1.05
			lb-in	2.9	3.0	3.1	5.4	5.6	5.6	7.4	7.5	7.6	7.7	9.1	9.2	9.3	9.3
Max Mechanical Speed ⑤	Nom	N _{max}	rpm	8000	8000	8000	8000	8000	8000	8000	8000	8000	8000	8000	8000	8000	8000
Peak Torque ①②	Nom	T _p	Nm	1.47	1.49	1.51	2.73	2.76	2.79	3.77	3.84	3.86	3.88	4.73	4.76	4.79	4.82
			lb-in	13.0	13.2	13.4	24.2	24.4	24.7	33.4	34.0	34.2	34.3	41.9	42.1	42.4	42.7
Peak Current	Nom	I _p	A _{RMS}	6.3	12.4	19.5	5.6	10.9	19.3	5.6	8.8	11.1	17.2	5.7	8.8	11.2	15.6
Rated Torque (speed) ①②④⑦	75 Vdc	T _{rtd}	Nm	-	0.43	0.41	-	0.80	0.78	-	-	-	1.10	-	-	-	1.34
			lb-in	-	3.8	3.7	-	7.1	6.9	-	-	-	9.8	-	-	-	11.9
Rated Speed	75 Vdc	N _{rtd}	rpm	-	2000	4000	-	1000	2500	-	-	-	1500	-	-	-	1000
Rated Power (speed) ①②④⑦	75 Vdc	P _{rtd}	kW	-	0.09	0.17	-	0.08	0.20	-	-	-	0.17	-	-	-	0.14
			Hp	-	0.12	0.23	-	0.11	0.27	-	-	-	0.23	-	-	-	0.19
Rated Torque (speed) ①②④⑦	120 Vdc / 160 Vdc	T _{rtd}	Nm	0.41	0.37	0.36	0.78	0.76	0.69	1.06	1.07	1.05	1.02	-	1.31	1.29	1.28
			lb-in	3.6	3.2	3.2	6.9	6.7	6.1	9.4	9.5	9.3	9.1	-	11.6	11.4	11.4
Rated Speed	120 Vdc / 160 Vdc	N _{rtd}	rpm	2500	7000	8000	1000	3500	7000	1000	1500	2500	4500	-	1500	2000	3000
Rated Power (speed) ①②④⑦	120 Vdc / 160 Vdc	P _{rtd}	kW	0.11	0.27	0.30	0.08	0.28	0.50	0.11	0.17	0.28	0.48	-	0.21	0.27	0.40
			Hp	0.14	0.36	0.40	0.11	0.37	0.67	0.15	0.23	0.37	0.65	-	0.28	0.36	0.54
Rated Torque (speed) ①②④⑦	240 Vdc / 320 Vdc	T _{rtd}	Nm	0.34	-	-	0.73	0.65	-	1.03	0.98	0.93	0.89	1.27	1.24	1.19	1.07
			lb-in	3.0	-	-	6.5	5.7	-	9.1	8.7	8.3	7.9	11.3	11.0	10.6	9.5
Rated Speed	240 Vdc / 320 Vdc	N _{rtd}	rpm	8000	-	-	3500	8000	-	2500	5000	6500	8000	2000	4000	5500	8000
Rated Power (speed) ①②④⑦	240 Vdc / 320 Vdc	P _{rtd}	kW	0.28	-	-	0.27	0.54	-	0.27	0.51	0.64	0.75	0.27	0.52	0.69	0.90
			Hp	0.38	-	-	0.36	0.73	-	0.36	0.69	0.85	1.00	0.36	0.70	0.92	1.21
Rated Torque (speed) ①②④⑦	400 Vdc / 560 Vdc	T _{rtd}	Nm	-	-	-	0.63	-	-	0.94	0.87	-	-	1.20	1.06	-	-
			lb-in	-	-	-	5.6	-	-	8.3	7.7	-	-	10.6	9.4	-	-
Rated Speed	400 Vdc / 560 Vdc	N _{rtd}	rpm	-	-	-	8000	-	-	5500	8000	-	-	4500	8000	-	-
Rated Power (speed) ①②④⑦	400 Vdc / 560 Vdc	P _{rtd}	kW	-	-	-	0.53	-	-	0.54	0.73	-	-	0.57	0.89	-	-
			Hp	-	-	-	0.71	-	-	0.73	0.98	-	-	0.76	1.19	-	-
Rated Torque (speed) ①②④⑦	480 Vdc / 640 Vdc	T _{rtd}	Nm	-	-	-	0.63	-	-	0.90	0.87	-	-	1.17	1.06	-	-
			lb-in	-	-	-	5.6	-	-	8.0	7.7	-	-	10.4	9.4	-	-
Rated Speed	480 Vdc / 640 Vdc	N _{rtd}	rpm	-	-	-	8000	-	-	7000	8000	-	-	5500	8000	-	-
Rated Power (speed) ①②④⑦	480 Vdc / 640 Vdc	P _{rtd}	kW	-	-	-	0.53	-	-	0.66	0.73	-	-	0.68	0.89	-	-
			Hp	-	-	-	0.71	-	-	0.89	0.98	-	-	0.91	1.19	-	-

See following page for notes.

AKMA2x Motor Parameters

Parameters	Tol	Symbol	Units	AKMA21			AKMA22			AKMA23				AKMA24			
				C	E	G	C	E	G	C	D	E	F	C	D	E	F
Torque Constant ①②	±10%	K_t	Nm/A _{rms}	0.30	0.16	0.10	0.61	0.32	0.18	0.80	0.52	0.42	0.27	0.97	0.63	0.50	0.36
			lb-in/A _{rms}	2.7	1.4	0.9	5.4	2.8	1.6	7.1	4.6	3.7	2.4	8.6	5.6	4.5	3.2
Back EMF Constant ③	±10%	K_e	V _{rms} /krpm	19.5	10.2	6.6	39.0	20.4	11.7	51.8	33.8	27.0	17.6	62.4	40.8	32.5	23.4
Motor Constant ①	Nom	K_m	N-m/√W	0.07	0.07	0.07	0.11	0.11	0.11	0.14	0.14	0.15	0.14	0.18	0.17	0.17	0.17
			lb-in/√W	0.61	0.62	0.61	0.98	1.00	0.98	1.26	1.28	1.28	1.28	1.55	1.53	1.55	1.52
Resistance (line-line) ④	±10%	R_m	ohm	13.00	3.42	1.44	19.98	5.22	1.77	21.23	8.77	5.44	2.34	20.40	9.02	5.44	2.94
Inductance (line-line)		L	mH	19.0	5.2	2.2	35.5	9.7	3.2	40.7	17.3	11.1	4.7	43.8	18.7	11.8	6.2
Inertia (includes feedback) ⑤	±10%	J_m	kg-cm ²	0.11			0.16			0.22				0.27			
			lb-in-s ²	9.7E-05			1.4E-04			1.9E-04				2.4E-04			
Optional Brake Inertia (additional)	±10%	J_m	kg-cm ²	0.013			0.013			0.013				0.013			
			lb-in-s ²	1.2E-05			1.2E-05			1.2E-05				1.2E-05			
Weight ⑥		W	kg	1.7			2.0			2.3				2.7			
			lb	3.7			4.4			5.1				6.0			
Static Friction ①		T_f	Nm	0.049			0.051			0.054				0.057			
			lb-in	0.43			0.44			0.48				0.50			
Viscous Damping ①		K_{dv}	Nm/krpm	0.005			0.006			0.007				0.007			
			lb-in/krpm	0.04			0.05			0.06				0.07			
Thermal Time Constant		TCT	minutes	8			9			10				11			
Thermal Resistance		R_{thw-a}	°C/W	1.43			1.19			1.10				1.07			
Pole Pairs				3			3			3				3			
Heat Sink Size				10"x10"x0.25" Aluminum Plate			10"x10"x0.25" Aluminum Plate			10"x10"x0.25" Aluminum Plate				10"x10"x0.25" Aluminum Plate			

Notes:

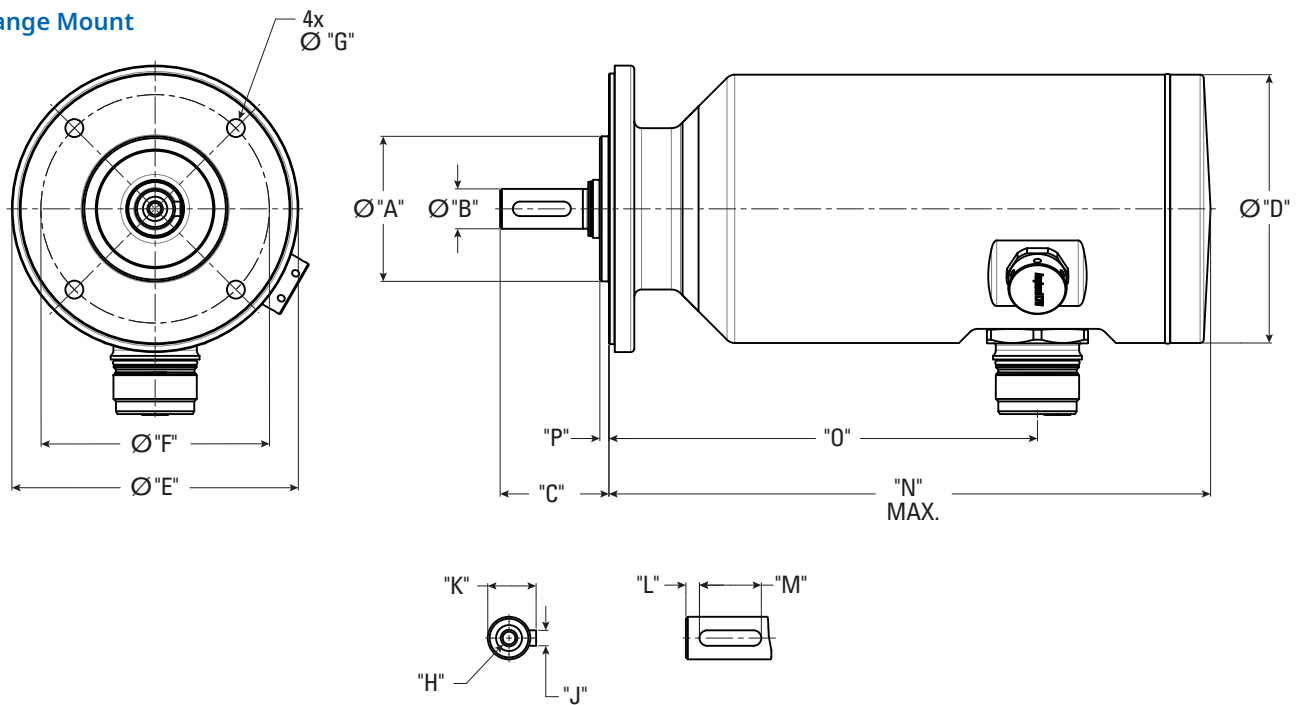
- ① Motor winding temperature rise, ΔT = 100 °C, at 40 °C ambient.
- ② All data referenced to sinusoidal commutation.
- ③ Add holding brake if applicable for total inertia.
- ④ Motor with 125 °C rated feedback and standard heat sink.
- ⑤ May be limited at some values of V_{bus}.
- ⑥ Measured at 25 °C.
- ⑦ Brake option reduces continuous torque rating by:
 AKMA21 = 0.00 Nm AKMA22 = 0.02 Nm AKMA23 = 0.05 Nm AKMA24 = 0.12 Nm
- ⑧ Brake option increases weight by 0.5 kg (1.1 lb)

AKMA2x Dimensional Data

AKMA 2 2 C - AN D N CA 1 K
 Motor Series Frame Size Winding Mount/Shaft Connection Brake Feedback Thermal Sensor Seal

AKMA2x Frame

Flange Mount



AKMA2x Dimension Data

Code	Shaft	Pilot Dia. "A"	Shaft Dia. "B"	Shaft Length "C"	Motor Body Dia. "D"	Flange Dia. "E"	Bolt Circle Dia. "F"	Bolt Hole Dia. "G"
AC	Keyway	Ø40j6	Ø11k6	30	74	79	63	4.8 +0.30/-0.0
AN	Smooth	Ø40j6	Ø11k6	30	74	79	63	4.8 +0.30/-0.0

Code	"H"	Key Width "J"	Key Height "K"	"L"	Key Length "M"	Pilot Height "P"
AC	M4 DIN332	4h9	12.5 +0/-0.13	3.5	16 +0/-0.20	2.5 +0/-0.25
AN	M4 DIN332	-	-	-	-	2.5 +0/-0.25

MODEL	Connector Position "O"		Motor Length "N"	
	W/O Brake	W/ Brake	W/O Brake	W/ Brake
AKMA21	118.2	164.8	166.2	212.8
AKMA22	137.2	183.8	185.2	231.8
AKMA23	156.2	202.8	204.2	250.8
AKMA24	175.2	221.8	223.2	269.8

Dimensions are in mm.

Notes

AK**M**A **2** **2** **C** - **A****N** **D** **N** **C****A** **1** **K**
Motor Series Frame Size Stack Length Winding Mount/Shaft Connection Brake Feedback Thermal Sensor Seal

2 mm divisions

AKMA3x Performance Data

AKMA3x Performance Data – Up to 640 Vdc

Parameters	Tol	Symbol	Units	AKMA31			AKMA32				AKMA33		
				C	E	H	C	D	E	H	C	E	H
Max Rated Voltage	Max	Vbus	Vac	480	240	120	480	480	480	240	480	480	240
			Vdc	640	320	160	640	640	640	320	640	640	320
Continuous Torque (Stall) for ΔT winding = 100 °C ①②④⑦	Nom	T _{CS}	Nm	1.10	1.15	1.18	1.95	1.98	1.99	2.05	2.66	2.75	2.84
			lb-in	9.8	10.2	10.5	17.2	17.5	17.6	18.2	23.6	24.3	25.1
Continuous Current (Stall) for ΔT winding = 100 °C ①②④⑦	Nom	I _{CS}	A _{RMS}	1.37	2.99	5.85	1.44	2.23	2.82	5.50	1.47	2.58	5.62
Continuous Torque (Stall) for ΔT winding = 60 °C ②④⑦	Nom	T _{CS}	Nm	0.85	0.89	0.92	1.51	1.53	1.54	1.59	2.06	2.13	2.20
			lb-in	7.6	7.9	8.1	13.4	13.6	13.7	14.1	18.3	18.9	19.4
Max Mechanical Speed ⑤	Nom	N _{max}	rpm	8000	8000	8000	8000	8000	8000	8000	8000	8000	8000
Peak Torque ①②	Nom	T _p	Nm	3.88	4.00	4.06	7.01	7.06	7.12	7.26	9.76	9.96	10.21
			lb-in	34.3	35.4	35.9	62.0	62.5	63.0	64.3	86.4	88.1	90.4
Peak Current	Nom	I _p	A _{RMS}	5.5	12.0	23.4	5.8	8.9	11.3	22.0	5.9	10.3	22.5
Rated Torque (speed) ①②④⑦		T _{rtd}	Nm	-	1.12	0.92	-	1.95	1.96	1.91	-	-	2.61
			lb-in	-	9.9	8.2	-	17.3	17.4	16.9	-	-	23.1
Rated Speed		N _{rtd}	rpm	-	2500	6000	-	1000	1000	3000	-	-	2500
Rated Power (speed) ①②④⑦		P _{rtd}	kW	-	0.29	0.58	-	0.20	0.21	0.60	-	-	0.68
			Hp	-	0.39	0.78	-	0.27	0.28	0.81	-	-	0.92
Rated Torque (speed) ①②④⑦		T _{rtd}	Nm	1.07	0.90	-	1.90	1.88	1.86	1.40	2.59	2.57	2.22
			lb-in	9.5	8.0	-	16.8	16.7	16.5	12.4	22.9	22.8	19.7
Rated Speed		N _{rtd}	rpm	2500	6000	-	1500	2500	3000	7000	1000	2000	5500
Rated Power (speed) ①②④⑦		P _{rtd}	kW	0.28	0.57	-	0.30	0.49	0.59	1.03	0.27	0.54	1.28
			Hp	0.38	0.76	-	0.40	0.66	0.78	1.38	0.36	0.72	1.72
Rated Torque (speed) ①②④⑦		T _{rtd}	Nm	0.95	-	-	1.81	1.60	1.45	-	2.49	2.29	-
			lb-in	8.4	-	-	16.0	14.2	12.9	-	22.1	20.3	-
Rated Speed		N _{rtd}	rpm	5000	-	-	3000	5500	6500	-	2000	4500	-
Rated Power (speed) ①②④⑦		P _{rtd}	kW	0.50	-	-	0.57	0.92	0.99	-	0.52	1.08	-
			Hp	0.67	-	-	0.76	1.24	1.33	-	0.70	1.45	-
Rated Torque (speed) ①②④⑦		T _{rtd}	Nm	0.86	-	-	1.78	1.53	1.17	-	2.45	2.22	-
			lb-in	7.6	-	-	15.8	13.6	10.4	-	21.7	19.7	-
Rated Speed		N _{rtd}	rpm	6000	-	-	3500	6000	8000	-	2500	5000	-
Rated Power (speed) ①②④⑦		P _{rtd}	kW	0.54	-	-	0.65	0.96	0.98	-	0.64	1.16	-
			Hp	0.73	-	-	0.88	1.29	1.32	-	0.86	1.56	-

See following page for notes.

AKMA3x Motor Parameters

Parameters	Tol	Symbol	Units	AKMA31			AKMA32				AKMA33		
				C	E	H	C	D	E	H	C	E	H
Torque Constant ①②	±10%	K_t	Nm/A _{rms}	0.85	0.41	0.21	1.40	0.92	0.73	0.39	1.86	1.10	0.52
			lb-in/A _{rms}	7.5	3.6	1.9	12.3	8.1	6.5	3.4	16.5	9.7	4.6
Back EMF Constant ⑥	±10%	K_e	V _{rms} /krpm	54.5	26.1	13.7	89.8	59.0	47.1	24.8	120.0	70.6	33.4
Motor Constant ①	Nom	K_m	N-m/√W	0.149	0.152	0.151	0.234	0.233	0.235	0.239	0.295	0.298	0.299
			lb-in/√W	1.32	1.35	1.34	2.07	2.06	2.08	2.12	2.61	2.64	2.64
Resistance (line-line) ⑥	±10%	R_m	ohm	21.40	4.74	1.29	23.76	10.30	6.32	1.69	26.59	9.01	1.96
Inductance (line-line)		L	mH	37.5	8.6	2.4	46.5	20.1	12.8	3.5	53.6	18.5	4.1
Inertia (includes feedback) ③	±10%	J_m	kg-cm ²	0.33			0.59				0.85		
			lb-in-s ²	2.9E-04			5.2E-04				7.5E-04		
Optional Brake Inertia (additional)	±10%	J_m	kg-cm ²	0.014			0.014				0.014		
			lb-in-s ²	1.2E-05			1.2E-05				1.2E-05		
Weight ⑧		W	kg	2.3			3.1				3.8		
			lb	5.1			6.8				8.4		
Static Friction ①		T_f	Nm	0.061			0.067				0.073		
			lb-in	0.54			0.59				0.65		
Viscous Damping ①		K_{dv}	Nm/krpm	0.002			0.003				0.004		
			lb-in/krpm	0.02			0.03				0.04		
Thermal Time Constant		TCT	minutes	14			17				20		
Thermal Resistance		R_{thw-a}	°C/W	1.11			0.92				0.78		
Pole Pairs				4			4				4		
Heat Sink Size				10"x10"x0.25" Aluminum Plate			10"x10"x0.25" Aluminum Plate				10"x10"x0.25" Aluminum Plate		

Notes:

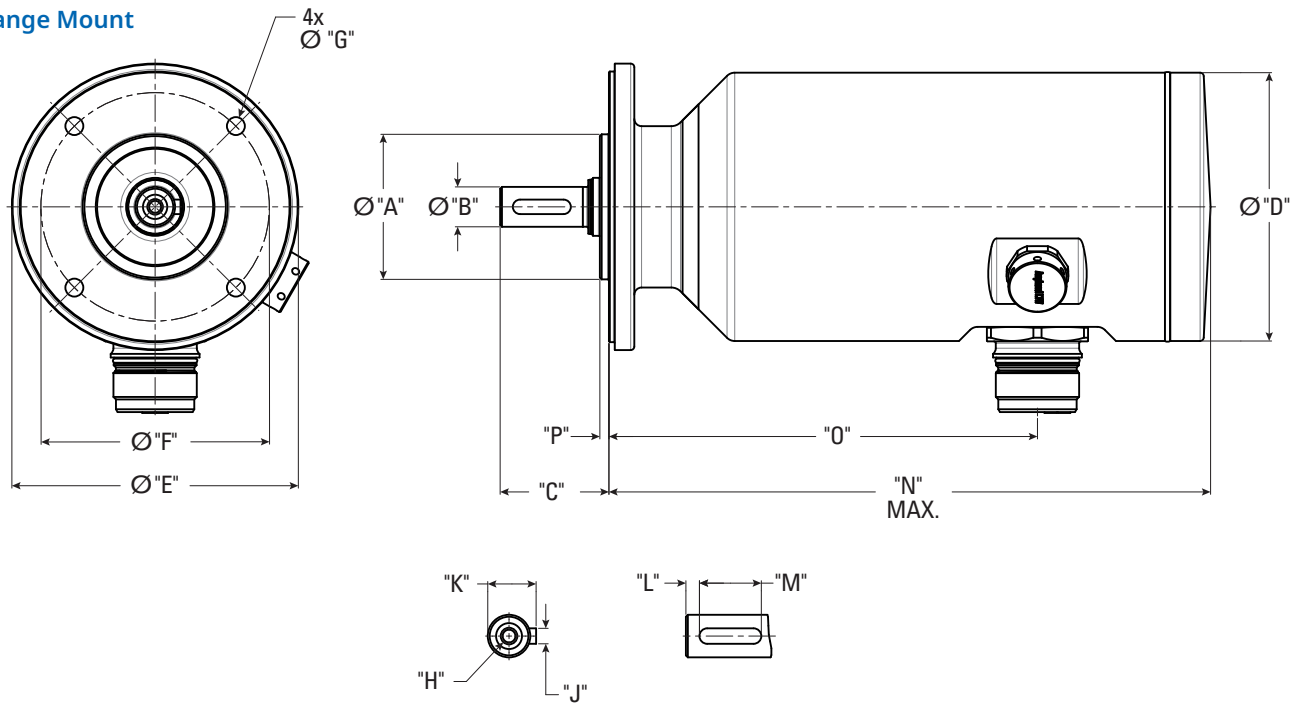
- ① Motor winding temperature rise, $\Delta T = 100\text{ }^\circ\text{C}$, at $40\text{ }^\circ\text{C}$ ambient.
- ② All data referenced to sinusoidal commutation.
- ③ Add holding brake if applicable for total inertia.
- ④ Motor with $125\text{ }^\circ\text{C}$ rated feedback and standard heat sink.
- ⑤ May be limited at some values of V_{bus} .
- ⑥ Measured at $25\text{ }^\circ\text{C}$.
- ⑦ Brake option reduces continuous torque rating by:
AKMA31 = 0.00 Nm AKMA32 = 0.1 Nm AKMA33 = 0.2 Nm
- ⑧ Brake option increases weight by 0.6 kg (1.3 lb)

AKMA3x Dimensional Data

AKMA 3 2 C - AN D N CA 1 K
 Motor Series Frame Size Winding Stack Length Mount/Shaft Connection Brake Feedback Thermal Sensor Seal

AKMA3x Frame

Flange Mount



AKMA3x Dimension Data

Code	Shaft	Pilot Dia. "A"	Shaft Dia. "B"	Shaft Length "C"	Motor Body Dia. "D"	Flange Dia. "E"	Bolt Circle Dia. "F"	Bolt Hole Dia. "G"
AC	Keyway	Ø60j6	Ø14k6	30	85	89	75	5.8 +0.30/-0.0
AN	Smooth	Ø60j6	Ø14k6	30	85	89	75	5.8 +0.30/-0.0

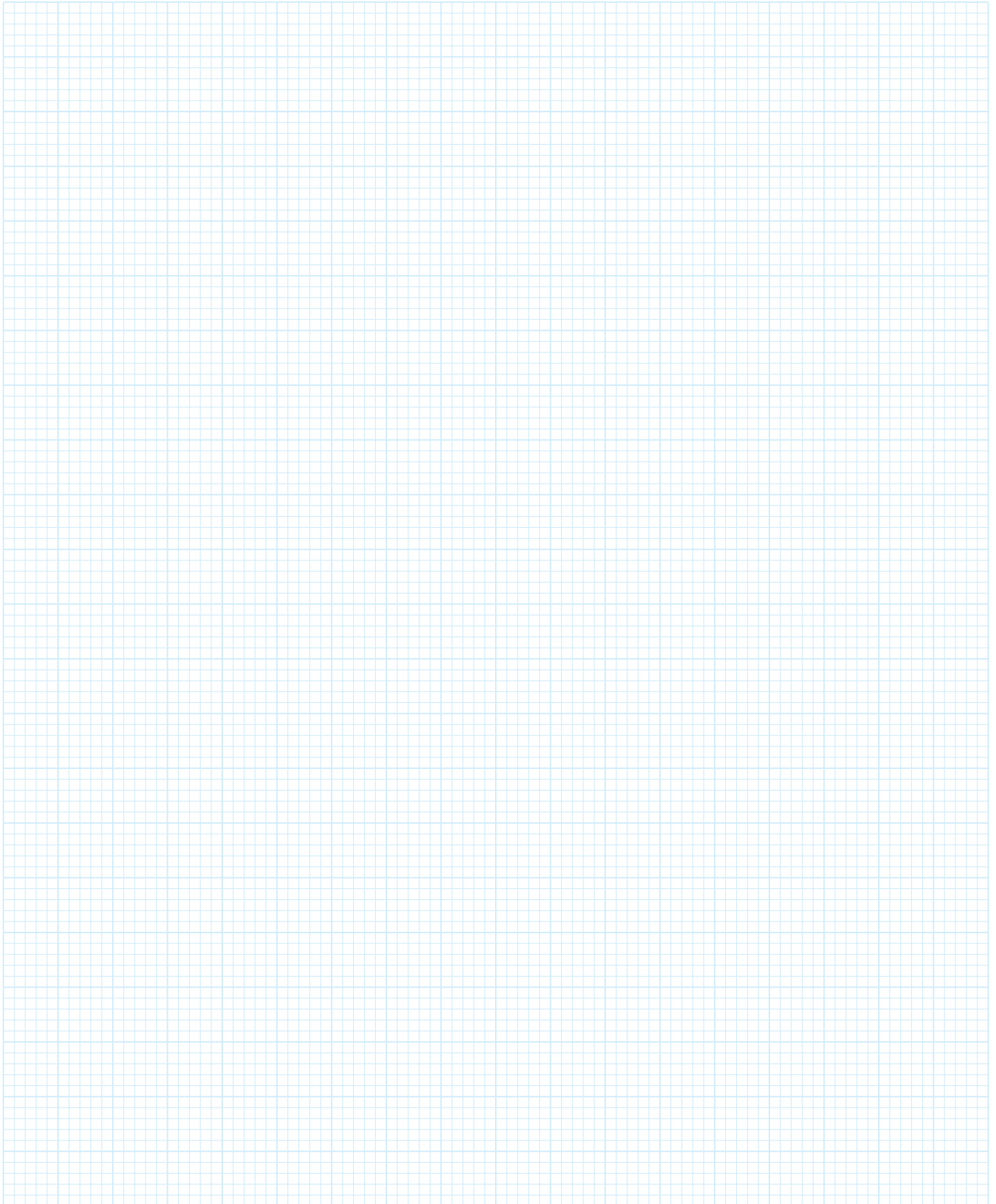
Code	"H"	Key Width "J"	Key Height "K"	"L"	Key Length "M"	Pilot Height "P"
AC	M5 DIN332	5h9	16+0/-0.13	3.5	16 +0/-0.20	2.5 +0/-0.25
AN	M5 DIN332	-	-	-	-	2.5 +0/-0.25

MODEL	Connector Position "O"		Motor Length "N"	
	W/O Brake	W/ Brake	W/O Brake	W/ Brake
AKMA31	118.3	156.3	166.4	204.3
AKMA32	149.3	187.3	197.4	235.3
AKMA33	180.3	218.3	228.4	266.3

Dimensions are in mm.

Notes

AK**M**A **3** **2** **C** - **A****N** **D** **N** **C****A** **1** **K**
Motor Series Frame Size Stack Length Winding Mount/Shaft Connection Brake Feedback Thermal Sensor Seal



2 mm divisions

AKMA4x Performance Data

AKMA41-42 Performance Data – Up to 640 Vdc

Parameters	Tol	Symbol	Units	AKMA41			AKMA42				
				C	E	H	C	E	G	H	J
Max Rated Voltage	Max	Vbus	Vac	480	480	240	480	480	480	240	240
			Vdc	640	640	320	640	640	640	320	320
Continuous Torque (Stall) for ΔT winding = 100 °C ①②④⑦	Nom	T _{CS}	Nm	1.78	1.85	1.89	3.18	3.25	3.36	3.37	3.39
			lb-in	15.7	16.4	16.7	28.1	28.8	29.7	29.8	30.0
Continuous Current (Stall) for ΔT winding = 100 °C ①②④⑦	Nom	I _{CS}	A _{RMS}	1.39	2.73	5.36	1.37	2.66	4.68	5.83	8.16
Continuous Torque (Stall) for ΔT winding = 60 °C ②④⑦	Nom	T _{CS}	Nm	1.38	1.43	1.46	2.46	2.52	2.60	2.61	2.63
			lb-in	12.2	12.7	12.9	21.8	22.3	23.0	23.1	23.2
Max Mechanical Speed ⑤	Nom	N _{max}	rpm	6000	6000	6000	6000	6000	6000	6000	6000
Peak Torque ①②	Nom	T _p	Nm	6.12	6.28	6.36	11.10	11.30	11.50	11.60	11.60
			lb-in	54.2	55.6	56.3	98.2	100.0	101.8	102.7	102.7
Peak Current	Nom	I _p	A _{RMS}	5.8	11.4	22.4	5.6	11.0	19.2	24.0	33.7
Rated Torque (speed) ①②④⑦		T _{rtd}	Nm	-	1.77	1.69	-	-	-	3.03	2.86
			lb-in	-	15.7	14.9	-	-	-	26.8	25.3
Rated Speed		N _{rtd}	rpm	-	1200	3000	-	-	-	2000	3000
Rated Power (speed) ①②④⑦		P _{rtd}	kW	-	0.22	0.53	-	-	-	0.63	0.90
			Hp	-	0.30	0.71	-	-	-	0.85	1.20
Rated Torque (speed) ①②④⑦		T _{rtd}	Nm	1.71	1.65	1.45	-	2.95	2.73	2.55	2.21
			lb-in	15.1	14.6	12.8	-	26.1	24.2	22.6	19.5
Rated Speed		N _{rtd}	rpm	1200	3000	6000	-	1800	3500	4500	6000
Rated Power (speed) ①②④⑦		P _{rtd}	kW	0.21	0.52	0.91	-	0.56	1.00	1.20	1.39
			Hp	0.29	0.69	1.22	-	0.75	1.34	1.61	1.86
Rated Torque (speed) ①②④⑦		T _{rtd}	Nm	1.60	1.41	-	2.93	2.64	2.18	-	-
			lb-in	14.2	12.5	-	25.9	23.4	19.3	-	-
Rated Speed		N _{rtd}	rpm	3000	6000	-	1500	3500	6000	-	-
Rated Power (speed) ①②④⑦		P _{rtd}	kW	0.50	0.89	-	0.46	0.97	1.37	-	-
			Hp	0.67	1.19	-	0.62	1.30	1.84	-	-
Rated Torque (speed) ①②④⑦		T _{rtd}	Nm	1.57	1.41	-	2.85	2.55	2.18	-	-
			lb-in	13.9	12.5	-	25.2	22.6	19.3	-	-
Rated Speed		N _{rtd}	rpm	3500	6000	-	2000	4000	6000	-	-
Rated Power (speed) ①②④⑦		P _{rtd}	kW	0.58	0.89	-	0.60	1.07	1.37	-	-
			Hp	0.77	1.19	-	0.80	1.43	1.84	-	-

See following page for notes.

AKMA41-42 Motor Parameters

Parameters	Tol	Symbol	Units	AKMA41			AKMA42				
				C	E	G	C	E	G	H	J
Torque Constant ①②	±10%	K_t	Nm/A _{rms}	1.34	0.71	0.37	2.40	1.26	0.74	0.59	0.43
			lb-in/A _{rms}	11.9	6.3	3.3	21.2	11.1	6.5	5.3	3.8
Back EMF Constant ⑥	±10%	K_e	V _{rms} /krpm	86.3	45.6	23.7	154.3	80.9	47.5	38.3	27.5
Motor Constant ①	Nom	K_m	N-m/√W	0.24	0.24	0.24	0.37	0.37	0.38	0.37	0.39
			lb-in/√W	2.10	2.09	2.11	3.30	3.25	3.33	3.31	3.41
Resistance (line-line) ⑥	±10%	R_m	ohm	21.30	6.02	1.56	27.50	7.78	2.51	1.65	0.80
Inductance (line-line)		L	mH	66.1	18.4	5.0	97.4	26.8	9.2	6.0	3.1
Inertia (includes feedback) ③	±10%	J_m	kg-cm ²	0.81			1.50				
			lb-in-s ²	7.2E-04			1.3E-03				
Optional Brake Inertia (additional)	±10%	J_m	kg-cm ²	0.058			0.058				
			lb-in-s ²	5.1E-05			5.1E-05				
Weight ⑧		W	kg	3.7			4.9				
			lb	8.2			10.8				
Static Friction ①		T_f	Nm	0.085			0.097				
			lb-in	0.75			0.86				
Viscous Damping ①		K_{dv}	Nm/krpm	0.0090			0.0130				
			lb-in/krpm	0.08			0.12				
Thermal Time Constant		TCT	minutes	13			17				
Thermal Resistance		R_{thw-a}	°C/W	0.97			0.80				
Pole Pairs				5			5				
Heat Sink Size				10"x10"x0.25" Aluminum Plate			10"x10"x0.25" Aluminum Plate				

Notes:

- ① Motor winding temperature rise, $\Delta T = 100\text{ }^\circ\text{C}$, at $40\text{ }^\circ\text{C}$ ambient.
- ② All data referenced to sinusoidal commutation.
- ③ Add holding brake if applicable for total inertia.
- ④ Motor with $125\text{ }^\circ\text{C}$ rated feedback and standard heat sink.
- ⑤ May be limited at some values of V_{bus} .
- ⑥ Measured at $25\text{ }^\circ\text{C}$.
- ⑦ Brake option reduces continuous torque rating by:
 AKMA41 = 0.12 Nm AKMA42 = 0.26 Nm AKMA43 = 0.35 Nm AKMA44 = 0.46 Nm
- ⑧ Brake option increases weight by 1.3 kg (2.9 lb)

AKMA4x Performance Data

AKMA43-44 Performance Data – Up to 640 Vdc (Continued)

Parameters	Tol	Symbol	Units	AKMA43					AKMA44				
				E	G	H	K	L	E	G	H	J	K
Max Rated Voltage	Max	Vbus	Vac	480	480	480	240	240	480	480	480	480	240
			Vdc	640	640	640	320	320	640	640	640	640	320
Continuous Torque (Stall) for ΔT winding = 100 °C ①②④⑦	Nom	T _{CS}	Nm	4.43	4.53	4.55	4.63	4.46	5.39	5.51	5.52	5.63	5.51
			lb-in	39.2	40.1	40.3	41.0	39.5	47.7	48.8	48.8	49.8	48.8
Continuous Current (Stall) for ΔT winding = 100 °C ①②④⑦	Nom	I _{CS}	A _{RMS}	2.64	4.67	5.23	9.19	10.70	2.70	4.73	5.34	8.38	9.59
Continuous Torque (Stall) for ΔT winding = 60 °C ②④⑦	Nom	T _{CS}	Nm	3.43	3.51	3.52	3.59	3.45	4.17	4.27	4.27	4.36	4.27
			lb-in	30.4	31.0	31.2	31.7	30.6	36.9	37.8	37.8	38.6	37.8
Max Mechanical Speed ⑤	Nom	N _{max}	rpm	6000	6000	6000	6000	6000	6000	6000	6000	6000	6000
Peak Torque ①②	Nom	T _p	Nm	15.90	16.10	16.10	16.40	16.00	20.20	20.30	20.20	20.50	20.20
			lb-in	140.7	142.5	142.5	145.1	141.6	178.8	179.7	178.8	181.4	178.8
Peak Current	Nom	I _p	A _{RMS}	11.0	19.5	21.6	38.4	44.6	11.6	20.0	22.4	35.2	40.4
Rated Torque (speed) ①②④⑦		T _{rtd}	Nm	-	-	4.19	3.81	3.51	-	-	5.07	-	4.53
			lb-in	-	-	37.1	33.7	31.1	-	-	44.9	-	40.1
Rated Speed		N _{rtd}	rpm	-	-	1200	2500	3000	-	-	1000	-	2000
Rated Power (speed) ①②④⑦		P _{rtd}	kW	-	-	0.53	1.00	1.10	-	-	0.53	-	0.95
			Hp	-	-	0.71	1.34	1.48	-	-	0.71	-	1.27
Rated Torque (speed) ①②④⑦		T _{rtd}	Nm	3.97	3.73	3.59	2.35	2.26	4.85	4.53	4.29	3.47	2.81
			lb-in	35.1	33.0	31.8	20.8	20.0	42.9	40.1	38.0	30.7	24.9
Rated Speed		N _{rtd}	rpm	1500	2500	3000	6000	6000	1200	2000	2500	4000	5000
Rated Power (speed) ①②④⑦		P _{rtd}	kW	0.62	0.98	1.13	1.48	1.42	0.61	0.95	1.12	1.45	1.47
			Hp	0.84	1.31	1.51	1.98	1.90	0.82	1.27	1.51	1.95	1.97
Rated Torque (speed) ①②④⑦		T _{rtd}	Nm	3.65	2.74	2.54	-	-	4.43	2.81	3.11	2.38	-
			lb-in	32.3	24.2	22.5	-	-	39.2	24.9	27.5	21.1	-
Rated Speed		N _{rtd}	rpm	2500	5000	5500	-	-	2000	5000	4500	6000	-
Rated Power (speed) ①②④⑦		P _{rtd}	kW	0.96	1.43	1.46	-	-	0.93	1.47	1.46	1.49	-
			Hp	1.28	1.92	1.96	-	-	1.24	1.97	1.96	2.00	-
Rated Torque (speed) ①②④⑦		T _{rtd}	Nm	3.49	2.30	2.31	-	-	4.19	2.57	2.56	2.38	-
			lb-in	30.9	20.3	20.4	-	-	37.1	22.7	22.6	21.1	-
Rated Speed		N _{rtd}	rpm	3000	6000	6000	-	-	2500	5500	5500	6000	-
Rated Power (speed) ①②④⑦		P _{rtd}	kW	1.10	1.44	1.45	-	-	1.10	1.48	1.47	1.49	-
			Hp	1.47	1.94	1.95	-	-	1.47	1.98	1.98	2.00	-

See following page for notes.

AKMA43-44 Motor Parameters

Parameters	Tol	Symbol	Units	AKMA43					AKMA44				
				E	G	H	K	L	E	G	H	J	K
Torque Constant ①②	±10%	K_t	Nm/A _{rms}	1.72	0.99	0.89	0.52	0.43	2.04	1.19	1.06	0.69	0.59
			lb-in/A _{rms}	15.2	8.8	7.9	4.6	3.8	18.1	10.5	9.3	6.1	5.2
Back EMF Constant ⑥	±10%	K_e	V _{rms} /krpm	110.8	63.9	57.4	33.2	27.5	131.6	76.6	68.0	44.2	37.8
Motor Constant ①	Nom	K_m	N-m/√W	0.48	0.48	0.49	0.48	0.46	0.57	0.58	0.57	0.57	0.57
			lb-in/√W	4.24	4.28	4.29	4.28	4.04	5.02	5.14	5.05	5.06	5.01
Resistance (line-line) ⑥	±10%	R_m	ohm	8.61	2.81	2.20	0.74	0.57	8.64	2.80	2.23	0.94	0.70
Inductance (line-line)		L	mH	32.6	10.8	8.7	2.9	2.0	33.9	11.5	9.1	3.8	0.7
Inertia (includes feedback) ③	±10%	J_m	kg-cm ²	2.10					2.70				
			lb-in-s ²	1.9E-03					2.4E-03				
Optional Brake Inertia (additional)	±10%	J_m	kg-cm ²	0.058					0.058				
			lb-in-s ²	5.1E-05					5.1E-05				
Weight ⑧		W	kg	6.1					7.3				
			lb	13.4					16.1				
Static Friction ①		T_f	Nm	0.11					0.12				
			lb-in	0.96					1.07				
Viscous Damping ①		K_{dv}	Nm/krpm	0.017					0.021				
			lb-in/krpm	0.15					0.19				
Thermal Time Constant		TCT	minutes	20					24				
Thermal Resistance		R_{thw-a}	°C/W	0.70					0.65				
Pole Pairs				5					5				
Heat Sink Size				10"x10"x0.25" Aluminum Plate					10"x10"x0.25" Aluminum Plate				

Notes:

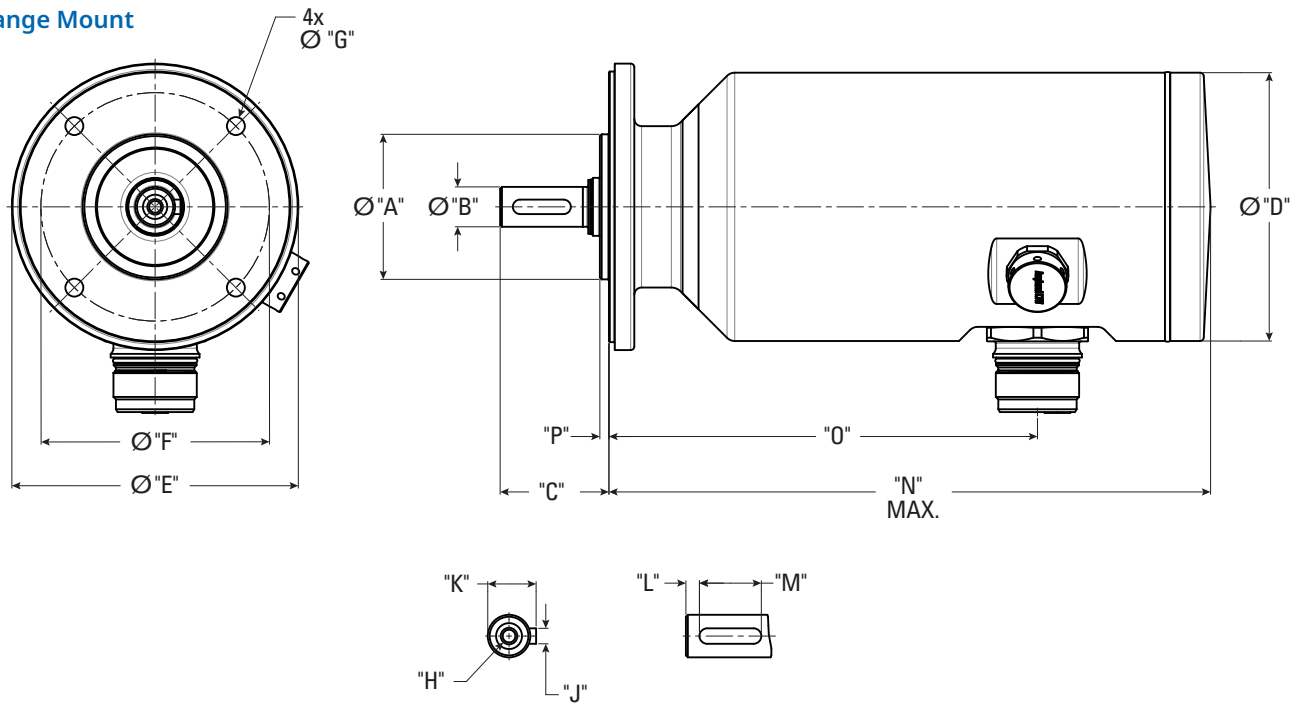
- ① Motor winding temperature rise, ΔT = 100 °C, at 40 °C ambient.
- ② All data referenced to sinusoidal commutation.
- ③ Add holding brake if applicable for total inertia.
- ④ Motor with 125 °C rated feedback and standard heat sink.
- ⑤ May be limited at some values of V_{bus}.
- ⑥ Measured at 25 °C.
- ⑦ Brake option reduces continuous torque rating by:
 AKMA41 = 0.12 Nm AKMA42 = 0.26 Nm AKMA43 = 0.35 Nm AKMA44 = 0.46 Nm
- ⑧ Brake option increases weight by 1.3 kg (2.9 lb)

AKMA4x Dimensional Data

AKMA 4 2 C - AN D N CA 1 K*
 Motor Series Frame Size Winding Mount/Shaft Connection Brake Feedback Thermal Sensor Seal

AKMA4x Frame

Flange Mount



AKMA4x Dimension Data

Code	Shaft	Pilot Dia. "A"	Shaft Dia. "B"	Shaft Length "C"	Motor Body Dia. "D"	Flange Dia. "E"	Bolt Circle Dia. "F"	Bolt Hole Dia. "G"
AC	Keyway	Ø80j6	Ø19k6	40	113	117	100	7 +0.3/-0.0
AN	Smooth	Ø80j6	Ø19k6	40	113	117	100	7 +0.3/-0.0

Code	"H"	Key Width "J"	Key Height "K"	"L"	Key Length "M"	Pilot Height "P"
AC	M6 DIN332	6h9	21.5 +0/-0.13	4	25 +0/-0.20	3.0 +0/-0.25
AN	M6 DIN332	-	-	-	-	3.0 +0/-0.25

MODEL	Connector Position "O"		Motor Length "N"	
	W/O Brake	W/ Brake	W/O Brake	W/ Brake
AKMA41	122.7	165.9	171.4	214.5
AKMA42	151.7	194.9	200.4	243.5
AKMA43	180.7	223.9	229.4	272.5
AKMA44	209.7	252.9	258.4	301.5

Dimensions are in mm.

Notes

AK**M**A **4** **2** **C** - **A****N** **D** **N** **C****A** **1** **K**
Motor Series Frame Size Stack Length Winding Mount/Shaft Connection Brake Feedback Thermal Sensor Seal

A large grid of 2 mm divisions for taking notes. The grid is composed of small squares, each measuring 2 mm by 2 mm. The grid covers most of the page area below the header and above the footer.

2 mm divisions

AKMA5x Performance Data

AKMA51-52 Performance Data – Up to 640 Vdc

Parameters	Tol	Symbol	Units	AKMA51					AKMA52				
				E	G	H	K	L	E	G	H	L	M
Max Rated Voltage	Max	Vbus	Vac	480	480	480	240	240	480	480	480	480	240
			Vdc	640	640	640	320	320	640	640	640	640	320
Continuous Torque (Stall) for ΔT winding = 100 °C ①②④⑦	Nom	T _{CS}	Nm	4.42	4.47	4.51	4.62	4.61	7.87	7.96	8.01	8.20	8.13
			lb-in	39.1	39.6	39.9	40.9	40.8	69.6	70.4	70.9	72.6	72.0
Continuous Current (Stall) for ΔT winding = 100 °C ①②④⑦	Nom	I _{CS}	A _{RMS}	2.67	4.68	5.85	9.17	11.53	2.89	4.54	5.68	11.16	12.60
Continuous Torque (Stall) for ΔT winding = 60 °C ②④⑦	Nom	T _{CS}	Nm	3.42	3.46	3.49	3.58	3.57	6.10	6.17	6.20	6.35	6.30
			lb-in	30.3	30.6	30.9	31.7	31.6	54.0	54.6	54.9	56.2	55.7
Max Mechanical Speed ⑤	Nom	N _{max}	rpm	6000	6000	6000	6000	6000	6000	6000	6000	6000	6000
Peak Torque ①②	Nom	T _p	Nm	11.60	11.70	11.70	11.90	12.00	21.30	21.50	21.60	22.00	21.90
			lb-in	102.7	103.5	103.5	105.3	106.2	188.5	190.3	191.2	194.7	193.8
Peak Current	Nom	I _p	A _{RMS}	8.2	14.5	18.0	28.2	35.7	9.0	14.2	17.7	34.8	39.4
Rated Torque (speed) ①②④⑦		T _{rtd}	Nm	-	-	4.18	3.87	3.67	-	-	-	7.42	-
			lb-in	-	-	37.0	34.2	32.5	-	-	-	65.7	-
Rated Speed		N _{rtd}	rpm	-	-	1200	2500	3000	-	-	-	2500	-
Rated Power (speed) ①②④⑦		P _{rtd}	kW	-	-	0.53	1.01	1.15	-	-	-	1.94	-
			Hp	-	-	0.70	1.36	1.55	-	-	-	2.60	-
Rated Torque (speed) ①②④⑦		T _{rtd}	Nm	4.13	3.74	3.59	2.07	1.72	-	7.22	7.06	5.93	4.73
			lb-in	36.6	33.1	31.8	18.3	15.2	-	63.9	62.5	52.5	41.9
Rated Speed		N _{rtd}	rpm	1200	2500	3000	5500	6000	-	1500	1800	3500	4500
Rated Power (speed) ①②④⑦		P _{rtd}	kW	0.52	0.98	1.13	1.19	1.08	-	1.13	1.33	2.17	2.23
			Hp	0.70	1.31	1.51	1.60	1.45	-	1.52	1.78	2.91	2.99
Rated Torque (speed) ①②④⑦		T _{rtd}	Nm	3.70	2.34	1.69	-	-	7.14	6.59	5.79	2.80	-
			lb-in	32.7	20.7	15.0	-	-	63.2	58.3	51.2	24.8	-
Rated Speed		N _{rtd}	rpm	2500	5000	6000	-	-	1500	2500	3500	6000	-
Rated Power (speed) ①②④⑦		P _{rtd}	kW	0.97	1.23	1.06	-	-	1.12	1.73	2.12	1.76	-
			Hp	1.30	1.64	1.42	-	-	1.50	2.31	2.85	2.36	-
Rated Torque (speed) ①②④⑦		T _{rtd}	Nm	3.52	1.66	1.69	-	-	6.81	6.19	5.30	2.80	-
			lb-in	31.2	14.7	15.0	-	-	60.3	54.8	46.9	24.8	-
Rated Speed		N _{rtd}	rpm	3000	6000	6000	-	-	2000	3000	4000	6000	-
Rated Power (speed) ①②④⑦		P _{rtd}	kW	1.11	1.04	1.06	-	-	1.43	1.94	2.22	1.76	-
			Hp	1.48	1.40	1.42	-	-	1.91	2.61	2.98	2.36	-

See following page for notes.

AKMA51-52 Motor Parameters

Parameters	Tol	Symbol	Units	AKM51					AKMA52				
				E	G	H	K	L	E	G	H	L	M
Torque Constant ①②	±10%	K_t	Nm/A _{rms}	1.71	0.99	0.80	0.52	0.41	2.79	1.79	1.44	0.75	0.66
			lb-in/A _{rms}	15.2	8.7	7.1	4.6	3.7	24.7	15.8	12.7	6.6	5.8
Back EMF Constant ③	±10%	K_e	V _{rms} /krpm	110.4	63.6	51.3	33.5	26.6	179.4	115.3	92.7	48.3	42.4
Motor Constant ①	Nom	K_m	N-m/√W	0.47	0.48	0.46	0.48	0.48	0.76	0.76	0.76	0.78	0.76
			lb-in/√W	4.13	4.21	4.05	4.29	4.22	6.73	6.73	6.71	6.86	6.72
Resistance (line-line) ④	±10%	R_m	ohm	8.98	2.87	1.97	0.75	0.49	8.96	3.70	2.35	0.61	0.49
Inductance (line-line)		L	mH	36.6	12.1	7.9	3.4	2.1	44.7	18.5	11.9	3.2	2.5
Inertia (includes feedback) ⑤	±10%	J_m	kg-cm ²	3.40					6.20				
			lb-in-s ²	3.0E-03					5.5E-03				
Optional Brake Inertia (additional)	±10%	J_m	kg-cm ²	0.166					0.166				
			lb-in-s ²	1.5E-04					1.5E-04				
Weight ⑥		W	kg	6.4					8.2				
			lb	14.1					18.1				
Static Friction ①		T_f	Nm	0.152					0.170				
			lb-in	1.35					1.50				
Viscous Damping ①		K_{dv}	Nm/krpm	0.03					0.04				
			lb-in/krpm	0.29					0.37				
Thermal Time Constant		TCT	minutes	20					24				
Thermal Resistance		R_{thw-a}	°C/W	0.68					0.56				
Pole Pairs				5					5				
Heat Sink Size				12"x12"x0.5" Aluminum Plate					12"x12"x0.5" Aluminum Plate				

Notes:

- ① Motor winding temperature rise, $\Delta T = 100\text{ }^\circ\text{C}$, at $40\text{ }^\circ\text{C}$ ambient.
- ② All data referenced to sinusoidal commutation.
- ③ Add holding brake if applicable for total inertia.
- ④ Motor with $125\text{ }^\circ\text{C}$ rated feedback and standard heat sink.
- ⑤ May be limited at some values of V_{bus} .
- ⑥ Measured at $25\text{ }^\circ\text{C}$.
- ⑦ Brake option reduces continuous torque rating by:
 AKMA51 = 0.24 Nm AKMA52 = 0.42 Nm AKMA53 = 0.55 Nm AKMA54 = 0.69 Nm
- ⑧ Brake option increases weight by 2.0 kg (4.4 lb)

AKMA5x Performance Data

AKMA53-54 Performance Data – Up to 640 Vdc

Parameters	Tol	Symbol	Units	AKMA53					AKMA54				
				H	K	L	M	P	H	K	L	N	P
Max Rated Voltage	Max	Vbus	Vac	480	480	480	240	240	480	480	400	240	240
			Vdc	640	640	640	320	320	640	640	560	320	320
Continuous Torque (Stall) for ΔT winding = 100 °C ①②④⑦	Nom	T _{CS}	Nm	10.79	10.89	10.89	10.69	10.69	13.21	13.41	13.11	13.11	13.41
			lb-in	95.5	96.4	96.4	94.6	94.6	116.9	118.7	116.0	116.0	118.7
Continuous Current (Stall) for ΔT winding = 100 °C ①②④⑦	Nom	I _{CS}	A _{RMS}	6.29	8.94	11.22	12.80	18.24	5.22	9.08	11.76	16.72	18.53
Continuous Torque (Stall) for ΔT winding = 60 °C ②④⑦	Nom	T _{CS}	Nm	8.36	8.44	8.44	8.28	8.28	10.23	10.39	10.15	10.15	10.39
			lb-in	74.0	74.7	74.7	73.3	73.3	90.6	91.9	89.9	89.9	91.9
Max Mechanical Speed ⑤	Nom	N _{max}	rpm	6000	6000	6000	6000	6000	6000	6000	6000	6000	6000
Peak Torque ①②	Nom	T _p	Nm	30.00	30.30	30.30	29.70	29.80	37.50	38.50	37.50	37.60	38.00
			lb-in	265.5	268.2	268.2	262.8	263.7	331.9	340.7	331.9	332.8	336.3
Peak Current	Nom	I _p	A _{RMS}	19.8	28.2	35.4	40.7	57.4	16.5	29.2	37.5	53.4	58.8
Rated Torque (speed) ①②④⑦		T _{rtd}	Nm	-	-	9.99	-	-	-	-	-	-	-
			lb-in	-	-	88.4	-	-	-	-	-	-	-
Rated Speed		N _{rtd}	rpm	-	-	1200	-	-	-	-	-	-	-
Rated Power (speed) ①②④⑦		P _{rtd}	kW	-	-	1.26	-	-	-	-	-	-	-
			Hp	-	-	1.68	-	-	-	-	-	-	-
Rated Torque (speed) ①②④⑦		T _{rtd}	Nm	9.79	9.39	8.88	8.01	5.17	12.41	11.71	10.51	8.86	8.24
			lb-in	86.6	83.1	78.6	70.9	45.8	109.8	103.6	93.0	78.4	72.9
Rated Speed		N _{rtd}	rpm	1500	2000	2500	3000	5000	1000	1800	2500	3500	4000
Rated Power (speed) ①②④⑦		P _{rtd}	kW	1.54	1.97	2.32	2.52	2.71	1.30	2.21	2.75	3.25	3.45
			Hp	2.06	2.64	3.12	3.37	3.63	1.74	2.96	3.69	4.35	4.63
Rated Torque (speed) ①②④⑦		T _{rtd}	Nm	8.12	6.94	5.29	-	-	11.61	9.06	7.14	-	-
			lb-in	71.9	61.4	46.8	-	-	102.7	80.2	63.2	-	-
Rated Speed		N _{rtd}	rpm	3000	4000	5000	-	-	1800	3500	4500	-	-
Rated Power (speed) ①②④⑦		P _{rtd}	kW	2.55	2.91	2.77	-	-	2.19	3.32	3.36	-	-
			Hp	3.42	3.90	3.71	-	-	2.93	4.45	4.51	-	-
Rated Torque (speed) ①②④⑦		T _{rtd}	Nm	8.11	6.14	3.34	-	-	11.21	8.26	-	-	-
			lb-in	71.8	54.3	29.6	-	-	99.2	73.1	-	-	-
Rated Speed		N _{rtd}	rpm	3000	4500	6000	-	-	2000	4000	-	-	-
Rated Power (speed) ①②④⑦		P _{rtd}	kW	2.55	2.89	2.10	-	-	2.35	3.46	-	-	-
			Hp	3.42	3.88	2.81	-	-	3.15	4.64	-	-	-

See following page for notes.

AKMA53-54 Motor Parameters

Parameters	Tol	Symbol	Units	AKM53					AKMA54				
				H	K	L	M	P	H	K	L	N	P
Torque Constant ①②	±10%	K_t	Nm/A _{rms}	1.75	1.24	0.99	0.85	0.60	2.57	1.50	1.13	0.80	0.74
			lb-in/A _{rms}	15.4	11.0	8.7	7.5	5.3	22.8	13.3	10.0	7.1	6.5
Back EMF Constant ③	±10%	K_e	V _{rms} /krpm	112.4	79.8	63.6	54.7	38.4	165.6	96.6	72.9	51.3	47.3
Motor Constant ①	Nom	K_m	N-m/√W	0.98	0.98	0.96	0.96	0.93	1.17	1.18	1.13	1.12	1.14
			lb-in/√W	8.70	8.70	8.49	8.50	8.20	10.39	10.43	10.03	9.91	10.10
Resistance (line-line) ④	±10%	R_m	ohm	2.10	1.06	0.69	0.51	0.27	3.20	1.08	0.65	0.33	0.27
Inductance (line-line)		L	mH	11.4	5.7	3.6	2.7	1.3	18.3	6.2	3.5	1.8	1.5
Inertia (includes feedback) ⑤	±10%	J_m	kg-cm ²	9.10					12.00				
			lb-in-s ²	8.1E-03					1.1E-02				
Optional Brake Inertia (additional)	±10%	J_m	kg-cm ²	0.166					0.166				
			lb-in-s ²	1.5E-04					1.5E-04				
Weight ⑥		W	kg	10.0					11.8				
			lb	22.0					26.0				
Static Friction ①		T_f	Nm	0.19					0.21				
			lb-in	1.66					1.83				
Viscous Damping ①		K_{dv}	Nm/krpm	0.052					0.061				
			lb-in/krpm	0.46					0.54				
Thermal Time Constant		TCT	minutes	28					31				
Thermal Resistance		R_{thw-a}	°C/W	0.50					0.45				
Pole Pairs				5					5				
Heat Sink Size				12"x12"x0.5" Aluminum Plate					12"x12"x0.5" Aluminum Plate				

Notes:

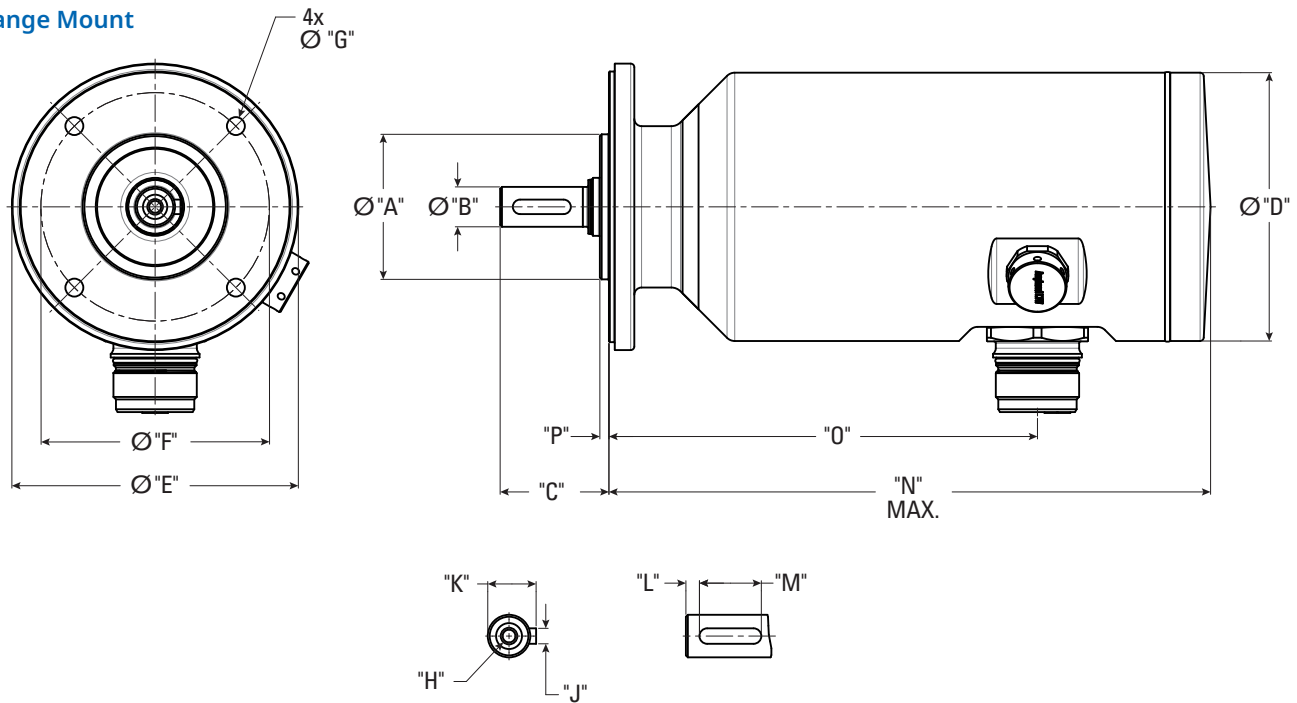
- ① Motor winding temperature rise, ΔT = 100 °C, at 40 °C ambient.
- ② All data referenced to sinusoidal commutation.
- ③ Add holding brake if applicable for total inertia.
- ④ Motor with 125 °C rated feedback and standard heat sink.
- ⑤ May be limited at some values of V_{bus}.
- ⑥ Measured at 25 °C.
- ⑦ Brake option reduces continuous torque rating by:
 AKMA51 = 0.24 Nm AKMA52 = 0.42 Nm AKMA53 = 0.55 Nm AKMA54 = 0.69 Nm
- ⑧ Brake option increases weight by 2.0 kg (4.4 lb)

AKMA5x Dimensional Data

AKMA 5 2 C - GN D N CA 1 K
 Motor Series Frame Size Winding Stack Length Mount/Shaft Connection Brake Feedback Thermal Sensor Seal

AKMA5x Frame

Flange Mount



AKMA5x Dimension Data

Code	Shaft	Pilot Dia. "A"	Shaft Dia. "B"	Shaft Length "C"	Motor Body Dia. "D"	Flange Dia. "E"	Bolt Circle Dia. "F"	Bolt Hole Dia. "G"
GC	Keyway	Ø95j6	Ø24k6	50	132	137	115	9+0.36/-0.0
GN	Smooth	Ø95j6	Ø24k6	50	132	137	115	9+0.36/-0.0

Code	"H"	Key Width "J"	Key Height "K"	"L"	Key Length "M"	Pilot Height "P"
GC	M8 DIN332	8h9	27 +0/-0.13	4	36 +0/-0.30	3.0 +0/-0.25
GN	M8 DIN332	-	-	-	-	3.0 +0/-0.25

MODEL	Connector Position "O"		Motor Length "N"	
	W/O Brake	W/ Brake	W/O Brake	W/ Brake
AKMA51	138.1	188.6	186.3	236.9
AKMA52	169.1	219.6	217.3	267.9
AKMA53	200.1	250.6	248.3	298.9
AKMA54	231.1	281.6	279.3	329.9

Dimensions are in mm.

*Complete AKMA series model nomenclature can be found on page 9.

Notes

AK**M**A **5** **2** **E** - **G****N** **D** **N** **C****A** **1** **K**
Motor Series Frame Size Stack Length Winding Mount/Shaft Connection Brake Feedback Thermal Sensor Seal

2 mm divisions

AKMA Motor Connector Pinouts

AKMAxx D- Connector Pinout

D- with SFD3 (CA)

AKMA x x x - xx **D 2 CA** x x
Connection Brake Feedback

D- with SFD-M (CB)

AKMA x x x - xx **D 2 CB** x x
Connection Brake Feedback

D- with HIPERFACE DSL (GU)

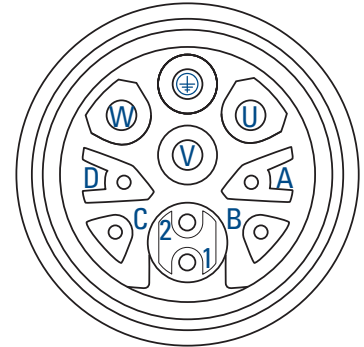
AKMA x x x - xx **D 2 GU** x x

D- with EnDAT 2.2 (LD)

AKMA x x x - xx **D 2 LD** x x

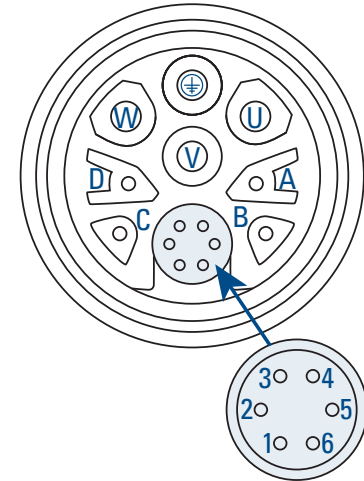
Power ± Brake + SFD-M/SFD3/HDSL

Function	AKMA M23
Phase U	U
Phase V	V
Phase W	W
PE	⊕
Brake +	A
N/C	B
N/C	C
Brake -	D
SFD-M/SFD3/HDSL+	1
SFD-M/SFD3/HDSL-	2



Power ± Brake + EnDAT 2.2

Function	AKMA M23
Phase U	U
Phase V	V
Phase W	W
PE	⊕
Brake +	A
N/C	B
N/C	C
Brake -	D
S+ Up	1
S- 0 V	2
Data+	3
Data-	4
Clock+	5
Clock-	6



Brake Option

Holding Brake

The holding brake is designed to provide motor shaft static holding torque with the brake coil de-energized. The brake must first be released (coil energized) prior to commanding motion as determined by its drop-out time. The optional brake is intended for stationary motor holding, or “parking,” and is NOT intended for dynamic braking (i.e. There should be absolutely no intended rotor motion when power is removed from the brake coil to physically engage brake.)

AKMA Servo Motor Brake Specifications

Motor	Minimum Static Torque @120 °C		Power Consumption @24V, 20 °C	Current @24V, 20 °C	Inertia		Closing Time (engage)	Opening Time (release)	Backlash	
	Nm	lb-in			kg-cm ²	lb-in-sec ²			Maximum	Typical
			Watts ±7%	A _{dc}			msec	msec	deg.	deg.
AKMA2	1.42	12.6	8.4	0.35	0.0128	1.81E-04	36	45	1.01	0.46
AKMA3	2.5	22.1	10.1	0.42	0.0135	1.91E-04	20	50	1.01	0.46
AKMA4	5.3	46.9	12.8	0.53	0.0579	8.20E-04	30	75	0.81	0.37
AKMA5	14.5	128	19.5	0.82	0.1658	2.35E-03	30	115	0.71	0.31

Note 1: Operating Voltage: 24 V_{bc} ± 10%.

Note 2: Maximum backlash is calculated using worst-case tolerancing, and typical backlash is calculated using statistical tolerancing.

AKMA Feedback Option Specifications

The AKMA motor is available with one of the four following feedback options and utilizes hybrid (power+brake+feedback) single-cable drive connectivity. A thermal sensor is connected to the encoder and temperature information is transferred over the communication protocol.

AKMA Feedback Option Specifications

Feedback	Description	Feedback Model	Technology	Single-turn resolution	Multi-turn resolution	Accuracy ±arc-min
CA	Smart Feedback Device	SFD3	Resolver	24 bits	---	8
CB	Smart Feedback Device, Multi-turn	SFD-M	Optical	24 bits	16 bits	1
GU	Hiperface DSL encoder	EEM37-2*	Capacitive	17 bits	12 bits (4096)	4
LD	EnDat 2.2 inductive encoder	EQI1131**	Inductive	19 bits	12 bits (4096)	2

■ Functional Safety Capable *SICK HIPERFACE DSL model EEM37-2KF0A017A. Please visit <https://www.sick.com> to download the latest safety data sheet.
**HEIDENHAIN models EQI1131. Please visit <https://www.heidenhain.com> to download the latest safety data sheets.

Absolute Digital Encoder Options

HIPERFACE DSL Capacitive (GU)

Type		Multi-Turn "GU"
Frame Size		AKMA2-5
Number of Absolute Ascertainable Revolutions		4096
Supply Voltage Range	V _{DC}	7 to 12
Current Consumption	mA MAX.	150
Operating Temperature	°C MIN/MAX	-40/115
Inertia	kg-cm ²	0.001
Output Interface		SICK HIPERFACE DSL
Vibration Resistance – EN 60068-2-6	g [m/s ²]	50 g [490 m/s ²] – 10 to 2000 Hz
Shock Resistance – EN 60068-2-27	g [m/s ²]	≤100 g [981 m/s ²] – 6 ms
Manufacturer Product Type		EEM37-2KF0A017A*

■ Functional Safety Capable *SICK HIPERFACE DSL model EEM37-2KF0A017A. Please visit <https://www.sick.com> to download the latest safety data sheet.

EnDat Inductive (LD)

Type		Multi-Turn "LD"
Frame Size		AKMA 2-5
Revolutions		4096
Input Voltage	V _{DC}	3.6 to 14
Current Consumption	mA Typical	5 V: 115 (without load)
Operating Temperature	°C MIN/MAX	-40/115
Inertia	kg-cm ²	0.0030
Output Interface		HEIDENHAIN EnDat 2.2/22*
Vibration Resistance – EN 60068-2-6	g [m/s ²]	Stator ≤41 g [400 m/s ²] – Rotor ≤61 g [600 m/s ²] – 55 to 2000 Hz
Shock Resistance – EN 60068-2-27	g [m/s ²]	≤100 g [981 m/s ²] – 6 ms
Manufacturer Product Type		EQI 1131*

■ Functional Safety Capable *HEIDENHAIN models EQI1131 & EQI1331. Please visit <https://www.heidenhain.com> to download the latest safety data sheets.

Encoder Alignment: With positive DC current into phase W and out of phase V (U floats) the encoder is aligned to ±3 electrical degrees.

Absolute Digital Encoder Options

Kollmorgen Smart Feedback Device, Multi-turn (SFD-M) (CB)

The SFD-M Feedback uses a single motor cable, requiring just one cable between the drive and motor.

The feedback has both power and communication on a single wire pair, reducing overall wiring costs. SFD-M offers 24-bit absolute single-turn resolution, batteryless 16-bit (65,536) multi-turn absolute revolutions and an absolute angular accuracy of +/- 1 arc-min.

In addition, the device includes onboard memory for an electronic motor datasheet which enables device auto-recognition for faster setup and commissioning when paired with any Kollmorgen Essentials, AKD, or AKD2G drive.

Angle Measurement:

Single-Turn Resolution: $2^{24} = 16,777,216$ counts per rev
Multi-Turn Absolute Range: $2^{16} = 65,536$ absolute revolutions* (batteryless)
Accuracy: < +/- 1 arc-min typical 25 °C
< +/- 3 arc-min worst case
Electrical Noise: < 2^{-22} Rev rms at full bandwidth
Bandwidth: > 2 kHz at -3 dB
> 1 kHz at -45° phase lag
Max Continuous Speed: 10,000 RPM
Velocity Ripple: < 1% p-p (typical)
Velocity Noise: < 0.3 RPM rms at full bandwidth

Power Supply:

Input Voltage: 7 V - 12 V accepted (at motor terminals)
Input current maximum: 140 mA DC

Digital Communications:

Baud rate: 2.5 MBaud
Signaling: RS-485 differential using differential Manchester encoding
Update period: New position sample every 51.2 μ s
Error detection: 5-bit CRC and running parity check

Environmental:

Feedback Operating Temperature: -40 to 120 °C
Humidity: 10% to 90% non-condensing
Vibration Resistance: 30g (294 m/s²) @ 55-2000 Hz (EN60068-2-6)
Shock Resistance: 100g (981 m/s²) @ 6 ms (EN60068-2-27)

* When paired with AKD, this is limited to 4096 absolute revolutions (12-bits)

Kollmorgen Smart Feedback Device, Gen 3 (SFD3) (CA)

Kollmorgen's proprietary SFD3 Feedback uses a single motor cable, requiring just one cable between the drive and motor. The feedback has both power and communication on a single wire pair, reducing overall wiring costs. In addition, the device includes onboard memory for an electronic motor datasheet.

Angle Measurement:

Resolution: $2^{24} = 16,777,216$ counts per rev
Accuracy: < ± 0.75 arc-min electrical + sensor error
Size 15 sensor error: ± 8 arc-min net (AKMA 2-4)
Size 21 sensor error: ± 9 arc-min net (AKMA 5)
Electrical Noise: < 2^{-17} Rev rms at full bandwidth
Bandwidth: > 2000 Hz at -3 dB
> 1000 Hz at -45° phase lag
Max Continuous Speed: 20,000 RPM
Velocity Ripple: < 0.2% p-p electronics only
Size 15 sensor: < 2.0% p-p net (AKMA 2-4)
Size 21 sensor: < 2.5% p-p net (AKMA 5)
Velocity Noise: < 4 RPM rms at full bandwidth

Environmental:

Operating ambient: -20 to 120 °C
Humidity: 10% to 90% non-condensing
Storage temperature: -40 to 135 °C

Digital Communications:

Baud Rate: 2.5 MBaud
Signaling: RS-485 differential using differential Manchester encoding
Update Period: Once every 51.2 μ s new position sample
Error Detection: 5 bit CRC and running parity check

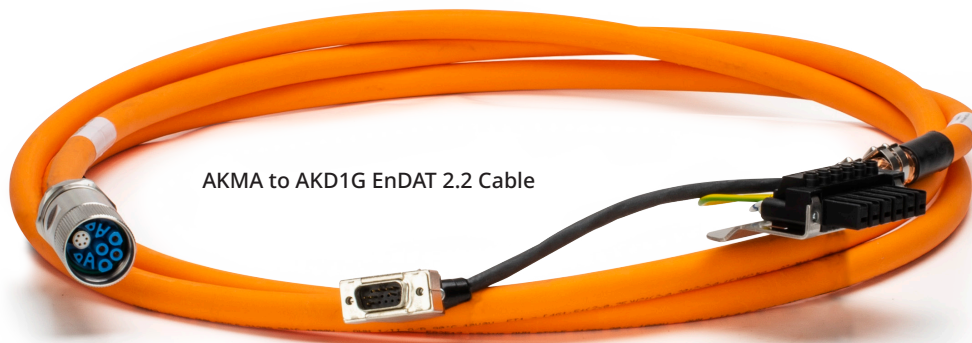
Power Supply:

Supply at Drive: 7 to 12 V
Supply at SFD in motor: 7 to 12 V
Nominal Supply Current: 65 mA at 10 V
Worst Case Supply: 110 mA at 10 V
Cable Resistance: Com+, Com- net < 10 Ohm net

AKMA Motor Cables

AKMA Cable Properties

Test voltage	3 kVAC
Operating voltage	1000 VAC
Temperature range	-40 °C/+90 °C static/dynamic/storage
Minimum bending radius - static	5 x Dia
Minimum bending radius - dynamic	8 x Dia
Max. speed	300 m/min
Max. acceleration	50 m/s ²
Max. torsion	30°/m
Max. number of cycles	5,000,000
Flame resistance	EN50265-1-2/IEC60332-1-2/UL VW-1/CSA FT1
Halogen free	EN50267-2-1/IEC60754-1
Hydrocarbons and oil resistance	UL1581/VDE0472 part 803 A/B

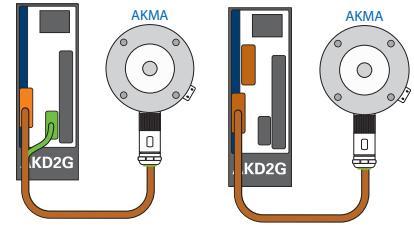


H2 - 21 - 015 - W1 - 00 - XXXX00

Cable Version
Drive Connector
Wire X-section
Motor Mating Connector
Customization
Length

AKD2G X1/X2 Connector

AKD2G X23 Feedback Connector



AKMAxx Motor to AKD2G Servo Drive Cables

Voltage (V _{AC})	Drive	Motor Feedback	Motor Connector	Current Rating* (A)	Hybrid Cable
120-240	AKD2G-SPx-6V03x	SFD3 (CA) SFD-M (CB) HIPERFACE DSL (GU)	Single straight IP69K	Rms < 11	H2-21-010-W1-00-XXXX00
	AKD2G-SPx-6V06x			Rms < 15	H2-21-015-W1-00-XXXX00
	AKD2G-SPx-6V12x				
AKD2G-SPx-7V03x					
AKD2G-SPx-7V06x					
240-480	AKD2G-SPx-7V12x			Rms < 20	H2-21-025-W1-00-XXXX00
	AKD2G-SPx-7V24x	Rms < 27	Contact Kollmorgen Support		
	120-240	AKD2G-SPx-6V03x	EnDat 2.2 (LD)	Single straight IP69K	Rms < 15
AKD2G-SPx-6V06x					
AKD2G-SPx-6V12x					
AKD2G-SPx-7V03x					
AKD2G-SPx-7V06x					
AKD2G-SPx-7V12x					
240-480	AKD2G-SPx-7V24x	Rms < 20	H2-21-025-W6-00-XXXX00		
		Rms < 27	Contact Kollmorgen Support		

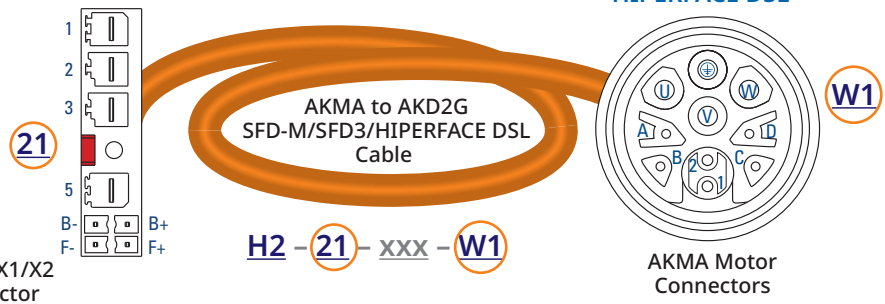
* Current ratings used on a IEC 60364-5-52 standard

AKD®2G Servo Drive Cable Pinouts

Power ± Brake + SFD-M/SFD3/HDSL

AKD2G X1/X2	Function	AKMA M23
1	Phase U	U
2	Phase V	V
3	Phase W	W
Retention Latch, Shield Screw		
5	PE	⊕
B+	Brake +	A
B-	Brake -	D
F+	SFD-M/SFD3/HDSL+	1
F-	SFD-M/SFD3/HDSL-	2

AKD2G X1/X2 Connector



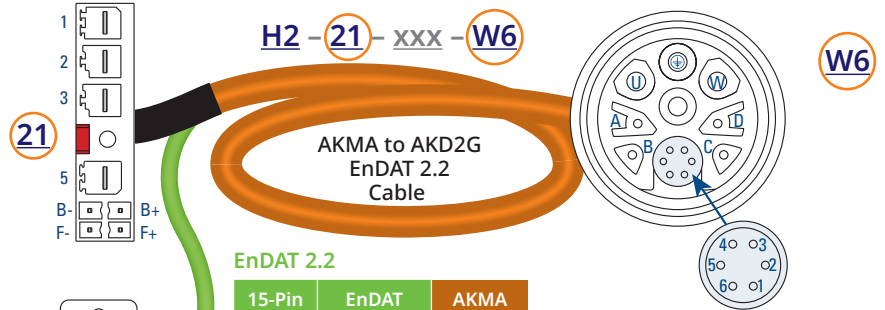
H2 - 21 - xxx - W1

H2 - 21 - xxx - W6

Power ± Brake

AKD2G X1/X2	Function	AKMA M23
1	Phase U	U
2	Phase V	V
3	Phase W	W
Retention Latch, Shield Screw		
5	PE	⊕
B+	Brake +	A
B-	Brake -	D
F+	-	-
F-	-	-

AKD2G X23 Connector



EnDAT 2.2

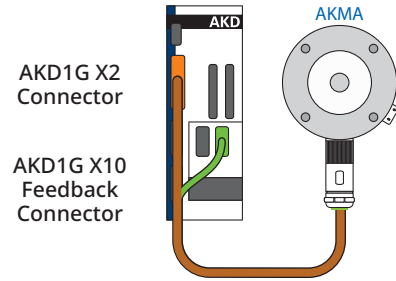
15-Pin Dsub	EnDAT 2.2*	AKMA M23
2	CLK+	5
3	CLK-	6
10	5.1 V+ Up	1
11	0 V- Un	2
6	DAT+	3
7	DAT-	4

EnDat2.2

AKMA Motor Cables

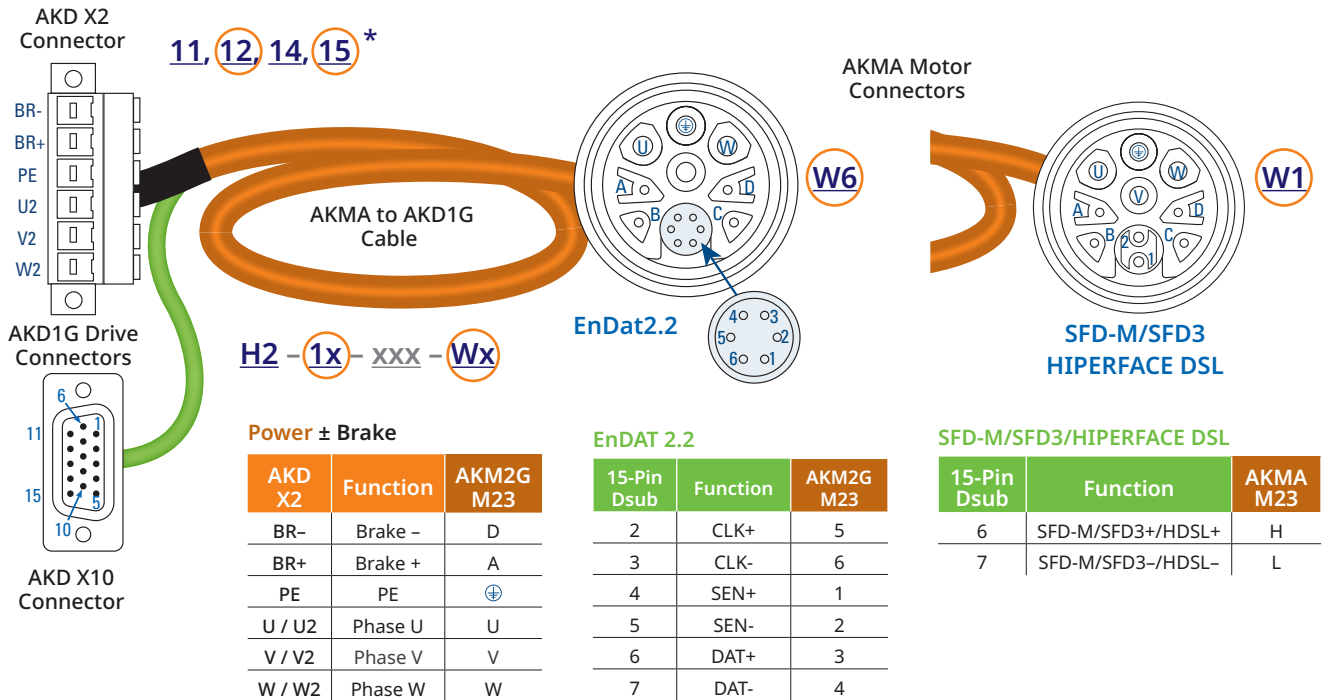
H2 - 12 - 015 - W1 - 00 - XXXX00
 Cable Version Drive Connector Wire X-section Motor Mating Connector Customization Length

AKMAxx Motor to AKD Servo Drive Cables



Voltage (V _{AC})	Drive	Motor Feedback	Motor Connector	Current Rating ¹ (A)	Hybrid Cable		
120-240	AKD-x00306 AKD-x00606	SFD3 (CA) SFD-M (CB) HIPERFACE DSL (GU)	Single straight IP69K	Rms < 11	H2-11-010-W1-00-XXXX00		
				Rms < 15	H2-11-015-W1-00-XXXX00		
	Rms < 15			H2-12-015-W1-00-XXXX00			
	Rms < 20			H2-12-025-W1-00-XXXX00			
	Rms < 27			H2-12-040-W1-00-XXXX00			
240-480	AKD-x00307 AKD-x01207 AKD-x02407	SFD3 (CA) SFD-M (CB) HIPERFACE DSL (GU)	Single straight IP69K	Rms < 15	H2-12-015-W1-00-XXXX00		
				Rms < 20	H2-12-025-W1-00-XXXX00		
				Rms < 27	H2-12-040-W1-00-XXXX00		
120-240	AKD-x00306 AKD-x00606			EnDAT 2.2 (LD)	Single straight IP69K	Rms < 15	H2-14-015-W6-00-XXXX00
						Rms < 15	H2-15-015-W6-00-XXXX00
	Rms < 20	H2-15-025-W6-00-XXXX00					
	Rms < 27	H2-15-040-W6-00-XXXX00					
	Rms < 15	H2-15-015-W6-00-XXXX00					
240-480	AKD-x00307 AKD-x01207 AKD-x02407	EnDAT 2.2 (LD)	Single straight IP69K	Rms < 15	H2-15-015-W6-00-XXXX00		
				Rms < 20	H2-15-025-W6-00-XXXX00		
				Rms < 27	H2-15-040-W6-00-XXXX00		

AKD Servo Drive Cable Pinouts



*Connector designation depends on the drive model. Please refer to the cable nomenclature on page 36 for more information.

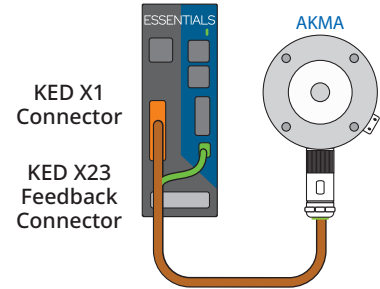
AKMA Motor Cables

H2 - 51 - 015 - W1 - 00 - XXXX00

Cable Version
Drive Connector
Wire X-section
Motor Making Connector
Customization
Length

AKMAxx Motor to Kollmorgen Essentials Servo Drive Cables*

*New product - please contact Kollmorgen Customer Support for availability.



Voltage (V _{AC})	Drive	Motor Feedback	Motor Connector	Current Rating ¹ (A)	Hybrid Cable*
120-240	KED-6V03	SFD3 (CA) SFD-M (CB)	Single straight IP69K	Rms < 15	H2-51-015-W1-00-XXXX00
	KED-6V06			Rms < 20	H2-52-025-W1-00-XXXX00
	KED-6V12			Rms < 15	H2-52-015-W1-00-XXXX00
240-480	KED-7V03			Rms < 20	H2-52-025-W1-00-XXXX00
	KED-7V06				
	KED-7V12				

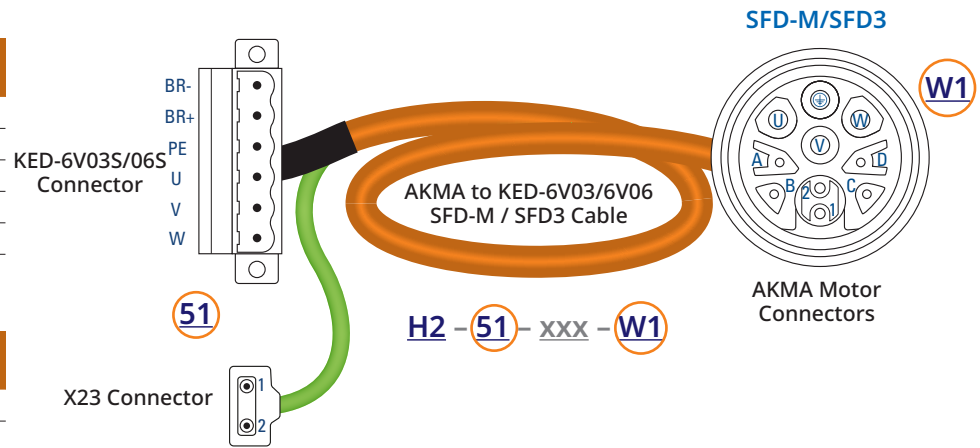
Kollmorgen Essentials Servo Drive Cable Pinouts

Power ± Brake

KED X1	Function	AKMA M23
BR-	Brake +	D
BR+	Brake -	A
PE	PE	⊕
U	Phase U	U
V	Phase V	V
W	Phase W	W

SFD-M/SFD3

KED X23	Function	AKMA M23
F-	SFD-M/SFD3	1
F-	SFD-M/SFD3	2

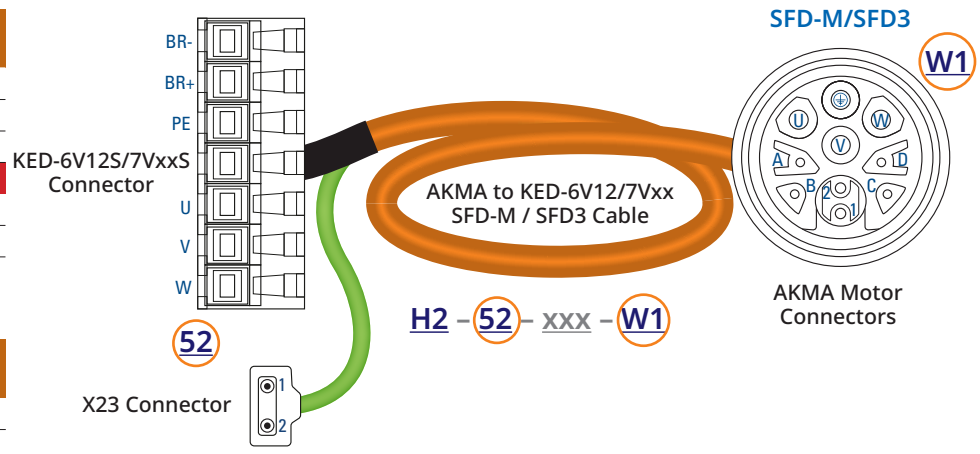


Power ± Brake

KED X1/X23	Function	AKMA M23
BR-	Brake +	D
BR+	Brake -	A
PE	PE	⊕
Retention Latch		
U	Phase U	U
V	Phase V	V
W	Phase W	W

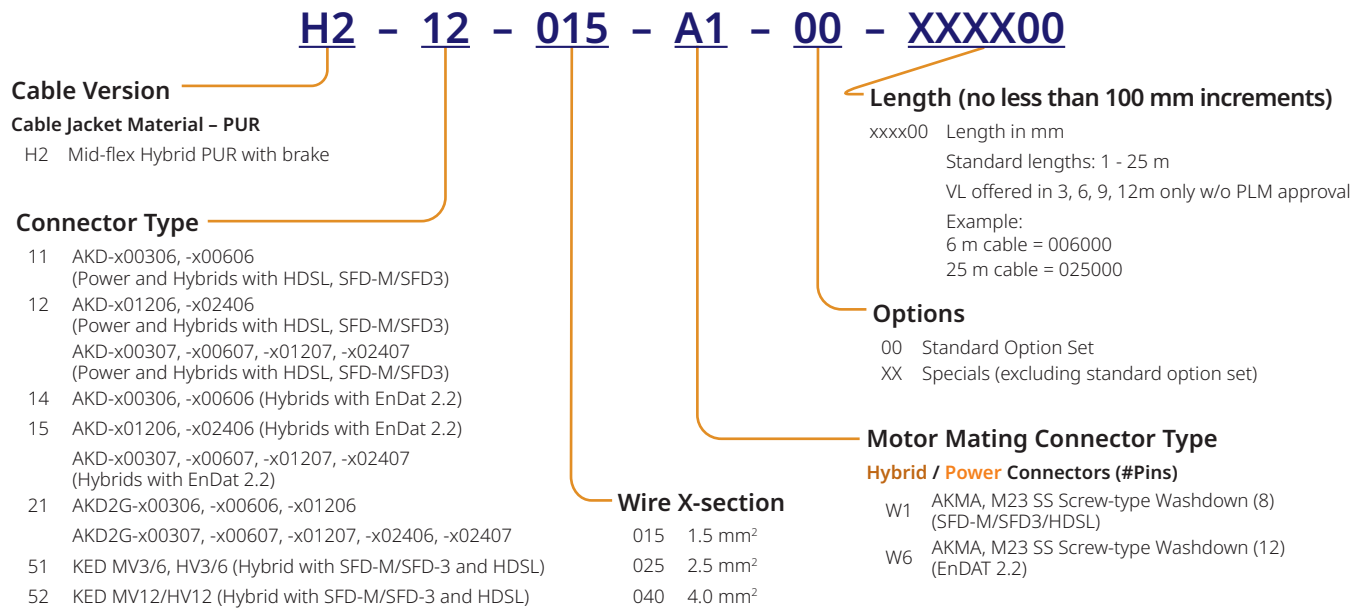
SFD-M/SFD3

KED X23	Function	AKMA M23
F-	SFD-M/SFD3	1
F-	SFD-M/SFD3	2



AKMA Motor Cables

AKMA 2G Cable Nomenclature



Notes



2 mm divisions

I. General Technical Data

Ambient Temperature: -20 °C to +40 °C for site altitude up to 1000 m amsl (at rated values). It is vital to consult our applications department for ambient temperatures above 40 °C and/or any enclosed environment.

Power De-rating (currents and torques): 1% / °C in range 40 °C...50 °C up to 1000 m amsl for site altitude above 1000 m amsl and 40 °C

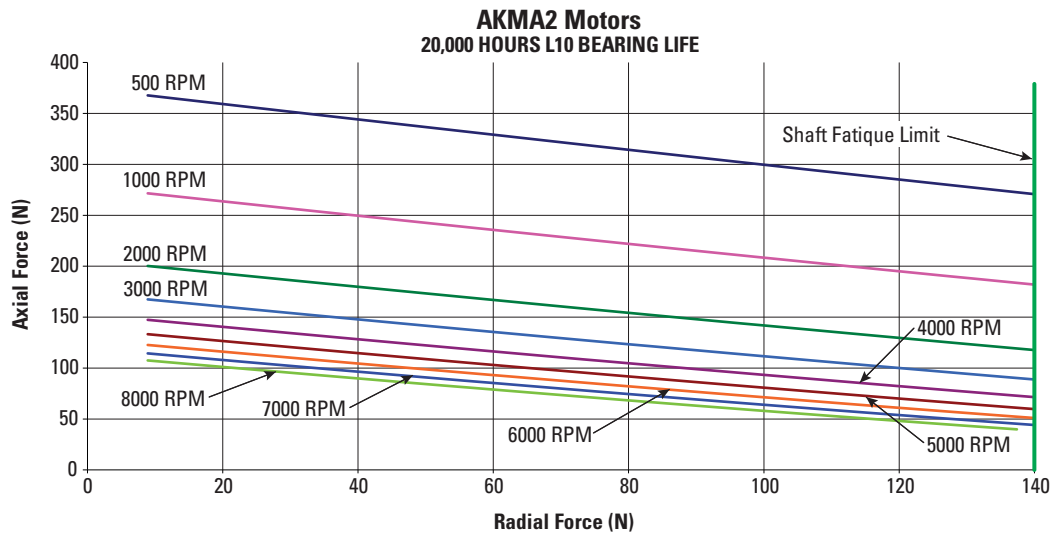
- » 6% up to 2000 m amsl
- » 17% up to 3000 m amsl
- » 30% up to 4000 m amsl
- » 55% up to 5000 m amsl

For site altitudes above 1000 m amsl, no de-rating with temperature reduction of 10 °C / 1000 m

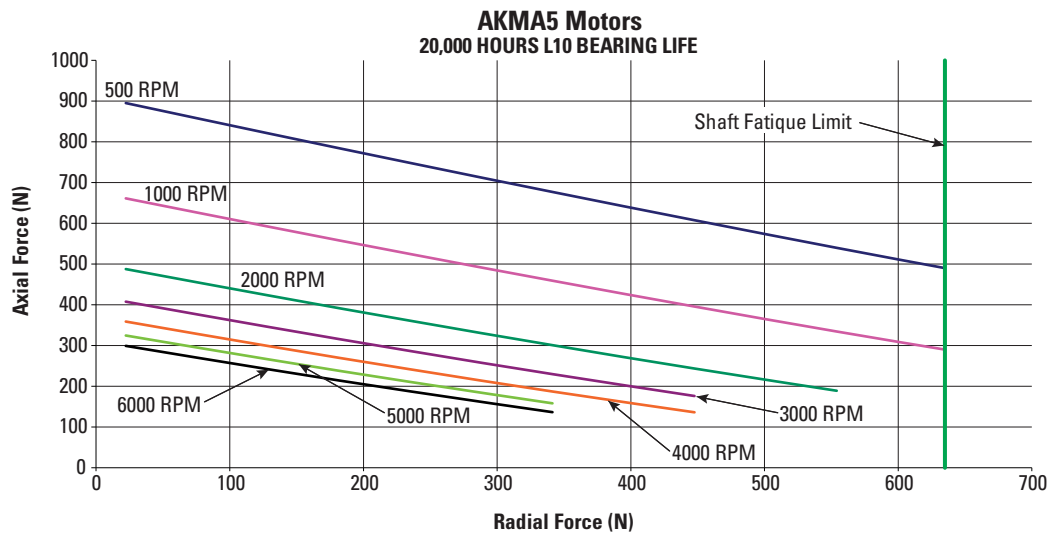
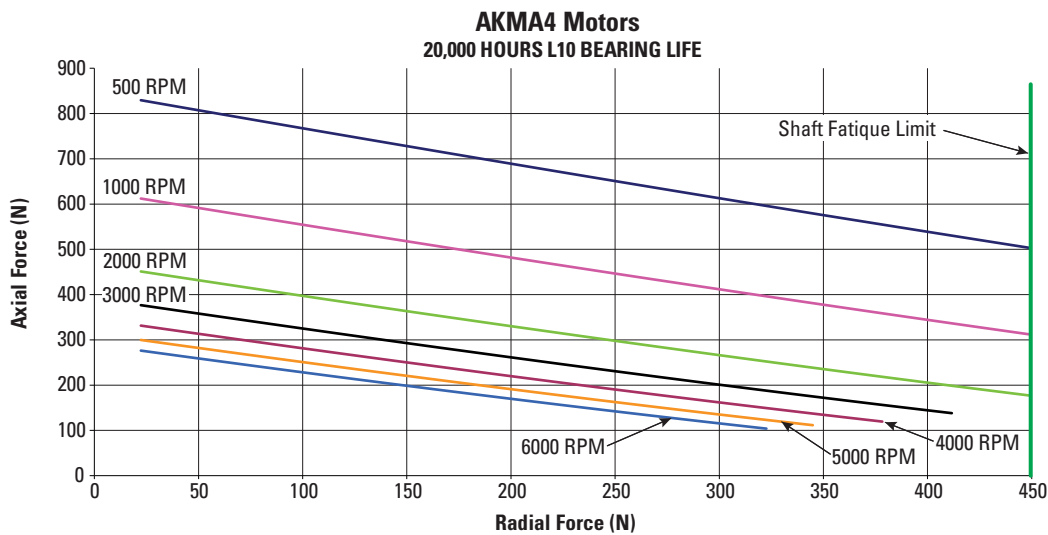
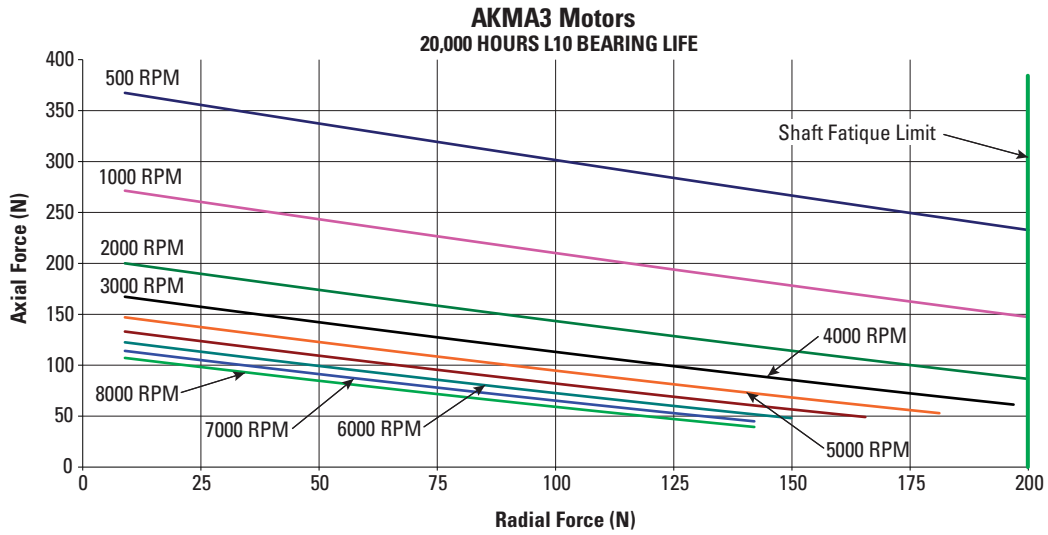
Temperature De-rating: If the application requires de-rating due to lower motor surface temperature, please contact our applications department.

Ball-bearing Life: ≥ 20,000 operating hours

II. L10 Bearing Fatigue



Continued on next page.



III. Shaft Loading

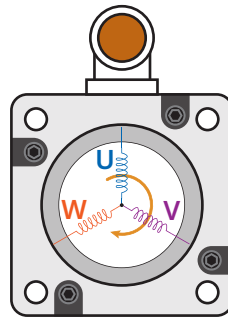
Motor	Max. Radial Force (N)	Max. Axial Force (N)
AKMA2xy-A	140	600
AKMA3xy-A	200	600
AKMA4xy-A	450	1400
AKMA5xy-G	635	1740

The maximum radial load ratings reflect the following assumptions:

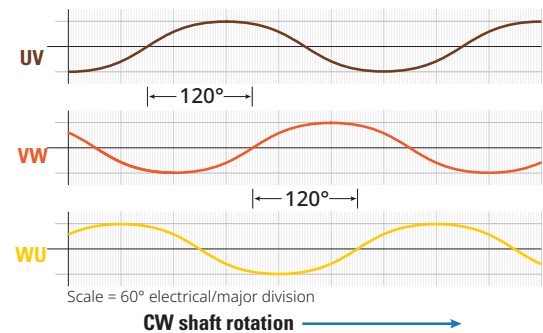
1. Motors are operated with peak torque of the longest stack length of the frame size.
2. Constant radial load on the end of the shaft for the smallest OD and longest standard shaft extension.
3. Infinite life with 99% reliability.
4. Safety factor = 2.

IV. Phasing Diagram - All Motors

- » When the motor is rotated C.W. (viewed from drive shaft end), the following BEMF voltage waveforms result:
- » Voltage phase-U, leads Voltage phase-V, by 120-degrees
- » Voltage phase-V, leads Voltage phase-W, by 120-degrees
- » Voltage phase-W, leads Voltage phase-U, by 120-degrees



BEMF Waveforms



V. Protection Class

Shaft Seal	Flange Sealing	Protection Class
PTFE	O-Ring: EPDM (K) or Viton (V)	IP69K

Protection class IP69K has been created for high pressure and high temperature cleaning according to DIN 40050-9. Code "6" (Dust tight. No ingress of dust.) defines the protection against solids. Code "9K" (Protected against close-range high pressure, high temperature spray downs.) defines the protection against liquids.

IP69K protection class is for static use only. This rating does not account for water present while the shaft is rotating. For applications that require sealing during rotation, please contact Kollmorgen Customer Support.

VI. Insulation Material

AKMA motors are insulation class F according to IEC 60085 (UL1446 class F).

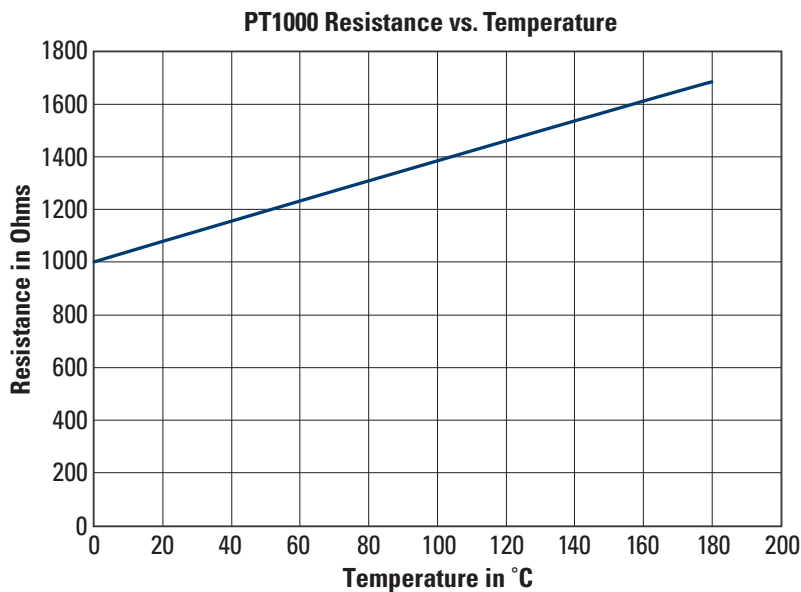
VII. Surface

The AKMA motor housing is made from anodized 6082 aluminum.

IX. Protective Device

AKMA motors are fitted with an electrically isolated temperature sensor (rated temperature $155\text{ }^{\circ}\text{C} \pm 5\%$) and integrate into the motor temperature monitoring system (e.g. Kollmorgen's AKD). The standard motor option is equipped with a PT1000 thermal sensor; with a threshold limit setting of 1592 Ohms.

The standard sensor option is defined by following diagram:



Please note, these protection devices are for monitoring and protecting the motor during normal operation and when attempting to maximize operation—they should not be expected to provide protection against a short or other overload event.

IX. Vibration Class

Velocity [rpm]	Max. Rel. Vibration Displacement [μm]	Max. Run-out [μm]
≤ 1800	90	23
> 1800	65	16

AKMA motors are designed and manufactured to meet vibration class A (EN 60034-14). Hence, a defined speed range of 600 to 3600 rpm, with a frame size between 56 and 132 mm, means the permitted vibration is 1.6 mm/s.

AKMA Hygienic Design Guide

Hygienic Design

The Food and Drug Administration (FDA) is an agency of the United States Department of Health and Human Services. The FDA is responsible for protecting and promoting public health through the regulation and supervision of food safety, vaccines, biopharmaceuticals, blood transfusions, medical devices and other products.

The “European Hygienic Engineering and Design Group” (EHEDG) is a European-based non-government organization devoted to the advancement of hygienic design and food engineering. European legislation requires that handling, preparation, processing, packaging, etc. of food is done hygienically, with hygienic machinery in hygienic premises (the food hygiene directive, the machine directive and the food contact materials directive).

Certifications: UL, CE, RoHs, UKCA

Surface: 6082 Aluminum Anodized; satin gray

Immunity: Against tested industrial cleaning agent, corrosion-proof

Degree of Protection: IP69K

Mounting Screw*: Stainless steel 316L/1.4404, sealant FDA 21 CFR 175.300

O-Ring: EPDM or Viton, FDA 21 CFR 177.2600

Shaft: Stainless steel 316L/1.4404

Rotary Shaft Seal: Mineral filled PTFE, single lip, mineral: FDA 21 CFR 175.300, PTFE: FDA 21 CFR 177.1500

Bearing Grease: Food-grade as per FDA 21 CFR 178.3570

Connector with Viton Seal: Stainless steel 1.4404, Viton seal FDA 21 CFR 177.2600

Name Plate: Laser marked in housing

Size: AKMA2 to AKMA5

*Optional, included in the mounting kit

AKMA Co-Engineered Solutions

With modified and custom AKMA solutions, you can rely on decades of Kollmorgen expertise to solve your motion challenges and help your machine stand out from the crowd.



Modified Standard

Because our application expertise runs deep and our product portfolio is so broad, we can take any standard product and modify to different degrees to suit your specific needs – without significant sacrifice of lead time or cost. This approach ensures quality, performance and reliability by leveraging our proven track record.

Kollmorgen application engineers have a great deal of experience helping OEM engineers achieve their objectives. Typical motor modifications include: shaft, housing, winding, feedback type, mounting and connectors.

Project Management

We follow a structured development process from initial concept to volume production. This enables us to provide a complete solution from design to implementation.

Our skilled engineering team is assigned to each project and ensures a high quality product designed and delivered on time, successfully taking the prototype to full production.

- Dedicated Resources & Equipment
- Real Time Customer Collaboration
- Validation of Performance, Cost & Manufacturability Before Volume Production

Customer Visibility Throughout the Entire Process

A communicative and proactive approach keeps you updated and aware of what is required throughout, what it will cost, and what to expect for design testing.

This not only puts you in charge of approving any modifications before installation, but ensures the product is up and running quickly, with minimal development time and maximum value.

Engineering Excellence

What really sets us apart is our engineering expertise. With over 50 years of successfully designing custom motors, we are able to quickly assess, design and implement a solution that meets your needs.

Our engineering team has decades of experience in motor design, which means they have designed solutions for almost every unique and challenging situation. Their insightfulness and expertise will guide you through the development and implementation of an optimized motor solution.

We rely on the most advanced simulation tools to deliver the best products, designed to withstand the most unique and challenging environments.

Why You Should Partner with Kollmorgen

- Experienced application engineers help define a customer's needs and identify the optimal Kollmorgen products and technologies
- Products optimized or developed by cross-functional teams to meet customer needs
- Rapid prototyping
- Smooth transition from prototype designs to sustainable and cost effective manufacturing
- Industry-proven quality, performance, and delivery
- Proven technology building blocks mitigate risks of customization

Contact Kollmorgen Customer Support today to discuss our design capabilities for a modified and co-engineered AKMA solution to meet your specific needs.

Kollmorgen Servo Drive Solutions

AKD Product Family

Kollmorgen offers an extensive range of servo drives, designed to provide precise control, optimum torque and a rich feature set to complement our wide range of rotary servo motors and linear positioning systems. The AKD product family of servo drives offer the broadest connectivity with the most advanced control technology, simplified commissioning and compact packaging available in the global marketplace.



AKD Product Family

Parameter	AKD2G	AKD	AKD BASIC	AKD PDMM	AKD-N/AKD-C
Base I/O	12 digital 2 analog	11 digital 2 analog	11 digital 2 analog	17 digital 2 analog	5 digital
Expansion I/O ¹	8 digital 2 analog *Drive size is the same	No	20 digital 2 analog *adds 30 mm to the drive width for drives up to 12A	Up to 1000+ remote I/O via EtherCAT	No
Safe I/O	2 digital inputs for Safey option 1 4 digital inputs for SafeMotion options	No	No	No	No
SafeMotion ²	Yes	STO only	STO only	STO only	STO only
Optimized for single cable ³	Yes	No	No	No	Yes
Continuous current limit ⁴	24A	48A	48A	48A	12A
Connectivity ⁵	Analog, EtherCAT, CANopen, Profinet IRT, Ethernet/IP, TCP/IP, Modbus/TCP	Analog, EtherCAT, CANopen, Profinet RT, Ethernet/IP, TCP/IP, Modbus/TCP	Analog	EtherCAT, CANopen, Profinet RT, Ethernet/IP, TCP/IP, Modbus/TCP	EtherCAT
Axis Configuration	single or dual	single	single	single	single
Drive-resident controller	No	No	No	Yes	No
Programmability	parameterized, 2 axes control loops, actlon table	parameterized	parameterized, BASIC programmable	parameterized, IEC 61131-3 via PLCopen or Pipe Network	parameterized
Graphical Display	160x128-pixel display	2 digit LED	2 digit LED	3 digit LED	Status LED
Removeable Memory ⁶	Yes	No	Yes	Yes	No
System Architecture	Centralized	Centralized	Centralized	Centralized	Decentralized
IP Rating	IP20	IP20	IP20	IP20	IP67 (AKD-N)

Notes:

- 1: Add EtherCAT multi-axis master, PCMM, to the AKD drive family to enable remote I/O expansion via EtherCAT. PCMM controller functionality is built into the PDMM
- 2: SafeMotion includes FSoE, STO, SS1, SS2, SOS, SDB, SBC/SBT, SLS, SSR, SSM, SDI, SAR, SLA, SLI, SLP, SCA up to SIL3 / PLe
- 3: Single cable optimized means one single cable for power & motor feedback with 1 connector at motor end and 1 connector at drive end
- 4: Higher power variants under development in some models. Consult factory for availability.
- 5: Consult factory on connectivity options for AKD2G.
- 6: Optional integrated SD card for easy backup and drive cloning

Essentials Means Unparalleled Connectivity

Kollmorgen Essentials Drive

Kollmorgen's Essentials Drive includes all of the performance described previously, and is optimized to interface to a single-connector motor with Kollmorgen's Smart Feedback Device options (SFD-M or SFD3)

Multi-Protocol Support

No need to find the correct communication protocol option for your machine! All Essentials drives support multiple communication protocols out of the box. Just select between EtherNet/IP CIP Sync, EtherCAT or PROFINET IRT during setup.

Super-fast setup

Get your application up and running in 20 minutes or less with Kollmorgen's Express Setup layout within WorkBench, a simple, graphical configuration tool for PC that supports you throughout the entire commissioning process.

Versatile I/O

Each Kollmorgen Essentials Drive offers two fast digital inputs with <math><1 \mu\text{s}</math> reaction time, which can also be utilized for a secondary, incremental feedback solution. Two standard digital inputs and outputs are also built-in.

STO

Safety is always essential!

All Essentials drives come equipped with the certified safety function Safe Torque Off (STO), up to SIL 2 / PL d.



3-6 Amp
100-240 VAC

12 Amp
100-240 VAC
3-6 Amp
240-480 VAC

12 Amp
240-480 VAC



100-240 VAC 1-3 ϕ	Continuous Current	Peak Current	Typical Shaft Power	Height	Width	Depth	Depth w/ cable bend radius
	(Arms)	(Arms)	(kW)	mm (in)	mm (in)	mm (in)	mm (in)
KED-SPM-6V03 -A100-0000-A	3	9	0.625	172 (6.77)	60 (2.36)	165 (6.50)	225 (8.86)
KED-SPM-6V06 -A100-0000-A	6	18	1.25				
KED-SPM-6V12 -A100-0000-A	12	30	2.5	200 (7.87)	70 (2.75)	202 (7.95)	262 (10.31)

240-480 VAC 3 ϕ	Continuous Current	Peak Current	Typical Shaft Power	Height	Width	Depth	Depth w/ cable bend radius
	(Arms)	(Arms)	(kW)	mm (in)	mm (in)	mm (in)	mm (in)
KED-SPM-7V03 -A100-0000-A	3	9	1.5	200 (7.87)	70 (2.75)	202 (7.95)	262 (10.31)
KED-SPM-7V06 -A100-0000-A	6	18	2.5				
KED-SPM-7V12 -A100-0000-A	12	30	5	220 (8.66)			

Universal Drive Solutions for Food, Beverage, and Pharmaceutical Industries

Motors from Kollmorgen provide the perfect mix of performance and hygiene

The Kollmorgen modular system includes a wide range of motors with carefully graduated performance data, a variety of connection options, and feedback devices. With more than 500,000 standard motor designs, you will definitely find a suitable motor to meet your requirements. Meeting the strict legal regulations and the customers' requests for innovative yet cost-effective drive solutions always poses a challenge to the mechanical engineer. Drive solutions from Kollmorgen provide the perfect mix of hygiene and performance data for applications in normal and difficult operating environments, as well as for hygienic drives. Kollmorgen has invested more than 50 years of experience in the AKM2G, AKM, AKM Washdown, AKM Washdown Food, AKMA anodized and AKMH stainless steel motor ranges that prove themselves on a daily basis in the testing conditions of the food, beverage, and pharmaceutical industries.



	AKM	AKM Washdown	AKM Food Grade	AKMA	AKMH
Housing Material & Coating	Square-frame A380 Aluminum polyester powder coating; matte black	Square-frame A380 Aluminum 2K epoxy paint; gray	Square-frame A380 Aluminum 2K epoxy FDA-compliant paint; white	Round-frame 6082 Aluminum Anodized; satin gray	Round-frame 1.4404/316 Stainless steel; Surface roughness < 0.8 µm per EHEDG requirement
Mounting Style	Flange	Flange	Flange	Flange	Flange or Face
Ingress Protection (IP)	IP65 (static); w/shaft seal	IP67 (static)	IP67 (static)	IP69K (static)	IP69K (static)
IP Rating Definition	6 = Dust-tight				
	5 = Water jets (7 is possible w/ straight conn.)	7 = Immersion up to 1m, for 30 min.		9K = High-pressure/High-temp	
Shaft Seal	1 = Teflon shaft seal	0W = includes Teflon shaft seal	0F = includes IP67 Food-Grade PTFE shaft seal	IP69K Food-Grade PTFE shaft seal	IP69K Food-Grade PTFE shaft seal
Typical Connectors	Nickel-plated TE/ Interconnect Connectors	SS Hummel Connectors (unpainted)	SS Hummel Connectors (unpainted)	IP69K SS Motor-mounted Hummel Connectors	IP69K integrated motor cable; optional IP69K SS Motor-mounted Hummel Connectors
Application Examples	<ul style="list-style-type: none"> General factory automation where exposure to contaminants (i.e. fluids, oil, dust) is possible 	<ul style="list-style-type: none"> Food and beverage Packaging (i.e. transport axes with no direct contact to food) General factory automation (i.e. similar applications to AKM with added protection and longevity) 	<ul style="list-style-type: none"> Food and beverage Packaging Cutting Packing and filling where direct contact to food is possible (motor positioned laterally or below food) 	<ul style="list-style-type: none"> Food and beverage (i.e. meat slicing, proportioning, dispensing applications where direct contact to food is likely) Pharmaceutical production Medical laboratories Radar stations Harsh outdoor applications 	<ul style="list-style-type: none"> Food and beverage (including food contact and splash zones) Packaging Machine applications requiring heavy sanitization or exclusive use of stainless components (i.e. use of highly acidic, caustic chemicals) Pharmaceutical production Medical laboratories
Relative Price	\$	\$+	\$++	\$\$	\$\$\$

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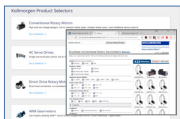
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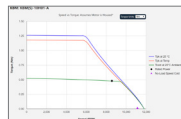
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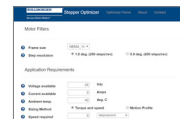
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Our global engineering, service and support network provides deep knowledge of all the major industries that rely on advanced motion control and automation technology. We offer world-class engineering expertise, self-service design tools, personalized field service, and easy access to our design, application and manufacturing centers in strategic locations across the globe.

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Kollmorgen, a Regal Rexnord brand, has more than 100 years of motion experience, proven in the industry's highest-performing, most reliable motors, drives, linear actuators, AGV (Automated Guided Vehicle) control solutions, and automation control platforms. We deliver breakthrough solutions that combine exceptional performance, reliability and ease of use, giving machine builders an irrefutable marketplace advantage.

KOLLMORGEN

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